



UNIVERSITÄT KARLSRUHE

The Automatic Computation of Second-Order Slope
Tuples for Some Nonsmooth Functions

Marco Schnurr

Preprint Nr. 07/09

Institut für Wissenschaftliches Rechnen
und Mathematische Modellbildung



76128 Karlsruhe

Anschrift des Verfassers:

Dr. Marco Schnurr
Institut für Angewandte und Numerische Mathematik
Universität Karlsruhe
D-76128 Karlsruhe

The Automatic Computation of Second-Order Slope Tuples for Some Nonsmooth Functions*

Marco Schnurr

Institute for Applied and Numerical Mathematics, University of Karlsruhe, D-76128
Karlsruhe, e-mail: marco.schnurr@math.uni-karlsruhe.de

Keywords: slope tuple, interval analysis, automatic slope computation, range enclosure

MSC 2000: 65G20, 65G99

Abstract

In this paper, we show how the automatic computation of second-order slope tuples can be performed. The algorithm allows for nonsmooth functions, such as $\varphi(x) = |u(x)|$ and $\varphi(x) = \max\{u(x), v(x)\}$, to occur in the function expression of the underlying function. Furthermore, we allow the function expression to contain functions given by two or more branches. By using interval arithmetic, second-order slope tuples provide verified enclosures of the range of the underlying function. We give some examples comparing range enclosures given by a second-order slope tuple with enclosures from previous papers.

1 Introduction

Automatic differentiation [13] is a tool for evaluating functions and derivatives simultaneously without using an explicit formula for the derivative. Combining this technique with interval analysis [1], enclosures of the function range and the derivative range on an interval $[x]$ may be computed simultaneously.

By using an arithmetic analogous to automatic differentiation, the automatic computation of first-order slope tuples is possible. For this purpose, the operations $+$, $-$, \cdot , $/$ and the evaluation of elementary functions need to be defined for first-order slope tuples. This approach goes back to Krawczyk and Neumaier [10] and was extended by Rump [16] and Ratz [14]. First-order slope tuples provide enclosures of the function range that may be sharper than enclosures obtained by the well-known mean value form. Moreover, slope tuples can be used in existence tests [4, 5, 11, 17, 19] or for verified global optimization [7, 8, 14, 15, 21].

In this paper, we extend this technique by defining a second-order slope tuple and by describing how the automatic computation of such tuples can be carried out. Shen and Wolfe [24] introduced an arithmetic for the automatic computation of second-order slope enclosures, and Kolev [9] improved this by providing optimal enclosures for convex and

*This paper contains some results from the author's dissertation [22].

concave elementary functions. However, both papers require the underlying function $f : D \subseteq \mathbb{R} \rightarrow \mathbb{R}$ to be twice continuously differentiable. In this paper, we present similar results that allow for nonsmooth functions $\varphi : D \subseteq \mathbb{R} \rightarrow \mathbb{R}$ occurring in the function expression of f , such as $\varphi(x) = |u(x)|$ and $\varphi(x) = \max\{u(x), v(x)\}$. Furthermore, the function expression of f may contain functions given by two or more branches. Moreover, intermediate results are enclosed by intervals. Hence, these algorithms can be used for verified computations on a floating-point computer.

The paper is organized as follows. Section 2 recalls slope functions and slope enclosures. In section 3, we define second-order slope tuples for univariate functions and explain how the automatic computation can be performed. In Section 4, we compare range enclosures obtained by second-order slope tuples with range enclosures given by other methods. Section 5 extends the technique from section 3 to multivariate functions. Furthermore, we explain an alternative approach called componentwise computation of slope tuples and give examples for both methods.

The numerical results were computed using Pascal-XSC programs on a floating-point computer under the operating system Suse Linux 9.3. The source code of the programs is freely available [18]. A current Pascal-XSC compiler is provided by the working group "Scientific Computing / Software Engineering" of the University of Wuppertal [25].

Throughout this paper, we let $[x] = [\underline{x}, \bar{x}] = \{x = (x_i) \in \mathbb{R}^n, \underline{x}_i \leq x_i \leq \bar{x}_i\}$ with $\underline{x}, \bar{x} \in \mathbb{R}^n$ denote an interval vector. The set of all interval vectors $[x] \subset \mathbb{R}^n$ is denoted by $\mathbb{I}\mathbb{R}^n$. For two interval vectors $[x], [y] \in \mathbb{I}\mathbb{R}^n$, the *interval hull* $[x] \sqcup [y]$ is the smallest interval vector in $\mathbb{I}\mathbb{R}^n$ containing $[x]$ and $[y]$, i.e.

$$([x] \sqcup [y])_i := [\min\{\underline{x}_i, \underline{y}_i\}, \max\{\bar{x}_i, \bar{y}_i\}].$$

Furthermore, by

$$\text{mid}[x] := \frac{\bar{x} + \underline{x}}{2}$$

we define the midpoint of $[x]$. Analogously, $\mathbb{I}\mathbb{R}^{n \times n}$ denotes the set of interval matrices $[A] = ([a]_{ij}) = \{A \in \mathbb{R}^{n \times n}, \underline{a}_{ij} \leq A_{ij} \leq \bar{a}_{ij}\}$.

In the following sections, we assume that a function f is given by a function expression consisting of a finite number of operations $+, -, \cdot, /$, and elementary functions (cf. [1]). Furthermore, we suppose that an interval arithmetic evaluation $f([x])$ on a given interval $[x]$ exists.

2 Slope Tuples

In this section, we consider functions $f : D \subseteq \mathbb{R} \rightarrow \mathbb{R}$.

Definition 2.1 (cf. [3]) Let $f \in C^n(D)$. Furthermore, let $p(x) = \sum_{i=0}^n a_i x^i$ be the Hermitean interpolation polynomial for f with respect to the nodes $x_0, \dots, x_n \in D$. Here, exactly $k+1$ elements of x_0, \dots, x_n are equal to x_i , if $f(x_i), \dots, f^{(k)}(x_i)$ are given for some node x_i . The leading coefficient a_n of p is called the *slope of n -th order of f with respect to x_0, \dots, x_n* . Notation:

$$\delta_n f(x_0, \dots, x_n) := a_n.$$

In the following theorem, we give some basic properties of slopes. The statements d) and e) in Theorem 2.2 are easy consequences of the Hermite-Genocchi Theorem (see [3]).

Theorem 2.2 Let $f \in C^n(D)$ and let $\delta_n f(x_0, \dots, x_n)$ be the slope of n -th order of f with respect to x_0, \dots, x_n . Then, the following statements hold:

- a) $\delta_n f(x_0, \dots, x_n)$ is symmetric with respect to its arguments x_i .
b) For $x_i \neq x_j$ we have the recursion formula

$$\delta_n f(x_0, \dots, x_n) = \frac{\delta_{n-1} f(x_0, \dots, x_{i-1}, x_{i+1}, \dots, x_n) - \delta_{n-1} f(x_0, \dots, x_{j-1}, x_{j+1}, \dots, x_n)}{x_j - x_i}.$$

- c) Setting $\omega_k(x) := \prod_{j=0}^{k-1} (x - x_j)$, we have

$$f(x) = \sum_{i=0}^{n-1} \delta_i f(x_0, \dots, x_i) \cdot \omega_i(x) + \delta_n f(x_0, \dots, x_{n-1}, x) \cdot \omega_n(x), \quad n \geq 1. \quad (1)$$

- d) The function $g : D \subseteq \mathbb{R}^{n+1} \rightarrow \mathbb{R}$ defined by

$$g(x_0, \dots, x_n) := \delta_n f(x_0, \dots, x_n)$$

is continuous.

- e) For the nodes $x_0 \leq x_1 \leq \dots \leq x_n$ there exists a $\xi \in [x_0, x_n]$ such that

$$\delta_n f(x_0, \dots, x_n) = \frac{f^{(n)}(\xi)}{n!}.$$

Definition 2.3 Let f be continuous and $x_0 \in D$ be fixed. A function $\delta f : D \rightarrow \mathbb{R}$ satisfying

$$f(x) = f(x_0) + \delta f(x; x_0) \cdot (x - x_0), \quad x \in D, \quad (2)$$

is called a *first-order slope function of f with respect to x_0* .

An interval $\delta f([x]; x_0) \in \mathbb{I}\mathbb{R}$ that encloses the range of $\delta f(x; x_0)$ on the interval $[x] \subseteq D$, i.e.

$$\delta f([x]; x_0) \supseteq \{ \delta f(x; x_0) \mid x \in [x] \},$$

is called a *(first-order) slope enclosure of f on $[x]$ with respect to x_0* .

In $x = x_0$, (2) is fulfilled for an arbitrary $\delta f(x_0; x_0) \in \mathbb{R}$. If f is differentiable in x_0 , then we always set $\delta f(x_0; x_0) := f'(x_0)$. Often, the midpoint $\text{mid}[x]$ of the interval $[x]$ is used for x_0 .

Remark 2.4 a) Let $\delta f([x]; x_0) = [\underline{\delta f}, \overline{\delta f}]$ be a first-order slope enclosure of f on $[x]$. Then, by (2), we have

$$f(x) \in f(x_0) + \delta f([x]; x_0) \cdot ([x] - x_0) \quad (3)$$

for all $x \in [x]$.

- b) Let f be differentiable on $[x]$ and $x_0 \in [x]$. Then, we have

$$\{ \delta f(x; x_0) \mid x \in [x], x \neq x_0 \} \subseteq \{ f'(x) \mid x \in [x] \}.$$

Therefore, (3) may provide sharper enclosures of the range of f on $[x]$ than the well-known mean value form.

For some continuous functions f and some $x_0 \in [x] \subseteq D$, a slope enclosure $\delta f([x]; x_0) \in \mathbb{IR}$ does not exist, e.g.

$$f(x) = \begin{cases} \sqrt{x} & \text{for } x \geq 0, \\ 0 & \text{for } x < 0, \end{cases}$$

with $x_0 = 0$, $[x] = [-1, 1]$. If f is continuous on $[x]$ and differentiable in $x_0 \in [x]$, then a slope enclosure $\delta f([x]; x_0) \in \mathbb{IR}$ exists. For a sufficient, more general existence criterion, we define the *limiting slope interval* [12].

