

H2020

McSAFE

High Performance Monte Carlo for Safety

Coupling TRANSURANUS with Monte Carlo and subchannel codes for pin-by-pin depletion in LWR

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McSAFE EU H2020 project



- Objectives:
 - Improve the prediction of local safety parameters through high-fidelity.
 - Develop multiphysics tools based on Monte Carlo particle transport, subchannel thermalhydraulics and fuel-performance analysis.
 - Solve steady-state, depletion and transient problems.
 - Optimize the codes for massive problems such as full-core burnup.
 - Validate with PWR and VVER plant data.
- Participants:
 - KIT (SUBCHANFLOW).
 - JRC, HZDR (TRANSURANUS).
 - VTT (Serpent2).
 - CEA (Tripoli), DNC (MCNP), AMEC (MONK), NRI, KTH.
 - EKK, CEZ, EdF.
- Continuation of the NURESAFE and HPMC projects.



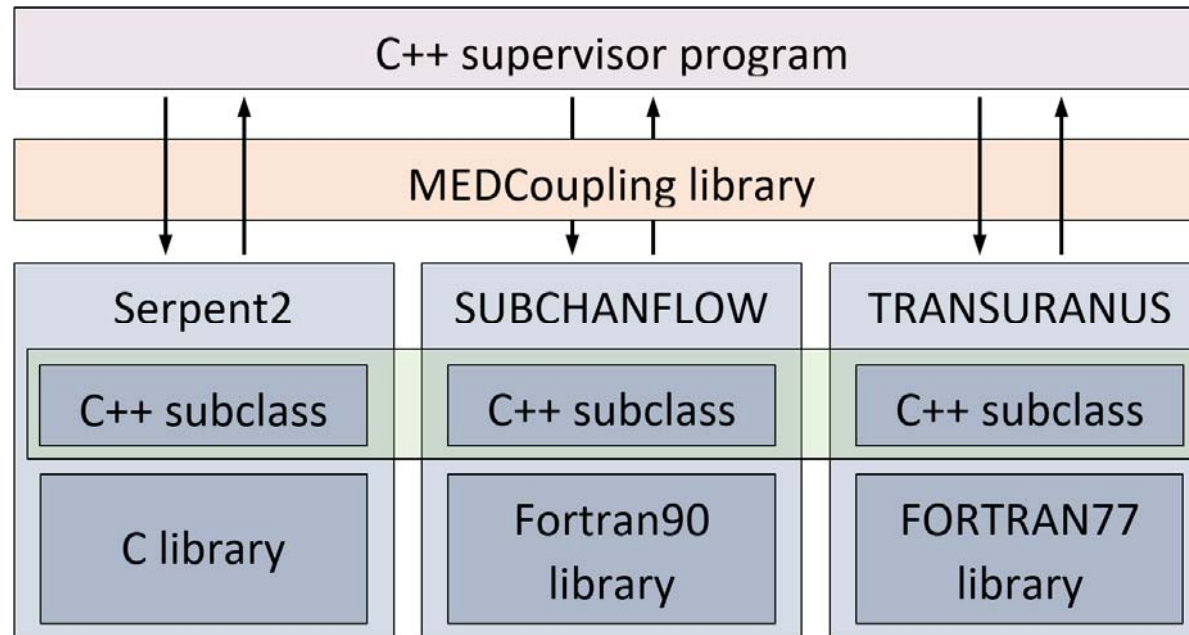
- Codes:
 - Serpent2: continuous-energy Monte Carlo particle transport.
 - SUBCHANFLOW: MATRA- (COBRA-) based subchannel code.
 - TRANSURANUS.
- Objectives:
 - Perform fully coupled pin-by-pin depletion calculations.
 - Optimize the system for High Performance Computing (HPC).
 - Develop a suitable modelling approach (pin-by-pin, hot channel) for full-core.
 - Validate with PWR and VVER experimental data from the industry partners.
- Coupling approach:
 - Pin-level feedback, fully coupled calculation scheme.
 - TRANSURANUS replaces the rod solver of SUBCHANFLOW.
 - Object-oriented design.
 - Mesh-based (geometry agnostic) field exchange.
 - Pre- and post-processing capabilities for PWR and VVER reactors.



