

# A Collision-based Domain Decomposition scheme for Serpent2

Manuel García, Karlsruhe Institute of Technology (KIT)



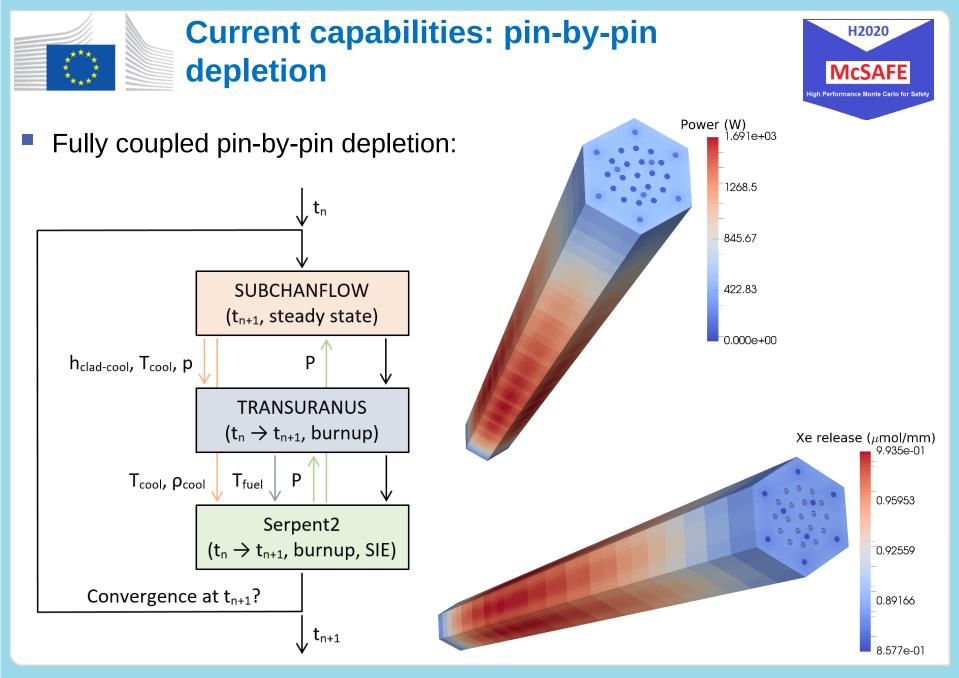
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### **Motivation: the McSAFE EU project**



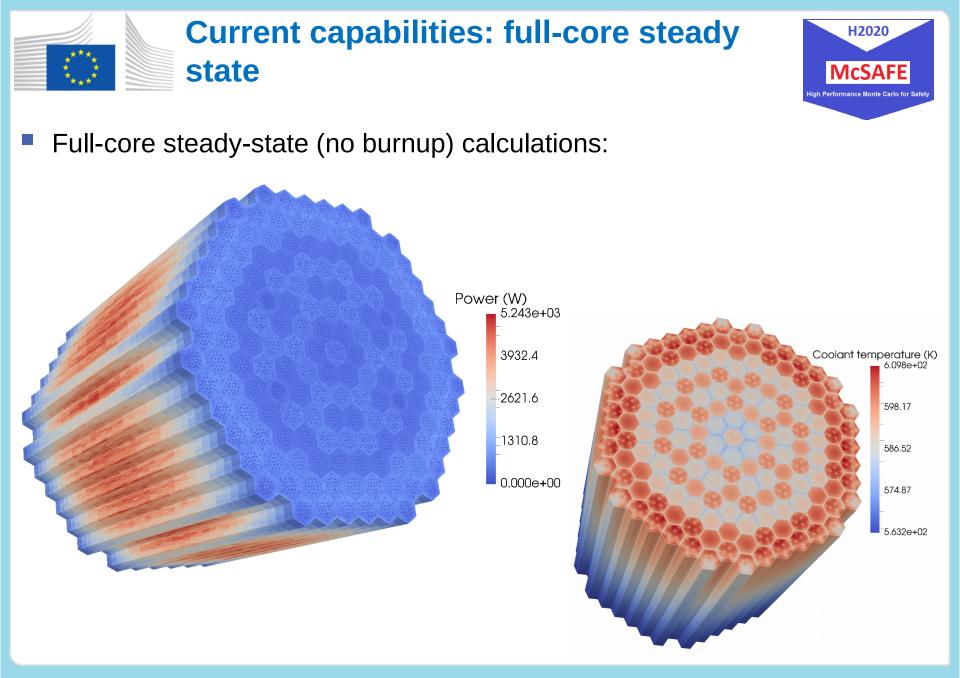
- Participants:
  - 9 research institutions: KIT, VTT, HZDR, JRC, CEA, NRI, KTH, AMEC, DNC.
  - 3 industry partners: EKK, CEZ, EdF.
- High-fidelity multiphysics for safety analysis of LWRs:
  - Monte Carlo neutron transport: Serpent2, Tripoli4, MCNP, MONK.
  - Subchannel thermalhydraulics: SUBCHANFLOW (SCF).
  - Fuel-performance analysis: TRANSURANUS (TU).
- Main developments:
  - Implementation of a Serpent2-SCF(-TU) coupling for steady-state, burnup and transient problems.
  - Optimization of steady-state and transient capabilities for HPC.
  - Optimization for massive (full-core) depletion problems.
- Validation with plant data:
  - PWR-Konvoi.
  - VVER-1000.

