CENTER MANIFOLDS AND DYNAMICS NEAR EQUILIBRIA OF QUASILINEAR PARABOLIC SYSTEMS WITH FULLY NONLINEAR BOUNDARY CONDITIONS

YURI LATUSHKIN, JAN PRÜSS, AND ROLAND SCHNAUBELT

Abstract. We study quasilinear systems of parabolic partial differential equations with fully nonlinear boundary conditions on bounded or exterior domains. Our main results concern the asymptotic behavior of the solutions in the vicinity of an equilibrium. The local center, center-stable, and center-unstable manifolds are constructed and their dynamical properties are established. Under natural conditions, we show that each solution starting close to the center manifold converges to a solution on the center manifold.

1. Introduction

The investigation of the long term behavior of solutions starting near an equilibrium is an essential step in the study of the qualitative properties of a nonlinear evolution equation. In many cases, the structure of the flow in a neighborhood of a steady state \( u_* \) is largely determined by the spectrum of the linearization at \( u_* \), see e.g. [4], [6], [13], [14], [16], [18], [19], [22]. In this paper we treat parabolic systems with nonlinear boundary conditions and we construct local invariant \( C^1 \)–manifolds consisting of solutions to the nonlinear problem. These local center, center-stable, and center-unstable manifolds are tangent at \( u_* \) to the corresponding spectral subspaces of the linearization. We also show that, under natural conditions, each solution starting close to the center manifold converges exponentially to a solution living on the center manifold. In this sense, in a vicinity of \( u_* \) the dynamics of the system is reduced to the dynamics on the center manifold which is governed by an ordinary differential equation. To be more precise, we consider the equations

\[
\begin{align*}
\partial_t u(t) + A(u(t))u(t) &= F(u(t)), & \text{on } \Omega, & t > 0, \\
B_j(u(t)) &= 0, & \text{on } \partial \Omega, & t \geq 0, & j = 1, \ldots, m, \\
u(0) &= u_0, & \text{on } \Omega,
\end{align*}
\]

on a (possibly unbounded) domain \( \Omega \) in \( \mathbb{R}^n \) with compact boundary \( \partial \Omega \), where the solution \( u(t, x) \) takes values in \( \mathbb{C}^N \). The main part of the differential equation is given by a linear differential operator \( A(u) \) of order \( 2m \) (with \( m \in \mathbb{N} \)) whose

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matrix–valued coefficients depend on the derivatives of \( u \) up to order \( 2m - 1 \), and \( F \) is a general nonlinear reaction term acting on the derivatives of \( u \) up to order \( 2m - 1 \). Therefore the differential equation is quasilinear. Our analysis focusses on the fully nonlinear boundary conditions

\[
[B_j(u)](x) := b(x, u(x), \nabla u(x), \cdots, \nabla^{m_j} u(x)) = 0, \quad x \in \partial \Omega, \quad j = 1, \cdots, m,
\]

for the partial derivatives of \( u \) up to order \( m_j \leq 2m - 1 \). We assume mild local regularity of the coefficients and that the linearization at a given steady state \( u_* \) is normally elliptic and satisfies the Lopatinskii–Shapiro condition (see Section 2). Regularity of the coefficients and that the linearization at a given steady state \( u \) for the partial derivatives of \( u \) \( X \) bedded into \( C^{1} \)

\[
\text{We have to require that } a, f \in C^1(\mathbb{R}), b \in C^3(\mathbb{R}) \text{ are real and that there is a steady state } u_0 \in W^2_0(\Omega) \text{ with } a(u_0) \geq \delta > 0, |b'(u_0)| \geq \delta > 0, \text{ and } p > n + 2.
\]

Fully nonlinear boundary conditions appear naturally in the treatment of free boundary problems, see e.g. [5] or [9], and in the study of diffusion through interfaces, see e.g. [11]. The results of the present paper do not directly cover such problems, but we think that our methods can be generalized in order to deal with moving boundaries and transmission problems in future work. We note that the recent work [15] already contains the linear spectral analysis which is necessary for applications of center manifold theory to the Stefan problem with surface tension.

We look for solutions \( u \) of (1.1) in the space \( E_1 = L_p([0, T]; W^{2m}_p(\Omega; \mathbb{C}^N)) \cap W^1_2([0, T]; L_p(\Omega; \mathbb{C}^N)) \) for a fixed finite exponent \( p > n + 2m \). The terms of highest order are thus contained in \( L_p \) spaces. The solution space \( E_1 \) is continuously embedded into \( C([0, T]; X_p) \) for the Slobodetskii space \( X_p = W^{2m-2m/p}_p(\Omega; \mathbb{C}^N) \), and \( X_p \) is the smallest space with this property. Since also \( X_p \hookrightarrow BC^{2m-1}((\Omega; \mathbb{C}^N)) \) by Sobolev’s embedding theorem, the nonlinear terms in (1.1) are continuous in \((t, x)\) up to \( t = 0 \), and thus the initial condition can be understood in classical sense. In particular, the initial value \( u_0 \) of (1.1) has to belong to \( X_p \) and must fulfill the boundary conditions \( B_j(u_0) = 0 \) by continuity. Moreover, the solution \( u \) is continuous in \( X_p \) on \([0, T]\), and the norm of \( X_p \) is the natural norm for our work. So our nonlinear phase space is the \( C^1 \) manifold in \( X_p \) given by

\[
\mathcal{M} = \{ u_0 \in X_p : B_1(u_0) = 0, \cdots, B_m(u_0) = 0 \}.
\]

In our previous work [12] we have established the local wellposedness and certain smoothing properties of (1.1), and we have constructed the local stable and unstable manifolds at the steady state \( u_* \) assuming that the spectrum of the linearization of (1.1) at \( u_* \) does not intersect \( i\mathbb{R} \). At first glance, we followed an approach that appears to be quite “standard”. One introduces a new function \( v(t) = u(t) - u_* \) in order to transform (1.1) into the problem (2.21) below, which involves a linear part and nonlinearities being of the same order as the linear part but vanishing at \( v = 0 \) together with their derivatives. The stable, resp. unstable, manifold consist of initial values of solutions \( u = v - u_* \) to (1.1) which belong to \( E_1 \)-type spaces of exponentially decaying functions on \( \mathbb{R}_+ \), resp. \( \mathbb{R}_- \), see (2.14). Such functions \( v \)
are obtained as fixed points of a Lyapunov–Perron map composed of the solution operator of the linearized inhomogeneous initial(final)–boundary value problem on \( \mathbb{R}_+ (\mathbb{R}_-) \) and of the substitution operators given by the nonlinearities in (2.21), cf. (4.5). The relevant definitions and results are briefly repeated in Section 2. Modifying our methods from [12], in Theorem 4.1 we construct the stable and unstable local manifolds \( M_s \) and \( M_u \) of (1.1) under the assumption that the linearization has spectral gaps in the left and the right open half plane, respectively. We point out that such gaps always exist if the underlying spatial domain \( \Omega \) is bounded.

However, the actual implementation of this “standard” approach faces a fundamental difficulty already for the stable manifold: The nonlinear compatibility condition defining the solution manifold \( M \) obstructs a direct application of the usual methods. It turns out that one has to construct \( M_s \) as a graph of a map defined on the (linearly) stable part of the tangent space \( X^0_p \) of \( M \). This leads to an additional term in the fixed point problem, see the additive term in (4.5).

Moreover, since we are not merely dealing with a semilinear problem, we need maximal regularity for the linearized initial–boundary value problem. This regularity property is known for compact time intervals (see [8] and the references therein). Using the spectral decompositions and semigroup theory, we could extend this result to unbounded intervals in [12, §3], cf. Propositions 2.5 and 2.6 below. We point out that in the maximal regularity result the boundary data must be contained in spaces involving fractional space and time regularity, see (2.14).

Yet another principal difficulty occurs when one tries to construct in a similar way the local center–unstable and center–stable manifolds \( M_{cu} \) and \( M_{cs} \) of (1.1), which should complement the stable and unstable manifolds \( M_s \) and \( M_u \) under the spectral assumptions of Theorem 4.1. Here, already in the linear case, \( M_{cu} \) and \( M_{cs} \) may contain exponentially growing functions. In the corresponding function spaces substitution operators behave badly; in particular, they are locally Lipschitz only under very restrictive conditions. A well known trick to overcome this difficulty is to multiply the nonlinearities in the transformed problem (2.21) by a suitable cutoff function, called \( \mathcal{F}(t,v) \) below, which is equal to 1 if \( v \) is small and equal to 0 if \( v \) is large in a suitable norm (see e.g. [4], [6], [13], [14], [16], [18], [19], [21], [22]). But here we run into severe troubles. The space for the boundary data has to involve (fractional) time regularity which we can only control by means of the full \( E_1 \)–norm of \( v \), say, on small time intervals. As a result, the cutoff must contain nonlocal terms of the form \( \|v\|_{E_1([t-a,t+a])} \), see (3.2). This fact leads to many technical problems, but most importantly, it changes the nature of our evolution equation drastically: It becomes nonlocal and even noncausal after introducing the cutoff, see (3.7). We treat these rather delicate questions in Section 3 in detail. We add that one also needs an additional argument (taken from [21]) in order to upgrade the invariant manifolds from being merely Lipschitz to the class \( C^1 \).

Our main results concern local center manifolds, where we use similar methods as for \( M_{cs} \) and \( M_{cu} \) (working on the time interval \( \mathbb{R} \) instead of \( \mathbb{R}_+ \) or \( \mathbb{R}_- \)). In the center case, we assume that the linearization has spectral gaps in both the left and the right open halfplanes, see (2.34). It is well known that local center manifolds are not uniquely determined, in general. (On a technical level, the nonuniqueness arises from possible modifications of the cutoff.) We show that “our” center manifold \( M_c \) is a \( C^1 \) manifold in \( X_p \) tangent to the center subspace of the linearized problem at \( u_* \) and that it is Lipschitz in the smaller Sobolev space \( X_1 = W^{2m}_p (\Omega; \mathbb{C}^N) \). Moreover,
Finally, \( J \) and \( C \) are considered to be (Lyapunov) stable with respect to the flow on the (finite dimensional) center manifold; the latter solution is given by the ordinary differential equation (4.7). In particular, \( u_0 \) is stable with respect to the full problem (1.1). Our proof is inspired by the arguments in [13, §9.3]. However, in contrast to [13], we cannot work with the cutoff problem because of its nonlocality. We managed to avoid the use of the cutoff by means of a careful analysis controlling the norms of all relevant functions in the proof. In these calculations we need the fact that the center manifold is Lipschitz in all relevant functions in the proof. The center–stable and center–unstable manifolds are proved in Theorem 5.1 and 5.2. Facts are presented in Theorem 4.2 and Corollary 5.3. Analogous results for the boundary problem were established by means of the results from [19]. We also refer to [12] for further literature concerning (1.1).

Center manifolds for fully nonlinear parabolic problems with linear boundary conditions were constructed and investigated in [6], [13], and [14]. Quasilinear equations with quasilinear boundary conditions were treated in [16] and [19]. We emphasize that in these works inhomogeneous boundary values do not appear explicitly in the analysis so that the above mentioned difficulties are not present in these papers. We note that in [10] the stability of a simplified Stefan type moving boundary problem was established by means of the results from [19]. We also refer to [12] for further literature concerning (1.1).

**Notation.** We set \( D_k = -i\partial_t - i\partial_j \partial x_k \) and use the multi index notation. The \( k \)-tensor of the partial derivatives of order \( k \) is denoted by \( \nabla^k \), and we let \( \nabla^k u = (u, \nabla u, \ldots, \nabla^k u) \). For an operator \( A \) on a Banach space we write \( \text{dom}(A), \text{ker}(A), \text{ran}(A) \), \( \sigma(A) \), and \( \rho(A) \) for its domain, kernel, range, spectrum, and resolvent set, respectively. \( B(X,Y) \) is the space of bounded linear operators between two Banach spaces \( X \) and \( Y \), and \( B(X) := B(X,X) \). A ball in \( X \) with the radius \( r \) and center at \( u \) will be denoted by \( B_X(u,r) \). For an open set \( U \subset \mathbb{R}^n \) with (sufficiently regular) boundary \( \partial U \), \( C^k(U) \) (resp., \( BC^k(U) \), \( BUC^k(U) \), \( C^0_b(U) \)) are the spaces of \( k \)-times continuously differentiable functions \( u \) on \( U \) (such that \( u \) and its derivatives up to order \( k \) are bounded, bounded and uniformly continuous, vanish at \( \partial U \) and at infinity (if \( U \) is unbounded), respectively), where \( BC^k(U) \) is endowed with its canonical norm. For \( C^k(\overline{U}) \), \( BC^k(\overline{U}) \), \( BUC^k(\overline{U}) \), we require in addition that \( u \) and its derivatives up to order \( k \) have a continuous extension to \( \partial U \). For unbounded \( U \), we write \( C^0_b(\overline{U}) \) for the space of \( u \in C^k(\overline{U}) \) such that \( u \) and its derivatives up to order \( k \) vanish at infinity. By \( W^k_p(U) \) we denote the Sobolev spaces, see e.g. [1, Def.3.1], and by \( W^{s,\sigma}_p(U) \) the Sobolev–Tikhonov spaces endowed with the norm

\[
|v|^{p}_{W^s_p(U)} = |v|^{p}_{L^p(U)} + \sum_{|\alpha| = k} |\partial^\alpha v^{p}_{W^{s-|\alpha|}_p(U)} , \quad [w]^{p}_{W^s_p(U)} = \iint_{U^2} \frac{|w(y) - w(x)|^p}{|y - x|^{n + s + \sigma p}} \, dx \, dy,
\]

for \( s = k + \sigma \) with \( k \in \mathbb{N}_0, \sigma \in (0,1) \), see [1, Thm.7.48] or [20, Rem.4.4.1.2]. Finally, \( J \subset \mathbb{R} \) is a closed interval with nonempty interior, \( c \) is a generic constant, and \( \varepsilon : \mathbb{R}_+ \rightarrow \mathbb{R}_+ \) is a generic nondecreasing function with \( \varepsilon(r) \rightarrow 0 \) as \( r \rightarrow 0 \).
2. Setting and Preliminaries

We introduce the setting of our paper; more details can be found in [12]. Let \( \Omega \subset \mathbb{R}^n \) be an open connected set with a compact boundary \( \partial \Omega \) of class \( C^{2m} \) and outer unit normal \( \nu(x) \), where \( m \in \mathbb{N} \) is given by (2.5) below. Throughout this paper, we fix a finite exponent \( p \) with
\[
p > n + 2m.
\]
Let \( E = \mathbb{C}^N \) with \( B(E) = \mathbb{C}^{N \times N} \) for some fixed \( N \in \mathbb{N} \). We put
\[
X_0 = L_p(\Omega; \mathbb{C}^N), \quad X_1 = W_p^{2m}(\Omega; \mathbb{C}^N), \quad X_p = W_p^{2m(1-1/p)}(\Omega; \mathbb{C}^N),
\]
and denote the norms of these spaces by \( \| \cdot \|_{X_0} \), \( \| \cdot \|_{X_1} \), and \( \| \cdot \|_p \), respectively. Recall that the spatial trace operator \( \gamma \) at \( \partial \Omega \) induces continuous maps
\[
\gamma : W_p^s(\Omega; \mathbb{C}^N) \to W_p^{s-1/p}(\partial \Omega; \mathbb{C}^N)
\]
for \( 1/p < s \leq 2 \) if \( s - 1/p \) is not an integer. We set
\[
Y_0 = L_p(\partial \Omega; \mathbb{C}^N), \quad Y_j = W_p^{2mj}(\partial \Omega; \mathbb{C}^N), \quad Y_{jp} = W_p^{2mj-2m/p}(\partial \Omega; \mathbb{C}^N),
\]
for \( j \in \{1, \ldots, m\} \), \( n_j \in \{0, \ldots, 2m-1\} \) given by (2.5), and the numbers
\[
\kappa_j = 1 - \frac{m_j}{2m} - \frac{1}{2mp}.
\]
Here the Sobolev–Slobodetskii spaces on \( \partial \Omega \) are defined via local charts, see [1, Thm.7.53], [20, Def.3.6.1]. We observe that \( X_1 \hookrightarrow X_p \hookrightarrow X_0 \), \( Y_{j1} \hookrightarrow Y_{jp} \hookrightarrow Y_0 \),
\[
X_p \hookrightarrow C_0^{2m+1}(\overline{\Omega}; \mathbb{C}^N), \quad Y_{jp} \hookrightarrow C_0^{2m-1-m_j}(\partial \Omega; \mathbb{C}^N)
\]
by (2.1), (2.3), and standard properties of Sobolev spaces, cf. [20, \S 4.6.1]. Our basic equations (1.1) involve the operators given by
\[
[A(u)v](x) = \sum_{|\alpha|=2m} a_\alpha(x, u(x), \nabla u(x), \ldots, \nabla^{2m-1}u(x)) D^\alpha v(x), \quad x \in \Omega,
\]
\[
[F(u)][x] = f(x, u(x), \nabla u(x), \ldots, \nabla^{2m-1}u(x)), \quad x \in \Omega,
\]
\[
[B_j(u)](x) = b_j(x, \gamma u(x), \gamma \nabla u(x), \ldots, (\gamma \nabla^{m_j}u)(x)), \quad x \in \partial \Omega,
\]
for \( j \in \{1, \ldots, m\} \) and functions \( u \in X_p \) and \( v \in X_1 \), where the integers \( m \in \mathbb{N} \) and \( m_j \in \{0, \ldots, 2m-1\} \) fixed. We set \( B = (B_1, \ldots, B_m) \). We assume throughout that the coefficients in (2.5) satisfy:

(R) \( a_\alpha \in C^1(\mathbb{R}^n \times \mathbb{R}^n \times \cdots \times \mathbb{R}^n; B(\overline{\Omega}; B(E))) \) for \( \alpha \in \mathbb{N}_0^n \) with \( |\alpha| = 2m \), \( a_\alpha(x, 0) \to a_\alpha(\infty) \) in \( B(E) \) as \( x \to \infty \), if \( \Omega \) is unbounded,
\[
f \in C^1(\mathbb{R}^n \times \cdots \times \mathbb{R}^{(n-1)/k}; B(\overline{\Omega}; B(E))),
\]
\[
b_j \in C^{2m+1-m_j}(\partial \Omega \times \mathbb{R}^n \times \cdots \times \mathbb{R}^{(n-1)/k}; E), \quad f \in \mathbb{C}^{2m+2-m_j}(\partial \Omega \times \mathbb{R}^n \times \cdots \times \mathbb{R}^{(n-1)/k}; E),
\]
for \( j \in \{1, \ldots, m\} \). Occasionally, we will need one more degree of smoothness of the coefficients as recorded in the following hypothesis:

(RR) \( a_\alpha \in C^2(\mathbb{R}^n \times \mathbb{R}^n \times \cdots \times \mathbb{R}^n; B(\overline{\Omega}; B(E))) \) for \( \alpha \in \mathbb{N}_0^n \) with \( |\alpha| = 2m \),
\[
f \in C^2(\mathbb{R}^n \times \cdots \times \mathbb{R}^n; B(\overline{\Omega}; B(E))),
\]
\[
b_j \in C^{2m+2-m_j}(\partial \Omega \times \mathbb{R}^n \times \cdots \times \mathbb{R}^{(n-1)/k}; E), \quad f \in \mathbb{C}^{2m+2-m_j}(\partial \Omega \times \mathbb{R}^n \times \cdots \times \mathbb{R}^{(n-1)/k}; E),
\]
for \( j \in \{1, \ldots, m\} \).
In view of (2.4), only continuous functions will be inserted into the nonlinearities. Thus we will omit the trace $\gamma$ in $B_j(u)$ and in similar expressions. We fix a numbering of the components of $\nabla^k$ so that a partial derivative $\partial^\beta u(x)$ of order $|\beta| = k$ is inserted at a fixed position called $l(\beta, k)$ into the functions $u_n$, $f$, and $b_j$. It is not difficult to see that

$$A \in C^1(X_p; B(X_1, X_0)) \text{ and } F \in C^1(X_p; X_0) \quad (2.6)$$

with the locally bounded derivatives

$$[F'(u)v](x) = \sum_{k=0}^{2m-1} \sum_{|\beta|=k} i^k \left( \partial_{l(\beta, k)} f \right)(x, u(x), \nabla u(x), \ldots, \nabla^{2m-1} u(x)) \, D^\beta v(x),$$

$$[A'(u)w](x) = A'(u)[v, w](x) \quad (2.7)$$

$$= \sum_{|\alpha|=2m} \sum_{|\beta|=k} \sum (\partial_{l(\beta, k)} \alpha)(x, u(x), \ldots, \nabla^{2m-1} u(x)) \, [D^\beta v(x), D^\alpha w(x)]$$

for $x \in \Omega$, $u, v \in X_p$, and $w \in X_1$, see [12, (25)] and the text before it. (Observe that $(\partial_{l(\beta, k)} \alpha)(x, z) : E^2 \to E$ is bilinear.) We further have

$$B_j \in C^1(X_p; Y_{jp}) \cap C^1(X_1; Y_{j1}), \quad j \in \{1, \ldots, m\}, \quad (2.8)$$

with the locally bounded derivatives

$$[B'_j(u)v](x) = \sum_{|\alpha|=2m} \sum_{|\beta|=k} i^k \left( \partial_{l(\beta, k)} b_j \right)(x, u(x), \nabla u(x), \ldots, \nabla^{m} u(x)) \, D^\beta v(x),$$

where $x \in \partial \Omega$ and $u, v \in X_p$, resp. $u, v \in X_1$. The continuous differentiability of $B_j : X_p \to Y_{jp}$ was shown in [12, Cor.12], and $B_j \in C^1(X_1; Y_{j1})$ can be proved by the arguments used in step (4) and (5) of the proof of [12, Prop.10], see in particular inequality (49) in [12]. We set $B'(u) = (B'_1(u), \ldots, B'_m(u))$.

The symbols of the principal parts of the linear differential operators are the matrix–valued functions given by

$$A_\#(x, z, \xi) = \sum_{|\alpha|=2m} a_\alpha(x, z) \xi^\alpha, \quad B_\#(x, z, \xi) = \sum_{|\beta|=m} i^m \left( \partial_{l(\beta, m)} b_j \right)(x, z) \xi^\beta$$

for $x \in \Omega$, $z \in E \times \cdots \times E^{(n \beta - 1)}$ and $\xi \in \mathbb{R}^n$, resp. $x \in \partial \Omega$, $z \in E \times \cdots \times E^{(n \beta)}$ and $\xi \in \mathbb{R}^n$. We further set $A_\#(\infty, \xi) = \sum_{|\alpha|=2m} a_\alpha(\infty) \xi^\alpha$ if $\Omega$ is unbounded.

We introduce the normal ellipticity and the Lopatinskiĭ–Shapiro condition for $A(u_0)$ and $B'(u_0)$ at a function $u_0 \in X_p$ as follows:

\begin{enumerate}
    \item [(E)] $\sigma(A_\#(x, \sum_{\beta=1}^{2m-1} u_0(x), \xi)) \subset \{ \lambda \in \mathbb{C} : \text{Re} \lambda > 0 \} =: \mathbb{C}_+$ and (if $\Omega$ is unbounded) $\sigma(A_\#(\infty, \xi)) \subset \mathbb{C}_+$, for $x \in \Omega$ and $\xi \in \mathbb{R}^n$ with $|\xi| = 1$.
    \item [(LS)] Let $x \in \partial \Omega$, $\xi \in \mathbb{R}^n$, and $\lambda \in \mathbb{C}_+$ with $\text{Im} \lambda > 0$ and $(\xi, \lambda) \neq (0, 0)$. Then the function $\varphi = 0$ is the only solution in $C_0(\mathbb{R}^n; \mathbb{C}^N)$ of the ode system

\begin{align}
    \lambda \varphi(y) + A_\#(x, \sum_{\beta=1}^{2m-1} u_0(x), \xi + iv(x) \partial_y) \varphi(y) &= 0, \quad y > 0, \\
    B_\#(x, \sum_{\beta=1}^{m} u_0(x), \xi + iv(x) \partial_y) \varphi(0) &= 0, \quad j \in \{1, \ldots, m\}.
\end{align}

\end{enumerate}

We refer to [3], [7], [8], and the references therein for more information concerning these conditions. We can now state our basic hypothesis.

**Hypothesis 2.1.** Condition (R) holds, and (E), (LS) hold at a steady state $u_* \in X_1$ of (1.1), i.e., $A(u_*)u_* = F(u_*)$ on $\Omega$, $B(u_*) = 0$ on $\partial \Omega$. 


