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The multiscale thermal-hydraulic simulation for nuclear reactors: A classification of the coupling approaches and a review of the coupled codes

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Summarv

Simulation is becoming increasingly important in the safety analysis of nuclear reactors nowadays. The physical phenomena in a nuclear power plant happen on three classified scales: system scale (phenomenon over the whole plant is concerned), component scale (phenomenon in specific component is concerned), and mesoscale (phenomenon in a small part of a component is concerned). Owing to the particular emphases, various codes are developed to simulate particular problems. System codes intend to predict the behavior of the whole power plant during normal or accidental phases (system scale). Subchannel codes are for core behavior predictions (component scale). CFD codes can simulate the thermal-hydraulic in a fixed part of the plant (mesoscale). Those codes are coupled together to better predict the conditions in a nuclear reactor in last the two decades, which is the multiscale thermal-hydraulic simulation approach for nuclear power systems. Diverse coupling approaches are developed and various coupling codes are implemented. This paper first proposes a classification of those approaches. It tells that a multiscale coupling is composed of five items: coupling architecture, operation mode, domain coupling, field mapping, and temporal coupling. Numbers of options are available for each item. For coupling architecture, it can be internal coupling, via-IO coupling, server-client, or serverless coupling. For operation mode, it can be either parallel or serial. For domain coupling, it can be either domaindecomposition or domain-overlapping coupling. For field mapping, it can be manual-definition, processed by user-developing toolkit, or handled by thirdparty libraries. For temporal coupling, it can be explicit coupling, semi-implicit coupling, or implicit coupling. An evaluation of the approaches is performed based on new-proposed criterion. A general review of the multiscale thermalhydraulic coupled codes is made based on the classification. Especially, a review of the domain-overlapping approach is present considering it is the most promising but challenging method for multiscale thermal-hydraulic simulation.

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KEYWORDS

classification of coupling approaches, multiscale thermal-hydraulic coupling, review of coupled codes, review of domain-overlapping

1 | INTRODUCTION

The commercial nuclear reactors have been in operation for electricity generation worldwide for many years and they were proved clean and safe. Nevertheless, continuous effort is still now made by the nuclear community to improve the power systems' safety and efficiency. In order to achieve this goal, the physical phenomenon inside the reactor has to be carefully and sufficiently identified and investigated as the base of new reactor design and methodologies. Additionally, various other aspects have to be carefully lucubrated as well, such as the economic risks and uncertainties,¹ the waste management and storage, and the spent fuel processing,² etc. Especially after the Fukushima accident, a review of the safety status for the nuclear power plants was necessary to identify areas that needs to be improved. In the meantime, safety analysis methodologies and the strategies for accident management are under continuous enhancement to adjust to the rapidly changing regulatory policies.³

Conducting experiment is a good way to investigate those problems. However, for a nuclear power plant, the experiment can hardly cover everything because of the expensive cost and measuring difficulties. Simulation poses perfect supplementary, thanks to its economic efficiency, super repeatability, and results' transparency. Its role in accident management was underscored and many severe accident studies were carried out.⁴ However, because of the limit of the computation power and the lack of mathematical models, different simulations have different emphasis according to the problem concerned. Some are interested in the dynamic of the whole system while some focus on the physical phenomenon in a specified component or part of a component.

In a nuclear reactor, the thermal-hydraulic phenomena take place at diverse spatial scales whose characteristic lengths vary from meters down to nanometers. Hence, the simulations are typically classified into three main scales^{5,6}:

1. System scale: the phenomenon which is tightly related to the dynamics of the overall nuclear power plant or facilities is concerned at this scale, eg, the large break loss of coolant accident, where the primary cooling system of the reactor fails and loss the coolant.⁷

- 2. Component scale: the phenomenon occurring in special reactor components such as the reactor core and the heat exchanger is concerned at this scale, eg, the departure from nucleate boiling which is very important concerning the reactor safety.
- 3. Mesoscale: the fine description of the reactor thermalhydraulics is concerned at this scale, eg, the unsymmetrical coolant mixing in the downcomer and lower plenum (coolant of different temperatures entering the reactor vessel from different inlet nozzles will mix with each other in the vessel) in the reactor pressure vessel (RPV).⁸

The European NURESIM and NURISP projects make a similar classification. In addition, another scale microscale—was taken into account, which focuses more on details of flow conditions.⁹ Besides, in Niceno et al,¹⁰ the thermal-hydraulic simulation expands to nanoscale referring to, eg, molecular dynamics modeling techniques. In order to describe the thermal-hydraulic processes undergoing at the various spatial scales, many thermal-hydraulic simulation codes were developed and applied worldwide, eg, 1D or 3D system thermalhydraulic codes, porous-media codes (CFD-porous media, subchannel codes, and porous-media 3D codes), open-medium-CFD, large eddy simulation, detached eddy simulation, and direct numerical simulation.¹¹

The system codes were to simulate almost all normal and accident scenarios of the whole nuclear power plant. It handles general tasks in the power plant, eg, the qualification of the safety margins (the threshold under which the system is assumed operating safely). It also defines and verifies the emergency operation procedure, etc.¹² The most widely spread system thermal-hydraulic codes developed for many decades is RELAP,¹³ TRACE,¹⁴ ATHLET,¹⁵ CATHARE,¹⁶ etc. The 1D or 3D coarse meshes favor a fast execution and robust numeric for the whole spectrum of design basis accidents. However, because of the coarse mesh applied, system codes are not intended to describe phenomena taking place at the meso or microscale, eg, turbulences.

Subchannel codes dedicate the description of thermal-hydraulics in the core region by dividing the core flow paths to groups of channels. Some of the famous codes are COBRA-TF,¹⁷ COBRA-FLX,¹⁸ VIPRE,¹⁹ FLICA,²⁰ SubChanFlow (SCF).^{21,22} They were

developed for an improved description of the core thermal-hydraulics using quasi-3D models at component scale (decimeter to centimeter scale) for the prediction of local safety parameters such as critical heat flux (CHF) ratio, critical power ratio (CPR), fuel centerline temperature, and fuel surface temperature. A very detailed review of subchannel analysis methods and codes can be found in Moorthi et al and Cheng and Rao.^{23,24} In order to simulate the core thermal-hydraulics of full cores using subchannel codes and to take profit from the increasing computer power, some subchannel codes were parallelized, eg, SCF and CORBA-TF.²⁵ In addition, the codes using porous models to simulate the dedicated 3D porous media two-phase flow with a Cartesian or unstructured grid are being developed to overcome the usually 1D limitations of the system thermal-hydraulic codes. Instances are CUPID,²⁶ PORFLOW,²⁷ TWOPORFLOW,²⁸ and PORFLO.29

Furthermore, to improve the simulation of 3D-effect within nuclear power plant circuits, CFD codes such as ANSYS-CFX, STAR-CD, OpenFOAM, TrioCFD are increasingly applied to nuclear system analysis. The main motivation is the increasing and cheap computation resources, the parallel capability of the codes, and the improved physical models and numerics.³⁰ General guidelines of how to use CFD in reactor safety complementary to the system codes are given in Mahaffy et al.³¹ Recent investigations have shown the potentials of CFDcodes for the simulation of complete nuclear power plants or part of it³²⁻³⁵ using meshing at different spatial scales ranging from millimeter to some centimeters. CFD codes work well for single-phase problems that may be encountered in the primary and secondary circuits as well as in the containment of NPPs. However, their application to two-phase flow is not yet comparable with the ones for single-phase flow due to some essential difficulties summarized in Bestion.³⁶ Nevertheless, new methods known as the computational multifluid dynamics (CMFD), which dedicates to simulate the two-phase flow on mesoscale or microscale are already one of the most promising trends for reactor applications.37 Recent research devoted to enhance and validate the CFD codes for two-phase flow problems of reactor safety has advanced.38-40

