



On the two-dimensional Boussinesq equations with temperature-dependent thermal and viscosity diffusions in general Sobolev spaces

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Abstract. We study the existence, uniqueness as well as regularity issues for the two-dimensional incompressible Boussinesq equations with temperature-dependent thermal and viscosity diffusion coefficients in general Sobolev spaces. The optimal regularity exponent ranges are considered.

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1. Introduction

In the present paper, we consider the two-dimensional incompressible Boussinesq equations

$$\begin{cases} \partial_t \theta + u \cdot \nabla_x \theta - \operatorname{div}_x (\kappa \nabla_x \theta) = 0, \\ \partial_t u + u \cdot \nabla_x u - \operatorname{div}_x (\mu S_x u) + \nabla_x \Pi = \beta \theta \vec{e}_2, \\ \operatorname{div}_x u = 0, \end{cases} \quad (1.1)$$

where $(t, x) \in [0, \infty) \times \mathbb{R}^2$ denote the time and space variables, respectively. The unknown temperature function $\theta = \theta(t, x) : [0, \infty) \times \mathbb{R}^2 \rightarrow \mathbb{R}$ satisfies the parabolic-type equation (1.1)₁, and the unknown velocity vector field $u = u(t, x) : [0, \infty) \times \mathbb{R}^2 \rightarrow \mathbb{R}^2$ together with the unknown pressure term $\Pi = \Pi(t, x) : [0, \infty) \times \mathbb{R}^2 \rightarrow \mathbb{R}$ satisfies the incompressible Navier–Stokes type equations (1.1)₂–(1.1)₃, respectively. We are going to study the well-posedness and regularity problems for the Boussinesq system (1.1) together with the initial data

$$(\theta, u) |_{t=0} = (\theta_0, u_0). \quad (1.2)$$

We write $x = \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} \in \mathbb{R}^2$ with x_1, x_2 denoting the horizontal and vertical components, respectively.

Let $u = \begin{pmatrix} u^1 \\ u^2 \end{pmatrix} : [0, \infty) \times \mathbb{R}^2 \rightarrow \mathbb{R}^2$, and let

$$\frac{1}{2} S_x u := \frac{1}{2} (\nabla_x u + (\nabla_x u)^T), \text{ with } \nabla_x u = (\partial_{x_j} u^i)_{1 \leq i, j \leq 2}$$

denote the symmetric deformation tensor in the second equation (1.1)₂ above. The vector field \vec{e}_2 denotes the unit vector in the vertical direction: $\vec{e}_2 = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$, and $\beta \theta \vec{e}_2$ stands for the buoyancy force, with the constant parameter $\beta > 0$ denoting the thermodynamic dilatation coefficient which will be assumed to be 1 in the following context for simplicity.

We consider the cases when the heat diffusion and the viscosity in the fluids are sensitive to the change of temperatures, that is, the thermal diffusivity κ and the viscosity coefficient μ may depend on the temperature function θ as follows

$$\kappa = a(\theta), \quad \mu = b(\theta), \quad \text{with } \kappa_* \leq a \leq \kappa^*, \quad \mu_* \leq b \leq \mu^*, \quad (1.3)$$

where $\kappa_* \leq \kappa^*$, $\mu_* \leq \mu^*$ are positive constants. We will not assume any smallness conditions on $\kappa^* - \kappa_*$ or $\mu^* - \mu_*$, and large variations in these diffusivity coefficients are permitted.

The Boussinesq system (1.1) arises from the zero order approximation to the corresponding inhomogeneous hydrodynamic systems, which are nonlinear coupling between the Navier–Stokes equations or Euler equations and the thermodynamic equations for the temperature or density functions: The Boussinesq approximation [5] ignores density differences except when they appear in the buoyancy term. They are common geophysical models describing the dynamics from large-scale atmosphere and ocean flows to solar and plasma inner convection, where density stratification is a typical feature [22, 34].

The temperature or density differences in the inhomogeneous fluids may cause *density gradients*. When the thermodynamical coefficients such as the heat conducting coefficients and the viscosity coefficients are assumed to be constant in the Boussinesq approximation [i.e., κ , μ are constants in (1.1)], density gradients influence the motion of the flows only through the buoyancy force, which may lead to finite time singularity in the flows (the formation of the finite time singularity is sensitive to the thermal and viscous dissipation and see Sect. 1.1 below for more references on this topic).