For the investigation of (1.1), we need several spaces of functions on $J \times \Omega$ and $J \times \partial \Omega$, where $J \subset \mathbb{R}$ is a closed interval with a nonempty interior. The base space and solution space of (1.1) are
\[
E_0(J) = L_p(J; L_p(\Omega; \mathbb{C}^N)) = L_p(J; X_0),
\]
\[
E_1(J) = W^1_p(J; L_p(\Omega; \mathbb{C}^N)) \cap L_p(J; W^{2m}_p(\Omega; \mathbb{C}^N)) = W^1_p(J; X_0) \cap L_p(J; X_1),
\]
respectively. We equip $E_0(J)$ with the usual $p$-norm and $E_1(J)$ with the norm
\[
\|u\|_{E_1(J)} = \left[ \|u\|_{E_0(J)}^p + \|\tilde{u}\|_{E_0(J)}^p + \sum_{|\alpha|=2m} \|\partial^\alpha u\|_{E_0(J)}^p \right]^{\frac{1}{p}}.
\]
Very often we use the crucial embeddings
\[
E_1(J) \hookrightarrow \text{BUC}(J; X_p) \hookrightarrow \text{BUC}(J; C_0^{2m-1}(\overline{\Omega}; \mathbb{C}^N)),
\]
see [2, Thm.III.4.10.2] for the first and (2.4) for the second embedding. We denote by $c_0 = c_0(J)$ the norm of the first embedding in (2.11), which is uniform for $J$ of length greater than a fixed $\ell > 0$. Observe that (2.11) implies that the trace operator $\gamma_0$ at time $0$ is continuous from $E_1(J)$ to $X_p$ if $0 \in J$. The boundary data of our linearized equations will be contained in the spaces
\[
F_j(J) = W^\infty_p(J; L_p(\partial\Omega; \mathbb{C}^N)) \cap L_p(J; W^{2m\infty}_p(\partial\Omega; \mathbb{C}^N))
\]
\[
= W^\infty_p(J; Y_0) \cap L_p(J; Y_{j1}), \quad j \in \{1, \ldots, m\},
\]
endowed with their natural norms, where $F(\cdot) := F_1(\cdot) \times \cdots \times F_m(\cdot)$. We have
\[
F_j(J) \hookrightarrow \text{BUC}(J; Y_{jp}) \hookrightarrow \text{BUC}(J \times \partial\Omega) \quad \text{and} \quad \gamma_0 \in \mathcal{B}(F_j(J), Y_{jp})
\]
if $0 \in J$, see [8, §3] and [12, §2]. For $\alpha, \beta \in \mathbb{R}$, we set $e_\alpha(t) = e^{\alpha t}$ for $t \in \mathbb{R}$ and define the function $e_{\alpha,\beta}(t)$ by setting $e_{\alpha,\beta}(t) = e_\alpha(t)$ for $t \leq 0$ and $e_{\alpha,\beta}(t) = e_\beta(t)$ for $t > 0$. Then we introduce the weighted spaces
\[
E_k(\mathbb{R}_+, \alpha) = \{ v : e_\alpha v \in E_k(\mathbb{R}_+) \}, \quad F(\mathbb{R}_+, \alpha) = \{ v : e_\alpha v \in F(\mathbb{R}_+) \},
\]
\[
E_k(\alpha, \beta) = \{ v : e_{\alpha,\beta} v \in E_k(\mathbb{R}) \}, \quad F(\alpha, \beta) = \{ v : e_{\alpha,\beta} v \in F(\mathbb{R}) \},
\]
where $k = 0, 1$, endowed with the canonical norms $\|v\|_{E_k(\mathbb{R}_+, \alpha)} = \|e_\alpha v\|_{E_k(\mathbb{R}_+)}$ etc. We also use the analogous norms on compact intervals $J$.

We assume that Hypothesis 2.1 holds. Due to (2.6) and (2.8), we can linearize the problem (1.1) at the steady state $u_* \in X_1$ obtaining the operators defined by
\[
A_* = A(u_*) + A'(u_*)u_* - F'(u_*) \in \mathcal{B}(X_1, X_0),
\]
\[
B_{j*} = B'_j(u_*) \in \mathcal{B}(X_p, Y_{jp}) \cap \mathcal{B}(X_1, Y_{j1}).
\]
We set $B_* = (B_{1*}, \ldots, B_{m*})$. We further define the nonlinear maps
\[
G \in C^1(X_1; X_0) \quad \text{and} \quad H_j \in C^1(X_p; Y_{jp}) \cap C^1(X_1; Y_{j1})
\]
with $G(0) = H_j(0) = 0$ and $G'(0) = H'_j(0) = 0$
\[
\text{for } j \in \{1, \ldots, m\} \text{ by setting}
\]
\[
G(v) = (A(u_*)v - A(u_* + v)v) - (A(u_*) + A(u_*)u_* - A(u_*)u_* - A'(u_*)u_*v) \]
\[+ (F(u_*)v - F(u_*) - F'(u_*)v),
\]
\[
H_j(v) = B'_j(u_*)v - B_j(u_* + v),
\]
(2.17, 2.18)
for \( v \in X_1, \) resp. \( v \in X_p. \) Again, we put \( H(v) = (H_1(v), \cdots, H_m(v)). \) The corresponding Nemytskii operators are denoted by

\[
G(v)(t) = G(v(t)), \quad \mathbb{H}_j(v)(t) = H_j(v(t)), \quad \mathbb{H}(v)(t) = H(v(t)) \tag{2.19}
\]

for \( v \in E^1_{loc}(J) \) (which is the space of \( v : J \to X_0 \) such that \( v \in E_1([a,b]) \) for all intervals \([a,b] \subset J). \) We recall a part of Proposition 10 from [12] describing the mapping properties of \( G \) and \( H. \)

**Proposition 2.2.** Let (R) hold. Define \( G \) and \( \mathbb{H} \) by (2.17), (2.18), (2.19) for some \( u_* \in X_1 \) with \( B(u_*) = 0. \) Take \( \delta \geq 0. \) Then we have:

\[
G \in C^1(E_1([a,b]); E_0([a,b])), \quad \mathbb{H} \in C^1(E_1([a,b]); F([a,b])),
\]

Moreover, \( G(0) = 0, \) \( G'(0) = 0, \) \( \mathbb{H}(0) = 0, \) and \( \mathbb{H}'(0) = 0. \)

Theorem 14 of [12] shows that (1.1) generates a local semiflow on the solution manifold

\[
\mathcal{M} = \{ u_0 \in X_p : B(u_0) = 0 \}. \tag{2.20}
\]

In particular, a function \( u_0 \) is the initial value of the (unique) solution \( u \in E_1([0,T]) \) of (1.1) for some \( T > 0 \) if and only if \( u_0 \in \mathcal{M}. \) Setting \( v = u - u_* \) and \( v_0 = u_0 - u_*, \) we further see that \( u_0 \in \mathcal{M} \) if and only if \( v_0 \in X_p \) and \( B_*v_0 = H(v_0) \) and that \( u \in E_1([0,T]) \) solves (1.1) if and only if \( v \in E_1([0,T]) \) satisfies

\[
\partial_t v(t) + A_* v(t) = G(v(t)) \quad \text{on } \Omega, \quad t > 0, \\
B_* v(t) = H_j(v(t)) \quad \text{on } \partial \Omega, \quad t \geq 0, \quad j \in \{1, \cdots, m\}, \tag{2.21}
\]

\[
v(0) = v_0, \quad \text{on } \Omega.
\]

**Remark 2.3.** Theorem 14(a) of [12] implies the following facts: For each given \( T > 0, \) there is a radius \( \rho = \rho(T) > 0 \) such that for every \( u_0 = u_* + v_0 \in \mathcal{M} \) with \( |v_0|_p \leq \rho \) there exists a unique solution \( u = u_* + v \) of (1.1) on \([0,T], \) and \( \|v\|_{E_1([0,T])} \leq c_* |v_0|_p \) with a constant \( c_* = c_*(T) \) independent of \( u_0 \) in this ball. \( \Diamond \)

We now recast and extend some results from [12] regarding the solvability of the inhomogeneous linear problem

\[
\partial_t v(t) + A_* v(t) = g(t) \quad \text{on } \Omega, \quad t \in J, \\
B_* v(t) = h(t) \quad \text{on } \partial \Omega, \quad t \in J, \tag{2.22}
\]

\[
v(0) = v_0, \quad \text{on } \Omega,
\]

in weighted function spaces on the unbounded interval \( J \in \{\mathbb{R}_+, \mathbb{R}_-, \mathbb{R}\}. \) We assume that Hypothesis 2.1 holds. (Actually, when dealing only with (2.22) we do not have to assume that \( u_* \in X_1 \) is a steady state of (1.1).) We recall from [8, Thm.2.1] that on a bounded interval \( J = [a,b] \) the boundary value problem obtained by combining the first two lines of (2.22) with the initial condition \( v(a) = v_0 \) has a unique solution \( v \in E_1([a,b]) \) if and only if \( g \in E_0([a,b]), h \in F([a,b]), \) \( v_0 \in X_p, \) and \( B_*v_0 = h(a). \) A solution \( v \in E^1_{loc}(J) \) of (2.22) on \( J \) will be denoted by \( v = S(v_0, g, h), \) where \( J \subset \mathbb{R} \) is any closed interval containing 0. We stress that this notation incorporates the compatibility condition \( B_*v_0 = h(0) \) because of the second line in (2.22) and (2.11). Moreover, the solution \( S(v_0, g, h) \) is unique if \( J = \mathbb{R}_+, \) but uniqueness may fail on \( J = \mathbb{R}_-. \)
As in [12, (31)], we define \( A_0 = A_1|_{\text{ker} B} \), with the domain \( \text{dom}(A_0) = \{ u \in X_1 : B_1u = 0, j = 1, \ldots, m \} \), and denote by \( T(\cdot) \) the analytic semigroup on \( X_0 \) generated by \(-A_0\). We further need the extrapolated semigroup \( T_{-1}(\cdot) \) and its generator \( A_{-1} \) acting on the extrapolation space \( X_{-1} \) of \( A_0 \); here, \( X_{-1} \) is the completion of \( X_0 \) with respect to the norm \(|u_0|_{-1} = |(\mu + A_0)^{-1}u_0|_0\) for some fixed \( \mu \in \rho(-A_0) \). We further employ the map

\[
\Pi = (\mu + A_{-1})N_1 \in B(Y_1, X_1)
\]  

(2.23)

where \( N_1 \in B(Y_1, X_1) \) is the solution operator, \( N_1 : \varphi \mapsto u \), of the elliptic boundary value problem \((\mu + A_0)u = 0 \) on \( \Omega \), \( B_1u = \varphi \) on \( \partial \Omega \), see [12, Prop.5]. Also, by the same Proposition 5 in [12], there exists a right inverse \( N'_p \in B(Y_p, X_p) \) of \( B_* \). Due to [12, Prop.6], the function \( v = S(v_0, g, h) \) is a solution of (2.22) if and only if \( v \in E_{\text{loc}}^1(J) \), \( v(0) = v_0 \), and the variation of constants formula

\[
v(t) = T(t - \tau)v(\tau) + \int_\tau^t [T(t - s)g(s) + T_{-1}(t - s)\Pi h(s)] \, ds
\]  

(2.24)

holds for all \( t \geq \tau \) in \( J \). If \( J = \mathbb{R}_+ \) (or \( J = [0, T] \)), it suffices to take \( \tau = 0 \) in (2.24), and \( v(0) = v_0 \) follows from (2.24).

In order to treat solutions of (2.22) on the intervals \( J = \mathbb{R}_\pm \), we assume that the (rescaled) semigroup \( \{e^{\delta t}T(\cdot)\}_{t \geq 0} \) is hyperbolic for \( \delta \in [\delta_1, \delta_2] \) for some segment \([\delta_1, \delta_2] \subseteq \mathbb{R} \) (i.e., \( \sigma(-A_0 + \delta) \cap i\mathbb{R} = \emptyset \)). Let \( P \) be the (stable) spectral projection for \(-A_0 + \delta \) corresponding to the part of \( \sigma(-A_0 + \delta) \) in the open left halfplane, and set \( Q = I - P \). Then \( T(t) \) is invertible on \( QX_0 \) with the inverse \( T_Q(\cdot)Q \), and \( \|e^{\delta t}T(t)P\|, \|e^{\delta t}T_Q(\cdot)Q\| \leq ce^{-\epsilon t} \) for \( t \geq 0 \) and some \( \epsilon > 0 \).

**Remark 2.4.** If \( e^{\delta t}T(\cdot) \) is hyperbolic on \( X_0 \) then \( e^{\delta t}T_{-1}(\cdot) \) is hyperbolic on \( X_{-1} \) with projections \( P_{-1} \) and \( Q_{-1} = I - P_{-1} \) being the extensions of \( P \) and \( Q \), respectively. Moreover, \( Q_{-1} \) maps \( X_{-1} \) into \( \text{dom}(A_0) \), and \( P \) leaves invariant \( X_p, X_1 \), and \( \text{dom}(A_0) \). (See [12, §2] for these facts.)

Given \((w_0, g, h) \in X_p \times E_0(\mathbb{R}_+, \delta) \times F(\mathbb{R}_+, \delta), (w_0, g, h) \in X_0 \times E_0(\mathbb{R}_-, \delta) \times F(\mathbb{R}_-, \delta), \) we can then define

\[
L^P_{P, A_0}(w_0, g, h)(t) = T(t)w_0 + \int_0^t [T(t - s)Pg(s) + T_{-1}(t - s)P_{-1}\Pi h(s)] \, ds
\]

\[
- \int_t^\infty T_Q(t - s)Q[g(s) + \Pi h(s)] \, ds, \quad t \geq 0,
\]  

(2.25)

\[
\phi^+_0 = -\int_0^\infty T_Q(-s)Q[g(s) + \Pi h(s)] \, ds,
\]  

(2.26)

\[
L^P_{P, A_0}(w_0, g, h)(t) = T_Q(t)w_0 + \int_0^t [T(t - s)Pg(s) + T_{-1}(t - s)P_{-1}\Pi h(s)] \, ds
\]

\[
- \int_t^\infty T_Q(t - s)Q[g(s) + \Pi h(s)] \, ds, \quad t \leq 0,
\]  

(2.27)

\[
\phi^-_0 = \int_0^\infty [T(-s)Pg(s) + T_{-1}(-s)P_{-1}\Pi h(s)] \, ds.
\]  

(2.28)

(We drop the subscript ‘\(-1\)’ in the \(Q\)-integrals.) As in [12, §3], one verifies that these integrals in fact exist. Clearly, a function \( v \in E_{\text{loc}}^1(J) \) solves (2.22) if and only
if \( \tilde{v} = e_{\delta}v \in \mathbb{R}^{1}_{\text{loc}}(J) \) is a solution of the rescaled problem

\[
\begin{align*}
\partial_t \tilde{v}(t) + (A_\delta - \delta)\tilde{v}(t) &= e^{\delta t}g(t) & \text{on } \Omega, & \text{a.e. } t \in J, \\
B_\delta \tilde{v}(t) &= e^{\delta t}h(t) & \text{on } \partial \Omega, & \text{t } \in J, \\
\tilde{v}(0) &= v_0, & \text{on } \Omega,
\end{align*}
\]

whose solution operator will be denoted by \( S_{A_\delta} \). We characterize the solvability of (2.22) at first in the case \( J = \mathbb{R}_+ \). Using (2.24), (2.25) and (2.26), we infer that

\[
e_{\delta}S_{A_\delta}(v_0, g, h) = S_{A_\delta - \delta}(v_0, e_\delta g, e_\delta h) = e_{\delta}T(\cdot)(Qv_0 - \phi_0^\delta) + L_{P,A_\delta}(Pv_0, e_\delta g, e_\delta h)
\]

Using (2.29), (2.30) and (2.31), we infer that

\[
e_\delta S_{A_\delta}(v_0, g, h) = e_\delta T(\cdot)(Qv_0 - \phi_0^\delta) + L_{P,A_\delta}(Pv_0, g, h).
\]

**Proposition 2.5.** Assume that Hypothesis 2.1 holds and that for \( \delta \in [\delta_1, \delta_2] \subset \mathbb{R} \) the semigroup \( e_{\delta}T(\cdot) \) is hyperbolic with the stable projection \( P \), and let \( Q = I - P \). Suppose that \( (v_0, g, h) \in X_\delta \times E_\delta(\mathbb{R}_+, \delta) \times F(\mathbb{R}_+, \delta) \) and \( B_\delta v_0 = h(0) \). Using the above notations, the following assertions are equivalent:

\[
\begin{align*}
(a) & \quad S_{A_\delta}(v_0, g, h) \in E_\delta(\mathbb{R}_+, \delta).
(b) & \quad L_{P,A_\delta}(v_0 - \phi_0^\delta, g, h) \in E_\delta(\mathbb{R}_+, \delta).
(c) & \quad \phi_0^\delta = Qv_0.
\end{align*}
\]

If these assertions hold, then \( S_{A_\delta}(v_0, g, h) = L_{P,A_\delta}(Pv_0, g, h) \in E_1(\mathbb{R}_+, \delta) \), and we have the maximal regularity estimate

\[
\|S_{A_\delta}(v_0, g, h)\|_{E_1(\mathbb{R}_+, \delta)} \leq c (\|v_0\|_P + \|g\|_{E_\delta(\mathbb{R}_+, \delta)} + \|h\|_{F(\mathbb{R}_+, \delta)}),
\]

where \( c \) does not depend on \( v_0, g, h, \) or \( \delta \).

**Proof.** Using rescaling as in (2.29) and (2.31), it suffices to prove the proposition for \( \delta = 0 \). For this case, assertions \( (b) \Leftrightarrow (c) \Rightarrow (a) \) and the last statement have been proved in [12, Prop.8], and \( (a) \Rightarrow (c) \) follows from (2.30).

The corresponding result for \( J = \mathbb{R}_- \) looks a bit different since in (2.27) we have to write \( T(t)Qv_0 \) rather than \( T(t)v_0 \) for negative \( t \). Moreover, Proposition 2.6 does not require a compatibility condition since it deals with a final value problem on \( J = \mathbb{R}_- \). The next result follows by rescaling from Proposition 9 of [12].

**Proposition 2.6.** Assume that Hypothesis 2.1 holds and that for \( \delta \in [\delta_1, \delta_2] \subset \mathbb{R} \) the semigroup \( e_{\delta}T(\cdot) \) is hyperbolic with the stable projection \( P \), and let \( Q = I - P \). Suppose that \( (v_0, g, h) \in X_\delta \times E_\delta(\mathbb{R}_-, \delta) \times F(\mathbb{R}_-, \delta) \). Using the above notations, there is a solution \( v = S_{A_\delta}(v_0, g, h) \) of (2.22) in \( E_\delta(\mathbb{R}_-, \delta) \) if and only if \( Pv_0 = \phi_0^\delta \). In this case, this solution is unique, \( v = L_{P,A_\delta}(v_0, g, h) \in E_1(\mathbb{R}_-, \delta) \), and

\[
\|S_{A_\delta}(v_0, g, h)\|_{E_1(\mathbb{R}_-, \delta)} \leq c (\|Qv_0\|_P + \|g\|_{E_\delta(\mathbb{R}_-, \delta)} + \|h\|_{F(\mathbb{R}_-, \delta)}),
\]

where \( c \) does not depend on \( v_0, g, h, \) or \( \delta \).

In order to treat the interval \( J = \mathbb{R} \), we assume that \( T(\cdot) \) has an exponential trichotomy, i.e., there is a splitting

\[
\sigma(-A_0) = \sigma_s \cup \sigma_c \cup \sigma_u
\]

with

\[
\max \text{Re } \sigma_s < -\omega_s < -\omega_c < \min \text{Re } \sigma_c \leq 0 \leq \max \text{Re } \sigma_c < \omega_c < \omega_u < \min \text{Re } \sigma_u.
\]

(If \( \Omega \) is bounded, \( \sigma(-A_0) \) is discrete and thus (2.34) automatically holds with \( \sigma_u \subset i\mathbb{R} \) and arbitrarily small \( \omega_c = \omega_u \).) We take numbers \( \alpha \in [\omega_c, \omega_s] \) and
β ∈ [\mathcal{W}, \omega_\alpha] and denote by \( P_k \) the spectral projections for \(-A_0\) corresponding to \( \sigma_k, k = s, c, u \). We set \( P_{cs} = P_s + P_c, P_{ca} = P_c + P_u, \) and \( P_{sa} = P_s + P_a \). Then the rescaled semigroups \( e^\omega T(\cdot) \) and \( e^{-\beta} T(\cdot) \) are hyperbolic on \( X_0 \) with stable projections \( P_s \) and \( P_{cs} \), respectively. The restriction of \( T(t) \) to \( P_k X_0 \) yields a group denoted by \( T_k(t), t \in \mathbb{R}, \) where \( k = c, u, cu \). For \( g \in E_0(\alpha, -\beta), h \in F(\alpha, -\beta) \) and \( w_0 \in X_0 \), we can then define

\[
L_{A_0}(w_0, g, h)(t) = T_c(t)P_c w_0 + \int_0^t T_c(t-s) P_c [g(s) + \Pi h(s)] \, ds \\
+ \int_{-\infty}^t [T(t-s) P_c g(s) + T_{-1}(t-s) P_{n-1} + \Pi h(s)] \, ds \\
- \int_t^\infty T_u(t-s) P_u [g(s) + \Pi h(s)] \, ds,
\]

(2.35)

\[
\phi_0 = \int_{-\infty}^0 [T(-s) P_c g(s) + T_{-1}(-s) P_{n-1} \Pi h(s)] \, ds \\
- \int_t^\infty T_u(-s) P_u [g(s) + \Pi h(s)] \, ds.
\]

(2.36)

The trichotomy and the assumptions on the data imply that the integrals are well-defined. The next result then easily follows from Propositions 2.5 and 2.6.

**Proposition 2.7.** Assume that Hypothesis 2.1 holds and that \( T(\cdot) \) has a trichotomy as in (2.34). Take \( \alpha \in [\mathcal{W}, \omega_\alpha] \) and \( \beta \in [\mathcal{W}, \omega_\alpha] \) and denote by \( P_k \) the spectral projections corresponding to \( \sigma_k, k = s, c, u \). Suppose that \((v_0, g, h) \in X_0 \times E_0(\alpha, -\beta) \times F(\alpha, -\beta) \). Using the above notations, there is a solution \( v = S_{A_0}(v_0, g, h) \) of (2.22) in \( E_0(\alpha, -\beta) \) if and only if \( P_{sa} v_0 = \phi_0 \). In this case, this solution is unique, and we have \( v = L_{A_0}(v_0, g, h) \in E_1(\alpha, -\beta) \) and

\[
\| S_{A_0}(v_0, g, h) \|_{E_{1}(\alpha, -\beta)} \leq c \left( \| P_c v_0 \|_0 + \| g \|_{E_{0}(\alpha, -\beta)} + \| h \|_{F_{0}(\alpha, -\beta)} \right),
\]

(2.37)

where \( c \) does not depend on \( v_0, g, h, \alpha, \) or \( \beta \).

3. THE CUTOFF PROBLEM AND THE CORRESPONDING NEMYTSKII OPERATORS

In this section we introduce a nonlocal and (if \( J = \mathbb{R} \)) time-invariant cutoff for (2.21) and discuss the mapping properties of the corresponding Nemytskii operators. The cutoff depends on a parameter \( \eta > 0 \) to be fixed in the following sections. For \( t \in \mathbb{R} \) and \( n \in \mathbb{Z}, \) we set

\[
J(t) = [t - \frac{3}{2}, t + \frac{3}{2}], \quad J_n = [n, n + 1], \quad J^*_n = [n - \frac{1}{2}, n + \frac{3}{2}],
\]

\[
J'_n = [n - \frac{1}{2}, n + \frac{1}{2}], \quad \text{and} \quad J''_n = [n - 2, n + 3].
\]

We further introduce

\[
N(t, v) = \| v \|_{E_{1}(J(t))} \quad \text{for} \quad v \in E_{1}^{loc}(\mathbb{R}).
\]

(3.1)

Given \( \eta > 0, \) we take even functions \( \chi, \gamma \in C^\infty(\mathbb{R}) \) such that \( 0 \leq \chi \leq 1, \chi(t) = 1 \) for \( t \in [-\eta, \eta], \) supp \( \chi \subset (-2\eta, 2\eta), \| \chi' \|_{\infty} \leq 2/\eta, \) and such that \( \gamma \geq 0, \) \( \int_{\mathbb{R}} \gamma(t) \, dt = 1, \) supp \( \gamma \subset (-1/4, 1/4). \) We now define the cutoff

\[
\Gamma(t, v) = \Gamma(t, v) := (\gamma \ast \chi(N(\cdot, v)))(t) = \int_{\mathbb{R}} \gamma(t-s) \chi(\| v \|_{E_{1}(J(t-s)2)}) \, ds
\]

(3.2)
for \( t \in \mathbb{R} \) and \( v \in E_1^{\text{loc}}(\mathbb{R}) \). Observe that the integrand is continuous in \( s \) and that \( F(t, v) \) depends on the restriction of \( v \) to \((t - 7/4, t + 7/4)\). For functions \( v \in E_1^{\text{loc}}(J) \), we define \( F(t, v) \) as in (3.2) for \( t \in [\frac{7}{4} + \inf J, -\frac{7}{4} + \sup J] \), where \( J \) is a closed interval of length greater than 7/2.