Considering the trends and the current capabilities of the different thermal-hydraulic codes for design and safety evaluations, the development of multiscale thermal-hydraulic simulations has been initiated in different teams worldwide, in order to enhance the nuclear reactor thermal-hydraulic simulation. Normally, the phenomena occurring on system scale, component scale, and mesoscale are simulated by system code, subchannel code, and CFD code, respectively. In the frame of ENERGY RESEARCH -WILEY-

different European projects, eg, NURESIM, NURISP, and NURESAFE, multiscale coupling approaches were systematically elaborated and various safety-relevant phenomena⁹ were investigated in detail from a multiscale perspective. Different publications⁴¹⁻⁴³ provide guidelines for potential coupling approaches.

During the last two decades, various multiscale thermal-hydraulic analysis has been carried out and diverse approaches were developed to couple various codes. An imperfection opposite to the prosperously developing of coupled codes and coupling approaches is that there is no acknowledged principles or standards on those approaches. The names of the coupling methods used by different developers usually differ from each other, although sometimes they refer to the same methodology. This situation causes misunderstanding or confusion very often, especially to researchers who have rare experience in this field. What is worse, the lack of wellorganized standard of performing multiscale thermalhydraulic coupling poses additional barriers during the planning of coupling tasks. Standards or guidelines for the multiscale coupling is imperative. This paper settles this issue by achieving two objectives:

- 1. Propose a clear, logical classification of the existing coupling approaches.
- 2. Evaluate the approaches and give a reference and guideline for developers who would like to develop a multiscale thermal-hydraulic coupled code from scratch.

Apart from that, another objective of the paper is to propose a review of the multiscale-coupled codes so that the history and development sequence is more accessible.

The first chapter gives the background of multiscale thermal-hydraulic coupling and describes the motivations and objectives of this paper. The second chapter sorts out the approaches and gives an overview and evaluation of the multiscale coupling schemes. The third chapter reviews the multiscale coupled codes. Finally, the conclusion completes the paper.

2 | THE MULTISCALE THERMAL-HYDRAULIC COUPLING APPROACHES

2.1 | A classification of the approaches

From the informatics point of view, the coupling of multiscale thermal-hydraulic codes can be either parallel or serial, as illustrated in Figure 1. In this context, parallel mode especially refers to the interprocess



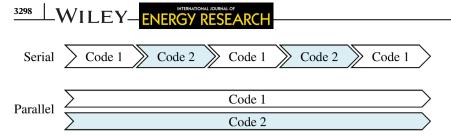


FIGURE 1 Operational logics of the serial and parallel coupling [Colour figure can be viewed at wileyonlinelibrary.com]

parallelization, eg, message passing interface (MPI)based models. On the contrary, the architecture-based classification differentiates between the internal and external coupling. In an internal coupled system, one code compiles as a static or dynamic library fully integrated inside the other code resulting in one single executable, see Figure 2; while the external coupling option offers three possibilities, see Figure 3:

- 1. Data exchange via input and output (IO) files.
- 2. Use a supervisor to coordinate the coupling procedures.
- 3. The two codes directly communicate with each other forming a serverless system.

The internal coupling is the most applied method because of its relative simplicity. The server-client and serverless external coupling can achieve high performance and pose better expandability and maintainability compared with the internal coupling. However, intensive programming effort is necessary as well as in-deep knowledge of the coding structure of the involved solvers is required. Moreover, the condition could become more complex when the parallel mode is expected.

In a multiscale coupling system, the system code, the subchannel code, and the CFD code are coupled to achieve a more realistic simulation of a nuclear power plant using a code-specific spatial resolution of the computational domain. For instance, the coarse mesh of system code for the whole nuclear power plant, the relatively refined mesh of subchannel code for the core region, and the fine mesh for several specific parts, eg, the downcomer. So, one of the critical tasks for the multiscale coupling is how to specify which code is in charge of which computational domains within the entire problem. In this context, the way of coupling the different computational domains of the involved thermalhydraulic solvers (system, subchannel, and CFD) is of great importance. Therefore, two methods are specified: domain decomposition and domain overlapping. Figure 4 demonstrates the two options with the simulation of a pipe using a system code and a CFD code.

For the domain overlapping case shown in Figure 4, the system code intends to model the entire pipe while the CFD code only simulates part of the pipe. The lower part of the figure illustrates the domain decomposition

Code	l - Executable
	Code 2 - Library

FIGURE 2 Arrangement of codes for internal code coupling [Colour figure can be viewed at wileyonlinelibrary.com]

method where the system code describes the pipe without the three central nodes, which are simulated by the CFDcode. The intercode data transfer occurs at the two boundaries between the CFD model and the system model, which is represented by the two double-sided arrows. The upper part of Figure 4 illustrates the domain overlapping method. There, the system code simulates the whole pipe and the CFD code simulates the three central cells only. These three cells represent the overlapping domain. The fields at the boundaries where the overlapping domain starts and ends are extracted from system code, and are then transferred to the CFD-code as its updated boundary conditions. The two 1-way arrows denote this data transfer. On the contrary, the data from CFD to the system code are body fields derived from the whole CFD computation domain. Those body data are used to correlate the system solution. A bunch of gray one-way arrows represents them.

In general, the meshes of system code, subchannel code, and CFD code have different spatial resolutions, see Figure 4. There, the CFD mesh is much finer than the one of the system code. Consequently, the fields have to be translated from one mesh to the other in a proper way before the data transfer. For it, three options are available:

- 1. Manual definition of mesh spatial matching relations. It is a direct method free of programming effort but calls for massive work at any time when a newly coupled code is developed.
- 2. User-developed toolkit. In this method, the mesh matching finalizes in an automatic way and it is relatively efficient. It can focus on specific mapping problems for a special coupling scheme but it is not universal and powerful.
- Use of a third-party mesh-processing toolkit, eg, the MEDCoupling library⁴⁴ of the SALOME platform. This toolkit is general and powerful. It can properly handle different mesh-mapping scenarios in an



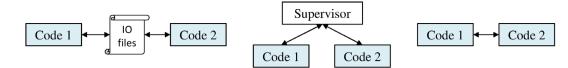
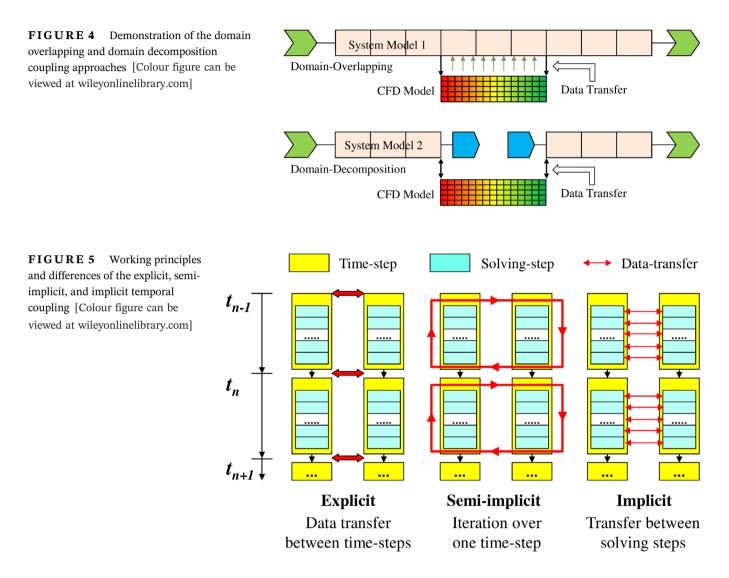


FIGURE 3 Schematics of data flows for external code coupling [Colour figure can be viewed at wileyonlinelibrary.com]



automatic manner. However, those toolkits mostly require mesh definitions while most of the system and subchannel codes do not have meshes.