However, the temperature variations do influence the thermal conductivity and the viscosity coefficients effectively, even for simple fluids such as pure water [32, Sect. 6].^{1, 2} In many applications in the engineering, one also aims for effective thermal conductivities in building thermal energy storage materials [21]. Therefore in plenty of physical models, density gradients would influence the motion of the fluids not only through buoyancy force, but also through the variations of the diffusion coefficients. It is then interesting to study the well-posedness and regularity problems of the Boussinesq system (1.1)–(1.3).

1.1. Known results

The well-posedness and regularity problems on the two-dimensional Boussinesq equations have attracted considerable attention from the PDE community. Many interesting mathematical results have been established in the past two decades, mainly in the cases with constant thermal diffusivity coefficient κ and viscosity coefficient μ :

$$\begin{cases} \partial_t \theta + u \cdot \nabla_x \theta - \kappa \Delta_x \theta = 0, \\ \partial_t u + u \cdot \nabla_x u - \mu \Delta_x u + \nabla_x \Pi = \theta \vec{e}_2, \\ \operatorname{div}_x u = 0, \\ (\theta, u) |_{t=0} = (\theta_0, u_0). \end{cases} \quad (1.4)$$

If $\kappa = \mu = 0$, the two-dimensional inviscid Boussinesq equations (1.4) can be compared with the three-dimensional incompressible axisymmetric Euler equations with swirl, where the buoyancy force corresponds to the vortex stretching mechanism [35]. The local-in-time well-posedness as well as some

¹The absolute viscosity of the water under nominal atmospheric pressure in units of millipascal seconds is given by 1.793 (0°), 0.547 (50°), 0.282 (100°), respectively [32, pp. 6–186]. The thermal conductivity of the water under nominal atmospheric pressure in units of Watt per meter kelvin is given by 0.5562 (0°), 0.6423 (50°), 0.6729 (100°), respectively [32, Page 6-214].

²It is common to adapt the exponential viscosity law $\mu(T) = C_1 \exp(C_2/(C_3+T))$ and quasi-constant heat conductivity law $\kappa(T) = C_4$ for the liquids, while the viscosity law $\mu(T) = (\mu(T_m)) \frac{T}{T_m} \frac{T_m+C_5}{T+C_6}$ and the thermal conductivity law $\kappa(T) = C_6 \mu(T)$ for the gases, where T denotes the absolute temperature, T_m denotes the reference temperature, and C_j , $1 \leq j \leq 6$ are positive constants [37, 1].

blowup criteria have been well known for decades, see, e.g., [10, 11, 42]. We mention that an (improved) lower bound for the lifespan which tends to infinity as the initial temperature tends to a constant (and correspondingly, as the initial swirl tends to zero for the 3D axisymmetric Euler equations) was given in [11]. The fundamental global regularity problem for the 2D inviscid Boussinesq equations remains still open. Recently, an interesting example of finite-energy strong solutions with a finite weighted Hölder norm in a wedge-shaped domain, which become singular at the origin in finite time, has been given in [19] (see also an interesting example of solutions in Hölder-type spaces with finite-time singularity for 3D axisymmetric Euler equations in [18]).

If $\kappa > 0$ and $\mu > 0$ are positive constants, on the contrary, the convection terms can be controlled thanks to the strong diffusion effects, and the global-in-time existence and regularity results can be established (see, e.g., [7]). Particular interests then raised if only partial dissipation is present, that is, either $\kappa = 0$ whereas $\mu > 0$ or $\kappa > 0$ whereas $\mu = 0$ (see, e.g., H.K. Moffatt's list of the twenty first century PDE problems [36]). The global-in-time results continue to hold, thanks to a priori estimates in the L^p -framework as well as the sharp Sobolev embedding inequality in dimension two with a logarithm correction, which help the partial diffusion terms to control the demanding term $\partial_{x_1}\theta$ successfully (see [9, 27] and see [24] for less regular cases). Further developments were made for horizontal dissipation cases (see, e.g., [13]), for vertical dissipation cases (see, e.g., [8]), and for the fractional dissipation cases (see, e.g., [25, 26]). See the review notes [43] and the references therein for more interesting results and sketchy proofs.