In order to treat \( v \in E_1^{\text{loc}}(\mathbb{R}_+) \) or \( w \in E_1^{\text{loc}}(\mathbb{R}_-) \), we further fix the extension operators \( R_\pm : E_1^{\text{loc}}(\mathbb{R}_\pm) \to E_1^{\text{loc}}(\mathbb{R}) \) given by

\[
(R_+ v)(t) = \begin{cases} v(t), & t \geq 0, \\ (1 + t)v(-t), & t \leq -1, \end{cases} \quad (R_- w)(t) = \begin{cases} w(t), & t \leq 0, \\ (1 - t)w(-t), & t \in [0, 1], \\ 0, & t \geq 1. \end{cases}
\]

Occasionally, we use the notation \( v_R := R_\pm v \) in both cases. We need the elementary estimates

\[
\|R_+ v\|_{E_1((1, 1])} \leq c_R \|v\|_{E_1([0, 1])}, \quad \|R_- v\|_{E_1([1, 1])} \leq c_R \|v\|_{E_1([-1, 0])}, \quad \|v\|_{E_1([0, T])} \leq c_E \|v\|_{E_1([R_+ - \alpha])}, \quad \|v\|_{E_1([0, 0])} \leq c_E \|v\|_{E_1([R_+ \alpha])}
\]

for constants \( c_R \) and \( c_E \) and for all \( T > 0 \) and \( \alpha \geq 0 \), where \( c_E \) depends on \( T \) and is uniform for \( \alpha \) in compact intervals. We then define the cutoffs

\[ f_{\pm}(t, v) := F(t, R_\pm v) = (\gamma \ast \chi(N(v, v_0)))(t) \quad \text{(3.5)} \]

for \( t \in \mathbb{R} \) and \( v \in E_1^{\text{loc}}(\mathbb{R}_\pm) \).

Finally, for \( v \in E_1^{\text{loc}}(J) \) and \( J \in \{\mathbb{R}, \mathbb{R}_+, \mathbb{R}_-\} \), we define the Nemitskii operators \( G_f, J(v)(t) = F_{J}(t, v)G(v(t)) \) and \( H_f, J(v)(t) = F_{J}(t, v)H(v(t)), t \in J \), for the cutoffs of the nonlinear maps \( G \) and \( H \) defined in (2.17) and (2.18), where we assume that \( (R) \) holds and that \( u_\alpha \in X_1 \) satisfies \( B(u_\alpha) = 0 \). We also abbreviate \( G_f = G_f, \mathbb{R}_+ = G_f, \mathbb{R}_+ \), \( H_f = H_f, \mathbb{R}_+ \), and \( H_f, \mathbb{R}_- = H_f, \mathbb{R}_- \). If Hypothesis 2.1 holds, we consider the cutoff version of the initial-boundary value problem (2.21) given by

\[
\partial_t v(t) + A_v v(t) = G_f, J(v)(t) \quad \text{on} \ \Omega, \quad \text{a.e.} \ t \in J, \\
B_v v(t) = H_f, J(v)(t) \quad \text{on} \ \partial \Omega, \quad t \in J, \\
v(0) = v_0, \quad \text{on} \ \Omega,
\]

where \( J \in \{\mathbb{R}, \mathbb{R}_+, \mathbb{R}_-\} \). We stress that the cutoff problem (3.7) is not local in time. In particular, even for \( J = \mathbb{R}_+ \) it is not a well-posed Cauchy problem. In fact, we will only solve (3.7) globally in function spaces on \( J \). By definition, a function \( v \in E_1^{\text{loc}}(J) \) solves (3.7) if and only if \( v = S(v_0, g, h) \) is a fixed point of the solution operator \( S = S_{\delta} \) of the linear problem (2.22) with \( g = G_f, J(v) \) and \( h = H_f, J(v) \). Hence, the compatibility condition \( B_{v0} h(0) = H_f, J(v)(0) \) must hold.

We now collect several properties of cutoffs (3.2) and (3.5) for \( J \in \{\mathbb{R}, \mathbb{R}_+, \mathbb{R}_-\} \). The first remark implies that a solution \( v \in E_1^{\text{loc}}(J) \) of (3.7) in fact satisfies (2.21) on \( [a, b] \subset J \) if \( \|v\|_{E_1(J(t - 2, t + 2) \cap J)} \) is sufficiently small for each \( t \in [a, b] \).

**Remark 3.1.** If \( v \in E_1^{\text{loc}}(J) \) satisfies \( \|v\|_{E_1(J(t-2, t+2))} \leq \eta \) for some \( t \in J \) (where \( |t| \geq 2 \) if \( J = \mathbb{R}_\pm \)), then \( F(t, v) = 1 \). This fact follows from the properties of \( \gamma \) and \( \chi \) in (3.2). If \( J = \mathbb{R}_\pm \) and \( t \in J \cap [-2, 2] \), then \( \|v\|_{E_1(J(t-2, t+2) \cap J)} \leq (1 + c_R)^{-1} \eta \) implies \( F_{\pm}(t, v) = 1 \). Indeed, for \( J = \mathbb{R}_0 + t \), \( t \in [0, 2] \), and \( s \in [t - \frac{1}{4}, t + \frac{1}{4}] \) we have

\[
\|R_+ v\|_{E_1(J(s))} \leq \|R_+ v\|_{E_1(J(s) \cap \mathbb{R}_+)} + \|R_+ v\|_{E_1(J(s) \cap \mathbb{R}_-)} \leq \|v\|_{E_1(J(s) \cap \mathbb{R}_+)} + c_R \|v\|_{E_1(J(s) \cap [0, 1])} \leq (1 + c_R) \|v\|_{E_1(J(s) \cap \mathbb{R}_+)} \leq \eta.
\]
due to (3.3) and the fact that $[0, 1] \subset J(s)$ if $J(s) \cap \mathbb{R}_- \neq \emptyset$. The case $J = \mathbb{R}_-$ can be treated in the same way. 

**Remark 3.2.** For $v \in \mathbb{E}_{1}^{\text{loc}}(\mathbb{R})$ and $J = \mathbb{R}$ the cutoff is time invariant. Indeed,

$$f(t, t_0, v) = \int_{t_0}^{t} \gamma(t) \chi(\|v\|_{\mathbb{E}_1([s+t_0-3/2, s+t_0+3/2])}) \, ds = f(t, v(-t_0))$$

for $t, t_0 \in \mathbb{R}$. As a result, if $v$ solves the cutoff problem (3.7) on $J = \mathbb{R}$ with $v(0) = v_0$, then $w = v(-t_0)$ solves the cutoff problem on $\mathbb{R}$ with $w(0) = v(t_0)$. In contrast to the case $J = \mathbb{R}_+$, for $J = \mathbb{R}_-$ the problem (3.7) is not translation invariant. 

**Remark 3.3.** Let us suppose that $f(t_0, v) \neq 0$ for some $v \in \mathbb{E}_{1}^{\text{loc}}(\mathbb{R})$, $t_0 \in J_n$, and $n \in \mathbb{N}$. Then there exists a $t \in J_n$ such that $\chi(N(t, v)) \neq 0$, and hence $\|v\|_{\mathbb{E}_1(J_n)} \leq 2\eta$. As a result, $\|v\|_{\mathbb{E}_1(J_n)} \leq 2\eta$ since $J_n \subset J(t)$ for each $t \in J_n$.

Similarly, if $f(t_0, v) \neq 0$ for some $t_0 \in J_n$, then $\|v\|_{\mathbb{E}_1(J_n)} \leq 2\eta$.

**Remark 3.4.** Assume that $v, u \in \mathbb{E}_{1}^{\text{loc}}(J)$ and $t, s \in J$. Temporarily, we set $v = v_R$ if $J = \mathbb{R}$. Then (3.2) and (3.3) imply the Lipschitz estimates

$$|f(t, v) - f(t, u)| \leq \sup_{|t-s| \leq 1/4} |\chi(\|v\|_{\mathbb{E}_1(J(s))}) - \chi(\|u\|_{\mathbb{E}_1(J(s))})|$$

$$
\leq 2\eta^{-1} \|v - u\|_{\mathbb{E}_1([t-7/4, t+7/4])} \leq \eta^{-1} \|v - u\|_{\mathbb{E}_1([t-7/4, t+7/4])}.
$$

**Remark 3.5.** Let $v \in \mathbb{E}_{1}^{\text{loc}}(\mathbb{R}_+)$, resp. $v \in \mathbb{E}_{1}^{\text{loc}}(\mathbb{R}_-)$. Then $f_\pm(t, v) = f(t, v)$ for $t \geq 7/4$ and $f_\mp(t, v) = f(t, v)$ for $t \leq -7/4$, respectively. Moreover, (3.8) holds for $t + t_0 \geq 7/4$, resp. $t + t_0 \leq -7/4$, and $t, t_0 \in \mathbb{R}$. (Here $v(-t_0)$ is defined on $[t_0, \infty)$, resp. on $(-\infty, -t_0]$.)

We now consider the maps $G_{f, J}$ and $H_{f, J}$, see (3.6), on the spaces $\mathbb{E}_1(\mathbb{R}_+, \mp \alpha)$ and $\mathbb{E}_1(\alpha, -\beta)$, where $\alpha, \beta > 0$ (these values of $\alpha, \beta$ were not treated in Proposition 2.2). We start with a preliminary result concerning the Lipschitz properties.

**Proposition 3.6.** Assume that (R) holds and $u_\ast \in X_1$ satisfies $B(u_\ast) = 0$. Take $\eta \in (0, d]$ and $\alpha, \beta \in [0, d]$ for some $d > 0$. Then the maps $G_{f, J} : \mathbb{E}_1(\mathbb{R}_+, \mp \alpha) \to \mathbb{E}_1(\mathbb{R}_+, \mp \alpha)$, $G_{f, J} : \mathbb{E}_1(\alpha, -\beta) \to \mathbb{E}_1(\alpha, -\beta)$, $H_{f, J} : \mathbb{E}_1(\mathbb{R}_+, \mp \alpha) \to \mathbb{F}(\mathbb{R}_+, \mp \alpha)$, and $H_{f, J} : \mathbb{E}_1(\alpha, -\beta) \to \mathbb{F}(\alpha, -\beta)$ are Lipschitz with the Lipschitz constant $\varepsilon(\eta)$ for a nondecreasing function $\varepsilon$ converging to 0 as $\eta \to 0$ which does not depend on $\alpha$ or $\beta$. Moreover, $G_{f, J}(0) = 0$ and $H_{f, J}(0) = 0$ for $J \in \{\mathbb{R}_+, \mathbb{R}_-\}$. 

**Proof.** We show the result only for the interval $J = \mathbb{R}_+$. The case $J = \mathbb{R}_-$ then follows by reflection, whereas the case $J = \mathbb{R}$ can be treated in a similar way as $J = \mathbb{R}_+$. In this proof we write $f$ instead of $f_+$ and $v$ instead of $R_+ v$ etc. We take $\alpha, \beta \in (0, d]$ and $u, v \in \mathbb{E}_1(\mathbb{R}_+, -\alpha)$. In this proof $\varepsilon$ and $c$ do not depend on $\alpha, u, v$, and $c$ does not depend on $\eta$.

(a) We first address the Lipschitz property of the $G_{f, J}$. We consider an interval $J_n$, $n \in \mathbb{N}_0$, and estimate $G_{f, J}(v) - G_{f, J}(u)$ on this interval. We may assume that $f(t_0, v) \neq 0$ for some $t_0 \in J_n$, thus

$$\|v\|_{\mathbb{E}_1(J_n)} \leq \|v\|_{\mathbb{E}_1(J_n)} \leq 2\eta$$
by Remark 3.3. For $t \in J_n$, one obtains
\[
\|G_F(v)(t) - G_F(u)(t)\|_0 \leq |F(t, v) - F(t, u)| \cdot |G(v(t))|_0 \\
+ |F(t, u)| \cdot |G(v(t)) - G(u(t))|_0.
\]
In the second term in the right-hand side of the last inequality we may assume that $F(t_0, u) \neq 0$ for some $t_0 \in J_n$ since otherwise this term is equal to zero on $J_n$. Remark 3.3 then shows that $\|u\|_{\mathbb{H}_1(J_n)} \leq \|u\|_{\mathbb{E}_1(J_n)} \leq 2\eta$. Estimate (3.9) in Remark 3.4 and Proposition 2.2 thus imply
\[
\int_{J_n} |G_F(v)(t) - G_F(u)(t)|^p e^{-\alpha pt} dt \\
\leq c\eta^p e^{-\alpha np} \|v - u\|_{\mathbb{E}_1(J_n)}^p e^{-\alpha np} \int_{J_n} |G(v(t))|^p dt + e^{-\alpha np} \int_{J_n} |G(v(t)) - G(u(t))|^p dt \\
\leq c\eta^p \|v - u\|_{\mathbb{L}^p(J_n)} e(\eta)^p e(\eta)^p \\
+ e^{-\alpha np} \sup_{\|v\|_{\mathbb{E}_1(J_n)} \leq 2\eta} \|G'(w)\|_{\mathbb{L}^p(J_n)} \|v - u\|_{\mathbb{E}_1(J_n)}^p \\
\leq c(\eta)^p \|v - u\|_{\mathbb{E}_1(J_n)}^p,
\]
where $c$ and $\epsilon$ do not depend on $n$. Now the Lipschitz estimate for $G_F$ easily follows, using also (3.3) and (3.4).

(b) We establish the Lipschitz property of $\mathbb{H}_F$. We deduce the inequality
\[
\|e_{-\alpha}(\mathbb{H}_F(v) - \mathbb{H}_F(u))\|_{\mathbb{L}^p(\mathbb{R}_+; Y_0)} \leq c\epsilon(\eta) \|v - u\|_{\mathbb{E}_1(\mathbb{R}_+; -\alpha)}
\]
similarly to the proof given in part (a). In order to estimate $e_{-\alpha}(\mathbb{H}_F(v) - \mathbb{H}_F(u))$ in $W^s(\mathbb{R}_+; Y_0)$, we fix a number $j \in \{1, \cdots, m\}$, and write $H$, $F$ and $\kappa$ instead of $H_j$, $F_j$ and $\kappa_j$. Let $t \in J_n$, $n \in \mathbb{N}_0$, and $|t - s| \leq 1/8$. Again, we may assume that $F(t_0, v) \neq 0$ for some $t_0 \in J_n$, so that (3.11) holds by Remark 3.3. Note that $s \in J_n^* \subset J_n'$. We further split:
\[
\Delta(t, s) := H_F(v)(t) - H_F(u)(s) - (H_F(u)(t) - H_F(u)(s)) \\
= [F(t, v) - F(s, v) - (F(t, u) - F(s, u))] H(v(t)) \\
+ [F(t, u) - F(s, u)] (H(v(t)) - H(v(s))) \\
+ [F(t, u) - F(s, u)] (H(v(s)) - H(u(s))) \\
=: S_1 + S_2 + S_3 + S_4.
\]
In the expression $S_1$ the term in square brackets satisfies the estimate
\[
\left| \int_{\mathbb{R}} (\gamma(t - \tau) - \gamma(s - \tau)) (\chi(N(\tau, v)) - \chi(N(\tau, u))) d\tau \right| \\
\leq c\eta^{|t - s|} \sup_{|\gamma(s - \tau) - \gamma(t - \tau)| \leq 1/4} |N(\tau, v) - N(\tau, u)| \\
\leq c\eta^{|t - s|} \sup_{|\gamma(s - \tau)| \leq 1/4} \|v - u\|_{\mathbb{E}_1(J_n)} \leq c\eta^{|t - s|} \|v - u\|_{\mathbb{E}_1(J_n')},
\]
By means of (2.13), (3.11), and Proposition 2.2, we estimate:
\[
\sup_{t_0 \in J_n} |H(v(t))| \leq c \|H(v)\|_{\mathbb{E}(J_n)} \leq c\epsilon(\eta) \|v\|_{\mathbb{E}_1(J_n)} \leq c\epsilon(\eta) \eta.
\]
As a result,
\[
|S_1| \leq c\epsilon(\eta) |t - s| \|v - u\|_{\mathbb{E}_1(J_n')},
\]

and thus
\[
\left( \int_{[t-s] \leq 1/8} \int_{t \in J_n} e^{-\alpha tp} \frac{|S_1|^p}{|t-s|^{1+\kappa p}} dt ds \right)^{\frac{1}{p}} \leq c \varepsilon(\eta) e^{-\alpha n} \| v - u \|_{E_1(J_n')}
\]
\[
\leq c \varepsilon(\eta) \| e_{-\alpha}(v - u) \|_{E_1(J_n')}.
\]

Next, we treat $S_2$. We may assume that $f(t_0, u) \neq 0$ for some $t_0 \in J_n$ (otherwise $S_2 = 0$). Hence, $\| u \|_{E_1(J_n')} \leq 2\eta$ by Remark 3.3. Using also (3.11) and Proposition 2.2, we derive
\[
\left( \int_{[t-s] \leq 1/8} \int_{t \in J_n} e^{-\alpha tp} \frac{|S_2|^p}{|t-s|^{1+\kappa p}} dt ds \right)^{\frac{1}{p}} \leq c \varepsilon(\eta) e^{-\alpha n} \| \mathbb{H}(v) - \mathbb{H}(u) \|_{W^p_p(J_n', Y_0)}
\]
\[
\leq c \varepsilon(\eta) \sup_{\| w \|_{E_1(J_n')} \leq 2\eta} \| \mathbb{H}'(w) \|_{E_1(J_n')} \| v - u \|_{E_1(J_n')}
\]
\[
\leq c \varepsilon(\eta) \| e_{-\alpha}(v - u) \|_{E_1(J_n')}.
\]

Dealing with $S_3$, we note that Remark 3.4 further yields:
\[
|S_3|_{Y_0} \leq c \eta^{-1} \| v - u \|_{E_1(J_n')} \| H(v(t)) - H(v(s)) \|_0.
\]

Therefore, we obtain
\[
\left( \int_{[t-s] \leq 1/8} \int_{t \in J_n} e^{-\alpha tp} \frac{|S_3|^p}{|t-s|^{1+\kappa p}} dt ds \right)^{\frac{1}{p}} \leq c \varepsilon(\eta) \eta^{-1} \| v - u \|_{E_1(J_n')} \| \mathbb{H}(v) \|_{W^p_p(J_n', Y_0)}
\]
\[
\leq c \varepsilon(\eta) \| e_{-\alpha}(v - u) \|_{E_1(J_n')} \| v \|_{E_1(J_n')} \leq c \varepsilon(\eta) \varepsilon(\eta) \| e_{-\alpha}(v - u) \|_{E_1(J_n')}
\]
due to (3.11) and Proposition 2.2. Finally, we estimate the expression $S_4$. We may assume that $f(t_0, u) \neq 0$ for some $t_0 \in J_n$ (otherwise $S_4 = 0$). Then $\| u \|_{E_1(J_n')} \leq 2\eta$ due to Remark 3.3. So (3.10), (2.13), (3.11), and Proposition 2.2 lead to
\[
\left( \int_{[t-s] \leq 1/8} \int_{t \in J_n} e^{-\alpha tp} \frac{|S_4|^p}{|t-s|^{1+\kappa p}} dt ds \right)^{\frac{1}{p}} \leq c \varepsilon(\eta) \sup_{s \in J_n} \| H(v(s)) - H(u(s)) \|_{Y_0}
\]
\[
\leq c \varepsilon(\eta) \| \mathbb{H}(v) - \mathbb{H}(u) \|_{E_1(J_n')}
\]
\[
\leq c \varepsilon(\eta) \sup_{\| w \|_{E_1(J_n')} \leq 2\eta} \| \mathbb{H}'(w) \|_{E_1(J_n')} \| v - u \|_{E_1(J_n')}
\]
\[
\leq c \varepsilon(\eta) \| e_{-\alpha}(v - u) \|_{E_1(J_n')}.
\]

Summing up, we arrive at the inequality
\[
\left( \int_{[t-s] \leq 1/8} \int_{t \in J_n} e^{-\alpha tp} \frac{\Delta(t, s)|v|^p}{|t-s|^{1+\kappa p}} dt ds \right)^{\frac{1}{p}} \leq c \varepsilon(\eta) \| e_{-\alpha}(v - u) \|_{E_1(J_n')}.
\]

Therefore, a variant of Lemma 11 of [12] and estimates (3.12), (3.3) and (3.4) imply:
\[
[e_{-\alpha}(\mathbb{H}_r(v) - \mathbb{H}_r(u))]_{W^p_p(\mathbb{R}^+; Y_0)}
\]
The Lipschitz property of Remark 3.7.

\[ \|b > a \|_{\mathbb{R}_+} \]

\[ \langle \chi, N'(t, u) \rangle = \| v \|_{\mathbb{R}_+} \sum_{|\alpha|=m, \beta, \gamma} \int_{\Omega} (\partial^\alpha u \partial^\beta \gamma) |\partial^\alpha u|^p dx ds \]

where \( \epsilon \) is a nondecreasing function with \( \epsilon(r) \rightarrow 0 \) as \( r \rightarrow 0 \) and \( \epsilon \) does not depend on \( v, w, J, \delta \). Indeed, to show this fact, one extends \( \epsilon \) to \( \epsilon_1, J, \delta \) such that \( \| \epsilon_1(\epsilon_1, J, \delta) \|_{\mathbb{R}_+} \leq c \| \epsilon_1 \|_{\mathbb{R}_+} \) and \( \| \epsilon_1(\epsilon_1, J, \delta) \|_{\mathbb{R}_+} \leq cr^2 \) for all \( \| s, s+2 \| \subset J \), where the constant \( c \) does not depend on \( J, \epsilon, \delta, \epsilon \). As in the proof of Proposition 3.6 one now treats the intervals \( J_n \) separately using Proposition 2.2.

Next, we want to establish the continuous differentiability of \( \gamma \) and \( \mathbb{H}_r \) in certain spaces. We start with the differentiability of \( F \). First we observe that for a measure space \( (M, \mu) \), the map \( q(u) = \int_M |u|^p d\mu \) belongs to \( C^1(L_p(M, d\mu)) \), and that its derivative at \( u \in L_p(M, d\mu) \) is given by

\[ \langle v, q'(u) \rangle = \int_M p \Re(w \chi)|u|^{p-2} d\mu. \]

This fact implies that for \( t \in \mathbb{R} \) the map \( u \mapsto N(t, u) = \| u \|_{\mathbb{R}_+} \), see (3.1), is continuously differentiable on \( \mathbb{R}_+(J(t)) \setminus \{0\} \), and its derivative \( N'(t, u) \in \mathbb{R}_+(J(t))^* \) is given by

\[ \langle v, N'(t, u) \rangle = \| u \|_{\mathbb{R}_+(J(t))}^{1-p} \int_{\Omega} \Re(w \chi)|u|^{p-2} dx ds + \int_{\Omega} \Re(w \chi)|u|^{p-2} dx ds \]

where \( \langle v, N'(t, u) \rangle \in \mathbb{R}_+(J(t))^* \) and \( \| v \|_{\mathbb{R}_+} \leq c \) for a constant depending only on \( m \). Take \( u \in \mathbb{R}_+(t-2, t+2) \) and \( |t-s| \leq 1/4 \), where \( u \neq 0 \) and \( \| u \|_{\mathbb{R}_+} < \| u \|_{\mathbb{R}_+} \). Denoting the restrictions of \( u \) and \( v \) to \( J(s) \subset [t-2, t+2] \) by the same symbols, we further deduce

\[ \langle N(s, u+v) - N(s, u) - \langle N'(s, u), v \rangle \rangle = \int_0^1 \langle N'(s, u+\theta v) - N'(s, u), v \rangle \, d\theta \]

Here \( c \) and \( \epsilon \) do not depend on \( t \) and \( s \) since \( N(\tau, u) = N(0, u(\cdot + \tau)) \). As a result, the map \( \mathbb{E}_1([t-2, t+2]) \ni u \mapsto F(t, u) \) is \( C^1 \) with the derivative \( F'(t, u) = [\gamma \star \chi(N(\cdot, u))N'(\cdot, u)](t) \), and the maps

\[ \Gamma_0 : u \mapsto \chi(N(\cdot, u)) \quad \text{and} \quad \Gamma_1 : u \mapsto F(\cdot, u) \quad \text{belong to} \quad C^1(\mathcal{E}_1(J''; C(J)) \quad (3.14) \]

where \( J = [a, b] \) and \( J'' = [a-2, b+2] \). (Here we set \( N'(0, 0) = 0 \) and note that \( F(t, u) = 1 \) and thus \( F'(t, u) = 0 \) provided \( \| u \|_{\mathbb{R}_+(t-2, t+2)} < \eta \). We further have

\[ \langle (F'(t, u), v) \rangle \leq c^{-1} \| v \|_{\mathbb{R}_+(t-2, t+2)}, \]

\[ \text{(3.15)} \]
\(|(F'(t, u) - F'(s, u), v)| \leq c|t - s| \|v\| \mathbb{E}_t(s, t - 2, t + 2)\)  \hfill (3.16)

for \(u, v \in \mathbb{E}_t(s, t + 2)\), for \(t \in \mathbb{R}\), \(|t - s| \leq 1/4\), and constants \(c\) independent of \(t, s, u, v, \eta\). Observe that the cutoffs \(F_\pm(t, v) = F(t, R_\pm v)\) on \(R_\pm\) have the analogous differentiability properties.