Object-oriented coupling



■ Object-oriented design:



■ Advantages:

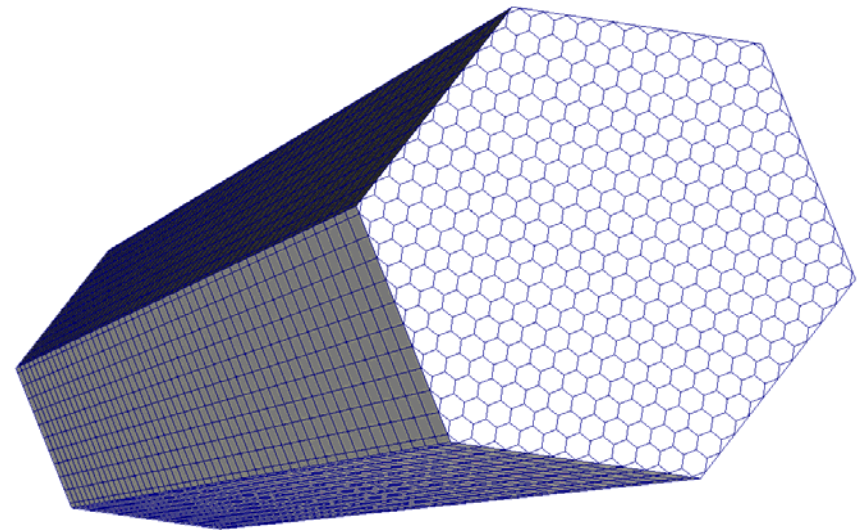
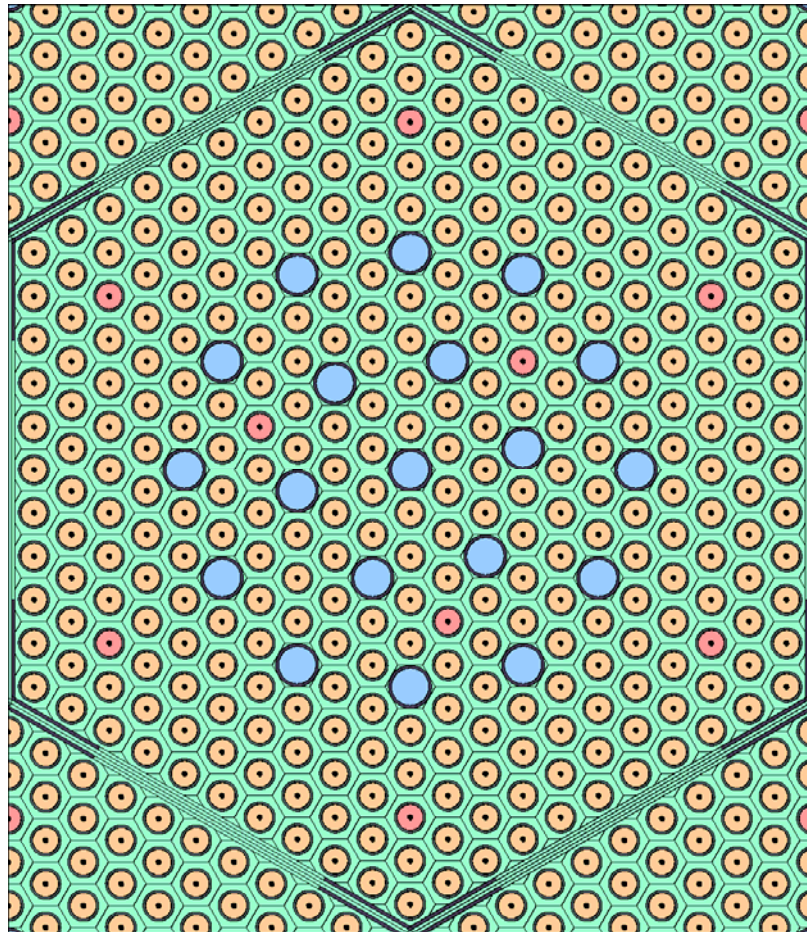
- The codes are kept completely separate and maintainability is enhanced.
- Suitable model for collaborative development projects.
- The coupling through the supervisor is flexible and somehow generic.



Mesh-based feedback



■ Serpent2:



Multiphysics interfaces:

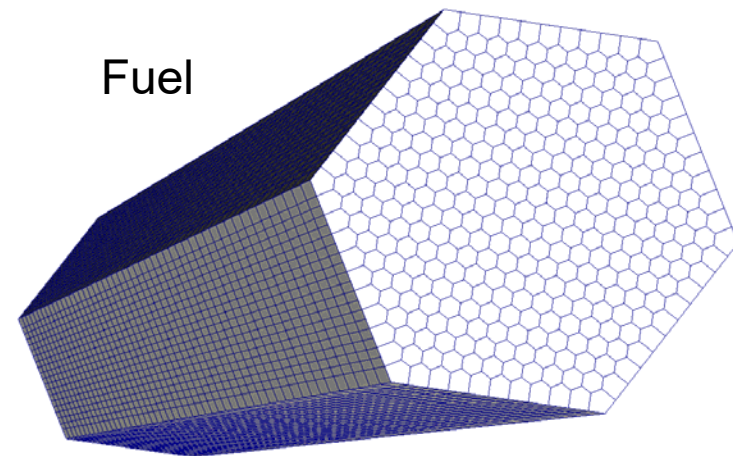
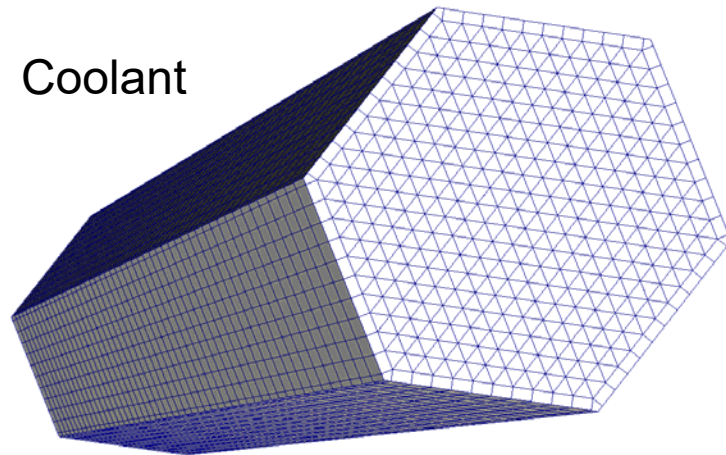
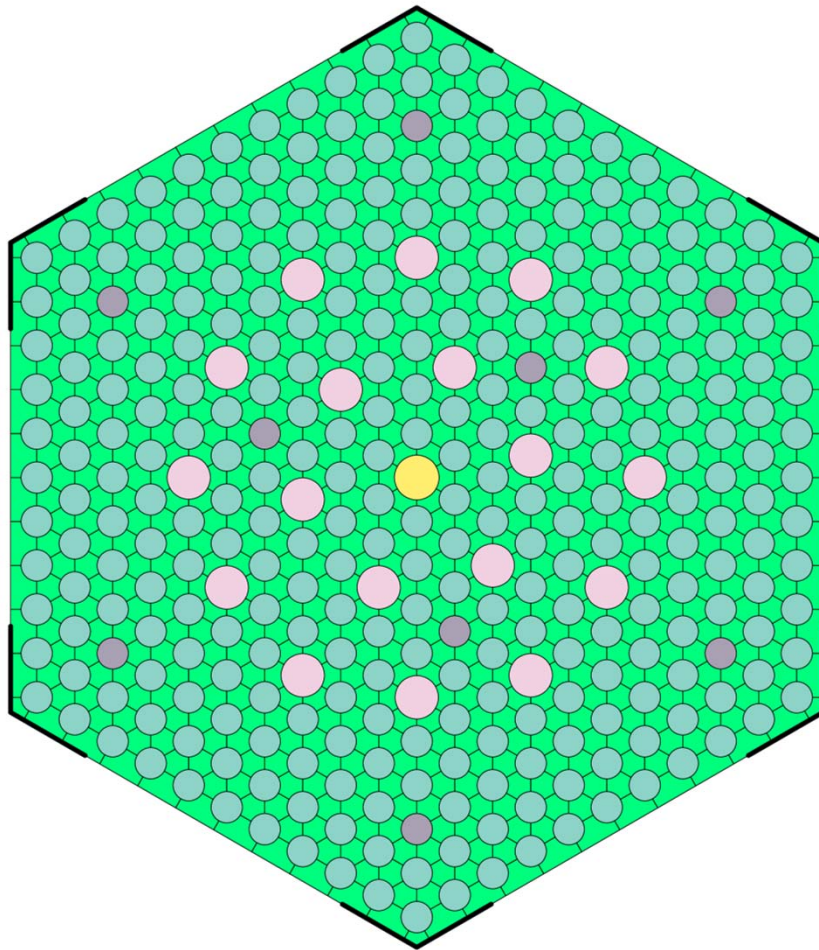
- Superimposed meshes.
- Not linked directly to the tracking geometry.
- Define temperatures and densities and tally power.



Mesh-based feedback



■ SUBCHANFLOW:

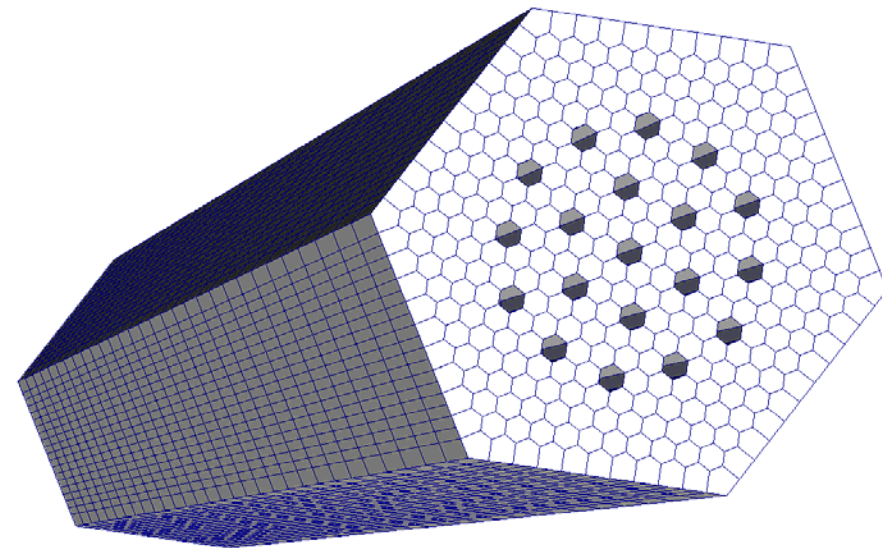
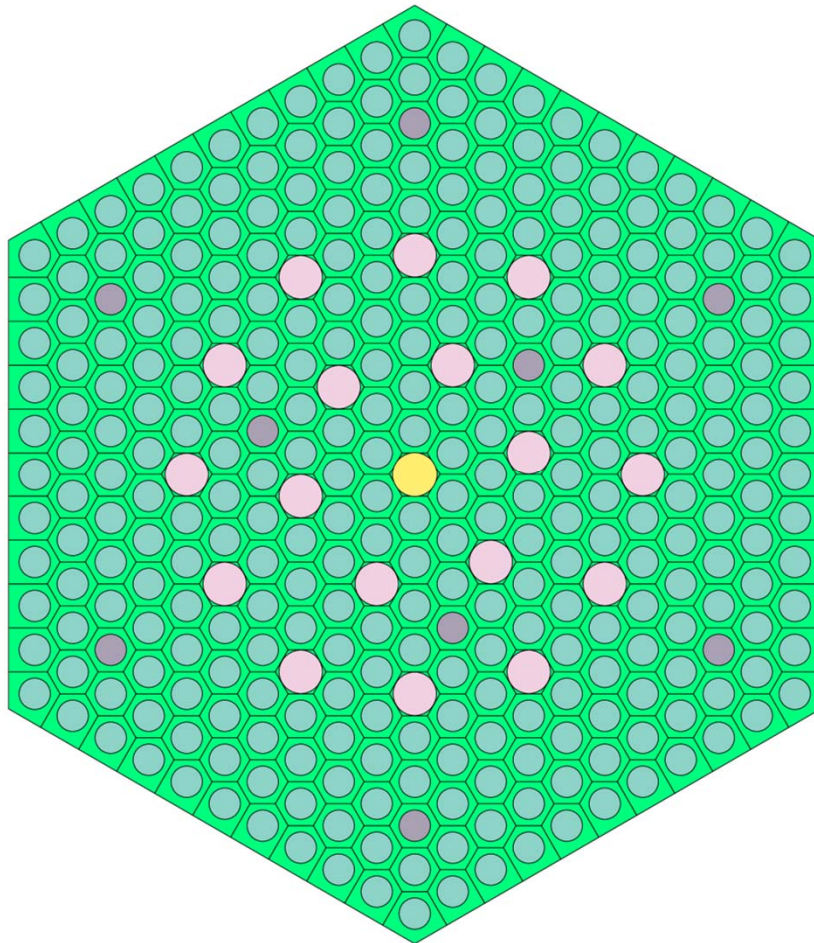




Mesh-based feedback



■ TRANSURANUS:

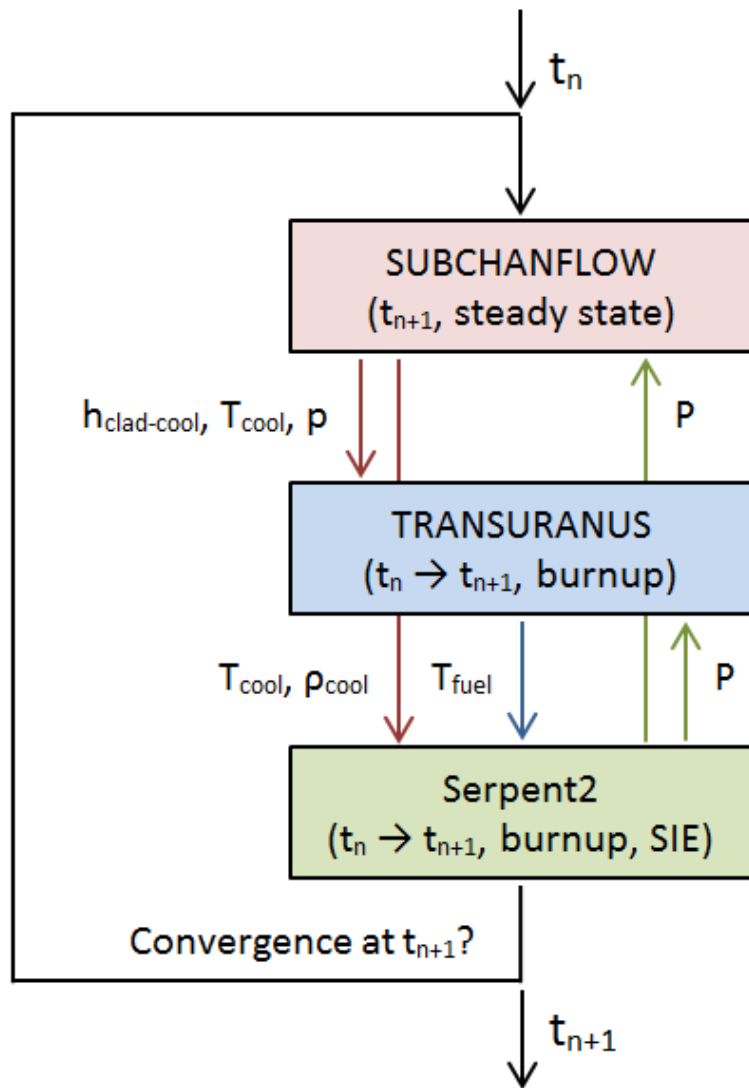


Multiphysics mesh:

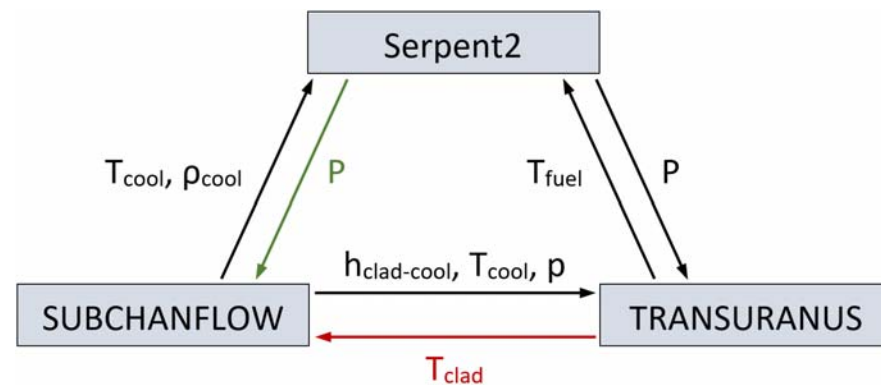
- Used to gather results and set input variables.
- Contains only the fuel rods.



Calculation scheme



- Semi-implicit depletion scheme.
- Solution of the Bateman equations both in TU and Serpent2.
- The only Serpent2 data used in TU is the power distribution.
- The TU neutronic model is still used.
- SCF does not model the rods.





Developments on TRANSURANUS



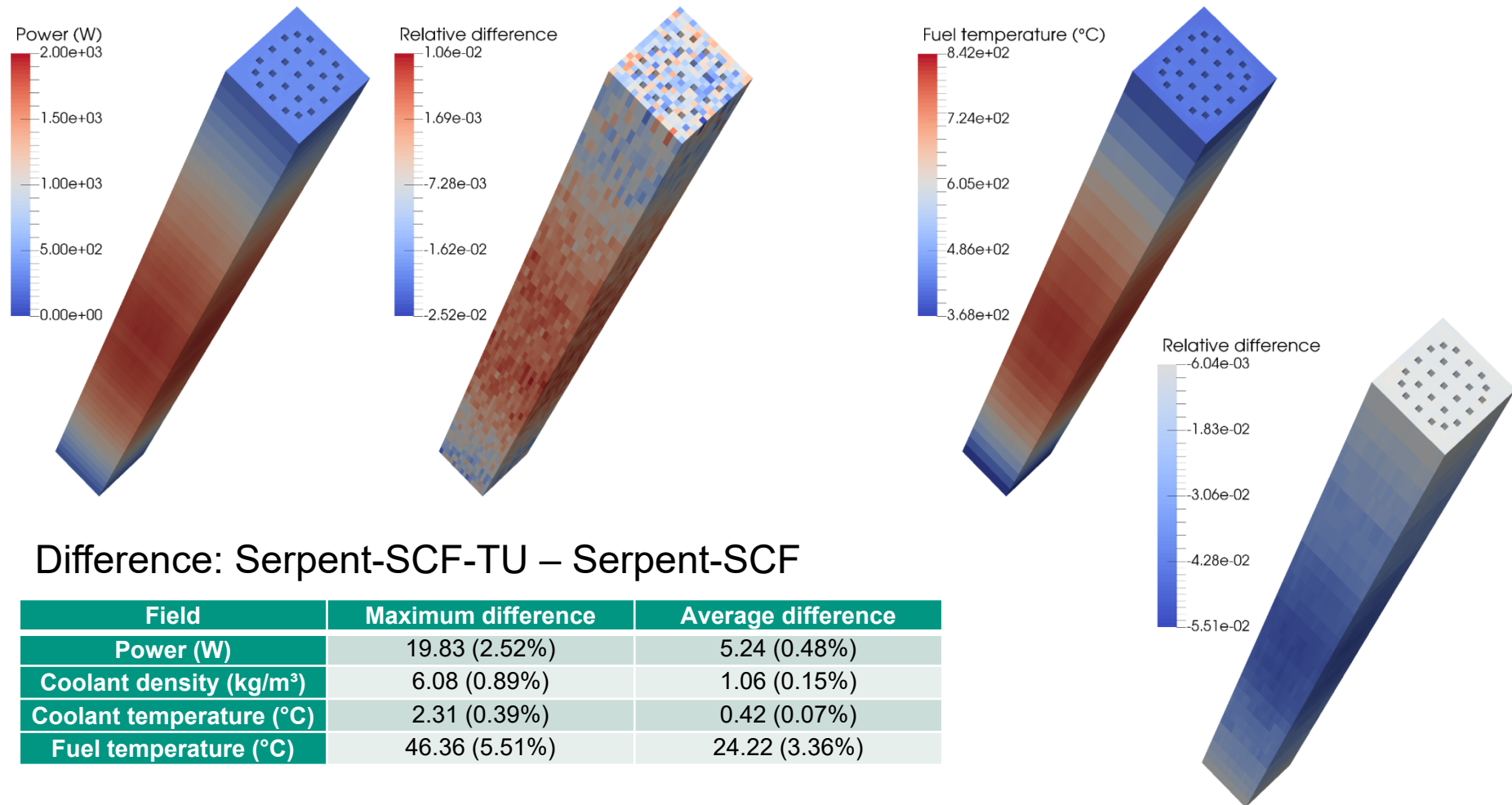
- No changes to the physical models.
- Code structure:
 - Kernel implemented as a library for flexible execution.
 - C++ wrapper to define the API used in the coupling scheme.
 - Support for multiple rods.
 - An unstructured mesh is used to gather results and handle input variables.
- Input:
 - Coolant boundary conditions ($h_{\text{clad-cool}}$, T_{cool} , p) from SUBCHANFLOW.
 - Linear heat rate from Serpent2.
- Output:
 - Fuel temperature to Serpent2.
 - Gap conductance, gap width, fission gas release (Xe, Kr, etc).
- Optimization:
 - MPI parallelization using domain decomposition.
 - Dynamic memory allocation ($\sim 12\text{GB} \rightarrow \sim 1.5\text{GB}$ for a VVER-1000 fuel).



Results: steady state



■ PWR: VERA Benchmark Problem 6.