Definition 2.5 Let f be continuous on $[x]$ and $x_0 \in [x]$. Suppose that both

$$\liminf_{x \rightarrow x_0} \frac{f(x) - f(x_0)}{x - x_0}$$

and

$$\limsup_{x \rightarrow x_0} \frac{f(x) - f(x_0)}{x - x_0}$$

exist. Then, the *limiting slope interval* $\delta f_{\text{lim}}([x_0]) \in \mathbb{IR}$ is

$$\delta f_{\text{lim}}([x_0]) := \left[\liminf_{x \rightarrow x_0} \frac{f(x) - f(x_0)}{x - x_0}, \limsup_{x \rightarrow x_0} \frac{f(x) - f(x_0)}{x - x_0} \right].$$

Remark 2.6 If f is Lipschitz continuous in some neighbourhood of x_0 , then the limiting slope interval $\delta f_{\text{lim}}([x_0])$ exists.

Example 2.7 For $f(x) = |x|$, $x_0 = 0$ we have $\delta f_{\text{lim}}([x_0]) = [-1, 1]$.

Lemma 2.8 Let f be continuous on $[x]$ and $x_0 \in [x]$. If $\delta f_{\text{lim}}([x_0]) \in \mathbb{IR}$ exists, then

$$\delta f([x]; x_0) = \left[\inf_{\substack{x \in [x] \\ x \neq x_0}} \frac{f(x) - f(x_0)}{x - x_0}, \sup_{\substack{x \in [x] \\ x \neq x_0}} \frac{f(x) - f(x_0)}{x - x_0} \right]$$

is a slope enclosure of f on $[x]$ with respect to x_0 .

Proof: $g : [x] \setminus \{x_0\} \rightarrow \mathbb{R}$, $g(x) := \frac{f(x) - f(x_0)}{x - x_0}$, is bounded. □

Remark 2.9 Let f be Lipschitz continuous in some neighbourhood of x_0 . Then, Muñoz und Kearfott [12] show the inclusion

$$\delta f_{\text{lim}}([x_0]) \subseteq \partial f(x_0), \tag{4}$$

where $\partial f(x_0)$ is the generalized gradient (see [2]). Furthermore, they give an example where

$$\delta f_{\text{lim}}([x_0]) \subset \partial f(x_0)$$

holds and also a sufficient condition for equality in (4).

Definition 2.10 Let f be continuous, $[x] \subseteq D$ and $x_0 \in [x]$. Assume that $f'(x_0)$ exists. A function $\delta_2 f : D \rightarrow \mathbb{R}$ satisfying

$$f(x) = f(x_0) + f'(x_0) \cdot (x - x_0) + \delta_2 f(x; x_0, x_0) \cdot (x - x_0)^2, \quad x \in D,$$

is called a *second-order slope function of f with respect to x_0* . An interval $\delta_2 f([x]; x_0, x_0) \in \mathbb{IR}$ with

$$f(x) \in f(x_0) + f'(x_0) \cdot (x - x_0) + \delta_2 f([x]; x_0, x_0) \cdot (x - x_0)^2, \quad x \in [x], \quad (5)$$

is called a *second-order slope enclosure of f on $[x]$ with respect to x_0* .

As an abbreviation we set $\delta_2 f(x; x_0) := \delta_2 f(x; x_0, x_0)$ and $\delta_2 f([x]; x_0) := \delta_2 f([x]; x_0, x_0)$. Furthermore, if f is twice differentiable in x_0 , then we always set $\delta_2 f(x; x_0) := \frac{1}{2} f''(x_0)$.

Remark 2.11 Assume that (5) holds. Then, we have the enclosure

$$f(x) \in f(x_0) + f'(x_0) \cdot ([x] - x_0) + \delta_2 f([x]; x_0) \cdot ([x] - x_0)^2$$

for all $x \in [x]$.

3 The automatic computation of second-order slope tuples for univariate functions

In this section, we consider univariate functions $u, v, w, z : D \subseteq \mathbb{R} \rightarrow \mathbb{R}$.

First, we recall the definition of a first-order slope tuple [14, 16]. Afterwards, we give a definition of second-order slope tuples that also permits nonsmooth functions.

Definition 3.1 Let u be continuous, $[x] \subseteq D$ and $x_0 \in [x]$. A triple $\mathcal{U} = (U_x, U_{x_0}, \delta U)$ with $U_x, U_{x_0}, \delta U \in \mathbb{IR}$ satisfying

$$\begin{aligned} u(x) &\in U_x, \\ u(x_0) &\in U_{x_0}, \\ u(x) - u(x_0) &\in \delta U \cdot (x - x_0), \end{aligned}$$

for all $x \in [x]$ is called a *first-order slope tuple for u on $[x]$ with respect to x_0* .

Definition 3.2 Let u be continuous, $[x] \subseteq D$ and $x_0 \in [x]$. A *second-order slope tuple for u on $[x]$ with respect to x_0* is a 5-tuple $\mathcal{U} = (U_x, U_{x_0}, \delta U_{x_0}, \delta U, \delta_2 U)$ with $U_x, U_{x_0}, \delta U_{x_0}, \delta U, \delta_2 U \in \mathbb{IR}$, $U_{x_0} \subseteq U_x$, satisfying

$$u(x) \in U_x, \quad (6)$$

$$u(x_0) \in U_{x_0}, \quad (7)$$

$$\delta u_{\text{lim}}([x_0]) \subseteq \delta U_{x_0}, \quad (8)$$

$$u(x) - u(x_0) \in \delta U \cdot (x - x_0), \quad (9)$$

$$u(x) - u(x_0) \in \delta U_{x_0} \cdot (x - x_0) + \delta_2 U \cdot (x - x_0)^2, \quad (10)$$

for all $x \in [x]$.

Remark 3.3 (10) does not imply that $\delta_2 U$ is a second-order slope enclosure in the sense of (5) because δU_{x_0} is a superset of $\delta u_{\text{lim}}([x_0])$. However, Remark 3.12 will explain why the term *slope tuple* is justified.

Remark 3.4 By (6)-(10) we get the enclosures

$$\begin{aligned} u(x) &\in U_x, \\ u(x) &\in U_{x_0} + \delta U \cdot ([x] - x_0), \\ u(x) &\in U_{x_0} + \delta U_{x_0} \cdot ([x] - x_0) + \delta_2 U \cdot ([x] - x_0)^2, \end{aligned}$$

for the range of u on $[x]$, where

$$([x] - x_0)^2 = \left[\min_{x \in [x]} (x - x_0)^2, \max_{x \in [x]} (x - x_0)^2 \right].$$

Remark 3.5 If $x = x_0$, then (9) and (10) are fulfilled for arbitrary δU , δU_{x_0} and $\delta_2 U$. So in checking these relations, we can restrict ourselves to $x \neq x_0$.

Lemma 3.6 $\mathcal{K} = (k, k, 0, 0, 0)$ is a second-order slope tuple for the constant function $u(x) \equiv k \in \mathbb{R}$ and $\mathcal{X} = ([x], x_0, 1, 1, 0)$ is a second-order slope tuple for the identity function $u(x) = x$ (both on $[x]$ with respect to $x_0 \in [x]$).

Definition 3.7 Let \mathcal{U} and \mathcal{V} be second-order slope tuples for the continuous functions u and v , respectively, on $[x] \subseteq D$ with respect to $x_0 \in [x]$.

a) For the addition or subtraction of \mathcal{U} and \mathcal{V} we define the 5-tuple $\mathcal{W} := \mathcal{U} \pm \mathcal{V}$ by

$$\begin{aligned} W_x &:= U_x \pm V_x, \\ W_{x_0} &:= U_{x_0} \pm V_{x_0}, \\ \delta W_{x_0} &:= \delta U_{x_0} \pm \delta V_{x_0}, \\ \delta W &:= \delta U \pm \delta V, \\ \delta_2 W &:= \delta_2 U \pm \delta_2 V. \end{aligned}$$

b) The multiplication $\mathcal{W} := \mathcal{U} \cdot \mathcal{V}$ is defined by

$$\begin{aligned} W_x &:= U_x \cdot V_x, \\ W_{x_0} &:= U_{x_0} \cdot V_{x_0}, \\ \delta W_{x_0} &:= \delta U_{x_0} \cdot V_{x_0} + U_{x_0} \cdot \delta V_{x_0}, \\ \delta W &:= \delta U \cdot V_{x_0} + U_x \cdot \delta V, \\ \delta_2 W &:= \delta_2 U \cdot V_{x_0} + U_x \cdot \delta_2 V + \delta U \cdot \delta V_{x_0}. \end{aligned}$$

c) If $0 \notin V_x$, then the division $\mathcal{W} := \mathcal{U}/\mathcal{V}$ is defined by

$$\begin{aligned} W_x &:= U_x / V_x, \\ W_{x_0} &:= U_{x_0} / V_{x_0}, \\ \delta W_{x_0} &:= (\delta U_{x_0} - W_{x_0} \cdot \delta V_{x_0}) / V_{x_0}, \\ \delta W &:= (\delta U - W_{x_0} \cdot \delta V) / V_x, \\ \delta_2 W &:= (\delta_2 U - W_{x_0} \cdot \delta_2 V - \delta W \cdot \delta V) / V_{x_0}. \end{aligned}$$

d) If φ is twice continuously differentiable, we define $\mathcal{W} := \varphi(\mathcal{U})$ by

$$\begin{aligned} W_x &:= \varphi(U_x), \\ W_{x_0} &:= \varphi(U_{x_0}), \\ \delta W_{x_0} &:= \delta\varphi(U_{x_0}; U_{x_0}) \cdot \delta U_{x_0}, \\ \delta W &:= \delta\varphi(U_x; U_{x_0}) \cdot \delta U, \\ \delta_2 W &:= \delta\varphi(U_x; U_{x_0}) \cdot \delta_2 U + \delta_2\varphi(U_x; U_{x_0}) \cdot \delta U_{x_0} \cdot \delta U. \end{aligned}$$