Given \(\alpha, \beta \geq 0\) and \(u \in \mathbb{E}_1(\alpha, -\beta)\), we introduce the linear operators \(G_f^\alpha\) and \(\mathbb{H}^\alpha_f\) acting on \(u \in \mathbb{E}_1(\alpha, -\beta)\) by the formulas

\[
[G_f^\alpha(u)v](t) = \langle v, F'(t, u) \rangle G(0) + F(t, u)G'(u)(v)(t),
\]

\[
[\mathbb{H}^\alpha_f(u)v](t) = \langle v, F'(t, u) \rangle H(0) + F(t, u)H'(u)(v)(t).
\]

Here \(G\) and \(H\) were defined in (2.17) and (2.18), and the brackets denote the scalar product in \(\mathbb{E}_1(J(t))\) applied to the restriction of \(v\) to the interval \(J(t)\). We also set

\[
[G_f^\alpha(u)v](t) = [G_f^\alpha(R_\pm u)R_\pm v](t),
\]

\[
[\mathbb{H}^\alpha_f(u)v](t) = [\mathbb{H}^\alpha_f(R_\pm u)R_\pm v](t)
\]

for \(t \in \mathbb{R}_\pm\) and \(u, v \in \mathbb{E}_1(R_+, -\alpha)\) in the case \(J = R_+\), respectively, \(u, v \in \mathbb{E}_1(R_-, \alpha)\) in the case \(J = R_-\).

The maps \(G_f^\alpha\) and \(\mathbb{H}^\alpha_f\) are not differentiable if the range space has the same weight function. But, as we will see in the next proposition, they become \(C^1\) maps with the derivatives \(G_f^\alpha\) and \(G_f^\alpha\) given in (3.17), (3.18) if we take a smaller weight function in the range space, cf. [21].

**Proposition 3.8.** Assume that \((R)\) holds and that \(u_x \in X_1\) satisfies \(B(u_x) = 0\). Let \(\eta \in (0, d]\), \(0 \leq \alpha \leq \beta \leq d\), and \(0 \leq \alpha' \leq \beta' \leq d\) for some \(d > 0\). Define the operators \(G_f^\alpha, G_f^\alpha, \mathbb{H}^\alpha_f,\) and \(\mathbb{H}^\alpha_f\) by (3.17), (3.18) and (3.19), respectively, where \(\eta\) is the parameter for the cutoff \(f\). Then the following assertions hold.

(a) The operators \(G_f^\alpha : \mathbb{E}_1(\alpha, -\alpha') \to \mathbb{E}_0(\beta, -\beta')\), \(\mathbb{H}^\alpha_f : \mathbb{E}_1(\alpha, -\alpha') \to \mathbb{E}_0(\beta, -\beta')\), \(G_f^\alpha : \mathbb{E}_1(\beta, -\beta') \to \mathbb{E}_0(\alpha, -\alpha')\), \(\mathbb{H}^\alpha_f : \mathbb{E}_1(\beta, -\beta') \to \mathbb{E}_0(\alpha, -\alpha')\) are all bounded by the norms \(\varepsilon(\eta)\), where \(\varepsilon\) is a nondecreasing function converging to \(0\) as \(\eta \to 0\) which does not depend on \(u, \alpha, \alpha', \beta, \beta'\).

(b) If \(\beta > \alpha\) and \(\beta' > \alpha'\), then the maps \(G_f^\alpha : \mathbb{E}_1(\alpha, -\alpha') \to \mathbb{E}_0(\beta, -\beta')\), \(\mathbb{H}^\alpha_f : \mathbb{E}_1(\alpha, -\alpha') \to \mathbb{E}_0(\beta, -\beta')\), \(G_f^\alpha : \mathbb{E}_1(\beta, -\beta') \to \mathbb{E}_0(\alpha, -\alpha')\), \(\mathbb{H}^\alpha_f : \mathbb{E}_1(\beta, -\beta') \to \mathbb{E}_0(\alpha, -\alpha')\) are continuously differentiable and the operators \(G_f^\alpha, G_f^\alpha, \mathbb{H}^\alpha_f, \) and \(\mathbb{H}^\alpha_f\) are their derivatives. Moreover, \(G_f^\alpha|J(0) = 0\) and \(\mathbb{H}^\alpha_f|J(0) = 0\) for \(J \in \{R_+, R_-\}\).

**Proof.** As in the proof of Proposition 3.6 we restrict ourselves to the case \(J = R_+\), and we write \(f\) instead of \(R_+ v\) and \(v\) instead of \(R_+ v\).

(a) **Norm estimates for \(G_f^\alpha\) and \(\mathbb{H}^\alpha_f\).** Since the spaces with the exponential weights form a scale, it is enough to give a proof for a := \(\beta = \alpha \in (0, d]\). Let \(t \in J_n\) for some \(n \in \mathbb{N}\) and \(\eta \in (0, d]\). If \(f(t_0, u) = 0\) and \(f'(t_0, u) = 0\) for all \(t_0 \in J_n\), then \(G_f^\alpha(u)v = 0\) on \(J_n\). Otherwise, we have \(\|u\|_{\mathbb{E}_1(J_n)} \leq 2\eta\), cf. Remark 3.3. So Proposition 2.2, (3.15) and (3.3) yield

\[
\|G_f^\alpha(u)v\|_{\mathbb{E}_0(J_n)} \leq \varepsilon(\eta) \|u\|_{\mathbb{E}_1(J_n)} \|v\|_{\mathbb{E}_1(J_n)},
\]

\[
\|G_f^\alpha(u)v\|^p_{\mathbb{E}_0(R_+, -\alpha)} \leq \sum_{n=0}^{\infty} e^{-\alpha np} \|G_f^\alpha(u)v\|^p_{\mathbb{E}_0(J_n)} \leq \varepsilon(\eta)^p \sum_{n=0}^{\infty} e^{-\alpha np} \|v\|^p_{\mathbb{E}_1(J_n)},
\]

\[
\leq \varepsilon(\eta)^p \|v\|^p_{\mathbb{E}_1(R_+, -\alpha)}.
\]

(3.20)

proving assertion (a) for \(G_f^\alpha\). Here and below in the proof of assertion (a) all constants are uniform for \(u, v, a, \text{and} \eta\), but may depend on \(d\). Starting the proof
for $\mathbb{H}'$, as in (3.20), one obtains that

$$\|e^{-a\mathbb{H}}(u)v\|_{L^p_{\mu}(\mathbb{R}^+,\mathbb{Y}_1)} \leq c\varepsilon(\eta)\|v\|_{\mathbb{E}_1(\mathbb{R}^+,-\alpha)}.$$ 

Further, let $|t-s| \leq 1/8$ and $t \in J_n$. We fix $j \in \{1, \cdots, m\}$ and write $H$, $\mathcal{F}$ and $\kappa$ instead of $H_j$, $\mathcal{F}_j$ and $\kappa_j$. It holds

$$\Delta(t, s) := \mathbb{H}'(u)v(t) - \mathbb{H}'(u)v(s)$$

$$= \langle F'(t, u) - F'(s, u), v \rangle H(u(t)) + \langle F'(s, u), v \rangle [H(u(t)) - H(u(s))]$$

$$+ [F(t, u) - F(s, u)]H'(u(t))v(t) + F(s, u)H'(u(s))v(s)$$

$$=: S_1 + S_2 + S_3 + S_4.$$

As before we can assume that $\|u\|_{\mathbb{E}_1(J_n)} \leq 2\eta$, cf. Remark 3.3. By means of (3.16), (3.15), (3.10), (2.13) and Proposition 2.2, we estimate

$$|S_1|_{\mathbb{Y}_0} \leq c\eta^{-1}|t-s| \|v\|_{\mathbb{E}_1(J_n')}\|H(u)\|_{C(J_n,\mathbb{Y}_0)} \leq c\varepsilon(\eta)|t-s| \|v\|_{\mathbb{E}_1(J_n')}$$

$$|S_2|_{\mathbb{Y}_0} \leq c\eta^{-1} \|v\|_{\mathbb{E}_1(J_n')} \|H(u(t)) - H(u(s))\|_{\mathbb{Y}_0},$$

$$|S_3|_{\mathbb{Y}_0} \leq c|t-s| \|\mathbb{H}'(u)v\|_{C(J_n,\mathbb{Y}_0)} \leq c|t-s| \|\mathbb{H}'(u)v\|_{\mathbb{Y}_0} \leq c\varepsilon(\eta)|t-s| \|v\|_{\mathbb{E}_1(J_n)},$$

$$|S_4|_{\mathbb{Y}_0} \leq c\|H'(u(t))v(t) - H'(u(s))v(s)\|_{\mathbb{Y}_0}.$$

Using Proposition 2.2 once, these inequalities lead to

$$\left(\int_{J_n} \int_{|t-s| \leq 1/8} e^{-at_0} \mathbb{E}_{\mathbb{E}_1(J_n')} \right)^{1/p} \leq c\varepsilon(\eta) \|v\|_{\mathbb{E}_1(J_n')} + c\eta^{-1} \|v\|_{\mathbb{E}_1(J_n')} \|H(u)\|_{C(J_n,\mathbb{Y}_0)} + c\|\mathbb{H}'(u)v\|_{\mathbb{Y}_0}$$

$$\leq c\varepsilon(\eta)\|v\|_{\mathbb{E}_1(J_n')}.$$

A slight variation of Lemma 11 from [12] and (3.3) now imply that

$$[e^{-a\mathbb{H}'}(u)v]_{\mathbb{E}^p_0(\mathbb{R}^+,-\alpha)} \leq c\varepsilon(\eta) \|v\|_{\mathbb{E}_1(\mathbb{R}^+,-\alpha)},$$

concluding the proof of assertion (a) in Proposition 3.8.

(b) We now assume that $\beta > \alpha$. We fix $u \in \mathbb{E}_1(\mathbb{R}^+,-\alpha)$ and $\eta > 0$. The constants below do not depend on $v \in \mathbb{E}_1(\mathbb{R}^+,-\alpha)$, but possibly on $u$, $\eta$, or $\beta - \alpha$.

(1) Differentiability of $\mathbb{G}_t$ : $\mathbb{E}_1(\mathbb{R}^+,-\alpha) \to \mathbb{E}_0(\mathbb{R}^+,-\beta)$. We have to estimate

$$\Delta_t G(t) = F(t, u + v)G(u(t) + v(t)) - F(t, u)G(u(t))$$

$$- (F''(t, u), v)G(u(t)) - (F'(t, u), v)G'(u(t))v(t)$$

for $t \geq 0$ and $v \in \mathbb{E}_1(\mathbb{R}^+,-\alpha)$. We first consider $t \geq n_0 \geq 2$ for some $n_0 \in \mathbb{N}$ to be fixed below. Proposition 3.6 then yields

$$\|e^{-\beta \Delta_t G}\|_{\mathbb{E}_0([n_0,\infty))} \leq c^{(\beta - \alpha)n_0} \|e^{-\alpha \beta} \|_{\mathbb{E}_1(\mathbb{R}^+,-\alpha)} + \|e^{-\alpha (\mathbb{F}'(t, u), v)G'(u(t))v(t)}\|_{\mathbb{E}_0([n_0,\infty))}$$

$$\leq c^{(\beta - \alpha)n_0} \varepsilon(\eta) \|v\|_{\mathbb{E}_1(\mathbb{R}^+,-\alpha)} + \|S_1 + S_2\|_{\mathbb{E}_0([n_0,\infty))},$$

where we set $S_1 = e^{-\alpha (\mathbb{F}'(t, u), v)G(u(t))}$ and $S_2 = e^{-\alpha (\mathbb{F}'(t, u), v)G'(u(t))v(t)}$. Let $t \in J_n$ for some $n \geq n_0$. If $F(t_0, u) = 0$ and $F'(t_0, u) = 0$ for all $t_0 \in J_n$, then $S_1 = S_2 = 0$ on $J_n$. Otherwise, we have $\|u\|_{\mathbb{E}_1(J_n')} \leq 2\eta$, cf. Remark 3.3. So we deduce from (3.15) and Proposition 2.2 that

$$\|S_1 + S_2\|_{\mathbb{E}_0(J_n)} \leq c e^{-\alpha\varepsilon(\eta)} \|v\|_{\mathbb{E}_1(J_n')} \leq c \|e^{-\alpha v}\|_{\mathbb{E}_0(J_n')}.
As a result,
\[ \| e^{-\beta \Delta t} G \|_{E_0([t_0, \infty))} \leq c e^{(\alpha - \beta) n_0} \| v \|_{E_1(\mathbb{R}^+,-\alpha)}, \]
(3.21)
where \( c \) does not depend on \( n_0 \). Let \( \epsilon > 0 \) be given. Recalling that \( \beta > \alpha \), we fix \( n_0 = n_0(\epsilon) \geq 2 \) such that the right hand side of (3.21) is less than \( \epsilon \| v \|_{E_1(\mathbb{R}^+,-\alpha)} \).

Second, we treat the interval \([0, n_0] \) for the number \( n_0 \) just fixed. Using Proposition 2.2, (3.14), (3.9) and (3.3), we infer that
\[ \| e^{-\beta \Delta t} G \|_{E_0([0, n_0])} \leq \| G(u + v) - G(u) - G'(u) v \|_{E_0([0, n_0])} \]
\[ + \| (F(\cdot, u + v) - F(\cdot, u) - F'((\cdot, u), v)) G(u) \|_{E_0([0, n_0])} \]
\[ + \| F(\cdot, u + v) - F(\cdot, u) \|_{E_0([0, n_0])} \]
\[ \leq c \epsilon \left( \| v \|_{E_1([0, n_0 + 2])} \| v \|_{E_1([0, n_0 + 2])} \right) \]
\[ \leq c \epsilon \left( \| v \|_{E_1(\mathbb{R}^+,-\alpha)} \right) \| v \|_{E_1(\mathbb{R}^+,-\alpha)}, \]
(3.22)
where \( c \) and \( \epsilon \) may depend on \( n_0 \). Here and below we often use the boundedness of the restriction operator from \( E_1(\mathbb{R}^+, -\alpha) \) to \( E_1([0, b]) \), see (3.4). The asserted differentiability of \( G_F \) now follows from (3.21) and (3.22).

(2) Differentiability of \( H_F \) : \( E_1(\mathbb{R}^+, -\alpha) \) to \( E_1([0, b]) \). This time we set
\[ \Delta H(t) = F(t, u + v) H(u(t) + v(t)) - F(t, u) H(u(t)) \]
\[ - \langle F'(t, u), v \rangle H(u(t)) - F(t, u) H'(u(t)) v(t) \]
for \( t \geq 0 \) and \( v \in E_1(\mathbb{R}^+, -\alpha) \). As above in part (1), we obtain
\[ \| e^{-\beta \Delta t} H \|_{L_v(\mathbb{R}^+, \mathcal{Y}_1)} \leq c \| v \|_{E_1(\mathbb{R}^+, -\alpha)}, \]
(3.23)
for each given \( \epsilon > 0 \) and all \( v \) with \( \| v \|_{E_1(\mathbb{R}^+, -\alpha)} \leq r \). In the estimates for \( \| \cdot \|_{W^p_{\mathcal{F}_r}} \), cf. (2.12), we fix \( j \in \{1, \ldots, n\} \) and write \( H, \mathcal{F} \) and \( \kappa \) instead of \( H_j, \mathcal{F}_j \) and \( \kappa_j \).

(i) We first consider \( t \geq n_0 \) and \( |t-s| \leq 1/8 \) for some \( n_0 \in \mathbb{N} \) with \( n_0 \geq 2 \) to be fixed below, and split:
\[ \Delta H(t) - \Delta H(s) = [F(t, u + v) H(u(t) + v(t)) - F(s, u + v) H(u(s) + v(s)) - \langle F(t, u) H(u(t)) - F(s, u) H(u(s)) \| v \rangle] \]
\[ - \langle F'(t, u), v \rangle H(u(t)) - F(t, u) H'(u(t)) v(t) \]
\[ - \langle F'(t, u), v \rangle H(u(t)) - F(t, u) H'(u(t)) v(t) \]
\[ = : S_1 + S_2 + S_3. \]

The Lipschitz estimate in Proposition 3.6 shows that
\[ \left( \int_{t_0}^{t} \int_{|t-s| \leq 1/8} e^{-\beta \Delta t} \frac{|s|}{|t-s|^{1+\epsilon}} ds dt \right)^{1/2} \]
\[ \leq e^{(\alpha - \beta) n_0} e^{-\alpha n \left( \| F(t, u + v) - F(t, u) \|_{E_1(\mathbb{R}^+, -\alpha)} + e^{-\alpha n} [H'(u(t)) v(t) - H'(u(s)) v(s)] \right)} \]
\[ + e^{-\alpha n} [H'(u(t)) v(t) - H'(u(s)) v(s)] \]
\[ \leq e^{(\alpha - \beta) n_0} e^{-\alpha n} \left( \| v \|_{E_1(\mathbb{R}^+, -\alpha)} + e^{-\alpha n} [H'(u(t)) v(t) - H'(u(s)) v(s)] \right), \]
(3.24)
\[ \left( \int_{J_n} \int_{|t-s| \leq 1/8} e^{-\beta \Delta t} \frac{|s|}{|t-s|^{1+\epsilon}} ds dt \right)^{1/2} \]
\[ \leq e^{-(\beta + \alpha) n_0} e^{-\alpha n \left( \| F(t, u + v) - F(t, u) \|_{E_1(\mathbb{R}^+, -\alpha)} + e^{-\alpha n} [H'(u(t)) v(t) - H'(u(s)) v(s)] \right)} \]
\[ + e^{-\alpha n} [H'(u(t)) v(t) - H'(u(s)) v(s)] \]
\[ \leq e^{-(\beta + \alpha) n_0} e^{-\alpha n} \left( \| v \|_{E_1(\mathbb{R}^+, -\alpha)} + e^{-\alpha n} [H'(u(t)) v(t) - H'(u(s)) v(s)] \right), \]
(3.25)
Similarly, (3.10) yields
\[ |e^{-\beta t} S_3|_{Y_0} \leq c^{(\alpha-\beta)\alpha_0} e^{-\alpha n} \left( |(F'(t, u) - F'(s, u), v)| \|H(u(t))\|_{C(J_n, Y_0)} + |(F'(s, u), v)| \|H(u(t)) - H(u(s))\|_{Y_0} \right) \leq c^{(\alpha-\beta)\alpha_0} \|e_{-\alpha v}\|_{E_1(J_n^0)} (|t - s| + |H(u(t)) - H(u(s))|)_{Y_0}, \]
\[
\left( \int_{J_n} e^{-\beta t} |S_i|_{Y_0}^p \frac{d s dt}{|t - s|^{1+\kappa p}} \right)^\frac{1}{p} \leq c^{(\alpha-\beta)\alpha_0} \|v\|_{E_1(\mathbb{R}_+, \alpha)},
\]
(3.24)
where \( c \) does not depend on \( n_0 \) or \( v \). Since \( \beta > \alpha \), for a given \( \epsilon > 0 \) we can fix \( n_0 = n_0(\epsilon) \geq 2 \) such that \( c^{(\alpha-\beta)\alpha_0} \leq \epsilon \) in (3.24).

(ii) Second, we take \( t, s \in [0, n_0] \) and \( |t - s| \leq 1/4 \) for this \( n_0 \), and infer:
\[
|\Delta H(t) - \Delta H(s)|_{Y_0} \leq |H(u(t) + v(t)) - H(u(t)) - H'(u(t))v(t) - (H(u(s) + v(s)) - H(u(s)) - H'(u(s))v(s))|_{Y_0} + |(F'(t, u) - F'(s, u), v)| \|H(u(t)) - H(u(s))\|_{Y_0}
\]
\[
+ |(F'(t, u) - F'(s, u), v)| \|H(u(t)) - H(u(s))\|_{Y_0} + |(F(t, u + v) - F(s, u + v))| \|H(u(t)) - H(u(s))\|_{Y_0} + |(F(t, u + v) - F(s, u + v))| \|H(u(t)) - H(u(s))\|_{Y_0} \leq S_1 + \cdots + S_6.
\]
We set \( \Delta H = H(u + v) - H(u) - H'(u)v \). In the remainder of this proof, we use Proposition 2.2, (2.13) and (3.3) without further notice, and \( c \) and \( \epsilon \) may depend on \( n_0 \). In the following integrals it is always understood that \( s \geq 0 \). We first obtain:
\[
\left( \int_0^{n_0} \int_{|t - s| \leq 1/4} e^{-\beta t} \frac{|S_i|^p}{|t - s|^{1+\kappa p}} ds dt \right)^{\frac{1}{p}} \leq |\Delta H|_{W^p_p([0, n_0 + 1/4], Y_0)} \leq \epsilon \|v\|_{E_1([0, n_0 + 1/4])} \|v\|_{E_1(\mathbb{R}_+, \alpha)} \leq c \epsilon \|v\|_{E_1(\mathbb{R}_+, \alpha)} \|v\|_{E_1(\mathbb{R}_+, \alpha)}.
\]
Similarly, (3.10) yields
\[
\left( \int_0^{n_0} \int_{|t - s| \leq 1/4} e^{-\beta t} \frac{|S_2|^p}{|t - s|^{1+\kappa p}} ds dt \right)^{\frac{1}{p}} \leq \epsilon \|\Delta H\|_{C([0, n_0 + 1/4], Y_0)} \leq \epsilon \|v\|_{E_1(\mathbb{R}_+, \alpha)} \|v\|_{E_1(\mathbb{R}_+, \alpha)}.
\]
Next, from (3.14) we deduce
\[
|S_3| \leq c \|H(u)\|_{C([0, n_0], Y_0)} |t - s| \sup_{-1 \leq \tau \leq n_0 + 1} |\chi(N(\tau, u + v)) - \chi(N(\tau, u)) - \chi(N(\tau, u))(N', \tau, u, v)|.
\]
Putting together the estimates obtained in (i) and (ii), we conclude that for each
implies that

Using \([12, \text{Lem.11}]\) and (3.23), we obtain

In the same way the inequality

implies that

Definition (3.2) of the cutoff leads to the estimate

so that

The term \(S_0\) can be treated similarly. Therefore we have shown that

Putting together the estimates obtained in (i) and (ii), we conclude that for each
there exists a \(r'\) such that if \(\|v\|_{E_1(\mathbb{R}^+,-\alpha)} \leq r'\), then

Using \([12, \text{Lem.11}]\) and (3.23), we obtain

for \(\|v\|_{E_1(\mathbb{R}^+,-\alpha)} \leq r'_0\), finishing the proof of the differentiability of \(H_f\).

It remains to establish the continuity of the maps \(u \mapsto G_f'(u)\) and \(u \mapsto H_f'(u)\) in \(\mathcal{B}(E_1(\mathbb{R}^+,-\alpha), E_0(\mathbb{R}^+,-\beta))\) and \(\mathcal{B}(E_1(\mathbb{R}^+,-\alpha), F(\mathbb{R}^+,-\beta))\), respectively. This can be done by similar arguments as above. \(\square\)

4. Stable, unstable and center manifolds

We first construct and study the local stable manifold \(\mathcal{M}_s\), resp. the local unstable manifold \(\mathcal{M}_u\), assuming that \(\sigma(-A_0)\) has a spectral gap in the open left, resp. right, halfplane. These manifolds are of class \(C^1\) in \(X_p\), and are tangent at \(u_0\) and \(P_0 X_0\), respectively. These results are established in Theorem 4.1 which is actually a somewhat simpler variant of Theorem 17 in [12] where the hyperbolic case \(i \mathbb{R} \subset \rho(-A_0)\) has been addressed. Next, in our main Theorem 4.2, we consider the case of trichotomy, assuming that \(\sigma(-A_0)\) has spectral gaps in both open left and right halfplanes, cf. (2.34).