There also have been remarkable progresses in solving the two dimensional Boussinesq equations (1.1)–(1.3) when the thermal and viscosity diffusion coefficients κ, μ are variable and depend smoothly on the unknown temperature function θ . In the variational formulation framework, the global-in-time existence of a solution of (1.1)–(1.3) has been established in [17] [see [20] for a similar formulation of (1.1)–(1.3)] for the motion of the so-called Bingham fluid (as a non-Newtonian fluid), where κ is a positive constant, $\beta = 0$ and μ depends not only on θ but also on $Su/|Su|$. The Boussinesq–Stefan model has been investigated in [38], where the phase transition was taken into account. The global-in-time existence and the uniqueness of the solutions for (1.1)–(1.3) have been shown in [15, 23, 33] under Dirichlet boundary conditions and in [37] under generalized outflow boundary conditions. We remark that the resolution of the nonhomogeneous Boussinesq system under more physical boundary conditions (e.g., with Dirichlet boundary conditions only on the inflow part of the boundary while with no prescribed assumptions on the outflow part) remains unsolved.

Lorca and Boldrini [33] (see also [15, 23]) studied the initial-boundary value problem of the Boussinesq system (1.1)–(1.3) in dimension two and three under the initial condition (1.2) and Dirichlet boundary conditions, and obtained a global-in-time weak solution

$$(\theta, u) \in (L_{\text{loc}}^\infty([0, \infty); L^2(\Omega)))^3$$

as well as a local-in-time unique strong solution

$$(\theta, u) \in L_{\text{loc}}^\infty([0, \infty); H^2(\Omega)) \times (L_{\text{loc}}^\infty([0, \infty); H^1(\Omega)))^2. \quad (1.5)$$

The remarkable global-in-time existence and uniqueness results of the smooth solutions

$$(\theta, u) \in (L_{\text{loc}}^\infty([0, \infty); H^s(\mathbb{R}^2)) \cap L_{\text{loc}}^2([0, \infty); H^{s+1}(\mathbb{R}^2)))^3, \quad s > 2 \quad (1.6)$$

have been successfully established by Wang and Zhang [41], which affirms the propagation of high regularities (without finite time singularity) of the two dimensional Boussinesq flow in the presence of viscosity variations (see [39] for the case $s = 2$). We remark that the L_x^2 -norm of the velocity vector field may grow in time due to the buoyancy forcing term, even provided with constant diffusion coefficients and smooth and fast decaying small initial data [6], and hence the norm with respect to the time variable in (1.5) and (1.6) is only locally in time.

It is still not clear whether there will be finite time singularity for the two-dimensional Boussinesq flow (1.1)–(1.3) in the presence of viscosity variations while no heat diffusion (i.e., $\kappa = 0$, $\mu = b(\theta)$),

and we mention a recent work [2] toward this direction in the case of less heat diffusion (with $\operatorname{div}(\kappa \nabla \theta)$ replaced by $(-\Delta)^{1/2}$) and the small viscosity variation assumption: $|\mu - 1| \leq \varepsilon$. A closely related question would pertain to the global-in-time well-posedness problem of the two-dimensional inhomogeneous incompressible Navier–Stokes equations with density-dependent viscosity coefficient

$$\begin{cases} \partial_t \rho + u \cdot \nabla_x \rho = 0, \\ \partial_t(\rho u) + \operatorname{div}_x(\rho u \otimes u) - \operatorname{div}_x(\mu S_x u) + \nabla_x \Pi = 0, \\ \operatorname{div}_x u = 0, \\ (\rho, \rho u)|_{t=0} = (\rho_0, m_0). \end{cases} \tag{1.7}$$

The global-in-time existence results of weak solutions of (1.7) (see, e.g., [3, 31]) as well as the local-in-time well-posedness results (see, e.g., [28]) have been well known, while the global-in-time regularities still remain open (see, e.g., [1, 16] for some interesting results under the assumption on the weak inhomogeneity).