Here, we require $\varphi(U_x) \in \mathbb{IR}$ and $\varphi(U_{x_0}) \in \mathbb{IR}$ to enclose the range of φ on U_x and U_{x_0} , respectively, and $\delta\varphi(U_{x_0}; U_{x_0}) \in \mathbb{IR}$ to enclose

$$\{\delta\varphi(\widetilde{u}_{x_0}; u_{x_0}) \mid \widetilde{u}_{x_0} \in U_{x_0}, u_{x_0} \in U_{x_0}\}, \quad (11)$$

$\delta\varphi(U_x; U_{x_0}) \in \mathbb{IR}$ to enclose

$$\{\delta\varphi(u_x; u_{x_0}) \mid u_x \in U_x, u_{x_0} \in U_{x_0}\}, \quad (12)$$

and $\delta_2\varphi(U_x; U_{x_0}) \in \mathbb{IR}$ to enclose

$$\{\delta_2\varphi(u_x; u_{x_0}) \mid u_x \in U_x, u_{x_0} \in U_{x_0}\}. \quad (13)$$

Theorem 3.8 The 5-tuples $\mathcal{W} = (W_x, W_{x_0}, \delta W_{x_0}, \delta W, \delta_2 W)$ in Definition 3.7 are second-order slope tuples for the functions $w = u \circ v$, $\circ \in \{+, -, \cdot, /\}$ and $w(x) = \varphi(u(x))$ on $[x]$ with respect to x_0 , i.e. they satisfy (6)-(10).

Proof: The proof of (6), (7), and (9) for \mathcal{W} are analogous to those in [14, 16]. So, we only need to prove (8) and (10). We will show this for $\mathcal{W} := \mathcal{U} \cdot \mathcal{V}$ and $\mathcal{W} := \varphi(\mathcal{U})$. The proofs for addition, subtraction, and division are similar. Details can be found in [22].

For $w(x) = u(x) \cdot v(x)$ and $x \in [x]$ we have

$$\begin{aligned} w(x) - w(x_0) &= u(x)v(x) - u(x)v(x_0) + u(x)v(x_0) - u(x_0)v(x_0) \\ &= \left(u(x) \cdot \delta v(x; x_0) + \delta u(x; x_0) \cdot v(x_0) \right) \cdot (x - x_0) \end{aligned}$$

and thus obtain

$$\begin{aligned} \delta w_{\lim}([x_0]) &\subseteq u(x_0) \cdot \delta v_{\lim}([x_0]) + \delta u_{\lim}([x_0]) \cdot v(x_0) \\ &\subseteq U_{x_0} \cdot \delta V_{x_0} + \delta U_{x_0} \cdot V_{x_0}, \end{aligned}$$

which is (8) for $\mathcal{W} = \mathcal{U} \cdot \mathcal{V}$.

Furthermore, by using interval analysis and the slope tuple properties of \mathcal{U} and \mathcal{V} we have

$$\begin{aligned} w(x) - w(x_0) &= u(x)(v(x) - v(x_0)) + v(x_0)(u(x) - u(x_0)) \\ &\in u(x) \left(\delta V_{x_0} \cdot (x - x_0) + \delta_2 V \cdot (x - x_0)^2 \right) \\ &\quad + v(x_0) \left(\delta U_{x_0} \cdot (x - x_0) + \delta_2 U \cdot (x - x_0)^2 \right) \\ &= \left(u(x) \cdot \delta V_{x_0} + v(x_0) \cdot \delta U_{x_0} \right) \cdot (x - x_0) \\ &\quad + \left(u(x) \cdot \delta_2 V + v(x_0) \cdot \delta_2 U \right) \cdot (x - x_0)^2 \\ &\subseteq \left(\left(u(x_0) + \delta U \cdot (x - x_0) \right) \cdot \delta V_{x_0} + v(x_0) \cdot \delta U_{x_0} \right) \cdot (x - x_0) \\ &\quad + \left(u(x) \cdot \delta_2 V + v(x_0) \cdot \delta_2 U \right) \cdot (x - x_0)^2 \\ &\subseteq \delta W_{x_0} \cdot (x - x_0) + \delta_2 W \cdot (x - x_0)^2, \end{aligned}$$

which proves (10).

Next, we consider $w(x) = \varphi(u(x))$ and $x \in [x]$. By

$$w(x) - w(x_0) = \delta\varphi(u(x); u(x_0)) \cdot (u(x) - u(x_0))$$

we get

$$\delta w_{\lim}([x_0]) \subseteq \varphi'(u(x_0)) \cdot \delta U_{x_0} \subseteq \delta\varphi(U_{x_0}; U_{x_0}) \cdot \delta U_{x_0},$$

which is (8) for $\mathcal{W} = \varphi(\mathcal{U})$. Because of

$$\begin{aligned} \varphi(u(x)) &= \varphi(u(x_0)) + \varphi'(u(x_0)) \cdot (u(x) - u(x_0)) \\ &\quad + \delta_2\varphi(u(x); u(x_0)) \cdot (u(x) - u(x_0))^2 \end{aligned}$$

we obtain

$$\delta\varphi(u(x); u(x_0)) = \varphi'(u(x_0)) + \delta_2\varphi(u(x); u(x_0)) \cdot (u(x) - u(x_0)).$$

Hence, we have

$$\begin{aligned} w(x) - w(x_0) &= \delta\varphi(u(x); u(x_0)) \cdot (u(x) - u(x_0)) \\ &\in \delta\varphi(u(x); u(x_0)) \cdot \left(\delta U_{x_0} \cdot (x - x_0) + \delta_2 U \cdot (x - x_0)^2 \right) \\ &= \varphi'(u(x_0)) \cdot \delta U_{x_0} \cdot (x - x_0) \\ &\quad + \delta_2\varphi(u(x); u(x_0)) \cdot \delta U_{x_0} \cdot (u(x) - u(x_0)) \cdot (x - x_0) \\ &\quad + \delta\varphi(u(x); u(x_0)) \cdot \delta_2 U \cdot (x - x_0)^2 \\ &\subseteq \delta\varphi(U_{x_0}; U_{x_0}) \cdot \delta U_{x_0} \cdot (x - x_0) \\ &\quad + \left(\delta_2\varphi(U_x; U_{x_0}) \cdot \delta U_{x_0} \cdot \delta U + \delta\varphi(U_x; U_{x_0}) \cdot \delta_2 U \right) \cdot (x - x_0)^2 \\ &\subseteq \delta W_{x_0} \cdot (x - x_0) + \delta_2 W \cdot (x - x_0)^2, \end{aligned}$$

which is (10). □

Remark 3.9 It is possible to define δW and $\delta_2 W$ differently in Definition 3.7 b)-d), such that they still satisfy (6)-(10). For example, an alternative definition of δW for the multiplication $\mathcal{W} = \mathcal{U} \cdot \mathcal{V}$ would be $\delta W := \delta U \cdot V_x + U_{x_0} \cdot \delta V$. Furthermore, the intersection of this alternative δW with the δW from Definition 3.7 b) may be used (cf. [16]).

Next, we compute enclosures $\delta\varphi(U_{x_0}; U_{x_0})$, $\delta\varphi(U_x; U_{x_0})$, $\delta_2\varphi(U_x; U_{x_0}) \in \mathbb{IR}$ of (11)-(13), where φ is twice continuously differentiable. Note that such enclosures exist because the sets (11)-(13) are bounded as a consequence of the assumptions on φ and \mathcal{U} .

By the Mean Value Theorem and Taylor's Theorem we have the enclosures

$$\delta\varphi(U_{x_0}; U_{x_0}) = \varphi'(U_{x_0}), \tag{14}$$

$$\delta\varphi(U_x; U_{x_0}) = \varphi'(U_x), \tag{15}$$

and

$$\delta_2\varphi(U_x; U_{x_0}) = \frac{1}{2} \varphi''(U_x) \tag{16}$$

of (11)-(13). However, for some functions, such as $\varphi(x) = x^2$ and $\varphi(x) = \sqrt{x}$, sharper enclosures for (12) and (13) can be found. By explicit computation of $\delta\varphi(u_x; u_{x_0})$ and $\delta_2\varphi(u_x; u_{x_0})$ we get the following two lemmas.

Lemma 3.10 Let \mathcal{U} be a second-order slope tuple for u on $[x]$ with respect to $x_0 \in [x]$, and let $\varphi : \mathbb{R} \rightarrow \mathbb{R}$, $\varphi(x) = x^2$. Then, we have the enclosures

$$\delta\varphi(u_x; u_{x_0}) \in U_x + U_{x_0},$$

$$\delta_2\varphi(u_x; u_{x_0}) \in [1, 1]$$

for all $u_x \in U_x$ and all $u_{x_0} \in U_{x_0}$.

Lemma 3.11 Let \mathcal{U} be a second-order slope tuple for u on $[x]$ with respect to $x_0 \in [x]$ such that $\inf(U_x) \geq 0$ and $\inf(U_{x_0}) > 0$. Furthermore, let $\varphi : \mathbb{R}_{\geq 0} \rightarrow \mathbb{R}$, $\varphi(x) = \sqrt{x}$. Then, for all $u_x \in U_x$ and all $u_{x_0} \in U_{x_0}$ we have

$$\delta\varphi(u_x; u_{x_0}) \in \frac{1}{\sqrt{U_x} + \sqrt{U_{x_0}}},$$

$$\delta_2\varphi(u_x; u_{x_0}) \in -\frac{1}{2\sqrt{U_{x_0}}(\sqrt{U_x} + \sqrt{U_{x_0}})^2}.$$

Furthermore, by exploiting convexity or concavity of φ and φ' we can get sharper enclosures for (12) and (13) than by (15) and (16). The formulas and the proofs can be found in [9] and [16]. Moreover, exploiting a unique point of inflection of φ or φ' may also give sharper enclosures for (12) or (13) than (15) or (16). This applies to functions such as $\varphi(x) = \sinh x$, $\varphi(x) = \cosh x$, etc. We omit the details of these formulas and refer to [20].