We choose the formulation of the spectral conditions for Theorem 4.1 in view of the situation in Theorem 4.2. We assume the existence of numbers \(\omega_s, \omega_u, \omega_{cu}, \omega_{cs} > 0\) such that at least one of the following assertions holds:

\[
\sigma(-A_0) = \sigma_s \cup \sigma_{cu} \quad \text{with} \quad \max \Re \sigma_s < -\omega_s < -\omega_{cu} < \min \Re \sigma_{cu},
\]
\[ \sigma(-A_0) = \sigma_{cs} \cup \sigma_u \quad \text{with} \quad \max \Re \sigma_{cs} < \omega_{cs} < \omega_u < \min \Re \sigma_u. \]

We denote by \( P_k \) the spectral projections for \(-A_0\) corresponding to \( \sigma_k, k \in \{s, cs, cu, u\}. \) As noted in Remark 2.4, we have \( P_u X_0 \subset P_{cu} X_0 \subset \text{dom}(A_0), \) and thus on \( P_{cu} X_0 \) the norms in \( X_0, \ X_p \) and \( X_1 \) are equivalent. Finally, we recall the notation \( X_p^0 = \{ z_0 \in X_p : B_s z_0 = 0 \} \) for the tangent space at \( u_* \) to the nonlinear phase space \( M = \{ u_0 \in X_p : B(u_0) = 0 \} \) for (1.1), and that \( P = I - N_p B_s \) projects \( X_p \) onto \( X_p^0, \) see the remarks before Theorem 14 in [12].

**Theorem 4.1.** Assume Hypothesis 2.1. Then there are numbers \( r \geq \rho > 0 \) and \( \rho_0 > 0 \) such that the following assertions hold.

(a) Let (4.1) hold and take any \( \alpha \in (\omega_{cs}, \omega_u) \). Then there are \( BC^1 \)-maps

\[ \phi_\ast : P_s X_p^0 \cap B_{X_p}(0, \rho_0) \to P_{cs} X_0 \quad \text{and} \quad \vartheta_\ast : P_s X_p^0 \cap B_{X_p}(0, \rho_0) \to P_{cs} X_0, \]

such that \( \phi_\ast (0) = \vartheta_\ast (0) = 0, \varphi_\ast (0) = \vartheta_\ast (0) = 0, \) and

\[ M_\ast := \left\{ u_0 = u_* + z_0 + \vartheta_\ast (z_0) + \varphi_\ast (z_0) \in B_{X_p}(u_*, \rho) : z_0 \in P_{cu} X_0^0 \cap B_{X_p}(0, \rho_0) \right\} = \left\{ u_0 \in M \cap B_{X_p}(u_*, \rho) : \exists \text{ solution u of (1.1) on } \mathbb{R}_+ \text{ with} \quad |u(t) - u_*|^p < r \quad \forall t \geq 0 \quad \text{and} \quad |u(t) - u_*|^1 \leq ce^{-\alpha t} \quad \forall t \geq 1 \right\}. \]

In (4.3) we can take \( c = \tau |u(0) - u_*|^p \) for a constant \( \tau \) independent of \( u_0, t, \alpha, \) and we have \( u = u_* + \Phi_\ast (P_s P_{U_0 - u_*}) \) for a map \( \Phi_\ast \in BC^1(P_s X_p^0 \cap B_{X_p}(0, \rho_0); E_1(\mathbb{R}_+, \alpha)). \)

If \( u_0 \in M_\ast \) and the forward solution \( u \) of (1.1) stays in \( B(u_*, \rho) \) on \( [0, t] \) for some \( t > 0, \) then \( u(t) \in M_\ast. \) If \( u_0 \in M_\ast \) and there is a backward solution \( u \) of (1.1) staying in \( B(u_*, \rho) \) on \( [t, 0] \) for some \( t < 0, \) then \( u(t) \in M_\ast. \)

(b) Let (4.2) hold and take any \( \beta \in (\omega_{cs}, \omega_u). \) Then there is a \( BC^1 \)-map

\[ \phi_\beta : P_u X_0 \cap B_{X_p}(0, \rho_0) \to P_{cs} X_p \]

such that \( \phi_\beta (0) = 0, \varphi_\beta (0) = 0, \) and

\[ M_\beta := \left\{ u_0 = u_* + z_0 + \phi_\beta (z_0) \in B_{X_p}(u_*, \rho) : z_0 \in P_u X_0 \cap B_{X_p}(0, \rho_0) \right\} = \left\{ u_0 \in M \cap B_{X_p}(u_*, \rho) : \exists \text{ solution u of (1.1) on } \mathbb{R}_- \text{ with} \quad |u(t) - u_*|^p < r \quad \text{and} \quad |u(t) - u_*|^1 \leq ce^{\beta t} \quad \forall t \leq 0 \right\}. \]

In (4.4) we can take \( c = \tau |u(0) - u_*|^p \) for a constant \( \tau \) independent of \( u_0, t, \beta, \) and we have \( u = u_* + \Phi_\beta (P_u (u_0 - u_*)) \) for a map \( \Phi_\beta \in BC^1(P_u X_0 \cap B_{X_p}(0, \rho_0); E_1(\mathbb{R}_-, -\beta)). \) The dimension of \( M_\beta \) is equal to the dimension of \( P_u X_0. \)

If \( u_0 \in M_\beta \) and the forward solution \( u \) of (1.1) stays in \( B(u_*, \rho) \) on \([0, t]\) for some \( t > 0, \) then \( u(t) \in M_\beta. \) If \( u_0 \in M_\beta \) and the solution \( u \) from (4.4) stays in \( B(u_*, \rho) \) on \([t, 0]\) for some \( t < 0, \) then \( u(t) \in M_\beta. \) Moreover, if \( \sigma_0 \neq 0, \) then \( u_* \) is (Lyapunov) unstable in \( X_p \) for (1.1). In addition, if (RR) holds, then the map \( \phi_\ast : P_s X_0 \cap B_{X_p}(0, \rho_0) \to P_{cs} X_1 \) is Lipschitz.

**Proof.** We provide only a sketch of the proof referring to [12, Thm.17] for missing details. The basic idea is to look for solutions \( v \) of (2.21) on \( \mathbb{R}_+ \) and \( \mathbb{R}_- \) which satisfy the decay properties of (4.3) and (4.4), respectively. The maps \( \phi_{s}, \varphi_{s} \) and \( \phi_{u} \) will then be defined in terms of the initial, respectively, final value \( v(0) \) of (2.21).
(a) We define the Lyapunov-Perron map \( L_s : P_s X_0^0 \times E_1(\mathbb{R}_+, \alpha) \to E_1(\mathbb{R}_+, \alpha) \) by

\[
L_s(z_0, v) = L^r_{P_s A_0}(z_0 + P_s N_{\rho c}^p H(v), G(v), H(v)),
\]

and \( (2.11) \), we then obtain

\[
u_\ast
\]

and that \( u \) solves \( (1.1) \) on \( [0, t] \), and we have \( |w(t) - u_*|_p = |u(t) - u_*|_p < \delta \) but \( |w(t) - u_*|_p = |u_0 - u_*|_p < \delta \) for some \( \delta > 0 \) with \( \alpha - \sigma \in (\omega_{c\alpha}, \omega_\alpha) \). Hence, \( d = \sigma/(2\alpha) \in (0, 1) \). For \( N \in \mathbb{N} \) and sufficiently small \( r > 0 \), Remark 2.3 yields

\[
\|c\alpha - \sigma v\|_{E_1(\mathbb{R}_+, \alpha)}^p \leq \sum_{n=0}^{N-1} e^{(\alpha - \sigma)n} \|v\|_{E_1(\mathbb{R}_+, \alpha)}^p
\]

where the constants do not depend on \( N \). Therefore \( v \in E_1(\mathbb{R}_+, \alpha - \sigma) \) with norm less than \( c\alpha^d \), and so \( v = L^r_{P_s A_0}(P_s v(0), G(v), H(v)) \) due to Proposition 2.5. Set \( z_0 = P_s v(0) - N_{\rho c}^p H(v(0)) \). Then \( |z_0|_p \leq c|v(0)|_p \leq c\rho < \rho_0 \) for sufficiently small \( \rho \).

We thus have the solution \( w = \Phi_s(z_0) \in E_1(\mathbb{R}_+, \alpha) \) of the equation \( w = L_s(z_0, w) \).

As in the proof of assertion (ii) of [12, Thm.17] we infer that \( w = w \) for sufficiently small \( r \). As a result, (4.3) holds. The invariance properties of \( \mathcal{M}_s \) follow from (4.3).

(b) All but last two assertions for \( \mathcal{M}_s \) can be shown in a similar way using (2.27) and Proposition 2.6, cf. [12, Thm.17]. The remaining two are proved as follows.

If \( \alpha \sigma \neq 0 \), then there exists a function \( u_0 \in \mathcal{M}_s \setminus \{u_*\} \) with a corresponding solution \( u \) of (1.1) on \( \mathbb{R}_- \) from (4.4). Hence, for each \( \delta > 0 \) there is a \( t = t(\delta) > 0 \) such that \( |u(-t) - u_*|_p \leq c e^{-\beta t} \delta \). Let \( \epsilon = |u_0 - u_*|_p/2 > 0 \) and set \( w = u(-t) \).

Then \( w \) solves (1.1) on \( [0, t] \), and we have \( |w(0) - u_*|_p = |u_0 - u_*|_p < \delta \) but \( |w(t) - u_*|_p = |u_0 - u_*|_p \geq \epsilon \). As a result, \( u_* \) is (Lyapunov) unstable in \( X_p \).

Let (RR) hold and take \( z_0, \bar{z}_0 \in P_s X_0 \cap B_{X_0}(0, \rho_0) \). Then we have solutions \( u = v + u_* \) and \( \bar{u} = \bar{v} + u_* \) of (1.1) on \( \mathbb{R}_- \) given by \( v = \Phi_s(z_0) \) and \( \bar{v} = \Phi_s(\bar{z}_0) \) for a \( BC^1 \)-map \( \Phi_s \) from \( P_s X_0 \cap B_{X_0}(0, \rho_0) \) to \( E_1(\mathbb{R}_-, -\beta) \). Employing Theorem A.1 and (2.11), we then obtain

\[
|\Phi_s(z_0) - \Phi_s(\bar{z}_0)|_{E_1(\mathbb{R}_-, -\beta)} \leq c |z_0 - \bar{z}_0|_p
\]

and (2.25), the discussion after (2.23), and also [12, (82)]. By means of Propositions 2.2 and 2.5, (2.13) and the implicit function theorem, we find numbers \( r_0, \rho_0 > 0 \) and a \( BC^1 \)-map \( \Phi_s : P_s X_0^0 \cap B_{X_0}(0, \rho_0) \to E_1(\mathbb{R}_+, \alpha) \) such that \( \Phi_s(z_0) = 0 \) and \( \Phi_s(z_0) \) is the unique solution of \( v = L_s(z_0, v) \) for \( \|v\|_{E_1(\mathbb{R}_+, \alpha)} < r_0 \) and \( |z_0|_p < \rho_0 \).

Set \( v = \Phi_s(z_0) \), \( u = v + u_* \), and \( u_0 = v(0) + u_* \). Then \( u \) solves (1.1) on \( \mathbb{R}_+ \) with \( u(0) = u_0 = u_* + \Phi_s(z_0)(0) \). Using also [12, Prop.15] and (2.11), we see that \( u \) satisfies the properties listed in (4.3) with \( c = \overline{\tau} |u(0) - u_*|_p \) and \( r = c' |z_0|_p \) for some constants \( \overline{\tau}, c' > 0 \). We further define the maps

\[
\theta_s(z_0) = P_s N_{\rho c}^p H(\Phi_s(z_0))
\]

and

\[
\phi_s(z_0) = -\int_0^\infty T_{\tau_0}(\tau) P_{\tau_0}[G(\Phi_s(z_0))(\tau) + \Pi H(\Phi_s(z_0))(\tau)] d\tau,
\]

which are of class \( BC^1 \) from \( P_s X_0^0 \cap B_{X_0}(0, \rho_0) \) to \( P_s X_0 \) and \( P_s X_0 \), respectively, and fulfill \( \phi_s(0) = \theta_s(0) = 0 \) and \( \phi'_s(0) = \theta'_s(0) = 0 \). Observe that \( z_0 = P_s(u_0 - u_* - N_{\rho c}^p H(u_0 - u_*)) = P_s P^\ast(\tau_0) H(u_0 - u_* - \Phi_s(z_0)) \) since \( H(u_0 - u_*) = B_0(\tau_0) \).

Let \( u \) be a solution of (1.1) with \( |u_0 - u_*|_p < \rho \), \( |u(t) - u_*|_p < r \), and \( |u(t) - u_*|_p \leq c e^{-\alpha t} |v|_p \) for all \( t \geq 0 \) and some \( c > 0 \) and \( \alpha \in (\omega_{c\alpha}, \omega_\alpha) \). Put \( v = u - u_* \). Take \( \sigma > 0 \) with \( \alpha - \sigma \in (\omega_{c\alpha}, \omega_\alpha) \). Hence, \( d = \sigma/(2\alpha) \in (0, 1) \). For \( N \in \mathbb{N} \) and sufficiently small \( r > 0 \), Remark 2.3 yields

\[
\|c\alpha - \sigma v\|_{E_1(\mathbb{R}_+, \alpha)}^p \leq \sum_{n=0}^{N-1} e^{(\alpha - \sigma)n} \|v\|_{E_1(\mathbb{R}_+, \alpha)}^p
\]

where the constants do not depend on \( N \). Therefore \( v \in E_1(\mathbb{R}_+, \alpha - \sigma) \) with norm less than \( c\alpha^d \), and so \( v = L^r_{P_s A_0}(P_s v(0), G(v), H(v)) \) due to Proposition 2.5. Set \( z_0 = P_s v(0) - N_{\rho c}^p H(v(0)) \). Then \( |z_0|_p \leq c |v(0)|_p \leq c\rho < \rho_0 \) for sufficiently small \( \rho \).

We thus have the solution \( w = \Phi_s(z_0) \in E_1(\mathbb{R}_+, \alpha) \) of the equation \( w = L_s(z_0, w) \). As in the proof of assertion (ii) of [12, Thm.17] we infer that \( v = w \) for sufficiently small \( r \). As a result, (4.3) holds. The invariance properties of \( \mathcal{M}_s \) follow from (4.3).
for constants independent of $z_0$ and $\sigma_0$, possibly after decreasing $\rho_0 > 0$.

We now establish the main result of this paper where we construct a local center manifold $\mathcal{M}_c$ and show some of its basic properties. In particular, $\mathcal{M}_c$ is a $C^1$–manifold in $X_p$ being tangent to $P_cX_0$ at $u_*$. Further properties of $\mathcal{M}_c$ are described in Corollary 5.3 and Theorem 6.1. We assume that the spectrum of $-A_0$ has the decomposition described in (2.34), and recall that this assumption automatically holds if the spatial domain $\Omega$ is bounded.

**Theorem 4.2.** Assume that Hypothesis 2.1 and (2.34) hold. Let the projections $P_\alpha$ and the numbers $\omega_k$ be given by (2.34). Take any $\alpha \in (\omega_\epsilon, \omega_\delta)$ and $\beta \in (\pi_\epsilon, \pi_\delta)$. Then there is a number $\eta_0 > 0$ such that for each $\eta \in (0, \eta_0]$ there exists a radius $\rho = \rho(\eta) > 0$ such that the following assertions hold, where the cutoff $F$ is defined in (3.2) for the chosen $\eta \in (0, \eta_0]$.

(a) There exists a map $\phi_c \in C^1(P_cX_0; P_{su}X_p)$ with a bounded derivative such that $\phi_c(0) = 0$, $\phi_c'(0) = 0$, and

$$
\tilde{\mathcal{M}}_c := \{ u_0 = u_* + z_0 + \phi_c(z_0) : z_0 \in P_cX_0 \}
= \{ u_0 = u_* + v(0) : \exists \text{ solution } v \in E_1(\alpha, \beta) \text{ of (3.7) on } J = \mathbb{R} \}. \quad (4.6)
$$

If $u_0 \in \tilde{\mathcal{M}}_c$, then $u_* + v(t) \in \mathcal{M}_c$ for each $t \in \mathbb{R}$ and $v = \Phi_c(P_l(u_0 - u_*)) = P_c v + \phi_c(P_c v)$ for a map $\Phi_c \in C^1(P_cX_0; E_1(\alpha, \beta))$ having a bounded derivative, where $v$ is the solution of the cutoff problem (3.7) given by (4.6).

(b) We define $\mathcal{M}_c = \mathcal{M}_c \cap B_{X_0}(u_*, \rho)$. Let $u_0 \in \mathcal{M}_c$ and $v$ be given by (4.6) with $u_0 = v(0) + u_*$. Then $F(t, v) = 1$ and $v$ solves the original equation (2.21) (at least) for $t \in [-3, 3]$, so that $\mathcal{M}_c \subset \mathcal{M}$. The dimension of $\mathcal{M}_c$ is equal to $\dim P_cX_0$.

(c) Let $u_0 \in \mathcal{M}_c$ and $v$ be given by (4.6). If the forward solution $u$ of (1.1) exists and stays in $B_{X_0}(u_*, \rho)$ on $[0, t_0]$ for some $t_0 > 0$, then $u(t) = v(t) + u_*$ in $\mathcal{M}_c$ for $0 \leq t \leq t_0$. If the function $\tilde{u} = v + u_*$ stays in $B_{X_0}(u_*, \rho)$ on $[t_0, 0]$ for some $t_0 < 0$, then $\tilde{u}(t) \in \mathcal{M}_c$ and $\tilde{u}$ solves (1.1) for $t_0 \leq t \leq 0$.

(d) Let $u_0 = u_* + v_0 \in \mathcal{M}_c$ and let $v$ be given by (4.6). Assume that $v(t) + u_* \in \mathcal{M}_c$ for all $t \in (a, b)$ and some $a < 0 < b$. Then $y = P_c v$ satisfies the equations

$$
\dot{y}(t) = -A_0 P_c y(t) + P_c \Pi H(y(t) + \phi_c(y(t))) + P_c G(y(t) + \phi_c(y(t))), \quad (4.7)
$$

on $P_cX_0$ for $t \in (a, b)$. Moreover, $v \in C((a, b); \mathcal{X}_1)$ and

$$
B_c \phi_c(P_c v_0) = B_c v_0 = H(v_0), \quad (4.8)
$$

$$
P_{su}(A_* v_0 - G(v_0)) = \phi'_c(P_c v_0) P_c(A_* v_0 - G(v_0)). \quad (4.9)
$$

(e) If $u$ solves (1.1) on $\mathbb{R}$ with $|u(t) - u_*| < \rho$ for all $t \in \mathbb{R}$, then $u(t) \in \mathcal{M}_c$ for all $t \in \mathbb{R}$.

(f) In addition, assume that (RR) holds. Then there is a $\rho_0 > 0$ such that the map $\phi_c : P_cX_0 \cap B_{X_0}(0, \rho_0) \to P_{su}X_1$ is Lipschitz.

**Proof.** We first construct a manifold $\tilde{\mathcal{M}}_c$ consisting of solutions on $\mathbb{R}$ in a weighted $\mathcal{X}_1$–space, similarly to Theorem 4.1. However, since $T_c(\cdot)$, in general, is an unbounded group, we must work in spaces containing exponentially growing functions. Therefore we have to treat the modified problem (3.7) with the cutoff $F$. The desired center manifold $\mathcal{M}_c$ is then obtained by restriction to small balls.
(a) We define the Lyapunov-Perron map \( \mathcal{L}_c : P_cX_0 \times E_1(\alpha, -\beta) \to E_1(\alpha, -\beta) \) by
\[
\mathcal{L}_c(z_0, v) = L_{A_0}(z_0, G_f(v), H_f(v)),
\]
where the operators \( L_{A_0}, G_f \) and \( H_f \) are given by (2.35) and (3.6). Due to Propositions 2.7 and 3.8, the map \( \mathcal{L}_c : v = (z_0, v) \) is \( C^1 \) from \( E_1(\alpha', -\beta') \) to \( E_1(\alpha, -\beta) \) for \( \alpha' \in (\mathcal{E}, \alpha) \) and \( \beta' \in (\mathcal{E}, \beta) \) and the derivative of \( \mathcal{L}_c \) is bounded by \( c_1\varepsilon(\eta) \) in the norm of both \( \mathcal{B}(E_1(\alpha', -\beta')) \) and \( \mathcal{B}(E_1(\alpha, -\beta)) \), independent of \( z_0 \in P_cX_0 \). Moreover, \( \mathcal{L}_c \) is Lipschitz in \( E_1(\alpha', -\beta') \) with Lipschitz constant \( c_1(\eta) \) independent of \( z_0 \in P_cX_0 \) by Proposition 3.6. Finally, the map \( z_0 \mapsto \mathcal{L}_c(z_0, v) \) is affine from \( P_cX_0 \) to \( E_1(\alpha', -\beta') \) with the derivative \( T(\cdot)P_c \).

We now fix \( \eta = \eta_0 > 0 \) such that \( c_1\varepsilon(\eta) \leq 1/2 \). (Note that this estimate holds for every \( \eta' \in (0, \eta) \).) Then Theorem 3 of [21] (with \( Y_0 = Y = E_1(\alpha', -\beta') \) and \( Y_1 = E_1(\alpha, -\beta) \)) shows that for each \( z_0 \in P_cX_0 \) there exists a unique solution \( \bar{v} = \Phi_c(z_0) \in E_1(\alpha', -\beta') \) of the equation \( \bar{v} = \mathcal{L}_c(z_0, v) \), where \( \Phi_c \in C^1(P_cX_0; E_1(\alpha, -\beta)) \) and \( \Phi_c(0) = 0 \). Employing [21, (4.4)], it is easy to check that \( \Phi'_c(z_0) \in \mathcal{B}(P_cX_0; E_1(\alpha, -\beta)) \) is bounded uniformly in \( z_0 \). We further define
\[
\phi_c(z_0) = \gamma_0 P_{su} \Phi_c(z_0) = \int_0^\infty T_{-1}(\tau) P_s[G_f(\Phi_c(z_0))](\tau) + \Pi H_f(\Phi_c(z_0))(\tau) \, d\tau
\]
for \( z_0 \in P_cX_0 \). Taking also into account (2.13), we see that \( \phi_c \in C^1(P_cX_0; P_{su}X_p) \), that \( \phi'_c \) is bounded, and that \( \phi_c(0) = 0 \) and \( \phi'_c(0) = 0 \). Equality (4.6) follows from Proposition 2.7. If \( u_0 \in \mathcal{M}_c \) with the corresponding solution \( v \) of (3.7) and \( t \in \mathbb{R} \), then \( v = v^0 + t \) solves (3.7) with the initial condition \( v(0) = v(t) \) thanks to Remark 3.2. This means that \( u_0 + v(t) \in \mathcal{M}_c \), and thus \( v(t) = P_c v(t) + \phi_c(P_c v(t)) \).

(b) Let \( u_0 \in \mathcal{M}_c \cap B_{X_F}(u_*, \rho) \). Set \( v_0 = u_0 - u_* \), \( z_0 = P_c v_0 \), and \( v = \Phi_c(z_0) \).

From (3.4) and part (a) we infer that
\[
\|v\|_{E_1([-5, 5])} \leq c\|v\|_{E_1(\alpha, -\beta)} = c\|\Phi_c(z_0) - \Phi_c(0)\|_{E_1(\alpha, -\beta)}
\]
\[
\leq c\|z_0\|_0 \leq c\|v_0\|_p \leq c_1\varepsilon(\eta_0) \rho.
\]
(4.10)

If we take \( \rho \leq \eta_0/c_1' \), Remark 3.1 implies that \( F(t, v) = 1 \) for \( t \in [-3, 3] \), so that \( v \) solves (2.21) on \([-3, 3]\) in this case.

(c) Take \( u_0 \in \mathcal{M}_c \) and let \( u \) be the forward solution of (1.1). Part (b) and the uniqueness of (1.1) yield that \( u = v + u_* \) on \([0, 2]\), where \( v \) is given by (4.6). Thus \( u(t) = v(t) + u_* \) \( \in \mathcal{M}_c \) by part (a) for \( t \in [0, 2] \). If \( u(t) \in B_{X_F}(u_*, \rho) \) for \( t \in [0, t_0] \) and \( t_0 \leq 2 \), we thus obtain \( u \in \mathcal{M}_c \) for \( t \in [0, t_0] \). If \( t_0 > 2 \), this argument can be iterated as long as \( u \) stays in \( B_{X_F}(u_*, \rho) \). The assertions concerning the backward invariance of \( \mathcal{M}_c \) are direct consequences of parts (a) and (b).

(d) Let \( u_0 = u_* + v_0 \in \mathcal{M}_c \) and let \( v \) be given by (4.6). By parts (a)–(c), the function \( v = y + \phi_c(y) \) solves (2.21) on \((a, b)\). Theorem 14 of [12] then shows that \( v \) is continuous in \( X_1 \). Moreover,
\[
\dot{y}(t) = P_c v(t) = P_c(-A_* v(t) + G(v(t))]
\]
\[
= -P_c(\mu + A_*)(v(t) - N_1 H(v(t))) + \mu P_c v(t) + P_c G(v(t))
\]
\[
= -A_0 P_c y(t) + P_c \Pi H(y(t) + \phi_c(y(t))) + P_c G(y(t) + \phi_c(y(t))).
\]
Equality (4.8) is clear since $B_s P_c = 0$ and $v_0 \in \mathcal{M}$. We further have
\[
\dot{v}(t) = -A_r v(t) + G(v(t)),
\]
\[
\dot{v}(t) = P_c(-A_r v(t) + G(v(t))) + \phi'_c(P_c v(t)) P_c(-A_r v(t) + G(v(t))),
\]
so that (4.9) follows by taking $t = 0$.

(e) For a global solution $u$ of (1.1) staying in $B_{X_0}(u_*, \rho)$, Remark 2.3 implies that $\|u\|_{E_1(t-2, t+2)} \leq c_r \rho$ for each $t \in \mathbb{R}$ (possibly after decreasing $\rho > 0$). In particular, $u \in E_1(\alpha, -\beta)$. Taking $\rho \leq \eta/c_r$, we further deduce that $v = u - u_*$ solves (3.7) on $J = \mathbb{R}$ using Remark 3.1. So (e) follows from the definition of $\mathcal{M}_c$.

(f) We first note that (4.10) and (2.11) imply $|v(0)|_{P_r} \leq c |z_0|_{P_r}$ for $u_0 = v(0) + u_* \in \tilde{\mathcal{M}}_c$ with $v = \Phi_c(z_0)$. Hence, there is a number $\rho_0$ such that $u_0 = u_* + z_0 + \phi_c(z_0) \in \mathcal{M}_c$ if $z_0 \in P_c X_0 \cap B_{X_0}(u_*, \rho_0)$. Then $v$ solves (2.21) on $[-1, 0]$. So we can show assertion (f) as the final assertion in Theorem 4.1(b). \hfill \Box

Remark 4.3. Given $r \geq \rho > 0$, the manifolds $\mathcal{M}_s$ and $\mathcal{M}_u$ from Theorem 4.1 are uniquely determined by (4.3) and (4.4) as sets of initial values of exponentially decaying solutions of (1.1). There is no such description for $\mathcal{M}_c$ from Theorem 4.2. In fact, there are simple ODEs in dimension two admitting infinitely many locally invariant manifolds which are tangent to $P_c X_0$ at $u_*$ and satisfy $\mathcal{M}_c \cap \mathcal{M}_s = \mathcal{M}_c \cap \mathcal{M}_u = \{u_*\}$ (cf. Corollary 5.3). However, if $u_*$ is stable in forward and backward time, then Theorem 4.2(e) implies that our $\mathcal{M}_c$ is the only manifold in $B_{X_0}(u_*, \rho)$ with these properties. \hfill \Box

5. Center stable and center unstable manifolds

In this section we go back to the situation of Theorem 4.1. In Theorem 5.1 we construct a local center–stable manifold $\mathcal{M}_{cs}$ assuming (4.2), and in Theorem 5.2 we construct a local center–unstable manifold $\mathcal{M}_{cu}$ assuming (4.1). These manifolds are of class $C^1$ in $X_{p_0}$, and are tangent to $P_{cs} X_0^0$, resp. to $P_{cu} X_0$, at $u_*$. They will be used to prove further properties of the center manifold in Corollary 5.3. Recall that $\mathcal{P} = I - N_p B_s$.

Theorem 5.1. Assume Hypothesis 2.1 and (4.2). Take any $\beta \in (\omega_{cs}, \omega_{cu})$. Then there is a number $\eta_{cs} > 0$ such that for each $\eta \in (0, \eta_{cs}]$ there exists a radius $\rho = \rho(\eta) > 0$ such that the following assertions hold, where the cutoff $F_+$ is defined in (3.5) for the chosen $\eta \in (0, \eta_{cs}]$.

(a) There exist maps $\phi_{cs} \in C^1(P_{cs} X_0^0, P_c X_0)$ and $\vartheta_{cs} \in C^1(P_{cs} X_0^0, P_c X_0^0)$ with bounded derivatives such that $\phi_{cs}(0) = \vartheta_{cs}(0) = 0$, $\phi'_{cs}(0) = \vartheta'_{cs}(0) = 0$, and

\[
\tilde{\mathcal{M}}_{cs} := \{ u_0 = u_* + z_0 + \vartheta_{cs}(z_0) + \phi_{cs}(z_0) : z_0 \in P_{cs} X_0^0 \}
\]

\[
= \{ u_0 = u_* + v(0) : \exists \text{ solution } v \in E_1(\mathbb{R}^+, -\beta) \text{ of (3.7) on } J = \mathbb{R}^+ \}. \quad (5.1)
\]

Moreover, the function $v$ in (5.1) is given by $v = \Phi_{cs}(P_c \mathcal{P}(u_0 - u_*))$ for a map $\Phi_{cs} \in C^1(P_{cs} X_0^0; E_1(\mathbb{R}^+, -\beta))$ having a bounded derivative.

(b) We define $\mathcal{M}_{cs} = \tilde{\mathcal{M}}_{cs} \cup B_{X_0}(u_*, \rho)$. Let $u_0 \in \mathcal{M}_{cs}$ and $v$ be the function from (5.1) with $u_0 = v(0) + u_*$. Then $F_+(t, v) = 1$ and $v$ solves the original equation (2.21) (at least) for $t \in [0, 4]$.

(c) Let $u_0 \in \mathcal{M}_{cs}$ and $v$ be given by (5.1). Assume that a forward or a backward solution $u$ of (1.1) exists and stays in $B_{X_0}(u_*, \rho)$ on $[0, t_0]$ or on $[-t_0, 0]$ for some $t_0 > 0$. Set $v(t) = u(t) - u_*$ for $-t_0 \leq t \leq 0$ in the second case. Then $u(t) =
for a constant $v$,

for constants independent of $v$ growing functions. Thus, as in Theorem 4.2, we have to involve the cutoff $u$ of (3.7) on that the semigroup $L$ is bounded by where the operators $L_{\rho}^{+}$, $G_{F^{+}}$ and $H_{F^{+}}$ are given by (2.25) and (3.6). Observe that the semigroup $\varepsilon_{-\beta}T(\cdot)$ is hyperbolic with the stable projection $P_{cs}$. Due to Propositions 3.5 and 3.8 and the embedding (2.13), the map $L^{0}: v \mapsto L_{cs}(z_{0}, v)$ is $C^{1}$ from $E_{1}(\mathbb{R}^{+}, -\beta')$ to $E_{1}(\mathbb{R}^{+}, -\beta)$ for $\beta' \in (\omega_{cs}, \beta]$ and the derivative of $L^{0}$ is bounded by $c_{1} \varepsilon(\eta)$ in the norm of both $B(E_{1}(\mathbb{R}^{+}, -\beta'))$ and $B(E_{1}(\mathbb{R}^{+}, -\beta))$, independent of $z_{0} \in P_{cs}X_{p}^{0}$. Moreover, $L^{0}$ is Lipschitz in $E_{1}(\mathbb{R}^{+}, -\beta')$ with the Lipschitz constant $c_{1} \varepsilon(\eta)$ independent of $z_{0} \in P_{cs}X_{p}^{0}$ by Proposition 3.6. Finally, the map $z_{0} \mapsto L_{cs}(z_{0}, v)$ is affine from $P_{cs}X_{p}^{0}$ to $E_{1}(\mathbb{R}^{+}, -\beta')$ with the derivative $T(\cdot)P_{cs}$.

We now fix $\eta = \eta_{cs} > 0$ such that $c_{1} \varepsilon(\eta) \leq 1/2$. (Note that this inequality also holds for each $\eta' \in (0, \eta)$.) Then Theorem 3 of [21] (with $Y_{0} = Y = E_{1}(\mathbb{R}^{+}, -\beta')$ and $Y_{1} = E_{1}(\mathbb{R}^{+}, -\beta)$) shows that for each $z_{0} \in P_{cs}X_{p}^{0}$ there exists a unique solution $v = \Phi_{cs}(z_{0}) \in E_{1}(\mathbb{R}^{+}, -\beta')$ of the equation $v = L_{cs}(z_{0}, v)$, where $\Phi_{cs} \in C^{1}(P_{cs}X_{p}^{0}, E_{1}(\mathbb{R}^{+}, -\beta'))$ and $\Phi_{cs}(0) = 0$. Due to [21, (4.4)], the derivatives $\Phi_{cs}'(z_{0}) \in B(P_{cs}X_{p}^{0}, E_{1}(\mathbb{R}^{+}, -\beta))$ are bounded uniformly in $z_{0}$. We then introduce

\[ \Phi_{cs}(z_{0}) = P_{cs}N_{\gamma}0H_{F^{+}}(\Phi_{cs}(z_{0})) \quad \text{and} \quad \phi_{cs}(z_{0}) = c_{0}P_{u}\Phi_{cs}(z_{0}) = -\int_{0}^{\infty} T_{u}(-\tau)P_{u}[G_{F^{+}}(\Phi_{cs}(z_{0}))(\tau) + \Pi H_{F^{+}}(\Phi_{cs}(z_{0}))(\tau)]d\tau, \]

for $z_{0} \in P_{cs}X_{p}^{0}$. Taking also into account (2.13), we see that $\phi_{cs} \in C^{1}(P_{cs}X_{p}^{0}, P_{u}X_{p})$ and $\phi_{cs}' \in C^{1}(P_{cs}X_{p}^{0}, P_{u}X_{p})$ with bounded derivatives and that $\phi_{cs}(0) = \phi_{cs}'(0) = 0$ and $\phi_{cs}''(0) = 0$. The inclusion ‘$c$’ in (5.1) is clear by the above definitions, with $v = \Phi_{cs}(z_{0})$. Moreover, $z_{0} = P_{cs}P(v(0)) = P_{cs}(u_{0} - u_{s})$. Conversely, let $v \in E_{1}(\mathbb{R}^{+}, -\beta')$ solve (3.7) on $J = \mathbb{R}^{+}$. Proposition 2.5 then implies $v = L_{P_{cs}A_{0}}(P_{cs}(v(0)), G_{F^{+}}(v), H_{F^{+}}(v))$. Setting $z_{0} = P_{cs}P(v(0))$ and using $B_{u}(v(0)) = H_{F^{+}}(v(0))$, we obtain $P_{cs}v(0) = z_{0} + P_{cs}N_{\gamma}0H_{F^{+}}(v)$. Therefore $v = L_{cs}(z_{0}, v)$ which entails $v = \Phi_{cs}(z_{0})$. This fact leads to $v(0) + u_{s} \in M_{cs}$.

(b) Take $u_{0} \in M_{cs} \cap B_{X_{s}}(u_{s}, \rho)$ for some $\rho > 0$ and the corresponding solution $v$ of (3.7) on $J = \mathbb{R}^{+}$ given by (5.1). From part (a) we deduce that

\[ \|v\|_{E_{1}(\mathbb{R}^{+}, -\beta')} = \|\Phi_{cs}(z_{0}) - \Phi_{cs}(0)\|_{E_{1}(\mathbb{R}^{+}, -\beta')} \leq c|z_{0}|p \leq c|v(0)|_{p} \]

for constants independent of $v$. So (3.4) yields

\[ \|v\|_{E_{1}((0, \delta])} \leq c\rho \]

for a constant $c'$ that does not depend on $v$ and $\rho$. We take

\[ \rho \leq \rho_{1} := \frac{\eta}{c(1 + c_{R})}, \]

Proof. We follow the strategy of the construction of the stable manifold in Theorem 4.1, but now we must work in the space $E_{1}(\mathbb{R}^{+}, -\beta)$ containing exponentially growing functions.
(c.i) Let \( u_0 \in M_{cs} \) and denote by \( u \) the solution of (1.1) on \([0, t_0]\) with \( u(0) = u_0 \), for some \( t_0 > 0 \). We set \( w = u - u_* \). Let \( v \in E_1(\mathbb{R}_+, -\beta) \) be the solution of (3.7) with \( v(0) = u_0 - u_* \) given by (5.1). We assume that \( |w(t)|_P < \rho \) for \( 0 \leq t \leq t_0 \). We want to show that \( w(t) = v(t) \) and \( u(t) \in M_{cs} \) for \( 0 \leq t \leq t_0 \). First we consider the case when \( t_0 \leq 2 \). Part (b) shows that \( F_\rho(t, v) = 1 \) and that \( w \) solves (2.21) for \( 0 \leq t \leq t_0 \). Then \( w(t) = v(t) \) for \( 0 \leq t \leq t_0 \) by the uniqueness of (1.1). We further set \( \tilde{v}(t) = v(t + t_0) \) for \( t \geq 0 \). Remark 3.5 yields that \( F_\rho(t, \tilde{v}) = F_\rho(t + t_0, v) \) for \( t \geq 2 \). Further, we have \( \|v\|_{E_1([t-2, t+2] \cap \mathbb{R}_+)} \leq \|v\|_{E_1([0, 6])} \leq \eta/(1 + c\rho) \) for \( 0 \leq t \leq 2 \) due to (5.4) and (5.5). Remark 3.1 thus implies that \( F_\rho(t, \tilde{v}) = 1 \) for \( 0 \leq t \leq 2 \). Finally, \( F_\rho(t + t_0, v) = 1 \) for \( 0 \leq t \leq 2 \) by part (b). Therefore \( F_\rho(t, v) = 1 \) for all \( t \geq 0 \), and \( v \) solves (3.7) on \( J = \mathbb{R}_+ \) with \( v(0) = v_0 \). This means that \( v(t_0) + u_* \in M_{cs} \cap B_X(u_*, \rho) = M_{cs} \). Since we can replace here \( t_0 \) by \( t \in [0, t_0] \), (the proof of) part (a) yields \( u(t) = u_* + v(t) = u_* + \rho c v(t) + \phi_{cs}(P_{cs} P v(t)) + \partial_{cs}(P_{cs} P v(t)) \in M_{cs} \) for \( 0 \leq t \leq t_0 \). If \( t_0 > 2 \), we obtain the assertion by a finite iteration of this argument.

(c.ii) Let \( u_0 \in M_{cs} \) and assume that there is a solution \( u \) of (1.1) on \([-t_0, 0]\) with \( u(0) = u_0 \), for some \( t_0 > 0 \). We set \( w(t) = u(t) - u_* \) and assume that \( |w(t)|_P < \rho \) for \( -t_0 \leq t \leq 0 \). Let \( v \in E_1(\mathbb{R}_+, -\beta) \) be the solution of (3.7) with \( v(0) = u_0 - u_* \) given by (5.1). We want to show that \( u(t) \in M_{cs} \) for \( -t_0 \leq t \leq 0 \). To this aim, we set \( \tilde{v}(t) = v(t) \) and \( z(t) = w(t - t_0) \) for \( t \geq 0 \). Clearly, \( z \in E_1(\mathbb{R}_+, -\beta) \), \( z(0) = w(-t_0) \), and \( z \) satisfies the first two equations in (2.21) on \([0, t_0 + 2]\) since \( w \) and \( v \) solve (2.21) on \([-t_0, 0]\) and \([0, 2]\), respectively. Take \( t \in [0, t_0 + 2] \) and \( s \) with \( |t - s| \leq 1/4 \). Note that \([0, 1] \subset J(s) \) if \( J(s) \cap \mathbb{R}_- \neq \emptyset \). We thus deduce from (3.3) that

\[
\|R_\rho z\|_{E_1(J(s))} \leq \|z\|_{E_1(J(s)) \cap [0, t_0]} + \|z\|_{E_1(J(s)) \cap [t_0, \infty)} + \|R_\rho z\|_{E_1(J(s)) \cap (-1, 0]} \leq (1 + c\rho)\left(\|w(-t_0)\|_{E_1(J(s)) \cap [0, t_0]} + \|w(-t_0)\|_{E_1(J(s)) \cap [t_0, \infty)}\right) + \|v\|_{E_1(J(s) \cap \mathbb{R}_+)}
\]

Since \( w \) solves (2.21) on \( J(s - t_0) \cap [-t_0, 0] \), \( s = [a, b] \) and \( |w(a)| < \rho \), Remark 2.3 with \( T = 3 \) yields \( \|w\|_{E_1([a, b])} \leq c_\beta \rho \) as soon as \( \rho > 0 \) is sufficiently small. Moreover, \( \|v\|_{E_1(J(s) \cap \mathbb{R}_+)} \leq c_\beta \rho \) because of (5.4) and \( J(s - t_0) \cap \mathbb{R}_+ \subset [0, 4] \). As a result,

\[
\|R_\rho z\|_{E_1(J(s))} \leq (1 + c\rho)(c_\beta + c_\rho) \rho \leq \eta \quad \text{for} \quad \rho \leq \rho_2 := \frac{\eta}{(1 + c\rho)(c_\beta + c_\rho)},
\]

and so \( F_\rho(t, z) = 1 \) for \( 0 \leq t \leq t_0 + 2 \). (Observe that \( \rho_2 \) is less than the number \( \rho_1 \) given by (5.5).) The function \( z \) thus satisfies (3.7) for \( 0 \leq t \leq t_0 + 2 \). For \( t \geq t_0 + 2 \), we have \( F_\rho(t, z) = F_\rho(t - t_0, v) \) by Remark 3.5. In particular, \( z \) fulfills the equations (3.7) also for \( t \geq t_0 + 2 \). Summing up, \( z \) solves (3.7) on \( \mathbb{R}_+ \) and so \( u_* + z(0) = u(-t_0) \in M_{cs} \cap B_X(u_*, \rho) = M_{cs} \). Replacing here \( -t_0 \) by \( t \in [-t_0, 0] \) and writing \( v(t) = w(t) \) for \( -t_0 \leq t \leq 0 \), we arrive at \( u(t) = u_* + v(t) = u_* + P_{cs} v(t) + \phi_{cs}(P_{cs} P v(t)) + \partial_{cs}(P_{cs} P v(t)) \in M_{cs} \) for \( -t_0 \leq t \leq 0 \).

(d) Assume that \( u_0 = v_0 + v_0 \in M_{cs} \cap M_\omega \). We take \( \beta \in (\beta, \omega_\nu) \). Let \( v \in E_1(\mathbb{R}_+, -\beta) \) be the solution of (3.7) with \( v(0) = v_0 \) given by (5.1). Due to Theorem 4.1(b), there is a solution \( w \) of (2.21) on \( \mathbb{R}_- \) with \( w(0) = v_0 \) satisfying

\[
|w(t)|_P \leq \tau c_\beta(t + 1)^{\beta + c_\rho} |v_0|_P \leq \tau \rho
\]
for all $t \leq 0$ if $\rho > 0$ is sufficiently small. We choose $\rho \leq \rho_1 := \rho_2/\tau$ (see (5.6)) and take $t \leq 0$. Then part (c.ii) of the proof implies that $u_* + w(t) \in M_{\rho}$ and that the function $z_t \in E_1(\mathbb{R}_+, -\beta)$ given by $z_t(\tau) = w(t + \tau)$ for $\tau \in [0, -t]$ and $z_t(\tau) = v(t + \tau)$ for $\tau \geq -t$ solves (3.7) on $J = \mathbb{R}_+$. From (5.3) we deduce that
\[
\|z_t\|_{E_1(\mathbb{R}_+, -\beta)} \leq c|z_t(0)|_{\rho} = c|w(t)|_{\rho},
\] (5.8)
where the constants do not depend on $t \leq 0$. Using (2.11), (5.8) and (5.7), we have
\[
|v_0|_{\rho} = ce^{-\beta t} \|z_t(-t)\|_{\rho} \leq ce^{-\beta t} \|z_t\|_{E_1(\mathbb{R}_+, -\beta)} \leq ce^{-\beta t}|w(t)|_{\rho} \leq ce^{\alpha t}|v(0)|_{\rho}
\]
with the constants independent of $t$. Letting $t \to -\infty$, we have $u_0 - u_* = v_0 = 0$. \(\square\)

**Theorem 5.2.** Assume Hypothesis 2.1 and (4.1). Take any $\alpha \in (\omega_{cu}, \omega_*).$ Then there is a number $\eta_{cu} > 0$ such that for each $\eta \in (0, \eta_{cu})$ there exists a radius $\rho = \rho(\eta) > 0$ such that the following assertions hold for the cutoff $f_-$ defined for the chosen $\eta \in (0, \eta_{cu})$.

(a) There exists a map $\phi_{cu} \in C^1(P_{cu}X_0; P_{cu}X_p)$ with a bounded derivative such that $\phi_{cu}(0) = 0$, $\phi_{cu}'(0) = 0$, and
\[
\tilde{M}_{cu} := \{u_0 = u_* + z_0 + \phi_{cu}(z_0) : z_0 \in P_{cu}X_0\}
\]
(5.9)
Moreover, the function $v$ in (5.9) is given by $v = \Phi_{cu}(P_{cu}(u_0 - u_*))$ for a map $\Phi_{cu} \in C^1(P_{cu}X_0; E_1(\mathbb{R}_+, \alpha))$ having a bounded derivative.

(b) Define $M_{cu} = \tilde{M}_{cu} \cap B_{X_p}(u_*, \rho)$. Let $u_0 \in M_{cu}$ and $v$ be the function from (5.9) with $u_0 = v(0) + u_*$. Then $f_-(t, v) = 1$ and $v$ solves the original equation (2.21) (at least) for $t \in [-4, 0]$. The dimension of $M_{cu}$ is equal to dim $P_{cu}X_0$.

(c) Let $u_0 \in M_{cu}$ and $v$ be given by (5.9). If the forward solution $u$ of (1.1) exists and stays in $B_{X_p}(u_*, \rho)$ on $[0, t_0]$ for some $t_0 > 0$, then $u(t) = u_* + v(t) \in M_{cu}$ for $0 \leq t \leq t_0$. If the function $\tilde{u} = u_* + v$ stays in $B_{X_p}(u_*, \rho)$ on $[t_0, 0]$ for some $t_0 < 0$, then $\tilde{u}(t) = u_* + v(t) \in M_{cu}$ and $\tilde{u}$ solves (1.1) for $t_0 \leq t \leq 0$. In particular, $v(t) = P_{cu}v(t) + \phi_{cu}(P_{cu}v(t))$ for $t \in [0, t_0]$, resp. $t \in [t_0, 0]$.

(d) We have $M_{cu} \cap M_u = \{u_*\}$.

(e) Assume, in addition, that $RR$ holds. Then there is a $\rho_0 > 0$ such that the map $\phi_{cu} : P_{cu}X_0 \cap B_{X_p}(0, \rho_0) \to P_{cu}X_1$ is Lipschitz.

**Proof.** Parts (a)–(d) of the following proof are similar to the proof of the previous theorem so we can omit some details and focus on the differences.

(a) We define the Lyapunov–Perron map $L_{cu} : P_{cu}X_0 \times E_1(\mathbb{R}_+, \alpha) \to E_1(\mathbb{R}_+, \alpha)$ by setting $L_{cu}(z_0, v) = L_{P_{cu}A_0}(z_0, G_{f_-}(v), H_{f_-}(v))$, where the operators $L_{P_{cu}A_0}$, $G_{f_-}$, and $H_{f_-}$ are given by (2.27) and (3.6). Using Propositions 2.6, 3.6 and 3.8, we find $\eta_{cu} > 0$ such that the assumptions of Theorem 3 of [21] hold for the cutoff $f_-$ with the parameter $\eta \in (0, \eta_{cu})$. As a result, for each $z_0 \in P_{cu}X_0$ there exists a unique solution $v = \Phi_{cu}(z_0) \in E_1(\mathbb{R}_+, \alpha')$ of the equation $v = L_{cu}(z_0, v)$, where $\Phi_{cu} \in C^1(P_{cu}X_0; E_1(\mathbb{R}_+, \alpha'))$, $\Phi_{cu}(0) = 0$, and the derivatives $\Phi_{cu}'(z_0) \in B(P_{cu}X_0, E_1(\mathbb{R}_+, \alpha'))$ are bounded uniformly in $z_0$. We then introduce the map
\[
\phi_{cu}(z_0) = \gamma_0 P_f \Phi_{cu}(z_0) = \int_{-\infty}^0 T(-\tau)P_f[\Phi_{cu}(z_0)](\tau) + \Pi H_{f_-}(\Phi_{cu}(z_0))(\tau) d\tau,
\]
for $z_0 \in P_{cu}X_0$. Due to (2.13), we obtain that $\phi_{cu} \in C^1(P_{cu}X_0; P_{cu}X_p)$ with a bounded derivative and that $\phi_{cu}(0) = 0$ and $\phi_{cu}'(0) = 0$. Equality (5.9) follows from Proposition 2.6, where $v = \Phi_{cu}(z_0)$ and $z_0 = P_{cu}(u_0 - u_*)$. 

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(b) Take $u_0 \in \tilde{M}_{\mathcal{M}_\alpha} \cap B_{X_p}(u_*, \rho)$ for some $\rho > 0$ and the corresponding solution $v$ of (3.7) given by (5.9). From (3.4) and part (a) we deduce
\[
\|v\|_{L(E, [0, t])} \leq c_E \|v\|_{E_1(\mathbb{R}^n, \alpha)} \leq c_E \|z_0\|_p \leq c' \|v(0)\|_p \leq c' \rho
\]
with the constants independent of $v$ and $\alpha$. We take
\[
\rho \leq \rho_1 := \frac{\eta}{c'(1 + c_R)},
\]
from (3.3). Then $F_-(t, v) = 1$ for $-4 \leq t \leq 0$ by Remark 3.1. As a result, $v$ solves the original problem (2.21) on $[-4, 0]$. (c.i) Take $u_0 \in \mathcal{M}_{\mathcal{C}_u}$ such that the solution $u$ of (1.1) on $[0, t_0]$ with $u(0) = u_0$ stays in $B_{X_p}(u_*, \rho)$ for some $\rho, t_0 > 0$. We set $w = u - u_*$. Let $v \in E_\eta(\mathbb{R}^n, \alpha)$ be the solution of (3.7) on $J = \mathbb{R}^n$ with $v(0) = u_0 - u_*$ given by (5.9). We further define $w(t) = v(t)$ and $z(t) = w(t + t_0)$ for $t \leq 0$ clearly, $z \in E_\eta(\mathbb{R}^n, \alpha)$, $z(0) = w(t_0)$, and $z$ satisfies the first two equations in (1.1) on $[-t_0 - 2, 0]$ since $w$ and $v$ solve (1.1) on $[0, t_0]$ and $[-2, 0]$, respectively. Take $t \in [-t_0 - 2, 0]$ and $s$ with $|t - s| \leq 1/4$.

As in part (c.ii) if the proof of Theorem 5.2, we deduce from (3.3) that
\[
\|R_- z\|_{E_\eta(J(s))} \leq (1 + c_\eta) \|w(\cdot + t_0)\|_{E_\eta(J(s) \cap [-t_0, 0])} + \|v(\cdot + t_0)\|_{E_\eta(J(s) \cap (-\infty, -t_0])}
\]
\[
= (1 + c_\eta) \|w\|_{E_\eta(J(s + t_0) \cap [0, t_0])} + \|v\|_{E_\eta(J(s + t_0) \cap \mathbb{R}^n)}.
\]
Remark 2.3 shows that $\|w\|_{E_\eta([a, b])} \leq c_s \rho$ for sufficiently small $\rho > 0$ since $w$ solves (1.1) on $J(s + t_0) \cap [0, t_0] = [a, b]$. Using $J(s + t_0) \cap \mathbb{R}^n \subset [-4, 0]$ and (5.10), we estimate $\|v\|_{E_\eta(J(s + t_0) \cap \mathbb{R}^n)} \leq c' \rho$. Consequently,
\[
\|R_- z\|_{E_\eta(J(s))} \leq (1 + c_\eta)(c_s + c') \rho \leq \eta \quad \text{for} \quad \rho \leq \rho_2 := \frac{\eta}{(1 + c_\eta)(c_s + c')},
\]
and hence $F_-(t, z) = 1$ for $-t_0 - 2 \leq t \leq 0$. The function $z$ thus satisfies (3.7) for $-t_0 - 2 \leq t \leq 0$. Moreover, Remark 3.5 yields $F_-(t, z) = F_-(t + t_0, v)$ for $t \leq -t_0 - 2$; and so $z$ fulfills the equations (3.7) for $t \leq -t_0 - 2$. Summing up, we have shown that $z$ solves (3.7) on $\mathbb{R}^n$, and so $u_* + z(0) = u(t_0) \in \mathcal{M}_{\mathcal{C}_u}$.

(c.ii) Let $v_0 \in \mathcal{M}_{\mathcal{C}_u}$ and $v$ be given by (5.9). Assume that $\dot{u} = u_* + v$ stays in $B_{X_p}(u_*, \rho)$ on $[t_0, 0]$ for some $t_0 < 0$. We first consider the case when $t_0 \in [-2, 0]$. Part (b) shows that $F_-(t, v) = 1$ and $v$ solves (2.21) on $[t_0, 0]$. We further set $\tilde{v}(t) = v(t + t_0)$ for $t \leq 0$. From Remark 3.5 it follows that $F_-(t, \tilde{v}) = F_-(t + t_0, v)$ for $t \leq -2$. Since $\|\tilde{v}\|_{E_\eta(J(s + t_0 + 2) \cap \mathbb{R}^n)} \leq \|v\|_{E_\eta(J(s + t + 2) \cap \mathbb{R}^n)} \leq \eta/(1 + c_\eta)$ for $-2 \leq t \leq 0$ by (5.3), Remark 3.1 yields $F_-(t, \tilde{v}) = 1$ for $-2 \leq t \leq 0$ finally, $F_-(t + t_0, \tilde{v}) = 1$ for $-2 \leq t \leq 0$ due to part (b); so that $F_-(t, \tilde{v}) = F_-(t + t_0, v)$ for all $t \leq 0$. As a result, $v_0 \in E_\eta(\mathbb{R}^n, \alpha)$ solves (3.7) on $J = \mathbb{R}^n$ with $v(0) = v(t_0)$. This means that $v(t) + u_* \in \mathcal{M}_{\mathcal{C}_u}$ for each $t \in [0, t_0]$, as asserted. The general case $t_0 < -2$ is then established by repeating the arguments for the first case finitely many times.

(d) Assume that $u_0 = u_* + v_0 \in \mathcal{M}_{\mathcal{C}_u} \cap \mathcal{M}_\alpha$. Let $v \in E_\eta(\mathbb{R}^n, \alpha)$ be the solution of (3.7) with $v(0) = v_0$ given by (5.9). For $\alpha + \epsilon \in (\alpha, \omega_\alpha)$, there is a solution $w$ of (2.21) on $\mathbb{R}^n$ with $w(0) = v_0$ satisfying $|w(t)|_p \leq c_{\epsilon}(\alpha + \epsilon)|v_0|_p \leq \rho_2/\epsilon$ for all $t \geq 0$ if $\rho > 0$ sufficiently small, due to Theorem 4.1. Set $w(t) = v(t)$ for $t \leq 0$. If we choose $\rho \leq \rho_3 := \rho_2/\epsilon$ (see (5.12)), then part (c.ii) of the proof shows that $u_* + w(t) \in \mathcal{M}_{\mathcal{C}_u}$ for $t \geq 0$ and that the function $z_t = w(\cdot + t) \in E_\eta(\mathbb{R}^n, \alpha)$ solves (3.7) on $J = \mathbb{R}^n$. So estimate (5.10) yields $\|z_t\|_{E_\eta(\mathbb{R}^n, \alpha)} \leq c|w(t)|_p$, where the constant does not depend on $t \geq 0$. Using also (2.11), we arrive at
\[
|v_0|_p = c^\alpha t^{\alpha(-c^\alpha)} z_t(\cdot - t)|_p \leq c^\alpha t^{\alpha(-c^\alpha)} \|z_t\|_{E_\eta(\mathbb{R}^n, \alpha)} \leq c^\alpha t^{\alpha(-c^\alpha)}|w(t)|_p \leq c^\alpha t^{\alpha(-c^\alpha)}|v(0)|_p
\]
for constants independent of $t \geq 0$. Letting $t \to \infty$, we deduce $u_0 - u_* = v_0 = 0$.

(e) Assertion (e) can be shown as the last assertion in Theorem 4.1(b).

**Corollary 5.3.** Assume that Hypothesis 2.1 and (2.34) hold. Then there is a number $\mathbf{p} > 0$ such that $M_c \cap B_{\mathbf{p}} = M_{cs} \cap M_{cn} \cap B_{\mathbf{p}}, \ M_c \cap M_s \cap B_{\mathbf{p}} = \{u_*\},$ and $M_c \cap M_u \cap B_{\mathbf{p}} = \{u_*\}$. Here, $B_{\mathbf{p}} = B_{X^0_c}(u_*, \mathbf{p})$ and $M_k, \ k \in \{s, cs, cu, u\}$, are the manifolds obtained in Theorems 4.1, 4.2, 5.1, and 5.2.

**Proof.** We set $\eta = \min\{\eta_c, \eta_{cs}, \eta_{cu}\} > 0$ and let $\rho'$ be less than or equal to the minimum of the numbers $\rho(\eta)$ obtained in Theorems 4.2, 5.1, and 5.2. For $u_0 \in M_c \cap B_{X^0_c}(u_*, \rho')$, there exists the function $v$ from (4.6) with $v(0) = u_0 - u_*$, where $f(t, v) = 1$ for $|t| \leq 2$. For $s \in [0, 9/4]$ and $\sigma \in [-9/4, 0]$, we have $\|R_+ v\|_{\mathcal{E}_s(t(\sigma))} \leq c_{\rho}'_{\mathcal{E}_s} \|v\|_{\mathcal{E}_s(0, 4)}$ and $\|R_+ v\|_{\mathcal{E}_s(t(t))} \leq c_{\rho}'_{\mathcal{E}_s} \|v\|_{\mathcal{E}_s(4, 1)}$ for some constant $c_{\rho}'_{\mathcal{E}_s}$. In view of (4.10), we can decrease $\rho'$ so as to ensure that we can take $f_\pm(t, v) = 1$ for $t \in [0, 2]$ and $f_\pm(t, v) = 1$ for $t \in [-2, 0]$. Thus $f(t, v) = f_\pm(t, v)$ for $t \in \mathbb{R}_\pm$ by Remark 3.5, and so the restrictions of $v$ to $\mathbb{R}_+$ and $\mathbb{R}_-$ belong to $\bar{M}_{cs}$ and $\bar{M}_{cu}$ by (5.1) and (5.9), respectively. As a result, $u_0 \in M_{cs} \cap M_{cu}$. The converse inclusion can be shown similarly, thereby fixing a possibly smaller $\rho' =: \mathbf{p}$. The last two equalities then follow from Theorems 5.1 and 5.2.

**Remark 5.4.** We now sketch an alternative construction of a local center manifold $\bar{M}_c$ as the intersection of $M_{cs}$ and $M_{cu}$, cf. [4]. Let the assumptions of Theorem 4.2 hold. Then Theorems 5.1 and 5.2 can be proved as above so that we have local center–stable and center–unstable manifolds $M_{cs}$ and $M_{cu}$ with corresponding maps $\phi_{cs}$, $\bar{\theta}_{cs}$ and $\phi_{cu}$. For technical reasons, we need another description of $M_{cs}$. To this aim, we solve the fixed point problem

$$v = L_{P_x,A_c}(v_0) + c_{\rho}'_{\mathcal{E}_s} H_{\mathcal{E}_s}(v), \mathcal{G}_{\mathcal{E}_s}(v), \mathcal{H}_{\mathcal{E}_s}(v)$$

(5.13)

for $v_0 \in P_{cs}X^0_p$ and $v \in \mathcal{E}_s(\mathbb{R}_+, -\beta)$. As in Theorem 5.1, for sufficiently small $\eta \leq \eta_c$ we obtain a solution map $\Phi_{\mathcal{E}_s} : v_0 \mapsto v$ for (5.13), and so we can define $\theta_{cs}(z_0) = P_{cu}^0 \mathcal{N}_{\mathcal{E}_s}(\Phi_{\mathcal{E}_s}(z_0)) \in P_{cu}X_p$ and $\phi_{cs}(z_0) = \gamma_0 \Phi_{\mathcal{E}_s}(z_0) - z_0 - \theta_{cs}(z_0) \in P_{cu}X_p$ for $z_0 \in P_{cu}X^0_p$. We now fix the same $\eta$ in the construction of $M_{cs}$. It is possible to show that $M_{cs} = \{u_0 = u_* + z_0 + \theta_{cs}(z_0) + \phi_{cs}(z_0) : z_0 \in P_{cs}X^0_p\}$. For $x_0 \in P_{cs}X^0_p$, $y \in P_{cu}X_0$ and $z \in P_{cu}X_0$ with norms less than $\rho_0 > 0$, we further set

$$\Psi(y, (x_0, z)) = \left(x_0 - \phi_{cu}(y + z) + P_{cu}^0 H(y + z + \phi_{cu}(y + z)), z - \phi_{cs}(x_0 + y)\right).$$

Observe that $B_x \phi_{cu}(y + z) = B_x(y + z + \phi_{cu}(y + z)) = H(y + z + \phi_{cu}(y + z)) = B_x P_{cu}^0 H(y + z + \phi_{cu}(y + z))$ since $v_0 = y + z + \phi_{cu}(y + z)$ is the final value of a solution $v$ to the cutoff problem satisfying $f_\pm(0, v) = 1$ if $\rho_0 > 0$ is small enough. Hence, $\Psi$ maps into the set $V := P_{cu}X^0_p \times P_{cu}X_0$. Because of $\Psi(0, 0) = 0$ and $D_2 \Psi(0, 0) = I_V$, there exist $r, \rho > 0$ and $\psi \in \mathcal{C}^1(B_{X_0}(0, \rho) \cap P_{cu}X_0, B_{X_0}(0, r) \cap V)$ such that $(x_0, z) = (y) $ is the unique solution of the equation

$$\Psi(y, (x_0, z)) = 0$$

in these balls. We now introduce

$$\hat{\phi}_{cs}(y) = \psi_s(y) + \theta_{cs}(y) + \psi_u(y), \hat{\phi}_{cu}(y) = \psi_s(y) + \phi_u(y),$$

$$\hat{\mathcal{M}}_c = \{u_* + y + \hat{\phi}_{cs}(y) : y \in B_{X_0}(0, \rho) \cap P_{cu}X_p\}.$$
useful to work with the new description of $M_c$. Finally it can be seen that $\tilde{M}_c$ has analogous properties as those stated for $M_c$ in Theorem 4.2(b)–(f) and Corollary 5.3. We point out that in this approach $\tilde{M}_c$ is not constructed as the restriction of a global object such as $M_c$ in Theorem 4.2(a). In particular, for $\tilde{M}_c$ there is no counterpart for the description given by (4.6) and the invariance property of $M_c$ stated in Theorem 4.2(a).

6. Stability and attractivity of the center manifold

We now investigate the stability of the steady state $u_*$ of (1.1) and the attractivity of $M_c$. As in Theorem 4.2, we assume that Hypothesis 2.1 and (2.34) hold. In parabolic problems, the center–unstable manifold is finite dimensional in many cases; e.g., if the spatial domain $\Omega$ is bounded. Moreover, there are important applications where $M_c$ consists of equilibria only, see e.g. [10, Prop.6.4], [15]. Thus it is quite possible that one can check the stability of $u_*$ with respect to the semiflow on $M_c$ generated by (1.1) without knowing a priori that $u_*$ is stable with respect to the full semiflow of (1.1) on $M$. In Theorem 6.1 below we show that $u_*$ is stable on $M$ under the following conditions: $s(-A_0) \leq 0$, $u_*$ is stable on $M_c = M_c$, $P_c = P_c^*$ has finite rank, and the additional regularity assumption (RR) holds. In fact, we establish a stronger result saying that each solution starting sufficiently close to $u_*$ converges exponentially to a solution on $M$. Here we can assume that $s(-A_0) \leq 0$ without loss of generality since by Theorem 4.1 $-A_0$ has no spectrum in the open right halfplane if $u_*$ is stable and $P_c$ has finite rank.

Theorem 6.1. Let Hypothesis 2.1 and (RR) hold. Assume that the spectrum of $-A_0$ admits a splitting $\sigma(-A_0) = \sigma_s \cup \sigma_c$ corresponding to the spectral projections $P_s$ and $P_c$ such that $P_c$ has finite rank, $\sigma_c \subset i\mathbb{R}$, and there is a number $\alpha$ with $\max \text{Re} \sigma_s < -\alpha < 0$. Suppose that for each $r > 0$ there is a $\rho > 0$ such that for $u_0 \in M_c$ with $|P_c(u_0 - u_*)|_0 < \rho$ the solution $u$ of (1.1) exists and $u(t) \in M_c \cap B_{X_p}(u_*, r)$ for all $t \geq 0$. Then there is a $\bar{P} > 0$ such that for every $u_0 = u_* + v_0 \in M$ with $|v_0|_p \leq \bar{P}$ the solution $u = u_* + v$ of (1.1) exists on $\mathbb{R}_+$ and there is a solution $\pi$ of (1.1) on $\mathbb{R}_+$ such that $\pi(t) \in M_c$ for all $t \geq 0$ and

$$|u(t) - \pi(t)|_1 \leq ce^{-\alpha t} |P_cv_0 - \phi_c(P_cv_0)|_p$$

(6.1)

for $t \geq 1$ and a constant $c$ independent of $u_0$. As a result, $u_*$ is stable for (1.1), i.e., for each $r > 0$ there exists a $\rho > 0$ such that for every $u_0 \in M \cap B_{X_p}(u_*, r)$ the solution $u$ of (1.1) exists on $\mathbb{R}_+$ and $u(t) \in B_{X_p}(u_*, r)$ for all $t \geq 0$.

Proof. Let $u = u_* + v$ solve (1.1) with the initial value $u_0 = u_* + v_0 \in M$. We proceed in three steps: First, we derive a forward evolution equation in $P_s X_p$ for the function $w = P_s v - \phi_c(P_cv)$ on a certain interval $[0, T]$ and estimate $w$ employing this equation. Second, we take the solution $z$ on $M_c$ with $P_c z(T) = P_c v(T)$ and estimate the function $y = P_c(v - z)$ on an interval $[t_0, T]$ by means of a backward evolution equation in $P_s X_p$ for $y$. Third, using the stability of $M_c$ we show that these estimates hold for all $T \geq t_0 \geq 1$ and construct the desired solution $\pi = u_* + \pi$ on $M_c$ by letting $T \to \infty$.

Step 1. Set $-\omega_s = \max \text{Re} \sigma_s < 0$ and take constants $N \geq 1$ and $\delta \in (0, \omega_s)$ such that $\|e^{-tA_0}P_c g(x_0)\| \leq Ne^{-\delta t}$ for all $t \leq 0$. Using Theorem 4.2, we fix a radius $\rho_c > 0$ such that $\phi_c$ is globally Lipschitz with the Lipschitz constant $\ell$ as
a map from $P_c X_0 \cap \overline{B}_{X_0}(0, \rho_c)$ to $X_1$ and $X_p$, and such that $\|\phi_c'(\xi)\|_{\mathcal{B}(X_0)} \leq \ell$ for $\xi \in P_c X_0 \cap \overline{B}_{X_0}(0, \rho_c)$. We set

$$\varepsilon_1(R) = \max_{x \in X_1, |x| \leq R} \{\|G'(x)\|_{\mathcal{B}(X_1, X_0)}, \|H'(x)\|_{\mathcal{B}(X_1, X_1)}\}. \quad (6.2)$$

Due to (2.16), we can fix a (small) number $R > 0$ such that

$$d := N\varepsilon_1(R)(1 + \|P_c \Pi\|_{\mathcal{B}(X_1, X_0)})(1 + \ell \|P_c\|_{\mathcal{B}(X_0, X_1)}) < \omega_s - \delta, \quad (6.3)$$

$$R \|P_c\|_{\mathcal{B}(X_0, X_1)} \leq \rho_c. \quad (6.4)$$

Then there exists a number $r > 0$ having the following properties:

(a) $r(1 + \ell)(\|P_c\|_{\mathcal{B}(X_1, X_0)} \leq R/2$ and $r \|P_c\|_{\mathcal{B}(X_0, X_0)} \leq \rho_c$.

(b) If $|x_0| > r$ or $|P_c x_0| \leq r$, then the solution $z$ on $\mathcal{M}_c$ with $P_c x_0 = P_c z(0)$ exists on $[-2, \infty)$ and $|z(t)| \leq R$ for all $t \geq -2$.

(c) If $w_0 + u_s \in \mathcal{M}$ and $|w_0| \leq r$, then the solution $w$ of (2.21) with $w(0) = w_0$ exists for $t \in [0, 2]$, $\|w\|_{\mathcal{B}_e([0, 2])} \leq c_r$ and $|w(t)| \leq R$ (where $c_r$ is the constant given by Remark 2.3 with $T = 2$).

(d) $\hat{c} \in (c_p, c) R_p$ is not a solution of (2.21). Recall the definition of $c_p$ in (2.12) and (2.13).

(To obtain (b) and (c), we use the stability of $u_s$ in $\mathcal{M}_c$, Theorem 4.2, and [12, Prop. 15].) Take $w_0 = v_0 + u_s \in \mathcal{M}$ with $|v_0| \leq \rho \leq \rho_1 \leq r$, where $\rho_1 > 0$ is chosen such that the solution $v$ of (2.21) exists on $[0, 4]$ and $|v(t)| \leq \rho$ for all $t \leq 4$. (Use Remark 2.3 and (2.11).) Hence, $|v(t)| \leq R$ for all $1 \leq t \leq 4$ and $|P_c v(t) - v(t)| \leq \rho_4$ for $0 \leq t \leq 4$ by Properties (c) and (a).) Let $T \geq 4$ be the supremum of all $t'$ such that the solution $v(t)$ exists on $[0, t']$ and $|v(t)| \leq r$ for all $t \in [0, t']$. Seeking a contradiction, we suppose that $T < \infty$. Then $T$ is in fact the maximum of all $t'$ as above, and $|v(t)| \leq R$ for $1 \leq t \leq T$, due to Property (c). Define

$$w = P_c v - \phi_c(P_c v), \quad w_0 = w(0), \quad x = v - w = P_c v + \phi_c(P_c v) \quad (6.5)$$

on $[0, T]$. Observe that $u_s + x(t) \in \mathcal{M}_c$ and $P_c x(t) = P_c v(t)$ for $t \in [0, T]$ and that, in general, $x$ is a solution of (2.21). Recall the definition of $A_0$, $N_1$ and $\Pi$, cf. (2.23). Using (2.21), (4.8), (4.9), (6.5), we deduce that

$$B_c w(t) = H(v(t)) - B_c \phi_c(P_c v(t)) = H(v(t)) - H(x(t)) = h(t), \quad (6.6)$$

$$\dot{w}(t) = P_c (-A_c v(t) + G(v(t))) - \phi_c'(P_c v(t)) P_c [G(v(t)) - A_c v(t)]$$

$$= -\phi_c'(P_c v(t)) P_c [A_c x(t) - G(x(t))] + P_c (A_c x(t) - G(x(t)))$$

$$= -A_0 P_c (A_0 + \mu)(w(t) - N_1 h(t)) + \mu P_c w(t) + P_c (G(v(t)) - G(x(t)))$$

$$+ \phi_c'(P_c v(t)) P_c [(A_0 + \mu)(w(t) - N_1 h(t)) - \mu w(t) + G(x(t)) - G(v(t))]$$

$$= -A_0 P_c w(t) + \Pi \dot{h}(t) + P_c (G(v(t)) - G(x(t)))$$

$$- \phi_c'(P_c v(t)) P_c [\Pi h(t) + G(v(t)) - G(x(t))]$$

for $t \in [0, T]$, where we also employed (6.6) in the second part and $\dot{w}(t)$ exists in $X_0$. Setting $g = G(v(t) - G(x(t)) - \phi_c'(P_c v) P_c [\Pi h(t) + G(v(t)) - G(x(t))]$, we obtain

$$w(t) = T(t - \tau) P_c w(\tau) + \int_\tau^t T(-\sigma) P_c [g(\sigma) + \Pi h(\sigma)] d\sigma$$

for $0 \leq \tau \leq t \leq T$. We take $t \in [0, T - 2]$ and $\alpha \in (0, \omega_s)$. In view of (6.6) and the exponential stability of $e_{\alpha} T(\cdot) P_c$, we can argue as in the proof of Proposition 8 in
[12] (see inequality (43)) and estimate:
\[ e^{-\alpha \tau} \|w\|_{E_1([\tau,T],\alpha)} \leq \tilde{c}_0 \left[ |w(\tau)|_\rho + e^{-\alpha \tau} \|g\|_{E_0([\tau,T],\alpha)} + e^{-\alpha \tau} \|h\|_{E([\tau,T],\alpha)} \right], \]  
with a constant \( \tilde{c}_0 \) independent of \( \tau, T, \alpha, \rho \), and chosen uniformly for \( \alpha \) contained in compact intervals in \((0, \omega_\alpha)\). Since \(|P_tw(t)|_0 \leq \rho_\alpha \) for \( t \in [0,T] \) by (a), formula (6.5) yields \( \|x\|_{E_1(J)} \leq c_P \|v\|_{E_1(J)} \) for intervals \( J \subset [0,T], \) where \( c_P = (1 + \ell)(\|P_c\|_{g(X_1)} + \|P_c\|_{g(Y_1,X_0)}) \). So we conclude from (6.7) and Remarks 2.3 and 3.7 that
\[ e^{-\alpha \tau} \|\phi\|_{E_1([\tau,T],\alpha)} \leq \tilde{c}_0 |\phi(\tau)|_\rho + \tilde{c}_2 (c_P \|G\|_{E_1([\tau,T],\alpha)}) e^{-\alpha \tau} \|\phi\|_{E_1([\tau,T],\alpha)}, \]
where \( c_P \) is the constant given by Remark 2.3 and
\[ \tilde{c}_2 := \tilde{c}_0 [2 + \ell(\|P_c\|_{g(X_n)} + \|P_c\|_{g(Y_1,X_0)})]. \]
Hence, for \( 0 \leq \tau \leq t \leq T \) with \( T - \tau \geq 2 \), Property (d) above and (2.11) imply that
\[ e^{-\alpha \tau} \|\phi\|_{E_1([\tau,T],\alpha)} \leq \tilde{c}_0 |\phi(\tau)|_\rho + \frac{1}{2} e^{-\alpha \tau} \|\phi\|_{E_1([\tau,T],\alpha)}, \]
\[ e^{\alpha(t-\tau)} |\phi(t)|_\rho \leq \tilde{c}_0 e^{-\alpha \tau} \|\phi\|_{E_1([\tau,T],\alpha)} \leq 2 \tilde{c}_0^2 |\phi(\tau)|_\rho. \]

**Step 2.** By Property (b), there exists a number \( a \leq T - 2 \) and a solution \( z(\cdot;T,P_tv(T)) = z = P_c z + \phi_c(P_c z) \) on \( \mathcal{M}_c \) of (2.21) on \([a,T]\) with \( P_c z(T) = P_c v(T) \). Also, there is a minimal number \( t_0 \in [1,T - 2] \) such that \( z(t) \in \mathcal{M}_c \) exists and \( |z(t)|_1 \leq R \) for \( t_0 \leq t \leq T \). We set \( y = P_c(v - z) \) and note that
\[ v - z = y + \phi_c(P_c v) - \phi_c(P_c z). \]
Since \( v \) and \( z \) solve (2.21), we obtain
\[ B_c(v(t) - z(t)) = H(v(t)) - H(z(t)) = h_1(t), \]
\[ \dot{y}(t) = P_c(-A_c(v(t) - z(t)) + P_c(G(v(t)) - G(z(t)) \]
\[ = -P_c[(A_0 + \mu)(v(t) - z(t) - \mathcal{N} \tilde{h}_1(t)) - \mu(v(t) - z(t))] + P_c g_1(t) \]
\[ = -A_0 P_c y(t) + P_c \mathcal{N} \tilde{h}_1(t) + P_c g_1(t) \]
(6.11)
for \( t \in [t_0,T], \) where \( g_1(t) := G(v(t)) - G(z(t)) \). Since \( y(T) = 0 \) and \( |v(t)|_1, |z(t)|_1 \leq R, \) equation (6.11) implies (cf. (6.2)) that
\[ g(t) = -\int_t^T e^{-(t-\tau)A_0} P_c(\mathcal{N} \tilde{h}_1(\tau) + \mathcal{N} \tilde{h}_1(\tau)) d\tau, \]
\[ |g(t)|_0 \leq \int_t^T Ne^{-(t-\tau)} (1 + \|P_c\|_{g(Y_1,X_0)}) |e_1(R)| |v(\tau) - z(\tau)|_1 d\tau. \]
Recalling the definition of \( d \) in (6.3) and setting \( d_0 = (1 + \ell \|P_c\|_{g(X_0,X_1)})^{-1} \), we then deduce from (6.10) and (6.4) that
\[ e^{d_t} |g(t)|_0 \leq d \int_t^T e^{d_{\tau}} |g(\tau)|_0 d\tau + d_0 \int_t^T e^{d_{\tau}} |v(\tau)|_1 d\tau. \]

Gronwall’s inequality and Fubini’s theorem thus yield
\[ e^{d_t} |g(t)|_0 \leq d_0 \int_t^T e^{d_{\tau}} |v(\tau)|_1 d\tau + dd_0 \int_t^T e^{d(\tau-\tau)} \int_\tau^T e^{d_{\sigma}} |v(\sigma)|_1 d\sigma d\tau \]
\[ = d_0 \int_t^T e^{d_{\tau}} |v(\tau)|_1 d\tau + dd_0 \int_t^T e^{d_{\tau}} |v(\tau)|_1 \int_\tau^T e^{d(\tau-\sigma)} d\sigma d\tau \]
\[ = d_0 \int_t^T e^{d_{\tau}} |v(\tau)|_1 d\tau + dd_0 \int_t^T e^{d_{\tau}} |v(\tau)|_1 \int_\tau^T e^{d(\tau-\sigma)} d\sigma d\tau. \]
There is an \( \alpha \in (d + \delta, \omega_s) \) due to (6.3). Hölder’s inequality and (6.9) thus lead to
\[
|y(t)|_0 \leq d_0 \int_0^T e^{(d+\delta)(\sigma-t)}|w(\sigma)|_1 \; d\sigma \leq c e^{-\alpha t} \|w\|_{E_1([t,T],\alpha)} \leq c |w(t)|_p \tag{6.12}
\]
for \( t \in [t_0,T] \) with \( T - t \geq 2 \). Here and below the constants \( c \) do not depend on \( t, t_0, T, v, \rho \). Observe that \( z = P_c(v - y) + \phi_c(P_c(v - y)) \). Employing (6.4), \( |v(t_0)|_p \leq r \), Property (a), (6.12) (6.9) and (6.5), we then estimate:
\[
|z(t_0)|_1 \leq (1 + \ell) (|P_c|_{\mathcal{F}_n(X_n, X_1)} |y(t_0)|_0 + |P_c|_{\mathcal{F}_n(X_n, X_1)} |v(t_0)|_p)
\leq c |w(t_0)|_p + R/2 \leq c |w(0)|_p + R/2 \leq c |v_0|_p + R/2.
\]
So we can find \( \rho_2 \in (0, \rho_1] \) such that \( |z(t_0)|_1 \leq 3R/4 \) if \( |v_0|_p \leq \rho \leq \rho_2 \). As a result, \( t_0 = 1 \) and
\[
|P_c z(1)|_0 \leq |y(1)|_0 + |P_c v(1)|_0 \leq c (|w(1)|_p + |v(1)|_p) \leq c |v(1)|_p \leq c |v_0|_p, \tag{6.13}
\]
where we used (6.12), (6.5), Remark 2.3, and (2.11). In view of (6.13) and the assumed stability of \( M_c \), there exists a \( \rho_3 \in (0, \rho_2] \) such that \( |z(T)|_p \leq \rho/2 \) if \( |v_0|_p \leq \rho \leq \rho_2 \). From (6.10), (6.12) and (6.9), we then deduce
\[
|v(T)|_p \leq |z(T)|_p + |y(T)|_p + \ell |y(T)|_0 + |w(T)|_p \leq \frac{\rho}{4} + c |w(0)|_p \leq \frac{\rho}{4} + c |v_0|_p < r,
\]
if we take \( |v_0|_p \leq \rho \leq \rho_4 \) for a sufficiently small \( \rho_4 \in (0, \rho_3] \). This fact contradicts the choice of \( r \) so that \( T = \infty \); i.e., \( v \) solves (2.21) on \( \mathbb{R}_+ \) and \( |v(t)|_p \leq r \) for all \( t \geq 0 \). Therefore (6.9) and (6.12) hold for all \( T \geq 4 \) with uniform constants.

**Step 3.** In (6.13) we have seen that \( P_c z(1) = P_c z(1; T, P_c v(T)) \) is bounded by \( c |v_0|_p \) for all \( T \geq 4 \). We fix \( \rho \in (0, \rho_1] \) with \( \rho/4 \leq r \) and take \( v_0 \) with \( |v_0|_p \leq \rho \leq \rho_4 \). Since \( P_c \) has finite rank, there are \( T_n \to \infty \) such that \( P_c z(1; T_n, P_c v(T_n)) \) converges to some \( \zeta \in P_c X_0 \) with \( |\zeta|_0 \leq \rho_0 \leq r \). Let \( \zeta \) be the solution on \( M_c \) with \( P_c \zeta(1) = \zeta \). By Property (b) and (6.4), \( \zeta(t) \in M_c \) exists for all \( t \geq 0 \) and \( |P_c \zeta(t)|_0 \leq \rho_0 \). The functions \( P_c \zeta \) and \( P_c z(1; T_n, P_c v(T_n)) \) satisfy the ode (4.7) so that
\[
P_c \zeta(t) = \lim_{n \to \infty} P_c z(t_1; 1, P_c z(1; T_n, P_c v(T_n))) = \lim_{n \to \infty} P_c z(t; T_n, P_c v(T_n)).
\]
Estimates (6.12) and (6.9) thus yield
\[
|P_c (v(t) - \zeta(t))|_0 = \lim_{n \to \infty} |P_c (v(t) - z(t; T_n, P_c v(T_n)))|_0 \leq c |w(t)|_p \leq c e^{-\alpha t} |w_0|_p
\]
for \( t \geq 1 \). Combining this inequality with (6.5) and (6.9), we also obtain
\[
|P_c (v(t) - \zeta(t))|_p \leq |w(t)|_p + |\phi_c(P_c v(t)) - \phi_c(P_c \zeta(t))|_p \leq c e^{-\alpha t} |w_0|_p.
\]
Inequality (6.1) now follows from the two preceding estimates and Theorem A.1. Moreover, \( |v(t)|_p \leq |v(t) - \zeta(t)|_p + |\zeta(t)|_p \leq c p + |\zeta(t)|_p \) for \( t \geq 0 \). Since \( |\zeta|_0 \leq \rho_0 \), the stability of \( \zeta \) is a consequence of the stability of \( M_c \).

**Appendix A. An additional regularity result**

We now establish an improved version of Proposition 15 of [12] needed to show that the center, center-unstable and unstable manifolds are Lipschitz in \( X_1 \).

**Theorem A.1.** Assume hypothesis (RR), and that (E) and (LS) hold at a function \( u_0 \in X_p \) with \( B(u_0) = 0 \). Fix a number \( T > 0 \) which is strictly smaller than the maximal existence time \( t^*(u_0) \) of the solution \( u \) of (1.1) such that conditions (E) and (LS) hold at the function \( u(t) \) for each \( t \in [0, T] \). Then there exists a \( \rho > 0 \)
such that for each initial value $v_0 \in \mathcal{M}$ with $|v_0 - u_0|_\rho \leq \rho$ the solution $v$ of (1.1) with $v(0) = v_0$ satisfies

\[ \|t(\dot{v} - \dot{u})\|_{E_\rho([0,T])} \leq c |v_0 - u_0|_\rho, \]

(A.1)

where the constant $c$ is independent of $v_0$ but may depend on $u, T, \rho$. In particular, for each $\tau \in (0,T)$ we have

\[ \|v - u\|_{C^{\frac{1}{1+\rho}}(\tau, T); X_1)} \leq c(\tau) |v_0 - u_0|_\rho. \]

(A.2)

Proof. The existence of a solution $v$ with the initial value $v_0 \in B(X_\rho(u_0, \rho)$ was shown in [12, Thm.14] for sufficiently small $\rho > 0$, whereas the number $T > 0$ exists due to Remark 1 of [12]. Similarly, there is an $\epsilon \in (0, 1/2)$ such that $T' = (1 + \epsilon)T < t^+(u_0)$ and (E), (LS) hold at all functions $u(t)$ for $t \in J = [0, T']$. We set $z(t) = v(t) - u(t)$, $z_0 = v_0 - u_0$, and $w_\lambda(t) = v(\lambda t) - u(\lambda t)$ for $t \in J = [0, T]$ and $\lambda \in (1 - \epsilon, 1 + \epsilon)$. As in Section 2 of [12], we define $A_\lambda(t), B_\lambda(t), G(t, \cdot)$, and $H(t, \cdot)$ as in (2.15), (2.17), and (2.18) replacing $u_*$ by $u(t)$. Note that $z$ solves the resulting version of equation (2.21) with $A_\lambda$ replaced by $A_\lambda(t)$ and $B_\lambda$ replaced by $B_\lambda(t)$. Moreover, we denote by $S$ the solution operator of the corresponding version of equation (2.22), see [12, Thm.2]. Then $w_\lambda$ satisfies:

\[ \partial_t w_\lambda(t) = \lambda(\dot{v}(\lambda t) - \dot{u}(\lambda t)) = \lambda(-A_\lambda(t)(v(\lambda t) - u(\lambda t)) + G(\lambda t, v(\lambda t) - u(\lambda t))), \quad \text{on } \Omega, t > 0, \]

\[ B_\lambda(\lambda t)w_\lambda(t) = H(\lambda t, v(\lambda t) - u(\lambda t)), \quad \text{on } \partial \Omega, t > 0, \]

\[ w_\lambda(0) = z_0, \quad \text{on } \Omega. \]

So $w_\lambda$ solves the initial-boundary value problem

\[ \partial_t w(t) + A_\lambda(t)w(t) = G(\lambda, w)(t), \quad \text{on } \Omega, t > 0, \]

\[ B_\lambda(t)w(t) = H(\lambda, w)(t), \quad \text{on } \partial \Omega, t > 0, \]

(A.3)

\[ w_0 = z_0, \quad \text{on } \Omega, \]

where we introduced the maps

\[ G(\lambda, w)(t) = (A_\lambda(t) - \lambda A_\lambda(t))w(t) + \lambda G(\lambda t, w(t)), \]

\[ \mathbb{H}(\lambda, w)(t) = (B_\lambda(t) - \lambda B_\lambda(t))w(t) + H(\lambda t, w(t)), \]

for $w \in \mathbb{E}_1(J), t \in J$, and $\lambda \in (1 - \epsilon, 1 + \epsilon)$. We observe that

\[ G(\lambda, w)(t) = A(u(t))w(t) + A'(u(t))(w(t), u(t)) - F'(u(t))w(t) - \lambda A(u(\lambda t) + w(t))(A(\lambda t) + w(t)) + \lambda A(u(\lambda t))u(\lambda t), \]

\[ \mathbb{H}(\lambda, w)(t) = B'(u(t))w(t) - B(u(\lambda t) + w(t)). \]

(A.4)

We claim that the map $\lambda \mapsto u(\lambda t)$ belongs to $C^1((1 - \epsilon, 1 + \epsilon), \mathbb{E}_1(J))$. Indeed, for $\mu, \lambda \in (1 - \epsilon, 1 + \epsilon) \subseteq (1/2, 3/2)$ we have:

\[ u(\mu t) - u(\lambda t) - (\mu - \lambda)u'(\lambda t) = \frac{\mu - \lambda}{\lambda} \int_0^1 \lambda t u'(\lambda t + \theta(\mu - \lambda) t) - u'(\lambda t)) d\theta \]

\[ = \frac{\mu - \lambda}{\lambda} \int_0^1 \left( ((\lambda + \theta(\mu - \lambda)) t)u'(\lambda t + \theta(\mu - \lambda) t) - \lambda t u'(\lambda t)) d\theta \]
We note that the expression in the square brackets in the last interval is contained in \([0,2]\), and recall that \(tu' \in \mathcal{E}_1(J')\) due to \([12, \text{Thm.14}]. Moreover, the dilation operators \(T_a\) given by \(T_a f(t) = f(at)\) on \(\mathcal{E}_1(\mathbb{R}_+)\) are strongly continuous in \(a > 0\).

(Below, we extend \(u\) from \(\mathcal{E}_1(J')\) to \(\mathcal{E}_1(\mathbb{R}_+)\) to use the strong continuity.) Thus \((A.6)\) yields

\[
\|u(\mu) - u(\lambda) - (\mu - \lambda)tu'(\lambda)\|_{\mathcal{E}_1(J)} \\
\leq 2|\mu - \lambda| \varepsilon(\theta|\mu - \lambda|) + c|\mu - \lambda|^2 \\
\leq |\mu - \lambda| \varepsilon(|\mu - \lambda|),
\]

showing that \(\partial_3 u(\lambda) = tu'(\lambda)\) in \(\mathcal{E}_1(J)\). Since also

\[
tu'(\lambda) - tu'(\mu) = \lambda^{-1}(\lambda tu'(\lambda) - \mu tu'(\mu)) + (\lambda^{-1} - \mu^{-1})\mu tu'(\mu),
\]

the map \(\lambda \mapsto u(\lambda) \in \mathcal{E}_1(J)\) is continuously differentiable. Combining this fact with the observations in \([12, \S2]\), we see that the map \((\lambda, w) \mapsto G(\lambda, w) \in \mathcal{E}_0(J)\) is continuously differentiable with \(G(1, w) = G(w), \partial_{\lambda} G(1, w) = G'(w), \partial_{w} G(1, w) = G'(w)\), and

\[
\begin{align*}
\partial_1 G(1, w) &= (A(u) - A(u + w))u - A(u + w)w + F(u + w) - F(u) \\
&\quad + (A'(u) - A'(u + w))[tu', u] - A'(u + w)[tu', w] \\
&\quad + (A(u) - A(u + w))tu' + (F(u + w) - F(u))tu', \quad (A.7)
\end{align*}
\]

We claim that \(B'(u) \in B(\mathcal{E}_1(J), \mathbb{R}(J))\). Indeed, due to Proposition 10(1b) of \([12]\) with \(u_0 = 0\) we only need to check that \(B'(0) \in B(\mathcal{E}_1(J), \mathbb{R}(J))\) which follows from (16) and (17) in \([12]\) and \([17, \text{Thm.4.6.4.1}]. Proposition 10 of [12] then implies that the map \(v \mapsto B(v)\) belongs to \(C^1(\mathcal{E}_1(J), \mathbb{R}(J))\). Therefore the map \((\lambda, w) \mapsto H(\lambda, w)\) is contained in \(C^1((1-\epsilon, 1+\epsilon) \times \mathcal{E}_1(J), \mathbb{R}(J))\) with

\[
H(1, w) = H(w), \quad \partial_3 H(1, w) = H'(w) \\
\partial_1 H(1, w) = -B'(u + w)tu' = (B'(u) - B'(u + w))tu', \quad (A.8)
\]

using that \(B(u(\lambda)) = 0\), and hence \(0 = \frac{d}{d\lambda} B(u(\lambda)) = B'(u(\lambda))tu'\). In order to solve \((A.3)\), we set

\[
\begin{align*}
\mathcal{L}(\lambda, w) &= w - S(z_0 - N_p H(0, z_0) + N_p \gamma_0 H((\lambda, w), G(\lambda, w), H(\lambda, w)), \quad (A.9)
\end{align*}
\]

where \(N_p \in B(\mathcal{E}_p, X_p)\) is a right inverse of \(B'(u_0) = B_0(0)\) (see \([12, \text{Prop.5}].\) Because of \(B(u_0 + z_0) = 0\), we infer:

\[
B_0(0)[z_0 - N_p H(0, z_0) + N_p \gamma_0 H((\lambda, w)))] = H(\lambda, w)(0).
\]

Therefore Theorem 2 of \([12], (2.13)\), and the properties of \(G\) and \(H\), established above, show that \(\mathcal{L} \in C^1((1-\epsilon, 1+\epsilon) \times \mathcal{E}_1(J), \mathcal{E}_1(J))\) and that

\[
\begin{align*}
\mathcal{L}(1, z) &= z - S(z_0, G(z), H(z)) = 0, \\
\partial_3 \mathcal{L}(1, z) &= I - S(N_p \gamma_0 H'(z), G'(z), H'(z)).
\end{align*}
\]

Since \(\|z\|_{\mathcal{E}_1(J)} \leq c|z_0|_p \leq cp\) by \([12, \text{Thm.14}].\), Theorem 2 and Proposition 10 of \([12]\) and (2.13) imply that \(\partial_3 \mathcal{L}(1, z)\) is invertible if \(p\) is sufficiently small. So we obtain a function \(\Psi \in C^1((1-\epsilon, 1+\epsilon), \mathcal{E}_1(J))\) for some \(0 < \epsilon < \delta\) satisfying \(\Psi(1) = z\) and \(\mathcal{L}(\lambda, \Psi(\lambda)) = 0\). Set \(w_0(\lambda) = \Psi(\lambda)(0)\). Using \([12, \text{Cor.12}].\) in the estimate, we derive

\[
\begin{align*}
w_0(\lambda) - z_0 &= N_p(\Psi(\lambda)(0) - H(0, z_0)) \\
&= N_p(B'(u_0)w_0(\lambda) - B(u_0 + w_0(\lambda)) - B'(u_0)z_0 + B(u_0 + z_0)) \\
&= -N_p(B(u_0 + w_0(\lambda)) - B(u_0 + z_0)) - B'(u_0 + z_0)(w_0(\lambda) - z_0) \\
&\quad + N_p(B'(u_0) - B'(u_0 + z_0))(w_0(\lambda) - z_0), \quad (A.10)
\end{align*}
\]
\(|w_0(\lambda) - z_0|_p \leq c_\varepsilon(|z_0 - w_0(\lambda)|_p)w_0(\lambda) - z_0|_p + c_\varepsilon(|z_0|_p)|w_0(\lambda) - z_0|_p.\)

Observe that \(|z_0 - w_0(\lambda)|_p \leq c \|z - \Psi(\lambda)\|_{E(\gamma)}\) by (2.11). Decreasing \(\hat{\varepsilon} > 0\) and \(\rho > 0\) if necessary, we thus conclude that \(w_0(\lambda) = z_0\). Hence, \(\Psi(\lambda)\) solves (A.3) due to (A.10) and (A.9). Possibly after decreasing \(\hat{\varepsilon} > 0\) once more, we deduce that \(\Psi(\lambda) = w_\lambda\) from (A.3) and Theorem 2 and Proposition 10 of [12]. As a result,

\[
t(\dot{v} - \dot{u}) = \Psi'(1) = -\partial_2L(1, z)^{-1}\partial_2L(1, z)
- \partial_2L(1, z)^{-1}S(N_p, \gamma_0, \Omega_1 \mathbb{H}(1, z), \partial_1G(1, z), \partial_1H(1, z)).
\]

Theorem 2 of [12], (A.7), (A.8), (2.7), (RR), and Lemma A.2 below now yield

\[
\|t(\dot{v} - \dot{u})\|_{E_1(\gamma)} \leq c(\|\partial_1G(1, z)\|_{E_0(\gamma)} + \|\partial_1H(1, z)\|_{F(\gamma)}) \leq c\|v - u\|_{E_1(\gamma)}.
\]

which is (A.1). Finally, for \(\tau \in (0, T)\) Sobolev’s embedding theorem implies that

\[
\|v - u\|_{C^{1-1/p}\left(\{\tau, T\}, X_1\right)} \leq c\|v - u\|_{W^{1,p}_p(\{\tau, T\}, X_1)} \leq c(\tau)\|\dot{v} - \dot{u}\|_{E_1(\gamma)} + c(\gamma)\|v - u\|_{E_1(\gamma)} \leq c(\tau)\|v - u\|_{E_1(\gamma)}.
\]

The proof of the following lemma is omitted. It uses arguments from the proof of Proposition 10 in [12].

**Lemma A.2.** Assume that (RR) holds and \(J = [0, T]\). Then the map \(v \mapsto B'(v) \in B(E_1(\gamma), F(\gamma))\) is locally Lipschitz on \(E_1(\gamma)\).

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Y. Latushkin, Department of Mathematics, University of Missouri, Columbia, MO 65211, USA.

E-mail address: yuri@math.missouri.edu

J. Prüss, FB Mathematik und Informatik, Martin-Luther-Universität, 06099 Halle, Germany.

E-mail address: pruess@mathematik.uni-halle.de

R. Schnaubelt, Department of Mathematics, University of Karlsruhe, 76128 Karlsruhe, Germany.

E-mail address: schnaubelt@math.uni-karlsruhe.de