The mesh interpolation and physical field mapping methods together with the domain coupling compose the spatial coupling since they deal with the geometric objects. Beyond the spatial coupling, the other element for multiscale coupling in terms of mathematics and physics is the temporal coupling approach that is in charge of the synchronization of the data transfer among the involved solvers. The spatial coupling solves the problem of how to transfer the data properly, while the temporal coupling solves the problem of how to use these data in order to establish a synchronous multiscale coupling code. The following three different temporal coupling approaches are implemented in different multiscale codes: (a) explicit coupling, (b) semi-implicit coupling, and (c) implicit coupling. Figure 5 illustrates the basic principles and the differences among these approaches.

The explicit coupling is the most straightforward temporal coupling method where the data transfer is carried out only once at the beginning or end of each time step. No check of the convergence of the codes' result within a time step is performed. Hence, the WILEY-ENERGY RESEARCH

results may be inconsistent with each other, which might result in a consequently unsteady situation during the solution.

In order to ensure the data consistency within one time step of the coupled codes, the semi-implicit coupling is implemented, where the data transfer is done many times until all the codes' result convergence within one time step. Hence, it is more robust than the explicit coupling, while on the other hand, it is more complicated to be implemented. Furthermore, the performance of the coupled codes can be improved by spreading the data transfer down to the solution procedures of the set of equations, which is the implicit coupling. This is the most efficient, robust coupling approach but needs significant modification of the source code, and hence it is challenging.

It is worth to note that Figure 5 only presents the general form of the three temporal coupling methods. The typical explicit coupling method is the operator splitting (OS) method, which is demonstrated in Chorin,⁴⁵ and now widely used in various coupling works. It is also called the operator splitting semi implicit (OSSI) method sometimes though it is actually an explicit method.⁴⁶ There are also diverse varieties for the semi-implicit^{47,48} and implicit⁴⁹ coupling methods. Moreover, some other acceleration techniques are also massively developed and implemented to the codes temporal coupling.⁵⁰⁻⁵³ They aimed at the optimization of the intercodes synchronization as well.⁵⁴ gives a review of the temporal coupling methods in detail. It is worth to note that those methods are not limited to multiscale coupling but they are universal methods for various coupling issues, eg, multiphysics coupling and for non-nuclear applications as well.

In view of the development of the multiscale coupling methods for thermal-hydraulic codes to solve reactor safety problems, it is important to look at the solution procedure applied to solve the system of equations in the thermalhydraulic codes. If the set of equations are solved separately in the thermal-hydraulic codes, it is a weakly coupled code. Otherwise, it is a strong coupling if the Figure 7 summarizes all possible coupling approaches for the multiscale coupling of thermal-hydraulic codes (a summary from Figures 1 to 6). There are four possibilities—S1.1, S1.2, S1.3, and S1.4—for Strategy 1 (S1, coupling architecture). Two options—S2.1 and S2.2—for Strategy 2 (S2, operation mode) and two choices—S3.1 and S3.2—for Strategy 3 (S3, domain coupling). Three methods—S4.1, S4.2, and S4.3—for Strategy 4 (S4, physical field mapping). Three patterns—S5.1, S5.2, and S5.3—for Strategy 5 (S5, temporal coupling). Each of the five strategies has to be determined for a coupling strategy. In other words, a multiscale coupling approach is composed of the five pieces below.

According to the universal standard of classification, there are mainly five challenges for a potential multiscale thermal-hydraulic codes coupling:

- 1. Selecting coupling architecture. Developers have to balance the complexity and efficiency according to their demands. From S1.1 to S1.4, the coupling architecture is getting more complex but more efficient and flexible.
- 2. Selecting the operating mode. Normally parallel is better than serial because it is more efficient and has good expandability. However, it is more complicated.
- Geometry adaption. Developers must specify the relations between the different codes' thermal-hydraulic domains. Different strategies mean distinct developing work.
- 4. Handling field mapping. The data and field translation between different codes' meshes is always a crucial problem for code coupling. Plenty of work is necessary for this task.
- Assuring data synchronization. This is the base of a correct coupled simulation. It is the temporal coupling between coupled codes.

If two or more codes are to be coupled, the above five challenges have to be solved and proper approaches have to be carefully selected.

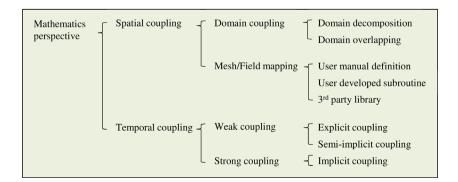


FIGURE 6 Classification cladogram of the multiscale coupling approaches from the mathematical perspective [Colour figure can be viewed at wileyonlinelibrary.com]

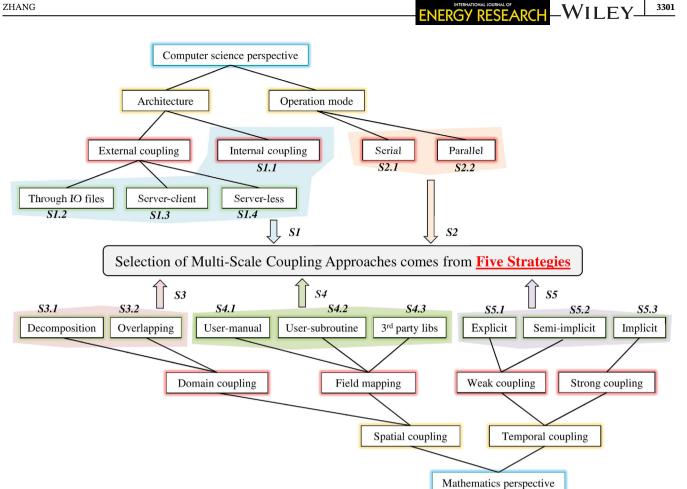


FIGURE 7 Overall classification of the multiscale coupling approaches and there are five strategies to identify a multiscale coupling system [Colour figure can be viewed at wileyonlinelibrary.com]

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TABLEI	The evaluation	criteria with	the weighting	g factors of	f the five r	nain coupling	strategies

Strategy Group	Evaluation Crit	eria-Weighting Fact	or		
S1: Architecture	Efficiency-5	Flexibility-4	Scalability-3	Maintainability-2	Simplicity-1
S2: Operation mode	Efficiency-4	Scalability-3	Maintainability-2	Simplicity-1	
S3: Domain coupling	Robustness-3	Realizability-2	Simplicity-1		
S4: Field mapping	Accuracy-5	Capability-4	Universality-3	Efficiency-2	Simplicity-1
S5: Temporal coupling	Accuracy-4	Robustness-3	Efficiency-2	Simplicity-1	

2.2 **Evaluation of the approaches**

This section presents and discusses the criteria considered for the selection of the different coupling strategies. On that basis, an evaluation of the coupling approaches is performed. All substrategies shown in Figure 7 are evaluated by a standardized scoring mechanism. From the general perspective of the coupling approaches, the more efficient the better, the more accurate the better, the more stable the better, and the easier the better. The evaluation criteria along with their weighting factors are listed in Table 1.