Remark 3.12 Let f be twice continuously differentiable and $\mathcal{F} = (F_x, F_{x_0}, \delta F_{x_0}, \delta F, \delta_2 F)$ be a second-order slope tuple for f on $[x]$ obtained by using Lemma 3.6 and Definition 3.7. Then, we get

$$f(x) - f(x_0) \in f'(x_0) \cdot (x - x_0) + \delta_2 F \cdot (x - x_0)^2, \quad x \in [x],$$

analogously to the proof of Theorem 3.8. This is stronger than (10). Hence, by (5), $\delta_2 F$ is a second-order slope enclosure of f on $[x]$ with respect to x_0 . This justifies the term *second-order slope tuple* in Definition 3.2.

Nonsmooth elementary functions

Let \mathcal{U} and \mathcal{V} be second-order slope tuples for u and v on $[x] \subseteq D$ with respect to $x_0 \in [x]$. We compute a second-order slope tuple \mathcal{W} for $w(x) = |u(x)|$, $w(x) = \max\{u(x), v(x)\}$ and $w(x) = \min\{u(x), v(x)\}$, so that the automatic computation of second-order slope tuples can be extended to some nonsmooth functions.

1. $w(x) = \varphi(u(x)) = |u(x)|$:

We define the evaluation of $\varphi(x) = |x|$ on an interval $[x] \in \mathbb{IR}$ by

$$|[x]| = \text{abs}([x]) := \{|x| \mid x \in [x]\} = \left[\min_{x \in [x]} |x|, \max_{x \in [x]} |x| \right].$$

Furthermore, we compute $\mathcal{W} = \varphi(\mathcal{U}) = \text{abs}(\mathcal{U})$ by

$$\begin{aligned} W_x &= \text{abs}(U_x), \\ W_{x_0} &= \text{abs}(U_{x_0}), \\ \delta W_{x_0} &= \delta\varphi(U_{x_0}; U_{x_0}) \cdot \delta U_{x_0}, \\ \delta W &= \delta\varphi(U_x; U_{x_0}) \cdot \delta U, \\ \delta_2 W &= [r], \end{aligned}$$

where

$$\delta\varphi(U_{x_0}; U_{x_0}) = \begin{cases} [-1, -1] & \text{if } \overline{u_x} \leq 0 \\ [1, 1] & \text{if } \underline{u_x} \geq 0 \\ [-1, -1] & \text{if } 0 \in U_x \wedge \overline{u_{x_0}} < 0 \\ [1, 1] & \text{if } 0 \in U_x \wedge \underline{u_{x_0}} > 0 \\ [-1, 1] & \text{otherwise,} \end{cases}$$

$$\delta\varphi(U_x; U_{x_0}) = \begin{cases} [-1, -1] & \text{if } \overline{u_x} \leq 0 \\ [1, 1] & \text{if } \underline{u_x} \geq 0 \\ \left[\frac{|u_x| - |u_{x_0}|}{\underline{u_x} - \underline{u_{x_0}}}, \frac{|\overline{u_x}| - |\overline{u_{x_0}}|}{\overline{u_x} - \overline{u_{x_0}}} \right] & \text{if } 0 \in U_x \wedge \underline{u_x} \neq \underline{u_{x_0}} \wedge \overline{u_x} \neq \overline{u_{x_0}} \\ \left[-1, \frac{|\overline{u_x}| - |\overline{u_{x_0}}|}{\overline{u_x} - \overline{u_{x_0}}} \right] & \text{if } 0 \in U_x \wedge \underline{u_x} = \underline{u_{x_0}} \wedge \overline{u_x} \neq \overline{u_{x_0}} \\ \left[\frac{|u_x| - |u_{x_0}|}{\underline{u_x} - \underline{u_{x_0}}}, 1 \right] & \text{if } 0 \in U_x \wedge \underline{u_x} \neq \underline{u_{x_0}} \wedge \overline{u_x} = \overline{u_{x_0}} \\ [-1, 1] & \text{otherwise,} \end{cases}$$

and

$$[r] = \begin{cases} -1 \cdot \delta_2 U & \text{if } \overline{u_x} \leq 0 \\ \delta_2 U & \text{if } \underline{u_x} \geq 0 \\ \delta\varphi(U_x; U_{x_0}) \cdot \delta_2 U + \left[0, -\frac{1}{2 \cdot \overline{u_{x_0}}} \right] \cdot \delta U_{x_0} \cdot \delta U & \text{if } 0 \in U_x \wedge \overline{u_{x_0}} < 0 \wedge -\overline{u_{x_0}} \in U_x \\ \delta\varphi(U_x; U_{x_0}) \cdot \delta_2 U + \left[0, \frac{2 \cdot \overline{u_x}}{(\overline{u_x} - \overline{u_{x_0}})^2} \right] \cdot \delta U_{x_0} \cdot \delta U & \text{if } 0 \in U_x \wedge \overline{u_{x_0}} < 0 \wedge -\overline{u_{x_0}} \notin U_x \\ \delta\varphi(U_x; U_{x_0}) \cdot \delta_2 U + \left[0, \frac{1}{2 \cdot \underline{u_{x_0}}} \right] \cdot \delta U_{x_0} \cdot \delta U & \text{if } 0 \in U_x \wedge \underline{u_{x_0}} > 0 \wedge -\underline{u_{x_0}} \in U_x \\ \delta\varphi(U_x; U_{x_0}) \cdot \delta_2 U + \left[0, -\frac{2 \cdot \underline{u_x}}{(\underline{u_x} - \underline{u_{x_0}})^2} \right] \cdot \delta U_{x_0} \cdot \delta U & \text{if } 0 \in U_x \wedge \underline{u_{x_0}} > 0 \wedge -\underline{u_{x_0}} \notin U_x \\ [-1, 1] \cdot \delta_2 U & \text{otherwise.} \end{cases}$$

2. $w(x) = \max\{u(x), v(x)\}$:

We define the evaluation of the max-function for two intervals $[a]$ and $[b]$ by

$$\max\{[a], [b]\} := [\max\{\underline{a}, \underline{b}\}, \max\{\overline{a}, \overline{b}\}].$$

Furthermore, we compute $\mathcal{W} = \max \{\mathcal{U}, \mathcal{V}\}$ by

$$\begin{aligned} W_x &= \max \{U_x, V_x\}, \\ W_{x_0} &= \max \{U_{x_0}, V_{x_0}\}, \\ \delta W_{x_0} &= \begin{cases} \delta U_{x_0} & \text{if } \underline{u_x} \geq \overline{v_x} \\ \delta V_{x_0} & \text{if } \underline{v_x} \geq \overline{u_x} \\ \delta U_{x_0} \sqcup \delta V_{x_0} & \text{otherwise,} \end{cases} \\ \delta W &= \begin{cases} \delta U & \text{if } \underline{u_x} \geq \overline{v_x} \\ \delta V & \text{if } \underline{v_x} \geq \overline{u_x} \\ \delta U \sqcup \delta V & \text{otherwise,} \end{cases} \\ \delta_2 W &= \begin{cases} \delta_2 U & \text{if } \underline{u_x} \geq \overline{v_x} \\ \delta_2 V & \text{if } \underline{v_x} \geq \overline{u_x} \\ \delta_2 U \sqcup \delta_2 V & \text{otherwise.} \end{cases} \end{aligned}$$

We compute \mathcal{W} for $w(x) = \min \{u(x), v(x)\}$ analogously to $w(x) = \max \{u(x), v(x)\}$.

Theorem 3.13 Let \mathcal{U} and \mathcal{V} be second-order slope tuples for u and v , respectively, on $[x] \subseteq D$ with respect to $x_0 \in [x]$. Then, the tuples $\mathcal{W} = \varphi(\mathcal{U}) = \text{abs}(\mathcal{U})$ and $\mathcal{W} = \max \{\mathcal{U}, \mathcal{V}\}$ defined above are second-order slope tuples for the functions $w(x) = \varphi(u(x)) = |u(x)|$ and $w(x) = \max \{u(x), v(x)\}$, respectively.

Proof: The proof of (6), (7), and (9) for \mathcal{W} can be found in [14]. Therefore, we only need to check (8) and (10).

1. $w(x) = \varphi(u(x)) = |u(x)|$:

We prove (8). For each $x \in [x]$ with $u(x) = u(x_0)$ we have

$$w(x) - w(x_0) = [a] \cdot (u(x) - u(x_0))$$

with an arbitrary $[a] \in \mathbb{IR}$. If $u(x) \neq u(x_0)$, then

$$\frac{w(x) - w(x_0)}{x - x_0} = \frac{|u(x)| - |u(x_0)|}{u(x) - u(x_0)} \cdot \frac{u(x) - u(x_0)}{x - x_0}$$

holds. By considering the various cases in the definition of δW_{x_0} we obtain $\delta w_{\text{lim}}([x_0]) \subseteq \delta W_{x_0}$.

Next, we prove (10).

Case 1: $\overline{u_x} \leq 0$.

We have

$$\begin{aligned} w(x) - w(x_0) &= -1 \cdot (u(x) - u(x_0)) \\ &\in -1 \cdot \delta U_{x_0} \cdot (x - x_0) - 1 \cdot \delta_2 U \cdot (x - x_0)^2. \end{aligned}$$

Case 2: $\underline{u_x} \geq 0$. This case is analogous to the previous case.

Case 3: $0 \in U_x \wedge \overline{u_{x_0}} < 0 \wedge -\overline{u_{x_0}} \in U_x$.