Difference: Serpent-SCF-TU – Serpent-SCF

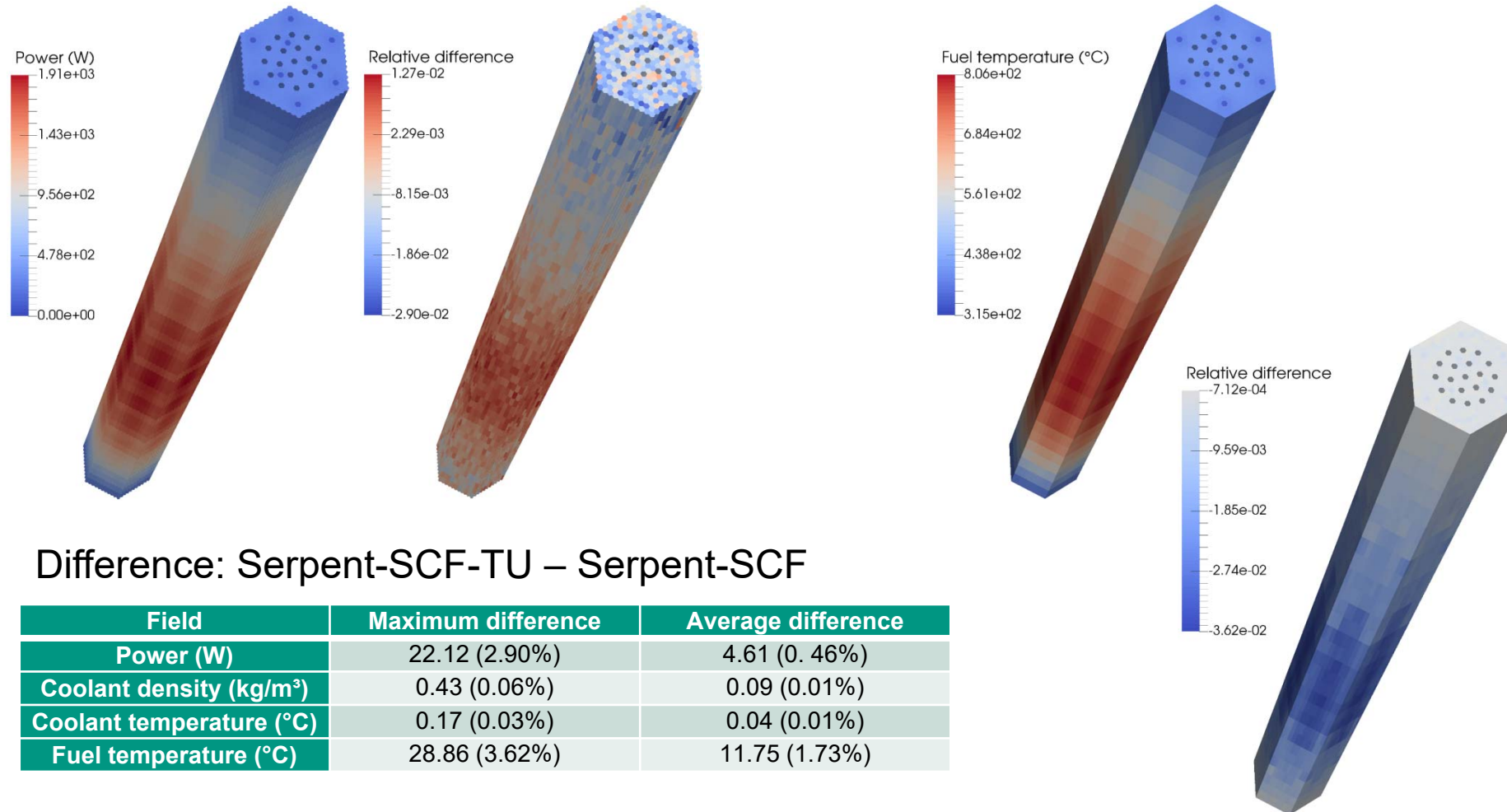
Field	Maximum difference	Average difference
Power (W)	19.83 (2.52%)	5.24 (0.48%)
Coolant density (kg/m ³)	6.08 (0.89%)	1.06 (0.15%)
Coolant temperature (°C)	2.31 (0.39%)	0.42 (0.07%)
Fuel temperature (°C)	46.36 (5.51%)	24.22 (3.36%)



Results: steady state



- VVER: 30AV5 VVER-1000 fuel-assembly type.



Difference: Serpent-SCF-TU – Serpent-SCF

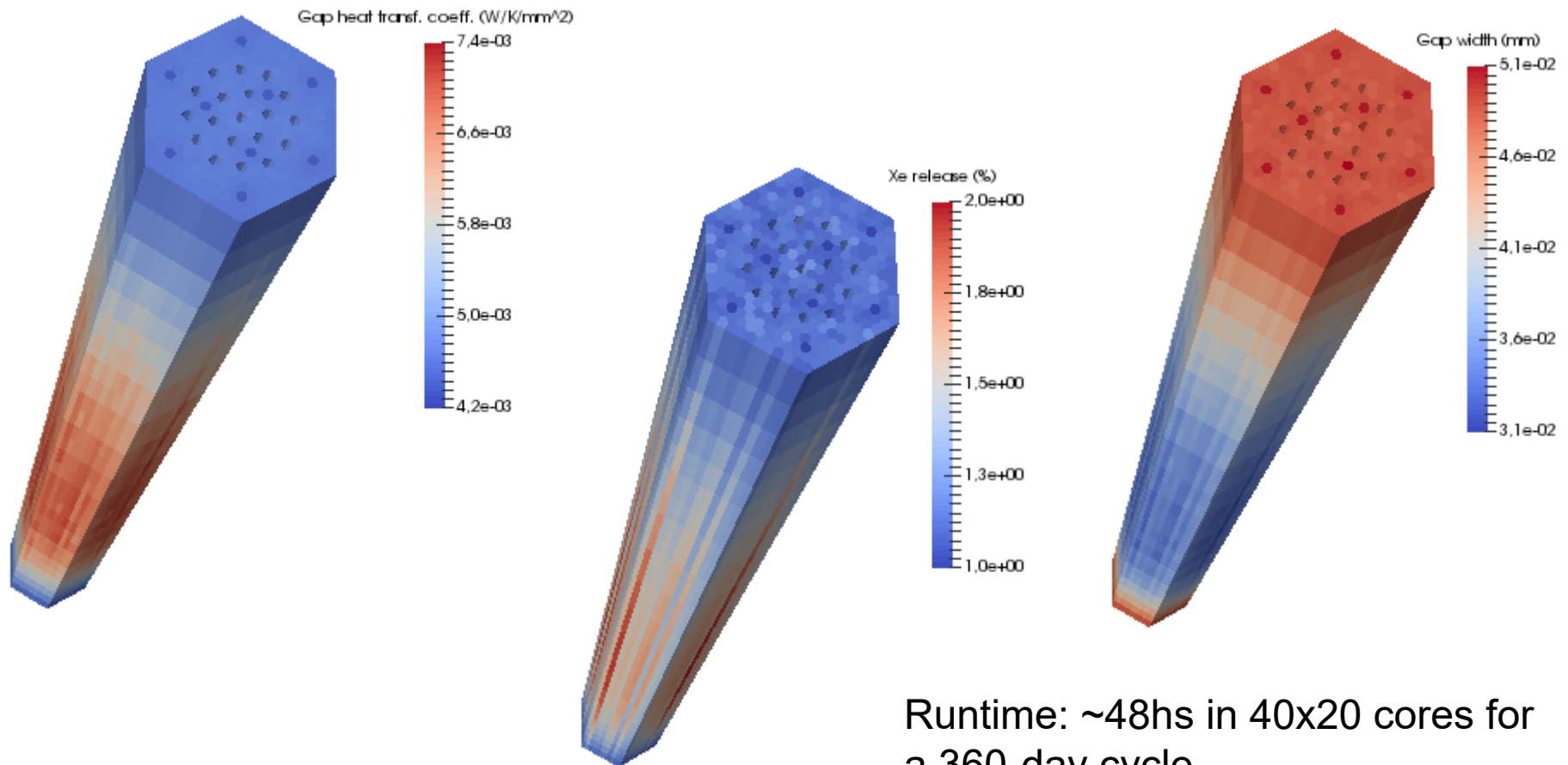
Field	Maximum difference	Average difference
Power (W)	22.12 (2.90%)	4.61 (0.46%)
Coolant density (kg/m ³)	0.43 (0.06%)	0.09 (0.01%)
Coolant temperature (°C)	0.17 (0.03%)	0.04 (0.01%)
Fuel temperature (°C)	28.86 (3.62%)	11.75 (1.73%)



Results: depletion



- VVER: 30AV5 VVER-1000 fuel-assembly type (t = 60 days).



Runtime: ~48hs in 40x20 cores for a 360-day cycle.



Open issues



- Neutronic feedback to TRANSURANUS:
 - Currently only the linear heat rate is used, the simplest possible feedback.
 - Using power and flux radial profiles not feasible, at least not with the current modelling approach, i. e. having all pins in TRANSURANUS.
 - Other average parameters? Isotope compositions?
- Doppler feedback to Serpent2:
 - Currently volume averaging or empirical formulas are used.
 - Analysis of radial fuel temperature profiles in the near future.
- Modelling approach:
 - With the current approach we'd simulate ~60,000 rods for full-core cases!
 - Hot-channel methodology? Average pin for each fuel-assembly?
- Memory bottleneck for Serpent2 depletion:
 - A full core takes about 2TB for pin-by-pin depletion.
 - Domain decomposition in progress.



Conclusions



- Current status:
 - Three code coupling with pin-level feedback implemented.
 - Verification with single-fuel-assembly PWR and VVER steady-state cases.
 - Analysis of single-fuel-assembly depletion cases underway.
 - Optimization towards full-core capabilities in progress.
- Open issues:
 - Analysis of the TRANSURANUS side of the depletion scheme, including adding more neutronic feedbacks from Serpent2.
 - Analysis of the Doppler feedback to Serpent2.
 - Optimization of the modelling in TRANSURANUS (and the other codes).
- McSAFE user group open to new participants!



Questions? Comments?