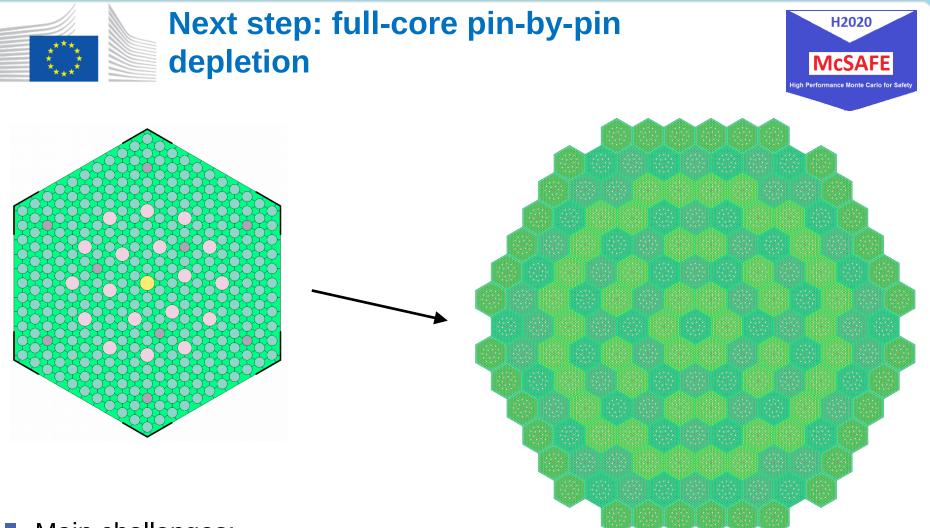


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KIT – INR / RPD group





#### Main challenges:

- Calculation time (~10<sup>9</sup> particles)  $\rightarrow$  optimizations in Serpent2, SCF and TU.
- Memory demand ( $\sim$ TB)  $\rightarrow$  domain decomposition for Serpent2.



## **Parallelization of Monte Carlo transport**



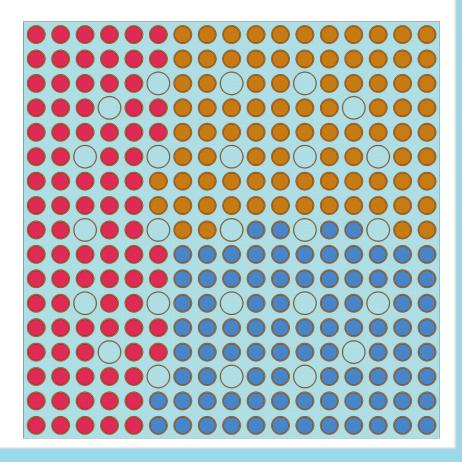
- Particle-based parallelism:
  - Particle histories are independent and can be calculated simultaneously.
  - Natural algorithm, embarrasingly parallel (not really).
  - Domain replication across MPI tasks, shared memory in OpenMP.
  - Typically very good speedup, but no memory scalability.
- Domain decomposition:
  - Geometry divided in domains somehow.
  - Particle histories are still independent, so particle-based parallelism is used.
  - Tracking algorithm more complex due to particles changing domains (if no approximations are introduced).
  - Domain decomposition across MPI tasks, shared memory in OpenMP.
  - Potentially poorer speedup, but memory scalability.
  - The decomposition of the geometry (CSG) can be quite challenging.
  - A few implementations done lately (OpenMC, RMC).



## **Collision-based Domain Decomposition**



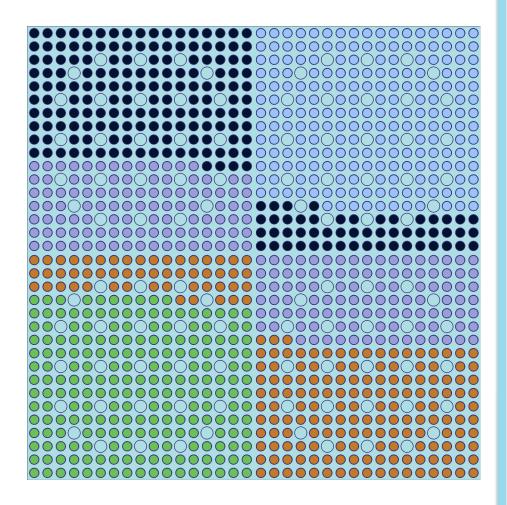
- Basic idea:
  - Divide burnable materials in domains (~ data decomposition).
  - Replicate non-burnable materials in all domains.
  - Each MPI task represents a domain.
- Particle tracking:
- Neutrons created in each domain in local fissile materials.
- Particles tracked until absorbed or leaked, or until a collision in a non-local material occurs.
- Particles buffered and sent across domains.
- A transport cycle is completed when all particle histories in the whole system are finished.