Three scores are used to evaluate the approaches, where 0 represents poor, 1 for normal, and 2 is good. Regarding the coupling architecture, five criteria were proposed and the corresponding weighting factors were assigned according to their importance to the integral coupling system. The final evaluating scores are calculated in Table 2 and the explanation follows.

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1. Efficiency: first of all, the data within an internal coupled system is exchanged via memory, which is the fastest way of data transfer. Nevertheless, the

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S1: Architecture	Effic-5	Flexi-4	Scala-3	Maint-2	Simp-1	Final Score
S1.1 Internal coupling	1	0	0	1	1	$1 \times 5 + 0 \times 4 + 0 \times 3 + 1 \times 2 + 1 \times 1 = 8$
S1.2 IO files coupling	0	0	0	1	2	$0 \times 5 + 0 \times 4 + 0 \times 3 + 1 \times 2 + 2 \times 1 = 3$
S1.3 Server-client	2	1	2	2	0	$2 \times 5 + 1 \times 4 + 2 \times 3 + 2 \times 2 + 0 \times 1 = 24$
S1.4 Server-less	2	2	2	2	0	$2 \times 5 + 2 \times 4 + 2 \times 3 + 2 \times 2 + 0 \times 1 = 28$

TABLE 2 The evaluation of the coupling architectures

interprocess parallel capability is impossible under this architecture. As to the server-client and serverless coupling, though the popular data transfer is through networks and the speed is slower than that via memory, the shared memory could achieve rather high data transfer rate. Moreover, the potential interprocess parallel capability of the two architectures makes it possible to handle big cases by dispersing the tasks to plenty of processors, which will increase the calculation efficiency. These are the reasons why the serverclient and serverless coupling architectures make two scores while the internal coupling gets only one. As to the last option-the coupling through IO files-it is actually not a fully independent coupling architecture from the other three. Because the IO data communication must be realized by, at least one of the other three options. Nevertheless, the reason to include it in the lists is that the data transfer is not through neither memory nor networks but files, which is the most inefficient coupling method.

- 2. Flexibility: the codes involved in a serverless architecture could communicate with each other through their private channels upon demand. It is easy to assign and change specified data at specified channels. While for that in a server-client system, all of the information has to be in the control of one code or a standalone supervisor. Each client code is isolated from the other client codes. Changes or assignments of the transferred data usually go to two channels and the server. So, two scores are for the serverless and one is for server-client. The internal coupling and the IO coupling are the least flexible architectures because everything is frozen once the coupling is established for the former method. Any changes to the data would lead to modifications to the entire coupling system. As to the latter method, the condition is even more complex since new logics have to be developed in order to change the writing or reading content in the files. Therefore, no score was given to these two architectures.
- 3. Scalability: for the server-client and serverless coupling, the new well-developed component can be conveniently plugged into the coupling system without

significant modifications to the existing codes. Thus, they both get two scores thanks to their good scalability. Because of the same drawback, as explained in the previous paragraph, if new code integration is necessary, the entire existing system of the internal coupling have to be reorganized as an integral and the IO writing and reading logics of the existing IO coupling system have to be updated to include the new components. This is a repeatable and error-prone work, which should be avoided. Thus, no score is assigned to both methods.

- 4. Maintainability: this character has positive correlations with the flexibility and scalability of the coupled systems. For the server-client and serverless system, the codes update or upgrade could focus on specified components while keeping others untouched. Therefore, they both make two scores. For the internal and IO coupling, as it is mentioned above, no matter where the maintenance takes place, the entire system is affected. This is not the ideal way to maintain the codes while neither the worst way. Therefore, they both get one score here.
- 5. Simplicity: normally, the IO coupling is the easiest method because there is no need to dig into the code's numerical source but just concerns the input and output logic. The internal coupling is a little bit complex because the codes numeric has to be carefully inspected in order to properly organize the computation sequence of the coupling system. The worst situation regarding simplicity is found in case of the server-client and serverless system because not only the codes numeric should be inspected but also the parallel mechanisms have to pay lots of effort in order to achieve successful synchronization of the codes.

The evaluation of the operation mode is closely relevant to that of the coupling architecture and hence it can be treated as its subset to some extent. The scores are calculated in Table 3. From the evaluation of the coupling architecture, the parallel operation has overwhelming superiority over the serial mode on efficiency and scalability. While conversely, that outstanding superiority results in the complexity of the maintenance and

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S2: Operation Mode	Effic-4	Scala-3	Maint-2	Simp-1	Final score
S2.1 Serial	0	0	2	2	$0 \times 4 + 0 \times 3 + 2 \times 2 + 2 \times 1 = 5$
S2.2 Parallel	2	2	0	0	$2 \times 4 + 2 \times 3 + 0 \times 2 + 0 \times 1 = 14$

TABLE 3	The evaluation	of the	operation	mode
IADLES	The evaluation	of the	operation	mode

TABLE 4	The evaluation of the
domain coupli	ng options

S3: Domain Coupling	Robust-3	Realize-2	Simp-1	Final score
S3.1 Decomposition	1	0	2	$1 \times 3 + 0 \times 2 + 2 \times 1 = 5$
S3.2 Overlapping	2	2	0	$2 \times 3 + 2 \times 2 + 0 \times 1 = 10$

development of such coupling approaches. It is worth to note that the "parallel" mode here not only refers to the interprocess but also the inprocess parallelization. So, for the internal coupling, though the interprocess parallel is not available, the process itself could be parallelized, eg, the CFD codes. As a consequence, the maintainability here focuses on the entire system while not specified components or functions, which is slightly different from that of the coupling architecture.

Regarding the domain coupling, Table 4 shows the scores assigned to the two options. As explained before, the domain overlapping method is more robust and hence superior compared with the domain decomposition method. The criteria realizability and simplicity are related to the evaluation of the workload for users and developers. Users have to split the integral system code model into several pieces in order to connect with the subchannel or CFD-pieces if the domain-decomposition method is adopted. This is a repeatable, error-prone work and not user-friendly. On the contrary, in the case of the domain overlapping method, the model of the system code can be directly used. The only challenging task is the identification of the proper location in the source code where to get and put data. Moreover, the use of modern mesh manipulation libraries, eg, the MEDCoupling library could simplify this identification work and high-level automation of the domain matching can be implemented. On the contrary, the easier for the user, the more difficult for the developer, so the domain overlapping is rather tough to implement.

Table 5 shows the results of the evaluation of the three field-mapping approaches using the criteria described above. It is worth to note that the scores for the criteria are conditional and assumed to be well-developed.

1. Accuracy: if the users define the mesh relationships, the overlapping and interpolation of the meshes can hardly be calculated correctly unless the meshes are all of the regular shapes and regularly arranged. Poor mesh mapping may lead to errors. Alternatively, the user can develop special routines to handle this problem in a more convenient and accurate manner. However, this is an open problem depending heavily on the selected method and level of the toolkit. Finally, the third party library is characterized by high accuracy and interpolation functions.

- 2. Capability: generally speaking, the third party library is more powerful than other alternatives and it can handle more complicated cases than the private subroutines.
- 3. Universality: the third party library is able to handle various mesh or field mapping types and it is accessible for various coupled codes.
- 4. Efficiency and simplicity: the third party library has superior capability and can be adapted to various situations and cases. Consequently, the inter logics must be complex and special effort has to be made in order to properly use it. For all other options, the logic can be quite simple and just focus on specified problems. Therefore, they could reach high efficiency compared with the third party libraries.

The last evaluation is related to the temporal coupling. The scores are presented in Table 6. The difference between the three temporal coupling methods has already been well-discussed in Section 2.1. The data convergence between the coupled codes is not guaranteed under explicit coupling while for semiimplicit and implicit, the convergences can be both achieved through inner-iteration techniques and inherent matrix solutions, respectively. This is why both the accuracy and robustness of the last two methods get two scores while the explicit gets one. Moreover, for most cases, the system efficiency keeps growing from explicit, semi-implicit to implicit coupling, as a benefit from the better performance of the convergence. In the opposite direction, the coupling system becomes more complex because of the applied techniques accelerating the convergence rate.

S4: Field Mapping	Accur-5	Capab-4	Univ-3	Effic-2	Simp-1	Final score
S4.1 User manual	0	0	0	2	2	0x5 + 0x4 + 0x3 + 2x2 + 2x1 = 6
S4.2 User subroutine	1	1	0	1	1	1x5 + 1x4 + 0x3 + 1x2 + 1x1 = 12
S4.3 third party library	2	2	2	0	0	2x5 + 2x4 + 2x3 + 2x2 + 0x1 = 24

TABLE 5 The evaluation of the mapping approaches

TABLE 6 The evaluation of the temporal coupling options

S5: Temporal Coupling	Accur-4	Robust-3	Effic-2	Simp-1	Final score
S5.1 Explicit	1	1	0	2	$1 \times 4 + 1 \times 3 + 0 \times 2 + 2 \times 1 = 9$
S5.2 Semi-implicit	2	2	1	1	$2 \times 4 + 2 \times 3 + 1 \times 2 + 1 \times 1 = 17$
S5.3 Implicit	2	2	2	0	$2 \times 4 + 2 \times 3 + 2 \times 2 + 0 \times 1 = 18$

Considering the above tables for reference, the higher the score is, the better is the performance of the coupling system; or in other words, the more advanced is the coupling system. Moreover, the scores supply a quantitative standard for the selection of the multi-scale coupling approach. Figure 8 shows the main strategies as well as their substrategies unified based on the scores calculated from Table 2 to Table 6. From this Figure, it can be inferred that the level of the coupling system can be represented by the area covered by the closed curves. Two instances are displays in the radar map, the orange pentagon denotes the internal-serial-domain-decompositionuser-subroutine-explicit coupling and the green pentagon denotes the server-client-parallel-domain-overlappingthird-party-library-semi-implicit coupling.

3 | A REVIEW OF THE MULTISCALE THERMAL-HYDRAULIC COUPLED CODES

3.1 | Coupling of system code and subchannel code

The first multiscale thermal-hydraulic simulation of a nuclear power plant was done with the coupled code TRAC/COBRA-TF by the Pacific Northwest National Laboratory (PNNL).⁵⁵ It was a tight coupling at the level of the governing equations. Another multiscale coupled code of the system and subchannel codes is RELAP5/COBRA-TF developed by Korea Atomic Energy Research Institute (KAERI) where COBRA-TF was merged with RELAP5/MOD3⁵⁶ using parallel virtual machines (PVM).⁵⁷ This coupled code was verified⁵⁸ and finally, it forms the basis of the modern MARS code.⁵⁹ Several years later, RELAP5-3D and COBRA-TF were coupled using the PVM at the Bettis Atomic Power Laboratory

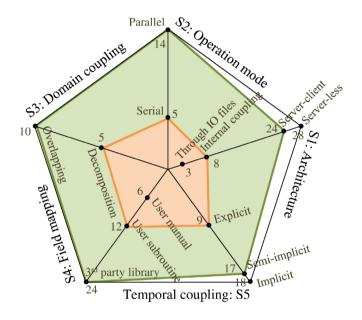


FIGURE 8 Quantized standard for the multi-scale coupling approaches selection [Colour figure can be viewed at wileyonlinelibrary.com]

(Betti Lab).⁶⁰ The new thermal-hydraulic code RELAP7 from the Idaho National Laboratory (INL) contains embedded subchannel capability that may be classified as an implicit coupling approach.⁶¹ The most recent coupling of system and subchannel codes are ATHLET/CTF developed at the Shanghai Jiaotong University (SJTU),⁶² Karlsruhe Institute of Technology (KIT)⁶³ (based on SALOME's⁶⁴ MEDCoupling library⁴⁴), and Technical University of Munich (TUM).⁶⁵ The system and subchannel thermal-hydraulic coupled codes are summarized in Table 7. In the table, the corresponding coupling approaches according to the classifications in Section 2.1 of those coupled codes are also given.

Moreover, the statics of the classified approaches are given in Figure 9, from which, it could be observed that developers intend to use relatively easier approaches to

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implement the coupling system, eg, internal over serverless coupling, serial over parallel coupling, domaindecomposition over overlapping coupling, user-manual definition of field mapping over third party universal libraries, and explicit over implicit coupling. As Section 2.2 stated, complex approaches usually indicate better performance of the coupled codes. The performance here could be the calculation efficiency and accuracy, the system's robustness, and the reliability and extensibility of the coupled codes.

3.2 | Coupling of system code and CFD code

It is worth to note that the coupling of system thermalhydraulic and CFD codes is a major trend in the context of multiscale coupling projects. Different versions of the RELAP5 code were first coupled with CFD code, eg, FLUENT. At INL, an in-deep review of the coupling methodologies and the treatment of the RELAP5-3D mass and energy conservation formulations,⁶⁶ the PVMEXEC tools⁶⁷ was carried out and base on it the coupling of RELAP-3D and FLUENT was realized.⁶⁸ The new capabilities of the RELAP-3D/FLUENT were demonstrated by the analysis of a very high-temperature reactor (VHTR).^{69,70} Later on, the Royal Institute of Technology (KTH) investigated the coupling of FLUENT with RELAP5 using novel methods^{71,72} where the FLU-ENT data is used to correlate the closure coefficient, eg, friction coefficients of RELAP5.73 Another attempt to couple RELAP5 and FLUENT is performed at the University of Illinois at Urbana-Champaign (UIUC).⁷⁴ This coupling approach was applied for the analysis of the gas turbine-modular helium reactor (GT-MHR).75,76 In addition, RELAP5 with FLUENT was also coupled at the Xian Jiaotong University (XJTU), where RELAP5 was compiled as a library (refer to Figure 2) and called by the FLUENT user-defined functions (UDF). It was verified with several cases⁷⁷ and went to practical applications.⁷⁸ At the University of Fukui (Uni Fukui), RELAP5 was coupled to FLUENT by means of IO-files, UDF, and a RELAP5 restart file.⁷⁹ This is a problem-oriented coupled system aiming to simulate the flow instability in steam generator U-tubes. At the University of Pisa (UniPi), RELAP5 was coupled with FLUENT UDF including parallel capability, where a MATLAB-script was written to wrap RELAP5.⁸⁰ It was applied for the simulation of natural and forced circulation tests⁸¹ and a heavy liquid metal system-TALL/3D (with a new semi-implicit method).82 At SCK-CEN, RELAP5-3D is coupled with FLUENT and tested using the data from the leadbismuth eutectic (LBE)—cooled test loop and facility.83,84

Review of the multiscale thermal-hydraulic coupling of system and sub-channel codes **TABLE 7**

Year	Year System	Sub or CFD	Sub or CFD Developer S1.1	S1.1	S1.2	S1.3	S1.3 S1.4 S2.1 S2.2 S3.1 S3.2 S4.1 S4.2 S4.3 S5.1 S5.2 S5.3 Ref	S2.1	S2.2	S3.1	S3.2	S4.1	S4.2	S4.3	S5.1	S5.2	S5.3	Ref
1983	TRAC	COBRA-TF	JNNI	×				x		x			x				x	Thurgood and George ⁵⁵
1992	RELAP5	COBRA-TF	KAERI			Х			х	×			х		х			Lee et al ⁵⁶
1999	MARS		KAERI	×				×		×			x		x			Jeong et al ⁵⁹
2002	RELAP5-3D	COBRA-TF	Bettis Lab			х			x	×						x		Aumiller et al ⁶⁰
2014	RELAP7			×				×		×							x	Zhang et al ⁶¹
2015	ATHLET	COBRA	SJTU					×			x	x			x			Liu and Cheng ⁶²
2016	ATHLET	COBRA	KIT			х			x		x			х	x			Escalante et al ⁶³
2016	ATHLET	COBRA-TF	TUM						х	х		х			х			Périn ⁶⁵
Note. S1.1,	internal coupling	r; S1.2, through IO	files; S1.3, server	-client;	S1.4, serve	srless; S2.	1, serial;	S2.2, pai	allel, S3.	1, decom	position;	S3.2, 0V6	erlapping	: S4.1, us	er manua	al; S4.2, u	iser subro	Note. S1.1. internal coupling: S1.2. through IO files: S1.3. server-client: S1.4. serverless: S2.1. serial: S2.2. parallel. S3.1. decomposition: S3.2. overlapping: S4.1. user manual: S4.2. user subroutine: S4.3. third party libs:

S5.1, explicit; S5.2, semi-implicit; S5.3, implicit.

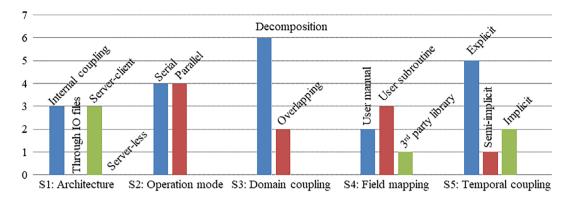


FIGURE 9 Statistical histogram of the system/sub-channel coupling approaches usage [Colour figure can be viewed at wileyonlinelibrary.com]

It was also applied to the analysis of a protected loss flow transient in an LBE-cooled experimental reactor.⁸⁵

Despite FLUENT, some other CFD or subchannel codes were also coupled to RELAP5 or RELAP5-3D. At Betti Lab, RELAP5-3D was coupled with CFX⁸⁶ using PVM and it was the first time where a semi-implicit coupling methodology⁸⁷ was implemented into the multiscale thermalhydraulic analysis.^{88,89} At the University of Pisa (UniPi), RELAP5-3D was coupled to CFX with a supervisor.⁹⁰

The system thermal-hydraulic code ATHLET was also coupled with CFX⁹¹ and was tested against the experimental data.^{92,93} The coupled code was then applied to some experimental facilities.^{94,95} In addition, UJV-Rez coupled ATHLET to FLUENT using IO-files for the data transfer and a supervisor script.^{96,97} Additionally, ATHLET was coupled to the open-source code OpenFOAM at KIT⁹⁸ and it was applied to simulate the natural convection test of sodium-cooled fast reactor (SFR)—Phénix.

The system code TRACE was first coupled to CFX at Paul the Scherrer Institute (PSI) using the PVM and both explicit and semi-implicit temporal coupling approach.99 The work was verified using data from the double Tjunction experiment and the FLORIS experiment.¹⁰⁰ At the National Tsing Hua University, TRACE was coupled to FLUENT and both the ROCOM test facility and Maanshan Nuclear Power Plant (NPP) were investigated.¹⁰¹ In addition, TRACE was coupled with the STAR-CCM+ at the University of Michigan. In this peculiar work, the CFDcode provides precise pressure drop to correlate the TRACE friction factors. Moreover, a new technique was developed to force TRACE to reproduce CFD-like velocity profiles. This new approach paved the way for new universal multiscale analysis tool for the nuclear reactor applications. It is able to handle both 1D¹⁰² and 3D¹⁰³ cases.¹⁰⁴ In connection with this work, the domain decomposition and overlapping methods¹⁰⁵ are discussed in detail.

Another multiscale coupling approach was implemented at CEA to couple CATHARE with TRIO_U in 2008. It was applied to the analysis of a gas fast reactor (GFR)¹⁰⁶ and later on to SFR,¹⁰⁷ ie, for the simulation of the Phenix reactor natural circulation test.^{108,109} At KAERI and Seoul National University (SNU), MARS was coupled to the CFD code CUPID^{110,111} These codes were applied to the simulation of tests such as PASCAL, VAPER,¹¹² and FRIGG and to assess the PWR steam generator (SG).¹¹³ Some other code pairs, eg, SAS4A-SASSYS-1/STAR-CD,¹¹⁴ CATHERA/STAR-CCM +,¹¹⁵ and FLOW1D/NPHASE.¹¹⁶ In different papers,¹¹⁷⁻¹¹⁹ the different multiscale coupling approaches are also compared with the coupling methods and the performance.

The coupling of system thermal-hydraulic codes and CFD codes as well as the applied coupling approaches are listed in Table 8 in chronological order.

Figure 10 plots the statistics of the various applied system/CFD coupling approaches. Similar to that of the system/ subchannel coupling approach, developers intend to use relatively easier approaches to implement the coupling system.

The coupling of CFD codes and system codes are now the main trend in the nuclear community. Nevertheless, the coupling of subchannel code and system code is also under consistent investigation. As a supplementation, the coupling of a subchannel code and CFD code is also drawing attention nowadays though there are limited cases published, eg, the coupling of TrioCFD with the subchannel code Subchanflow in the University of Science and Technology of China where the domain-decomposition, explicit, and MEDCoupling methods are used. Another such coupled code was in CEA where TrioCFD couples with a subchannel code—Trio MC. Moreover, they are coupled with the system code—CATHARE. This work is under the framework of the ASTRID project for a generation-IV sodium fast reactor.¹²³

3.3 | A special review of the domain overlapping approach

Domain decomposition and domain overlapping are the two options for domain coupling. Since domain overlapping is a new, efficient, promising, but complicated

S5.2 S5.3 Ref	Kliem et al ¹²⁰	Aumiller et al ⁸⁶	x Aumiller et al ⁸⁹	x Aumiller et al ⁶⁰	Schultz and Weaver ⁶⁸	Perdu and Vandroux ¹⁰⁶	Papukchiev and Lerchl ⁹¹	Cadinu and Kudinov ⁷²	Fanning and Thomas ¹¹⁴	x Yan ⁷⁶	x Bertolotto ¹⁰⁰	Mengali et al ⁹⁰	Macek and Vyskoci ⁹⁶	Huber et al ⁹⁸	Szymanski ¹¹⁵	Park et al ¹¹⁰	Palazzi et al ¹²¹	Cheng and Hassan ¹²²	x Theodoridis et al ⁹³	Bavière et al ¹⁰⁹	Cho et al ¹¹¹	Li et al ⁷⁷	Watanabe et al ⁷⁹	Martelli et al ⁸⁰	Ku et al ¹⁰¹	Grunloh and Manera ¹⁰²	x Toti et al ⁸³	Grunloh and Manera ¹⁰³
S5.1			~	ĥ																								
S4.3 S		x			X	X	X	X	×	X	×	×	×	x	X	X	X	x	X	X	X	X	X	X		X	X	X
S4.2																												
S4.1	×	×	x		х		х	x	х	×	×	×	×	×	x	х	x	x	x	x	×	x	x	x		x	x	х
S3.2						Х		х	x				х					х		х						Х		x
S3.1	×	×	×	x	x	x	x			×	×	×		×	x	x	×		×		×	×	×	×			×	
S2.2		x	х	х	х					×	x									х				х				
S2.1	x						х	х	x	x		x	x	х	х	Х	х	х	х		х	х	х			Х	Х	x
S1.4										х	х																Х	
S1.3		х	х	х	х	х						x	x							х								
S1.2							х		×	×		x	x	х	Х								х	х			х	
S1.1								x								х		х	х		x	x				x		х
Developer	FZR	Bettis Lab	Bettis Lab	Bettis Lab	INL	CEA	GRS	KTH	ANL	UIUC	ISI	UniPi	UJV Rez	KIT	McMacter	KAERI	ICL	KTH	GRS	CEA	SNU	XJTU	U-fukui	UniPi	NTHU	UMICH	SCK-CEN	UMICH
Sub or CFD	CFX	CFX	CFX	COBRA-TF	FLUENT	TRIO_U	CFX	FLUENT	STAR-CD	FLUENT	CFX	CFX	FLUENT	OpenFOAM	STAR-CCM+	CUPID	STAR-CCM+	STAR-CCM+	CFX	TRIO_U	CUPID	FLUENT	FLUENT	FLUENT	FLUENT	STAR-CCM+	FLUENT	STAR-CCM+
System	ATHLET	RELAP5-3D	RELAP5-3D	RELAP5-3D	RELAP5-3D	CATHARE	ATHLET	RELAP5	SAS4A- SASSYS-1	RELAP5-3D	TRACE	RELAP5	ATHLET	ATHLET	CATHENA	MARS	RELAP5-3D	RELAP5	ATHLET	CATHARE2	MARS	RELAP5	RELAP5	RELAP5	TRACE	TRACE	RELAP5-3D	TRACE
Year	1999	2001	2002	2002	2002	2008	2009	2009	2010	2011	2011	2012	2013	2013	2013	2013	2013	2013	2014	2014	2014	2014	2014	2014	2015	2016	2017	2017

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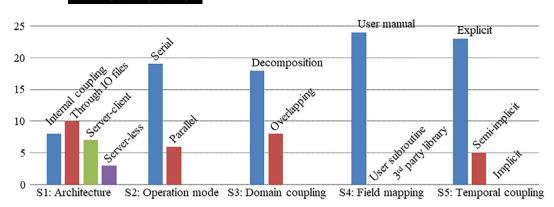


FIGURE 10 Statistical histogram of the system/CFD coupling approaches usage [Colour figure can be viewed at wileyonlinelibrary.com]

approach in a code coupling picture, it is essential to make a deep investigation of it. Here, a special review of this approach is presented.

In a multiscale domain overlapping simulation, system codes simulate the whole model and subchannel or CFD codes simulate specific components or parts resulting in several obvious overlapped domains. The revealed superiority of the domain overlapping approach over the domain decomposition approach is that the former method is more robust and efficient than the latter one. Meanwhile, another latent advantage of the domain overlapping approach is that the models for coupled and standalone system codes are identical. Thus, no additional modifications are required to transfer models from system code standalone to a coupled version, which is always a compulsory task for a domain-decomposition approach where some additional interfaces have to be defined and added to the original standalone models.

Despite the two superiorities, drawbacks of the domain-overlapping approach are also apparent:

- intensive alterations to the system code source could go deep down to the governing equation set in order to properly use the data from subchannel or CFD codes since there are no predefined interfaces in the system code receiving the incoming data as updated boundary conditions;
- 2. as a consequence of the first drawback, in-depth understanding of the source code and heavy programming work are necessary.

Because of the above difficulties, the domain overlapping approach is only applied to limited multiscale coupling cases, despite its seductive superiorities.

3.3.1 | CATHARE/TRIO_U

The first domain overlapping effort for multiscale coupling reported in literature is the development of the coupling system of a system code—CATHARE and a CFD code TRIO_U. CATHARE was developed in collaboration between CEA, EDF, IRSN, and AREVA-NP for more than 30 years. It could simulate various types of nuclear reactors including pressurized water reactors, gas-cooled reactors, and heavy metal reactors, etc. TRIO_U was developed in CEA and is specially designed for industrial CFD calculations on structured and nonstructured grids. It was split into the TRUST platform and an open-source CFD code—TrioCFD in 2015.

Their coupled pair was first presented and used for transient analysis in a GFR, in which the two involved codes were equipped with a generic API and were coordinated by a third supervisor.¹⁰⁶ The simulated transient was a blackout scenario where the whole reactor is modeled with CATHARE while only the 3D upper plenum is modeled with TRIO_U. During the coupling calculation, CATHARE provides coolant mass flow rate and temperature at the core outlet as the inlet boundary conditions of TRIO U, while the outflow coolant mass flow rate from CATHARE was used as the TRIO U outlet boundary condition instead of the classical imposed pressure outlet. After completing a step forward, TRIO U gives feedback on the coolant temperature exiting the plenum and no further hydraulic feedbacks is available for CATHARE correlations.

An advanced application of the coupled codes to the Phénix SFR to better simulate the significant 3D TH phenomena due to nonsymmetrical situations or local buoyancy effects was mentioned in Tenchine et al¹⁰⁷ and was then minutely described by Bavière.¹⁰⁹ Moreover, it was further compared with a domain-decomposition coupled pairs—ATHLET/OpenFOAM in Pialle.¹¹⁸ This application also adopts a domain overlapping approach where the CFD domain is restricted to the core whereas the system code domains include both the core and the loops with their components. During the coupling calculation, CATHERA supplies coolant mass flow rate and enthalpy both as the inlet and outlet boundary conditions for

TRIO_U from the experience gained from the last application to GFR. TRIO_U then gives feedback of enthalpy and pressure difference at the codes' joint boundaries to CATHARE forcing, which reproduces the CFD-like TH results.

Compared with the application to GFR, the SFR application includes the pressure correlation. However, for both of them, only the physical fields locating downstream after the overlapped domains were correlated in the system codes, while the fields in the overlapped domains of the system code were never touched or correlated.

3.3.2 | SAS4A/SASSYS-1/STAR-CD

SAS4A/SASSYS-1 was a nuclear system code developed by the US Argonne National Laboratory, which was originally developed for SFR while now extended to other liquid metal reactors. STAR-CD is the legacy CFD package of CD-adapco which is a commercial CFD code with a wide range of applications including buoyancy-driven flows and heat transfer. The first coupling attempt was performed with a 4S facility model whose main bodies are a core and an outlet plenum. Kind of a domain overlapping method was applied here since SAS4A/SASSYS-1 models the whole facility while STAR-CD simulates the outlet plenum. However, this case can be hardly classified as classical coupling because the new thermalhydraulic boundary data of STAR-CD was simply exported from SAS4A/SASSYS-1 while no feedback was available in the reverse direction. In other words, it is a so-called "one-way" coupling.

Later on, with the same facility, the capability of the coupled pair was improved by implementing feedbacks from STAR-CD to SAS4A/SASSYS-1 and the correlations now are on the fly.¹¹⁴ During the coupling calculation, the thermal-hydraulic parameters, eg, coolant mass flow rate, temperature, and pressure are transferred from SAS4A/SASSYS-1 as updated inlet and outlet boundary conditions to STAR-CD. Once the CFD code finishes the current step calculation, the pressure difference was added to the plenum inlet in the system code to correlate its total pressure drop and mass flow rate. The system temperature is correlated in a little bit complicated but similar way. Apparently, all of the fine feedback from STAR-CD to SAS4A/SASSYS-1 performs only in the boundary nodes. Though the pressure field in the overlapped domain of the system model was quasi-correlated due to the additional pressure source at the plenum inlet, the field distribution does not reflect the CFD results. This is a similar spatial coupling approach as that of CATHARE/TRIO_U.

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3.3.3 | RELAP5/STAR-CCM+

RELAP5 is the outstanding system code by the US NRC, and STAR-CCM+ is the commercial CFD software which is one of the featured products of CD-adapco since 2004. This coupling work was carried out under the European project THINS which devoted to the development and validation of advanced multiscale simulation tools for Gen IV reactors.^{124,125} The LBE thermal-hydraulic loop TALL-3D which has three vertical "legs" and a pool-type 3D test section was used to test the coupled pair, in which, RELAP5 models the entire facility while only the 3D test section was simulated by STAR-CCM+. From the perspective of modeling, this is a domain overlapping coupling, but the limitation is that the feedback from CFD codes only takes place at the boundaries of the overlapped domains in the system codes. Especially, the feedback in this case only contains coolant temperature by adding a so-called "virtual heater," which is assumed having extremely high thermal conductivity and extremely low heat capacity to the outlet of the overlapped domain in the system model. Similar to CATH-ARE/TRIO U, only the downstream after the 3D test section could be influenced.

3.3.4 | RELAP5/FLUENT

A refreshing method was invented for the coupling of RELAP5 and FLUENT, which is significantly different from the previous three attempts and points out the most promising direction for the domain overlapping approach. In this coupled pair, the feedback from CFD codes no longer only takes place at the codes' joint boundaries but to the entire overlapped domains of the system codes. Benefit from this feature, the system codes now could produce CFD-like fields in the entire overlapped domains. Different from the typical additional source term method (ASTM), the fine-resolution fields from CFD codes are now used to update the energy loss coefficients caused by form and friction in the system code. It behaves differently from directly appending fixed sources or sinks to the governing equations, thus force system code produces CFD-like pressure drop and distribution in a more logical and robust manner.

This method uses data from FLUENT to close the RELAP5 equation set, thus was named to "closure-on-demand"⁷¹ or "coupling-by-closure"⁷² method. It inspected the motion equation of RELAP5 in detail and drops the calculation units of the convective pressure drop as well as the form-friction pressure drop from the equation and use the total pressure drop from FLUENT

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to represent the two drop items by imposing the two effects all into the form-friction loss coefficient. It is worth to note here that the correlation is only for the pressure field since only the motion equation was modified. Moreover, this work is a "one-way" coupling since only data from FLUENT was passed to RELAP5 while nothing was done to update FLUENT boundary conditions. Another clue indicating this is a not well-developed coupling work is that the synchronization between RELAP5 and FLUENT is not guaranteed because the correlations performed with pretty large time intervals compared with the real transient time step size. At the very beginning of the development work, the results of FLU-ENT were first processed forming a reference data table. Then the correlations to RELAP5 were evaluated on the fly by linear interpolation from the table values. Even for the follow-up strengthened method where the correlations from CFD were written in the RELAP5 restart file for potential usage, it is still not that a convenient and automatic way for efficient coupling.

Despite the insufficient development of the coupled code—RELAP5/STAR-CCM+, the idea using CFD data to calculate closure coefficients for the whole overlapped domain in the system code is the most precious highlight and figuring out the most effective direction to implement domain-overlapping coupling.

3.3.5 | TRACE/STAR-CCM+

Following the basic idea from the previous coupling work of RELAP5/FLUENT, a new coupled pair of the US NRC system code TRACE and the CFD code STAR-CCM+ was developed. The updated boundary conditions of STAR-CCM+ first come from a complete step of TRACE and then its fine fields are used to calculate the new closure coefficients for TRACE, forcing which produce CFD-like TH distributions in the entire overlapped domain. This coupled pair works well for both 1D¹⁰² and 3D¹⁰⁴ system models. And as a supplement to the correlation for convective and form-friction pressure drops in RELAP5/FLUENT, the initial effect was also wellexamined and eliminated from the total pressure drop from STAR-CCM+ to counteract the non-erasable initial pressure drop in TRACE motion equation. What's more, the velocity fields in the system overlapped domain could be correlated by applying a newly developed "velocity matching faces (VMF)" method to reconstruct the disrupted inner-relationship between the pressure and velocity fields. Another highlight of this work is the indepth exploration and optimization of the performance of this domain overlapping coupling approach, and as a consequence of which the inertial domain overlapping (IDO) and stabilized IDO (SIDO) methods were put forward.

This is the first well-developed coupled code using the closure-updated method for domain overlapping coupling where the feedback is bidirectional and the data synchronization is strictly ensured by adopting an operator splitting (OP) temporal coupling method.⁵⁴ For the test phase, various academic cases were applied and the results were quite encouraging.

4 | CONCLUSION

Multiscale thermal-hydraulic analysis and code coupling for nuclear power system simulations are increasingly becoming a promising area nowadays. Within the scope, the particular capabilities of nuclear system codes, subchannel codes, and CFD codes are combined together to better describe and predict physical phenomena inside a nuclear power system. This paper classifies the multiscale coupling approaches to five main strategies: coupling architecture, operation mode, domain coupling, field mapping, and temporal coupling. Each of the five main strategies is further classified into several subcategories in order to cover all possible coupling approaches. Consequently, the paper puts forward a standard summarizing and classifying the multiscale thermal-hydraulic coupling approaches. On the basis of the standard, the paper evaluates those classified approaches based on a newproposed criterion. Quantized scores are graded to the approaches, thus researchers now have a clear and logical guideline when planning the coupling project and selecting appropriate coupling methods. Furthermore, a general review of the multiscale thermal-hydraulic coupled codes including the coupling of system code and subchannel code and the coupling if system code and CFD code is made based on the standard. The review helps researchers have clear picture of the history and development sequence of the coupled codes. Especially, a review of the domain overlapping approach is made considering it is the most promising but challenging method for multiscale thermal-hydraulic simulation. In short, this work supplies a reference for future multiscale simulation tools' development. It is an effort to standardize the nomenclature and selection of the multiscale thermal-hydraulic coupling procedures.

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