For all $x \in [x]$ with $u(x) \geq 0$ we get

$$\begin{aligned}
w(x) - w(x_0) &\in \frac{|u(x)| - |u(x_0)|}{u(x) - u(x_0)} \cdot \left(\delta U_{x_0} \cdot (x - x_0) + \delta_2 U \cdot (x - x_0)^2 \right) \\
&= \left(-1 + \frac{2u(x)}{u(x) - u(x_0)} \right) \cdot \delta U_{x_0} \cdot (x - x_0) \\
&\quad + \frac{|u(x)| - |u(x_0)|}{u(x) - u(x_0)} \cdot \delta_2 U \cdot (x - x_0)^2 \\
&= -\delta U_{x_0} \cdot (x - x_0) + \left(\frac{|u(x)| - |u(x_0)|}{u(x) - u(x_0)} \cdot \delta_2 U \right. \\
&\quad \left. + \frac{2u(x)}{(u(x) - u(x_0))^2} \cdot \frac{u(x) - u(x_0)}{x - x_0} \cdot \delta U_{x_0} \right) \cdot (x - x_0)^2.
\end{aligned}$$

Because of $u(x) \geq 0$ we have

$$0 \leq \frac{2u(x)}{(u(x) - u(x_0))^2} \leq \frac{2u(x)}{(u(x) - \bar{u}_{x_0})^2}. \quad (17)$$

By computing the maximum of the right expression in (17) and by using $u(x) \geq 0$ and $-\bar{u}_{x_0} \in U_x$, we obtain

$$\frac{2u(x)}{(u(x) - \bar{u}_{x_0})^2} \leq \frac{2(-\bar{u}_{x_0})}{(-\bar{u}_{x_0} - \bar{u}_{x_0})^2}.$$

Thus, we have

$$\frac{2u(x)}{(u(x) - u(x_0))^2} \in \left[0, -\frac{1}{2\bar{u}_{x_0}} \right]. \quad (18)$$

Therefore, for all $x \in [x]$ with $u(x) \geq 0$ we have shown that

$$\begin{aligned}
w(x) - w(x_0) &\in -\delta U_{x_0} \cdot (x - x_0) + \left(\delta \varphi(U_x; U_{x_0}) \cdot \delta_2 U \right. \\
&\quad \left. + \left[0, -\frac{1}{2\bar{u}_{x_0}} \right] \cdot \delta U_{x_0} \cdot \delta U \right) \cdot (x - x_0)^2
\end{aligned} \quad (19)$$

holds. For all $x \in [x]$ with $u(x) < 0$ we get

$$\begin{aligned}
w(x) - w(x_0) &= (u(x) - u(x_0)) \\
&\in -\delta U_{x_0} \cdot (x - x_0) - \delta_2 U \cdot (x - x_0)^2.
\end{aligned}$$

Because of $-1 \in \delta \varphi(U_x; U_{x_0})$ and $0 \in \left[0, -\frac{1}{2\bar{u}_{x_0}} \right]$ we have

$$\begin{aligned}
&-1 \cdot \delta_2 U \cdot (x - x_0)^2 \\
&\subseteq \left(\delta \varphi(U_x; U_{x_0}) \cdot \delta_2 U + \left[0, -\frac{1}{2\bar{u}_{x_0}} \right] \cdot \delta U_{x_0} \cdot \delta U \right) \cdot (x - x_0)^2.
\end{aligned}$$

Hence, (19) also holds for all $x \in [x]$ with $u(x) < 0$. Thus, we have

$$w(x) - w(x_0) \subseteq \delta W_{x_0} \cdot (x - x_0) + \delta_2 W \cdot (x - x_0)^2$$

for all $x \in [x]$.

Case 4: $0 \in U_x \wedge \overline{u_{x_0}} < 0 \wedge -\overline{u_{x_0}} \notin U_x$.

The proof is analogous to case 3. Instead of (18), we get

$$\frac{2 \cdot u(x)}{(u(x) - u(x_0))^2} \in \left[0, \frac{2 \cdot \overline{u_x}}{(\overline{u_x} - \overline{u_{x_0}})^2} \right].$$

Case 5: $0 \in U_x \wedge \underline{u_{x_0}} > 0 \wedge -\underline{u_{x_0}} \in U_x$. This case is analogous to case 3.

Case 6: $0 \in U_x \wedge \underline{u_{x_0}} > 0 \wedge -\underline{u_{x_0}} \notin U_x$. This case is analogous to case 4.

Case 7: We have

$$\begin{aligned} |u(x)| - |u(x_0)| &\in [-1, 1] \cdot (u(x) - u(x_0)) \\ &\subseteq [-1, 1] \cdot \delta U_{x_0} \cdot (x - x_0) + [-1, 1] \cdot \delta_2 U \cdot (x - x_0)^2, \end{aligned}$$

which completes the proof.

2. $w(x) = \max\{u(x), v(x)\}$:

Case 1: $\underline{u_x} \geq \overline{v_x}$.

We have $\max\{u(x), v(x)\} = u(x)$ and $\max\{u(x_0), v(x_0)\} = u(x_0)$. Therefore, the proof of (8) and (10) is obvious.

Case 2: $\underline{v_x} \geq \overline{u_x}$. This case can be proven analogously to case 1.

Case 3: In the remaining case we have

$$\delta w_{\lim}([x_0]) \subseteq \delta U_{x_0} \sqcup \delta V_{x_0}.$$

Therefore, we get (8). Next, we prove (10).

If $\max\{u(x), v(x)\} = u(x)$ and $\max\{u(x_0), v(x_0)\} = v(x_0)$, then we have

$$v(x) - v(x_0) \leq u(x) - v(x_0) \leq u(x) - u(x_0),$$

and therefore,

$$w(x) - w(x_0) \in (\delta U_{x_0} \sqcup \delta V_{x_0}) \cdot (x - x_0) + (\delta_2 U \sqcup \delta_2 V) \cdot (x - x_0)^2 \quad (20)$$

holds. Clearly, (20) also holds, if $\max\{u(x), v(x)\} = u(x)$ and $\max\{u(x_0), v(x_0)\} = u(x_0)$. Analogously, (20) is fulfilled, if u and v are interchanged. Therefore, we get (10). \square

Continuous functions given by two or more branches

In order to automatically compute second-order slope tuples for continuous functions given by two or more branches, we first define the function $\text{ite} : \mathbb{R}^3 \rightarrow \mathbb{R}$ ("if-then-else").

Definition 3.14 $\text{ite} : \mathbb{R}^3 \rightarrow \mathbb{R}$ is the function

$$\text{ite}(z, u, v) := \begin{cases} u & \text{if } z < 0 \\ v & \text{otherwise.} \end{cases} \quad (21)$$

Let $u, v, z : D \subseteq \mathbb{R} \longrightarrow \mathbb{R}$ be continuous, $[x] \subseteq D$ and define $w : D \subseteq \mathbb{R} \longrightarrow \mathbb{R}$ by

$$w(x) = \text{ite}(z(x), u(x), v(x)). \quad (22)$$

w is now a function given by two branches u and v , with the function z determining which branch is chosen. For details see [23].

Definition 3.15 We define the evaluation of the ite-function for intervals $[z] = [\underline{z}, \overline{z}]$, $[u] = [\underline{u}, \overline{u}]$ and $[v] = [\underline{v}, \overline{v}]$ by

$$\text{ite}([z], [u], [v]) := \begin{cases} [u] & \text{if } \overline{z} < 0 \\ [v] & \text{if } \underline{z} \geq 0 \\ [u] \sqcup [v] & \text{otherwise.} \end{cases} \quad (23)$$

Theorem 3.16 Let \mathcal{U}, \mathcal{V} and \mathcal{Z} be second-order slope tuples for the continuous functions u, v and z on some interval $[x] \subseteq D$ with respect to $x_0 \in [x]$. Furthermore, let $w(x) = \text{ite}(z(x), u(x), v(x))$ be continuous on $[x]$. We define the 5-tuple $\mathcal{W} = \text{ite}(\mathcal{Z}, \mathcal{U}, \mathcal{V})$ by

$$W_x = \text{ite}(Z_x, U_x, V_x),$$

$$W_{x_0} = \text{ite}(Z_{x_0}, U_{x_0}, V_{x_0}),$$

$$\delta W_{x_0} = \begin{cases} \delta U_{x_0} & \text{if } \overline{z_x} < 0 \\ \delta V_{x_0} & \text{if } \underline{z_x} \geq 0 \\ \delta U_{x_0} \sqcup (\delta V_{x_0} + (\delta U_{x_0} - \delta V_{x_0}) \cdot [0, 1]) & \text{if } 0 \in Z_x \wedge \overline{z_{x_0}} < 0 \\ \delta V_{x_0} \sqcup (\delta U_{x_0} + (\delta V_{x_0} - \delta U_{x_0}) \cdot [0, 1]) & \text{if } 0 \in Z_x \wedge \underline{z_{x_0}} \geq 0 \\ \left(\delta U_{x_0} \sqcup (\delta V_{x_0} + (\delta U_{x_0} - \delta V_{x_0}) \cdot [0, 1]) \right) \\ \sqcup \left(\delta V_{x_0} \sqcup (\delta U_{x_0} + (\delta V_{x_0} - \delta U_{x_0}) \cdot [0, 1]) \right) & \text{otherwise,} \end{cases}$$

$$\delta W = \begin{cases} \delta U & \text{if } \overline{z_x} < 0 \\ \delta V & \text{if } \underline{z_x} \geq 0 \\ \delta U \sqcup (\delta V + (\delta U - \delta V) \cdot [0, 1]) & \text{if } 0 \in Z_x \wedge \overline{z_{x_0}} < 0 \\ \delta V \sqcup (\delta U + (\delta V - \delta U) \cdot [0, 1]) & \text{if } 0 \in Z_x \wedge \underline{z_{x_0}} \geq 0 \\ \left(\delta U \sqcup (\delta V + (\delta U - \delta V) \cdot [0, 1]) \right) \\ \sqcup \left(\delta V \sqcup (\delta U + (\delta V - \delta U) \cdot [0, 1]) \right) & \text{otherwise,} \end{cases}$$

$$\delta_2 W = \begin{cases} \delta U & \text{if } \overline{z_x} < 0 \\ \delta V & \text{if } \underline{z_x} \geq 0 \\ \delta_2 U \sqcup (\delta_2 V + (\delta_2 U - \delta_2 V) \cdot [0, 1]) & \text{if } 0 \in Z_x \wedge \overline{z_{x_0}} < 0 \\ \delta_2 V \sqcup (\delta_2 U + (\delta_2 V - \delta_2 U) \cdot [0, 1]) & \text{if } 0 \in Z_x \wedge \underline{z_{x_0}} \geq 0 \\ \left(\delta_2 U \sqcup (\delta_2 V + (\delta_2 U - \delta_2 V) \cdot [0, 1]) \right) \\ \sqcup \left(\delta_2 V \sqcup (\delta_2 U + (\delta_2 V - \delta_2 U) \cdot [0, 1]) \right) & \text{otherwise.} \end{cases}$$

Then, $\mathcal{W} = \text{ite}(\mathcal{Z}, \mathcal{U}, \mathcal{V})$ is a second-order slope tuple for w on $[x]$ with respect to x_0 .