- Implemented options:
  - By material index (set dd 1).







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- By angular sector (set dd 2).

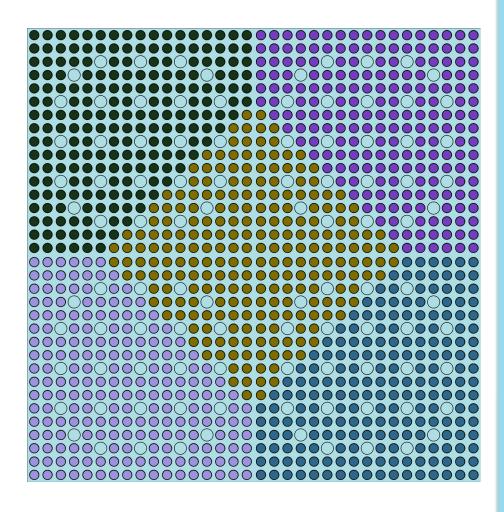
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- Implemented options:
  - By material index (set dd 1).
  - By angular sector (set dd 2).
  - By angular sector with a central

zone (set dd 3).



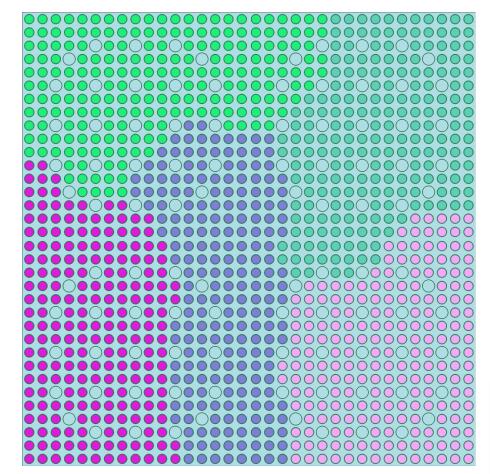




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- By graph partition (set dd 4).
- Graph-based division:
  - Material graph:
    - Vertices: materials.
- Edges: material connections with cutoff maximum distance.
  - $\succ$  Weights: inverse of the distance.
- Cartesian mesh to avoid comparing all materials (O(n<sup>2</sup>)).
  - Partition done with Metis.







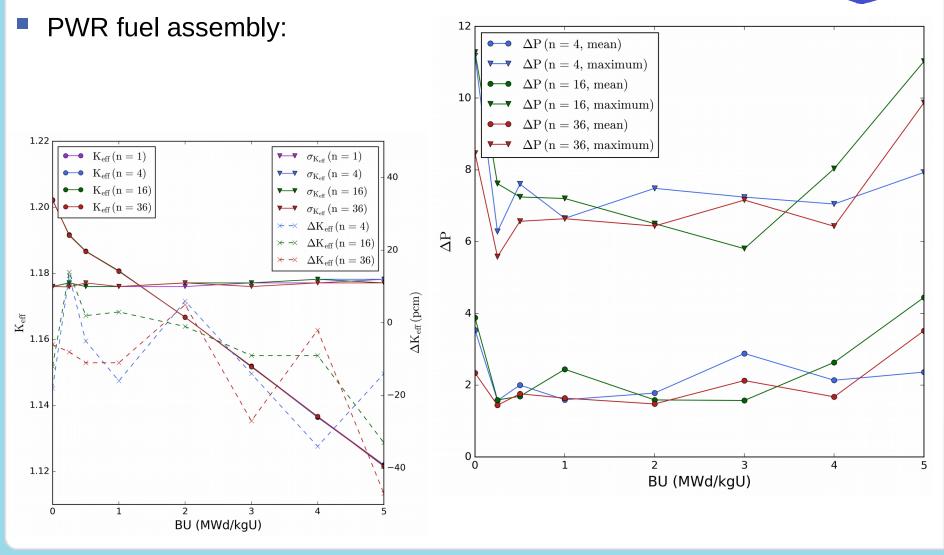
- Particle transfers:
  - Particles are sent across domains when collisions in non-local materials occur.
  - Buffers used to send particles in larger messages.
  - Asynchronous communications (MPI\_Isend(), MPI\_Irecv()).
  - Direct task-to-task messages.

#### Termination control:

- All histories in the whole system need to be completed.
- Tricky due to the use of asynchronous communications.
- Stopping criteria: all local particles tracked, all messages sent received.
- Two step calculation of the particle balance:
  - Asynchronous reduction to get an estimation.
  - > Synchronous reduction to make sure.
- Binary tree to handle collective communications.











#### Homogeneous system:

