

Verification Methods for the Horizontal Linear Complementarity Problem

Uwe Schäfer*

Institut für Angewandte und Numerische Mathematik, Universität Karlsruhe, D-76128 Karlsruhe

© 2008 WILEY-VCH Verlag GmbH & Co. KGaA, Weinheim

1 Introduction

Given $N, M \in \mathbb{R}^{n \times n}$ and $q \in \mathbb{R}^n$ the horizontal linear complementarity problem (HLCP) is to find two vectors $w, z \in \mathbb{R}^n$ satisfying

$$Nw - Mz = q, \quad w \geq o, \quad z \geq o, \quad w^T z = 0$$

or to show that no such vectors exist. Here, the \geq -sign is meant componentwise. If N is the identity, then the HLCP is a classical LCP. For an application of the HLCP we refer to [3].

Sometimes by reordering of the columns of N and of M the new N is invertible and the HLCP can be reduced to the classical LCP. See [5]. However, nothing guarantees the existence of such a reordering.

Example 1: Let

$$N = \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix}, \quad M = \begin{pmatrix} 2 & 2 \\ 2 & 2 \end{pmatrix}.$$

Then no reordering of any columns of N and of M results in an invertible matrix. □

Moreover, if the reduction is possible, the matrix inversion might be ill-conditioned. So we attack the HLCP directly. See also [3], [4], [7].

Lemma 1: Let $N, M \in \mathbb{R}^{n \times n}$ and $q \in \mathbb{R}^n$. Furthermore, let

$$f(x) := (N + M)x - (N - M)|x| + q, \tag{1}$$

where $|x| = (|x_i|) \in \mathbb{R}^n$. If $f(x^*) = o$, then

$$w := |x^*| - x^*, \quad z := |x^*| + x^* \tag{2}$$

is a solution of HLCP defined by N, M, q .

Proof: From (2) we have

$$w \geq o, \quad z \geq o. \tag{3}$$

On the other hand, it is

$$\left. \begin{array}{l} x_i^* \geq 0 \Rightarrow w_i = 0 \\ x_i^* < 0 \Rightarrow z_i = 0 \end{array} \right\} \quad i = 1, \dots, n. \tag{4}$$

Finally, we have $o = f(x^*) = (N + M)x^* - (N - M)|x^*| + q$. This is equivalent to

$$N(|x^*| - x^*) - M(|x^*| + x^*) = q. \tag{5}$$

Therefore, due to (2)-(5), w and z solve the HLCP defined by N, M and q . □

If N is the identity; i.e., $N = I$, and if $I + M$ is regular, then

$$f(x^*) = o \Leftrightarrow x^* = (I + M)^{-1} \left((I - M) \cdot |x^*| - q \right). \tag{6}$$

The fixed point iteration based on (6) was developed in [6] and was called the modulus algorithm. See also [2].

* E-mail: Uwe.Schaefer@math.uni-karlsruhe.de, Phone: +49 721 608 7746, Fax: +49 721 608 3767

```

for  $j := 1$  to  $n$  do begin
if  $\underline{x}_j \geq 0$  then  $G(\hat{x}, [x])_{.j} := 2 \cdot M_{.j}$ 
else if  $\bar{x}_j \leq 0$  then  $G(\hat{x}, [x])_{.j} := 2 \cdot N_{.j}$ 

else if  $\hat{x}_j \geq 0$  then  $G(\hat{x}, [x])_{.j} := N_{.j} + M_{.j} - \left[ \frac{\hat{x}_j + \underline{x}_j}{\hat{x}_j - \underline{x}_j}, 1 \right] \cdot (N_{.j} - M_{.j})$ 

           else  $G(\hat{x}, [x])_{.j} := N_{.j} + M_{.j} - \left[ -1, \frac{\bar{x}_j + \hat{x}_j}{\bar{x}_j - \hat{x}_j} \right] \cdot (N_{.j} - M_{.j})$ 

end.

```

Table 1 Algorithm for calculating $G(\hat{x}, [x])$

2 Verification methods

Let $[x] = ([\underline{x}_i, \bar{x}_i])$ be an n -dimensional interval vector; i.e., $[x]$ is a vector where the components are intervals. Furthermore, let $f : [x] \rightarrow \mathbb{R}^n$ be a continuous function. If there exists an interval matrix $G(\hat{x}, [x])$ such that for fixed $\hat{x} \in [x]$ one can conclude that

$$\forall y \in [y] \exists G(\hat{x}, y) \in G(\hat{x}, [x]) : f(y) - f(\hat{x}) = G(\hat{x}, y) \cdot (y - \hat{x}), \quad (7)$$

we define the so-called Krawczyk-Operator $K(\hat{x}, R, [x]) := \hat{x} - R \cdot f(\hat{x}) + (I - R \cdot G(\hat{x}, [x])) \cdot ([x] - \hat{x})$, where $R \in \mathbb{R}^{n \times n}$ has to be a regular matrix. If

$$K(\hat{x}, R, [x]) \subseteq [x], \quad (8)$$

then there exists $\xi \in K(\hat{x}, R, [x])$ with $f(\xi) = 0$. See [1]. Concerning the function f from (1) a corresponding interval matrix $G(\hat{x}, [x])$ satisfying (7) is given in Table 1. The proof of this fact will be published elsewhere.

Example 2: Let $N = 1$, $M = \frac{1}{2}$ and $q = -\frac{1}{10}$. Then, $f(x) = (N + M) \cdot x - (N - M) \cdot |x| + q = \frac{3}{2}x - \frac{1}{2}|x| - \frac{1}{10}$. Since $f(\frac{1}{20}) = -\frac{1}{20}$ we have that $\tilde{x} := \frac{1}{20}$ is an ε -approximation for $\varepsilon = 0.1$ and for $f(x) \stackrel{!}{=} 0$. Defining $\hat{x} := \tilde{x} = \frac{1}{20}$ and $[x] := [\tilde{x} - \varepsilon, \tilde{x} + \varepsilon] = [-\frac{1}{20}, \frac{3}{20}]$, Table 1 gives $G(\hat{x}, [x]) = 1 + \frac{1}{2} - \left[\frac{\frac{1}{20} - \frac{1}{20}}{\frac{1}{20} + \frac{1}{20}}, 1 \right] (1 - \frac{1}{2}) = [1, \frac{3}{2}]$. Choosing $R := \frac{4}{5}$ we get

$$K(\hat{x}, R, [x]) = \frac{1}{20} - \frac{4}{5} \left(-\frac{1}{20} \right) + \left(1 - \frac{4}{5} \cdot [1, \frac{3}{2}] \right) \cdot \left(\left[-\frac{1}{20}, \frac{3}{20} \right] - \frac{1}{20} \right) = \left[\frac{7}{100}, \frac{11}{100} \right] \subseteq [x].$$

So, by [1], within $[\frac{7}{100}, \frac{11}{100}]$ there is a zero of f . Using Lemma 1 we get that $w^* = 0$ and some $z^* \in [0.14, 0.22]$ are a solution of the HLCP. For the sake of completeness, we mention that the unique solution is $w^* = 0$, $z^* = \frac{2}{10}$. \square

Bigger examples, where the verification test (8) is done by a machine, will be published elsewhere.

References

- [1] G. E. Alefeld, X. Chen and F. A. Potra, Numerical validation of solutions of linear complementarity problems, Numer. Math. **83**, pp. 1-23 (1999).
- [2] B. C. Eaves and C. E. Lemke, Equivalence of LCP and PLS, Math. Oper. Res. **6**, pp. 475-484 (1981).
- [3] B. de Moor, L. Vandenberghe and J. Vandewalle, The generalized linear complementarity problem and an algorithm to find all its solutions, Math. Program. **57**, pp. 415-426 (1992).
- [4] F. A. Potra, Corrector-predictor methods for monotone linear complementarity problems in a wide neighborhood of the central path, Math. Program. **111**, pp. 243-272 (2008).
- [5] R. H. Tütüncü and M. J. Todd, Reducing horizontal linear complementarity problems, Linear Algebra Appl. **223/224**, pp. 717-729 (1995).
- [6] W. M. G. van Bokhoven, Piecewise linear modelling and analysis, Proefschrift, Eindhoven 1981.
- [7] Y. Zhang, On the convergence of a class of infeasible interior-point methods for the horizontal linear complementarity problem, SIAM J. Optim. **4**, pp. 208-227 (1994).