Proof: See [22] and [23]. □

Remark 3.17 In some papers, the formula

$$\delta W = \begin{cases} \delta U & \text{if } \bar{z} < 0 \\ \delta V & \text{if } \underline{z} \geq 0 \\ \delta U \sqcup \delta V & \text{otherwise} \end{cases}$$

is used for computation of a first-order slope tuple for $w(x) = \text{ite}(z(x), u(x), v(x))$ on $[x]$. However, this formula is not correct because it does not provide a slope enclosure of w on $[x]$ for all possible choices of z, u, v . For details see [22] and [23].

4 Numerical results

We use the technique from the previous section to automatically compute a second-order slope tuple

$$\mathcal{F} = (F_x, F_{x_0}, \delta F_{x_0}, \delta F, \delta_2 F)$$

for f on $[x]$ with respect to $x_0 \in [x]$. In this way, we obtain the range enclosures

$$S_1 := F_{x_0} + \delta F \cdot ([x] - x_0) \quad (24)$$

and

$$S_2 := F_{x_0} + \delta F_{x_0} \cdot ([x] - x_0) + \delta_2 F \cdot ([x] - x_0)^2 \quad (25)$$

of f on $[x]$ (see Remark 3.4). S_1 was already considered in [14]. If f is twice continuously differentiable, we can also compare these results with the centered forms

$$D_1 := f(x_0) + f'([x]) \cdot ([x] - x_0) \quad (26)$$

and

$$D_2 := f(x_0) + f'(x_0) \cdot ([x] - x_0) + \frac{1}{2} f''([x]) \cdot ([x] - x_0)^2. \quad (27)$$

Here, $f'([x])$ and $f''([x])$ are enclosures of the range of f' and f'' on $[x]$. They are computed via automatic differentiation.

Remark 4.1 By using machine interval arithmetic on a floating-point computer for the operations from section 3, the slope tuple properties (6)-(10) are preserved. Hence, by applying machine interval arithmetic, we obtain verified range enclosures.

We consider the following examples:

1. $f(x) = (x + \sin x) \cdot \exp(-x^2)$
2. $f(x) = x^4 - 10x^3 + 35x^2 - 50x + 24$
3. $f(x) = (\ln(x + 1.25) - 0.84x)^2$
4. $f(x) = \frac{2}{100}x^2 - \frac{3}{100} \exp\left(-\left(20(x - 0.875)\right)^2\right)$
5. $f(x) = \exp(x^2)$
6. $f(x) = x^4 - 12x^3 + 47x^2 - 60x - 20 \exp(-x)$
7. $f(x) = x^6 - 15x^4 + 27x^2 + 250$

8. $f(x) = (\arctan(|x-1|))^2 / (x^6 - 2x^4 + 20)$
9. $f(x) = \max \left\{ \exp(-x), \sin(|x-1|) \right\}$
10. $f(x) = \text{ite} \left(x-1, x^4 - 1 + \sin(x-1), \left| x^2 - \frac{5}{2}x + \frac{3}{2} \right| \right)$
11. $f(x) = |(x-1)(x^2 + x + 5)| \cdot \exp((x-2)^2)$
12. $f(x) = \max \{ x^5 - x^2 + x, \exp(x) \cdot (x-1) + 1 \}$
13. $f(x) = \text{ite} \left(x-1, (x-1) \cdot \arctan x \cdot \exp(x + \sin x), \left| \left(x^2 - \frac{5}{2}x + \frac{3}{2} \right) \cdot \sin x \right| \right)$

In each case, we consider $[x] = [0.75, 1.75]$ and set $x_0 := \text{mid}[x]$. Examples 1-7 have also been considered in [14].

We obtained the following results:

No.	D_1	D_2	S_1	S_2
1	[-2.262, 3.184]	[-0.910, 2.889]	[-0.939, 1.861]	[-0.247, 1.476]
2	[-44.75, 42.95]	[-5.215, 7.598]	[-22.84, 21.04]	[-1.778, 3.536]
3	[-0.376, 0.412]	[-0.042, 0.190]	[-0.199, 0.235]	[-0.041, 0.151]
4	[-10.51, 10.57]	[-1835, 3.062]	[-0.133, 0.195]	[-0.345, 0.115]
5	[-32.65, 42.19]	[-1.193, 48.82]	[-11.84, 21.39]	[-1.193, 21.39]
6	[-85.86, 29.28]	[-40.03, -11.73]	[-61.07, 4.492]	[-35.76, -16.47]
7	[119.5, 399.3]	[182.7, 304.4]	[185.9, 332.9]	[210.4, 275.1]
8	-	-	[-0.333, 0.339]	[-0.386, 0.233]
9	-	-	[-0.214, 0.787]	[-0.284, 1.271]
10	-	-	[-7.375, 7.500]	[-5.945, 7.516]
11	-	-	[-19.85, 26.70]	[-8.953, 34.22]
12	-	-	[-10.13, 15.61]	[-2.615, 15.11]
13	-	-	[-15.00, 15.12]	[-12.64, 13.27]

For the examples 1-7, S_1 and S_2 provide sharper enclosures than D_1 and D_2 , respectively. Furthermore, S_2 is a subset of S_1 for the examples 1-7 except for example 4.

For nonsmooth functions φ , it is possible that a very large interval $\delta_2 W$ is computed for $\mathcal{W} = \varphi(\mathcal{U})$. Hence, S_2 is not always contained in S_1 in our examples. However, except for example 9, one or both bounds of S_2 provide sharper bounds for the range of f than S_1 .

5 The automatic computation of second-order slope tuples for multivariate functions

In this section, let $f : D \subseteq \mathbb{R}^n \rightarrow \mathbb{R}$. We define slope enclosures and the limiting slope interval analogously to section 2.

Definition 5.1 Let f be continuous and $x_0 \in D$ be fixed. A function $\delta f : D \rightarrow \mathbb{R}^{1 \times n}$ satisfying

$$f(x) = f(x_0) + \delta f(x; x_0) \cdot (x - x_0), \quad x \in D,$$

is called a *first-order slope function of f with respect to x_0* .

An interval matrix $\delta f([x]; x_0) \in \mathbb{IR}^{1 \times n}$ with

$$\delta f([x]; x_0) \supseteq \{\delta f(x; x_0) \mid x \in [x]\}$$

is called a *(first-order) slope enclosure of f on $[x]$ with respect to x_0* .

A slope function of $f : \mathbb{R}^n \rightarrow \mathbb{R}$ is not unique, and there are various ways for computing one, see for example [6, 7].

Definition 5.2 Let f be continuous on $[x] \in \mathbb{IR}^n$, $[x] \subseteq D$. Furthermore, let $x_0 \in [x]$ and $f_i(t) := f((x_0)_1, \dots, (x_0)_{i-1}, t, (x_0)_{i+1}, \dots, (x_0)_n)$. If

$$\liminf_{t \rightarrow (x_0)_i} \frac{f_i(t) - f_i((x_0)_i)}{t - (x_0)_i}$$

and

$$\limsup_{t \rightarrow (x_0)_i} \frac{f_i(t) - f_i((x_0)_i)}{t - (x_0)_i}$$

exist for all $i \in \{1, \dots, n\}$, then we define the *limiting slope interval* $\delta f_{\text{lim}}([x_0]) \in \mathbb{IR}^n$ by

$$\left(\delta f_{\text{lim}}([x_0])\right)_i := \left[\liminf_{t \rightarrow (x_0)_i} \frac{f_i(t) - f_i((x_0)_i)}{t - (x_0)_i}, \limsup_{t \rightarrow (x_0)_i} \frac{f_i(t) - f_i((x_0)_i)}{t - (x_0)_i} \right].$$

Definition 5.3 Let f be continuous, $[x] \subseteq D$, $x_0 \in [x]$, and assume that $f'(x_0)$ exists. A function $\delta_2 f : D \rightarrow \mathbb{R}^{n \times n}$ satisfying

$$f(x) = f(x_0) + f'(x_0) \cdot (x - x_0) + (x - x_0)^T \cdot \delta_2 f(x; x_0, x_0) \cdot (x - x_0), \quad x \in D,$$

is called a *second-order slope function of f with respect to x_0* .

An interval matrix $\delta_2 f([x]; x_0, x_0) \in \mathbb{IR}^{n \times n}$ with

$$f(x) \in f(x_0) + f'(x_0) \cdot (x - x_0) + (x - x_0)^T \cdot \delta_2 f([x]; x_0, x_0) \cdot (x - x_0), \quad x \in [x],$$

is called a *second-order slope enclosure of f on $[x]$ with respect to x_0* .

Definition 5.4 Let $u : D \subseteq \mathbb{R}^n \rightarrow \mathbb{R}$ be continuous, $[x] \in \mathbb{IR}^n$ with $[x] \subseteq D$, and $x_0 \in [x]$. A *second-order slope tuple for u on $[x]$ with respect to x_0* is a 5-tuple $\mathcal{U} = (U_x, U_{x_0}, \delta U_{x_0}, \delta U, \delta_2 U)$ with $U_x, U_{x_0} \in \mathbb{IR}$, $\delta U_{x_0}, \delta U \in \mathbb{IR}^n$, $\delta_2 U \in \mathbb{IR}^{n \times n}$, $U_{x_0} \subseteq U_x$, satisfying

$$u(x) \in U_x, \tag{28}$$

$$u(x_0) \in U_{x_0}, \tag{29}$$

$$\delta u_{\text{lim}}([x_0]) \subseteq \delta U_{x_0}, \tag{30}$$

$$u(x) - u(x_0) \in \delta U^T \cdot (x - x_0), \tag{31}$$

$$u(x) - u(x_0) \in \delta U_{x_0}^T \cdot (x - x_0) + (x - x_0)^T \cdot \delta_2 U \cdot (x - x_0) \tag{32}$$

for all $x \in [x]$.

Lemma 5.5 Let $[x] \in \mathbb{IR}^n$, $x_0 \in [x]$, $i \in \{1, \dots, n\}$, and let $e^i \in \mathbb{R}^n$ be the i -th unit vector.

a) $\mathcal{K} = (k, k, 0, 0, 0)$ is a second-order slope tuple for the constant function $u : \mathbb{R}^n \rightarrow \mathbb{R}$, $u(x) \equiv k \in \mathbb{R}$, on $[x]$ with respect to x_0 . Here, the first and the second 0 symbolize the zero vector, and the last 0 stands for the zero matrix.

b) $\mathcal{X} = ([x]_i, (x_0)_i, e^i, e^i, 0)$ is a second-order slope tuple for $u : \mathbb{R}^n \rightarrow \mathbb{R}$, $u(x) = x_i$, on $[x]$ with respect to x_0 . Here, 0 stands for the zero matrix.

For the automatic computation of second-order slope tuples, the definitions and theorems are completely analogous to section 3. We only have to take into account that $\delta U_{x_0}, \delta U, \delta V_{x_0}, \delta V \in \mathbb{IR}^n$ and $\delta_2 U, \delta_2 V \in \mathbb{IR}^{n \times n}$. Therefore, we get $\delta U_{x_0} \cdot \delta U^T$ instead of $\delta U_{x_0} \cdot \delta U$ and $(x - x_0)^T \cdot \delta_2 U \cdot (x - x_0)$ instead of $\delta_2 U \cdot (x - x_0)^2$. For details, see [22].

The componentwise computation of second-order slope tuples

The automatic computation of slope tuples for multivariate functions can be reduced to the one-dimensional case by the *componentwise computation of slope tuples*. For first-order slope tuples, Ratz [14] uses this technique for verified global optimization. Hence, we also consider the componentwise computation of second-order slope tuples in this paper.

Definition 5.6 Let $u : \mathbb{R}^n \rightarrow \mathbb{R}$ be continuous on $[x]$ and let $i \in \{1, \dots, n\}$ be fixed. We define the family of functions

$$\mathcal{G}_i := \left\{ \begin{array}{l} g : [x]_i \subseteq \mathbb{R} \rightarrow \mathbb{R}, \quad g(t) := u(x_1, \dots, x_{i-1}, t, x_{i+1}, \dots, x_n) \\ \text{with } x_j \in [x]_j \text{ fixed for } j \in \{1, \dots, n\}, j \neq i. \end{array} \right\} \quad (33)$$

Each $g \in \mathcal{G}_i$ is a continuous function of one variable t . Hence, for each $g \in \mathcal{G}_i$ the automatic computation of a second-order slope tuple on $[x]_i$ with respect to a fixed $(x_0)_i \in [x]_i$, $(x_0)_i \in \mathbb{R}$, is defined as in section 3.

For the componentwise computation we have to modify the definition of a second-order slope tuple as follows:

Definition 5.7 Let $u : D \subseteq \mathbb{R}^n \rightarrow \mathbb{R}$ be continuous and $[x] \in \mathbb{IR}^n$, $[x] \subseteq D$. Furthermore, let $i \in \{1, \dots, n\}$ and $(x_0)_i \in [x]_i \subseteq \mathbb{R}$ be fixed. A *second-order slope tuple for u on $[x]$ with respect to the i -th component* is a 5-tuple $\mathcal{U} = (U_x, U_{x_0}, \delta U_{x_0}, \delta U, \delta_2 U)$ with $U_x, U_{x_0}, \delta U_{x_0}, \delta U, \delta_2 U \in \mathbb{IR}$, $U_{x_0} \subseteq U_x$, satisfying

$$\begin{aligned} g(x_i) &\in U_x, \\ g((x_0)_i) &\in U_{x_0}, \\ \delta g_{\text{lim}}([x_0]_i) &\subseteq \delta U_{x_0}, \\ g(x_i) - g((x_0)_i) &\in \delta U \cdot (x_i - (x_0)_i), \\ g(x_i) - g((x_0)_i) &\in \delta U_{x_0} \cdot (x_i - (x_0)_i) + \delta_2 U \cdot (x_i - (x_0)_i)^2 \end{aligned}$$

for all $x_i \in [x]_i$ and all $g \in \mathcal{G}_i$, where \mathcal{G}_i is defined by (33).

Remark 5.8 Let \mathcal{U} be a second-order slope tuple for u on $[x]$ with respect to the i -th component. Then, for all $x \in [x]$ we have

$$u(x) \in U_{x_0} + \delta U \cdot \left([x]_i - (x_0)_i \right), \quad (34)$$

$$u(x) \in U_{x_0} + \delta U_{x_0} \cdot ([x]_i - (x_0)_i) + \delta_2 U \cdot ([x]_i - (x_0)_i)^2. \quad (35)$$

Hence, we have reduced the automatic computation of second-order slope tuples to the one-dimensional case from section 3. Therefore, the same formulas can be used except for Lemma 3.6. We need to modify Lemma 3.6 as follows:

Lemma 5.9 Let $[x] \in \mathbb{IR}^n$, $x_0 \in [x]$, and $i \in \{1, \dots, n\}$.

a) For each $i \in \{1, \dots, n\}$, the tuple $\mathcal{K} = (k, k, 0, 0, 0)$ is a second-order slope tuple for the constant function $u : \mathbb{R}^n \rightarrow \mathbb{R}$, $u(x) \equiv k \in \mathbb{R}$, on $[x]$ with respect to the i -th component.

b) For $u : \mathbb{R}^n \rightarrow \mathbb{R}$, $u(x) = x_k$, a second-order slope tuple on $[x]$ with respect to the i -th component is given by

$$\mathcal{X} = \begin{cases} ([x]_k, [x]_k, 0, 0, 0), & \text{if } k \neq i, \\ ([x]_i, (x_0)_i, 1, 1, 0), & \text{if } k = i. \end{cases}$$

Remark 5.10 Using a technique similar to [6, 7], we obtain range enclosures that are sharper than (34) and (35). For a fixed $x_0 \in [x] \subseteq D$ we have

$$\begin{aligned} f(x_1, \dots, x_n) - f((x_0)_1, \dots, (x_0)_n) &= f(x_1, \dots, x_n) - f((x_0)_1, x_2, \dots, x_n) \\ &\quad + f((x_0)_1, x_2, \dots, x_n) - f((x_0)_1, (x_0)_2, x_3, \dots, x_n) \\ &\quad + f((x_0)_1, (x_0)_2, x_3, \dots, x_n) - \dots \\ &\quad + f((x_0)_1, \dots, (x_0)_{n-1}, x_n) - f((x_0)_1, \dots, (x_0)_n). \end{aligned} \quad (36)$$

for all $x \in [x]$. For each $i \in \{1, \dots, n\}$, we now compute a second-order slope tuple

$$\mathcal{F}_i := (F_{x;i}, F_{x_0;i}, \delta F_{x_0;i}, \delta F_i, \delta_2 F_i)$$

for the function

$$\begin{aligned} f_i : ((x_0)_1, \dots, (x_0)_{i-1}, [x]_i, [x]_{i+1}, \dots, [x]_n) &\rightarrow \mathbb{R}, \\ f_i(x) := u((x_0)_1, \dots, (x_0)_{i-1}, x_i, x_{i+1}, \dots, x_n) & \\ \text{for } x \in ((x_0)_1, \dots, (x_0)_{i-1}, [x]_i, [x]_{i+1}, \dots, [x]_n), & \end{aligned}$$

on $((x_0)_1, \dots, (x_0)_{i-1}, [x]_i, [x]_{i+1}, \dots, [x]_n)$ with respect to the i -th component.

Then, by (36) we have

$$f(x) \in F_{x;1}, \quad (37)$$

$$f(x) \in F_{x_0;n} + \sum_{j=1}^n \delta F_j \cdot ([x]_j - (x_0)_j) =: S_{c;1}, \quad (38)$$

$$f(x) \in F_{x_0;n} + \sum_{j=1}^n \delta F_{x_0;j} \cdot ([x]_j - (x_0)_j) + \sum_{j=1}^n \delta_2 F_j \cdot ([x]_j - (x_0)_j)^2 =: S_{c;2} \quad (39)$$

for all $x \in [x]$.

Examples

We consider the following examples $f : \mathbb{R}^n \rightarrow \mathbb{R}$. Most of them have been considered in [14]:

1. $f(x) = \left(\left(\frac{5}{\pi}x_4 - \frac{5.1}{4\pi^2}x_4^2 + x_2 - 6 \right)^2 + 10 \left(1 - \frac{1}{8\pi} \right) \cos x_4 + 10 \right) \cdot x_3^2 - x_1^5 + x_2 \frac{\sinh(x_5)}{x_6^2 + 1} x_6 - \exp(x_3) \cdot x_5$
2. $f(x) = 4x_1^2 - 2.1x_1^4 + \frac{1}{3}x_1^6 + x_1x_2 - 4x_2^2 + 4x_2^4$
3. $f(x) = 100(x_2 - x_1^2)^2 + (x_1 - 1)^2$
4. $f(x) = 12x_1^2 - 6.3x_1^4 + x_1^6 + 6x_2(x_2 - x_1)$
5. $f(x) = \sin x_1 + \sin\left(\frac{10}{3}x_1\right) + \ln x_1 - 0.84x_1 + 1000x_1x_2^2 \exp(-x_3^2)$
6. $f(x) = (x_1 + \sin x_1) \exp(-x_1^2) + \ln(x_3) \frac{x_2^2}{x_1}$

In each example, we take

$$[x] = ([x]_1, \dots, [x]_n) = ([4, 4.25], \dots, [4, 4.25])$$

and $x_0 = \text{mid}[x]$.

Using the technique from section 5, we compute a second-order slope tuple

$$\mathcal{F} = (F_x, F_{x_0}, \delta F_{x_0}, \delta F, \delta_2 F)$$

for f on $[x]$. Then, by (28)-(32) we have

$$f(x) \in F_{x_0} + \delta F^T \cdot ([x] - x_0) =: S_{m;1}$$

and

$$f(x) \in F_{x_0} + \delta F_{x_0}^T \cdot ([x] - x_0) + ([x] - x_0)^T \cdot \delta_2 F \cdot ([x] - x_0) =: S_{m;2}$$

with $F_{x_0} \in \mathbb{IR}$, $\delta F_{x_0}, \delta F \in \mathbb{IR}^n$ and $\delta_2 F \in \mathbb{IR}^{n \times n}$.

We compare the range enclosures $S_{m;1}$ and $S_{m;2}$ with $S_{c;1}$ and $S_{c;2}$ obtained via Remark 5.10.

We obtained the following results:

No.	$S_{m;1}$	$S_{m;2}$	$S_{c;1}$	$S_{c;2}$
1	[-1497.1, -973.01]	[-1494.0, -976.12]	[-1497.9, -972.20]	[-1495.2, -986.94]
2	[1809.5, 2609.1]	[1816.2, 2602.5]	[1809.5, 2609.1]	[1843.0, 2602.5]
3	[13 467, 19 786]	[13 467, 19 786]	[13 467, 19 786]	[13 619, 19 786]
4	[2538.7, 4074.7]	[2558.4, 4055.0]	[2538.7E, 4074.7]	[2619.5, 4055.0]
5	[-2.1275, -1.7755]	[-2.0521, -1.8508]	[-2.1275, -1.7755]	[-2.0499, -1.9322]
6	[5.1531, 6.5377]	[5.1529, 6.5379]	[5.1532, 6.5376]	[5.1647, 6.5357]

Except for the first example, we have $S_{c;1} \subseteq S_{m;1}$ and $S_{c;2} \subseteq S_{m;2}$. Furthermore, for each of the examples $S_{c;2} \subseteq S_{c;1}$ holds.

6 Conclusion

In this paper, we have shown how the automatic computation of second-order slope tuples can be performed. Here, the function expression of the underlying function may contain nonsmooth functions such as $\varphi(x) = |u(x)|$ and $\varphi(x) = \max\{u(x), v(x)\}$. Furthermore, we allow for functions given by two or more branches. Some examples illustrated that second-order slope tuples may provide sharper enclosures of the function range than first-order slope enclosures. Machine interval arithmetic yields verified range enclosures on a floating-point computer. Hence, the automatic computation of second-order slope tuples can also be applied to verified global optimization [22].

References

- [1] G. Alefeld and J. Herzberger. *Introduction to Interval Computations*. Academic Press, New York, 1983.
- [2] F. H. Clarke. *Optimization and Nonsmooth Analysis*. John Wiley & Sons, New York, 1983.
- [3] P. Deuffhard and A. Hohmann. *Numerical Analysis*. de Gruyter, Berlin, 1995.
- [4] A. Frommer, B. Lang, and M. Schnurr. A comparison of the Moore and Miranda existence tests. *Computing*, 72:349–354, 2004.
- [5] A. Goldsztejn. Comparison of the Hansen-Sengupta and the Frommer-Lang-Schnurr existence tests. *Computing*, 79:53–60, 2007.
- [6] E. R. Hansen. Interval forms of Newton’s method. *Computing*, 20:153–163, 1978.
- [7] E. R. Hansen and G. W. Walster. *Global Optimization Using Interval Analysis: Second Edition, Revised and Expanded*. Marcel Dekker, New York, 2004.
- [8] R. B. Kearfott. *Rigorous Global Search: Continuous Problems*. Kluwer Academic Publishers, Dordrecht, 1996.
- [9] L. Kolev. Use of interval slopes for the irrational part of factorable functions. *Reliab. Comput.*, 3:83–93, 1997.
- [10] R. Krawczyk and A. Neumaier. Interval slopes for rational functions and associated centered forms. *SIAM J. Numer. Anal.*, 22:604–616, 1985.
- [11] R. E. Moore. A test for existence of solutions to nonlinear systems. *SIAM J. Numer. Anal.*, 14(4):611–615, 1977.
- [12] H. Muñoz and R. B. Kearfott. Slope intervals, generalized gradients, semigradients, slant derivatives, and csets. *Reliab. Comput.*, 10(3):163–193, 2004.
- [13] L. B. Rall. *Automatic Differentiation: Techniques and Applications, Lecture Notes in Computer Science, Vol. 120*. Springer, Berlin, 1981.
- [14] D. Ratz. *Automatic Slope Computation and its Application in Nonsmooth Global Optimization*. Shaker Verlag, Aachen, 1998.

- [15] D. Ratz. A nonsmooth global optimization technique using slopes – the one-dimensional case. *J. Global Optim.*, 14:365–393, 1999.
- [16] S. M. Rump. Expansion and estimation of the range of nonlinear functions. *Math. Comp.*, 65(216):1503–1512, 1996.
- [17] U. Schäfer and M. Schnurr. A comparison of simple tests for accuracy of approximate solutions to nonlinear systems with uncertain data. *J. Ind. Manag. Optim.*, 2(4):425–434, 2006.
- [18] M. Schnurr. Webpage for software download.
<http://iamlasun8.mathematik.uni-karlsruhe.de/~ae26/software/>.
- [19] M. Schnurr. On the proofs of some statements concerning the theorems of Kantorovich, Moore, and Miranda. *Reliab. Comput.*, 11:77–85, 2005.
- [20] M. Schnurr. *Computing Slope Enclosures by Exploiting a Unique Point of Inflection*. Preprint Nr. 07/08, Institut für Wissenschaftliches Rechnen und Mathematische Modellbildung, Universität Karlsruhe, Germany, 2007.
- [21] M. Schnurr. *A Second-Order Pruning Step for Verified Global Optimization*. Preprint Nr. 07/10, Institut für Wissenschaftliches Rechnen und Mathematische Modellbildung, Universität Karlsruhe, Germany, 2007.
- [22] M. Schnurr. *Steigungen höherer Ordnung zur verifizierten globalen Optimierung*. PhD thesis, Universität Karlsruhe, 2007.
<http://digbib.ubka.uni-karlsruhe.de/volltexte/1000007229>.
- [23] M. Schnurr and D. Ratz. Slope enclosures for functions given by two or more branches. Submitted for Publication.
- [24] Z. Shen and M. A. Wolfe. On interval enclosures using slope arithmetic. *Appl. Math. Comput.*, 39:89–105, 1990.
- [25] XSC Website. Website on programming languages for scientific computing with validation.
<http://www.xsc.de> [December 2007].

IWRMM-Preprints seit 2006

- Nr. 06/01 Willy Dörfler, Vincent Heuveline: Convergence of an adaptive *hp* finite element strategy in one dimension
- Nr. 06/02 Vincent Heuveline, Hoang Nam-Dung: On two Numerical Approaches for the Boundary Control Stabilization of Semi-linear Parabolic Systems: A Comparison
- Nr. 06/03 Andreas Rieder, Armin Lechleiter: Newton Regularizations for Impedance Tomography: A Numerical Study
- Nr. 06/04 Götz Alefeld, Xiaojun Chen: A Regularized Projection Method for Complementarity Problems with Non-Lipschitzian Functions
- Nr. 06/05 Ulrich Kulisch: Letters to the IEEE Computer Arithmetic Standards Revision Group
- Nr. 06/06 Frank Strauss, Vincent Heuveline, Ben Schweizer: Existence and approximation results for shape optimization problems in rotordynamics
- Nr. 06/07 Kai Sandfort, Joachim Ohser: Labeling of n-dimensional images with choosable adjacency of the pixels
- Nr. 06/08 Jan Mayer: Symmetric Permutations for I-matrices to Delay and Avoid Small Pivots During Factorization
- Nr. 06/09 Andreas Rieder, Arne Schneck: Optimality of the fully discrete filtered Backprojection Algorithm for Tomographic Inversion
- Nr. 06/10 Patrizio Neff, Krzysztof Chelminski, Wolfgang Müller, Christian Wieners: A numerical solution method for an infinitesimal elasto-plastic Cosserat model
- Nr. 06/11 Christian Wieners: Nonlinear solution methods for infinitesimal perfect plasticity
- Nr. 07/01 Armin Lechleiter, Andreas Rieder: A Convergence Analysis of the Newton-Type Regularization CG-Reginn with Application to Impedance Tomography
- Nr. 07/02 Jan Lellmann, Jonathan Balzer, Andreas Rieder, Jürgen Beyerer: Shape from Specular Reflection Optical Flow
- Nr. 07/03 Vincent Heuveline, Jan-Philipp Weiß: A Parallel Implementation of a Lattice Boltzmann Method on the Clearspeed Advance Accelerator Board
- Nr. 07/04 Martin Sauter, Christian Wieners: Robust estimates for the approximation of the dynamic consolidation problem
- Nr. 07/05 Jan Mayer: A Numerical Evaluation of Preprocessing and ILU-type Preconditioners for the Solution of Unsymmetric Sparse Linear Systems Using Iterative Methods
- Nr. 07/06 Vincent Heuveline, Frank Strauss: Shape optimization towards stability in constrained hydrodynamic systems
- Nr. 07/07 Götz Alefeld, Günter Mayer: New criteria for the feasibility of the Cholesky method with interval data
- Nr. 07/08 Marco Schnurr: Computing Slope Enclosures by Exploiting a Unique Point of Inflection
- Nr. 07/09 Marco Schnurr: The Automatic Computation of Second-Order Slope Tuples for Some Nonsmooth Functions

Eine aktuelle Liste aller IWRMM-Preprints finden Sie auf:

www.mathematik.uni-karlsruhe.de/iwrmm/seite/preprints