To the best of our knowledge, there are no global-in-time regularity propagation results by the two-dimensional Boussinesq flow with temperature-dependent diffusion coefficients (1.1)–(1.2)–(1.3) in the low regularity regime

$$H^s, \quad s < 2,$$

or in the general Sobolev setting

$$\theta_0 \in H_x^{s_\theta}(\mathbb{R}^2), \quad u_0 \in (H_x^{s_u}(\mathbb{R}^2))^2$$

with different regularity indices s_θ and s_u . In this paper, we are going to investigate the existence, uniqueness as well as the regularity problems in these general Sobolev functional settings.

To conclude this subsection, let us just mention some recent interesting progresses on the stability of the stationary shear flow solutions (together with the corresponding striated temperature function) to the Boussinesq equations (1.4), with full dissipation or partial dissipation, in, e.g., [14, 40, 44] and references therein. It should also be interesting to investigate the stability of the stationary striated solutions of the Boussinesq equations with variable diffusion coefficients (1.1). We mention a recent work in this direction on the incompressible Navier–Stokes equations with constant density function but with variable viscosity coefficient [30].

1.2. Main results

We are going to show the global-in-time existence of weak solutions to the Cauchy problem for the Boussinesq system (1.1)–(1.2)–(1.3) in the whole two-dimensional space \mathbb{R}^2 under the low-regularity initial condition $(\theta_0, u_0) \in L^2(\mathbb{R}^2) \times (L^2(\mathbb{R}^2))^2$. The uniqueness result holds true if the initial temperature function becomes smoother $(\theta_0, u_0) \in H^1(\mathbb{R}^2) \times (L^2(\mathbb{R}^2))^2$. Finally, we will establish the global-in-time regularity of the solutions in the general Sobolev setting $(\theta_0, u_0) \in H^{s_\theta}(\mathbb{R}^2) \times (H^{s_u}(\mathbb{R}^2))^2 \subset H^1(\mathbb{R}^2) \times (L^2(\mathbb{R}^2))^2$ with the restriction $s_u - 1 \leq s_\theta \leq s_u + 2$. These regularity exponent ranges are optimal for the existence, uniqueness and regularity results, respectively, by view of the formulations of the Boussinesq equations (1.1) with temperature-dependent diffusion coefficients (see Remark 1.3 below for more details).

We first define the weak solutions as follows.

Definition 1.1. (*Weak solutions*) We say that a pair (θ, u) is a weak solution of the Boussinesq equations (1.1)–(1.3) with the given initial data $(\theta_0, u_0) \in (L^2(\mathbb{R}^2))^3$ if the following statements hold:

- The temperature function

$$\theta = \theta(t, x) \in C([0, \infty); L_x^2(\mathbb{R}^2)) \cap L_{\text{loc}}^2([0, \infty); H_x^1(\mathbb{R}^2))$$

satisfies the initial condition $\theta|_{t=0} = \theta_0$, the energy equality

$$\frac{1}{2} \|\theta(T, \cdot)\|_{L^2_x(\mathbb{R}^2)}^2 + \int_0^T \int_{\mathbb{R}^2} (\kappa |\nabla \theta|^2)(t, x) dx dt = \frac{1}{2} \|\theta(0, \cdot)\|_{L^2_x(\mathbb{R}^2)}^2, \tag{1.8}$$

for all positive times $T > 0$, and the equation

$$\partial_t \theta + u \cdot \nabla \theta - \operatorname{div}_x (\kappa \nabla \theta) = 0 \tag{1.9}$$

in $L^2_{\text{loc}}([0, \infty); H_x^{-1}(\mathbb{R}^2))$.

- The velocity vector field

$$u = u(t, x) \in C([0, \infty); (L^2_x(\mathbb{R}^2))^2) \cap L^2_{\text{loc}}([0, \infty); (H^1_x(\mathbb{R}^2))^2)$$

satisfies the initial condition $u|_{t=0} = u_0$, the divergence-free condition $\operatorname{div}_x u = 0$, the energy equality

$$\begin{aligned} & \frac{1}{2} \|u(T, \cdot)\|_{L^2_x(\mathbb{R}^2)}^2 + \frac{1}{2} \int_0^T \int_{\mathbb{R}^2} (\mu |Su|^2)(t, x) dx dt \\ &= \frac{1}{2} \|u(0, \cdot)\|_{L^2_x(\mathbb{R}^2)}^2 + \int_0^T \int_{\mathbb{R}^2} (\theta u_2)(t, x) dx dt, \quad \forall T > 0, \end{aligned} \tag{1.10}$$

and the equation

$$\partial_t u + u \cdot \nabla_x u - \operatorname{div}_x (\mu S_x u) + \nabla_x \Pi = \theta \vec{e}_2 \tag{1.11}$$

in $L^2_{\text{loc}}([0, \infty); (H_x^{-1}(\mathbb{R}^2))^2)$ for some scalar function $\Pi \in L^2_{\text{loc}}([0, \infty) \times \mathbb{R}^2)$ with $\nabla \Pi \in L^2_{\text{loc}}([0, \infty); (H_x^{-1}(\mathbb{R}^2))^2)$ and $\int_{B_1} \Pi dx = 0$ a.e. t (with B_1 denoting the unit disk in \mathbb{R}^2).

For any fixed $T > 0, p \geq 1, q \geq 1, s \geq 0$ and for any fixed (vector-valued) function $f : [0, T] \times \mathbb{R}^2 \mapsto \mathbb{R}^m, m \geq 1$, we denote

$$\|f\|_{L^p_T X_x} := \|\|f(t)\|_{X_x(\mathbb{R}^2; \mathbb{R}^m)}\|_{L^p_t([0, T])} \text{ with } X = H^s \text{ or } L^q. \tag{1.12}$$

The functional space $L^p([0, T]; H^s(\mathbb{R}^2; \mathbb{R}^m))$ consists of all functions $f : [0, \infty) \times \mathbb{R}^2 \rightarrow \mathbb{R}^m$ satisfying $\|f\|_{L^p_T H^s_x} < \infty$. We have the following existence, uniqueness as well as global-in-time regularity results for the solutions of the Cauchy problem for the Boussinesq equations (1.1)-(1.2)-(1.3) on the whole two-dimensional space \mathbb{R}^2 .

Theorem 1.2. (Existence, uniqueness and global-in-time regularity) *For any initial data $\theta_0 \in L^2(\mathbb{R}^2)$ and $u_0 \in (L^2(\mathbb{R}^2))^2$, there exists a global-in-time weak solution*

$$(\theta, u) \in C([0, \infty); (L^2(\mathbb{R}^2))^3) \cap L^2_{\text{loc}}([0, \infty); (H^1(\mathbb{R}^2))^3)$$

of the initial value problem (1.1)–(1.2)–(1.3).

If $\theta_0 \in H^1(\mathbb{R}^2), u_0 \in (L^2(\mathbb{R}^2))^2$ and the functions $a \in C^2_b(\mathbb{R}; [\kappa_, \kappa^*]), b \in C^2_b(\mathbb{R}; [\mu_*, \mu^*])$ have finite first and second derivatives, then the weak solution is indeed unique, and satisfies*

$$\theta \in C([0, \infty); H^1(\mathbb{R}^2)) \cap L^2_{\text{loc}}([0, \infty); H^2(\mathbb{R}^2)),$$

as well as the following energy estimates for any given $T > 0$,

$$\|u\|_{L^\infty_T L^2_x}^2 + \|\nabla u\|_{L^2_T L^2_x}^2 \leq C(T \|\theta_0\|_{L^2}^2 + \|u_0\|_{L^2}^2), \tag{1.13}$$

$$\begin{aligned} & \|\theta\|_{L^\infty_T H^1_x}^2 + \|(\partial_t \theta, \nabla^2 \theta)\|_{L^2_T L^2_x}^2 \\ & \leq C \|\theta_0\|_{H^1}^2 (1 + \|\nabla \theta_0\|_{L^2}^2) \exp(C(T^2 \|\theta_0\|_{L^2}^4 + \|u_0\|_{L^2}^4)), \end{aligned} \tag{1.14}$$

where C is a positive constant depending only on $\|a\|_{\text{Lip}}, \kappa_*, \kappa^*, \mu_*$.

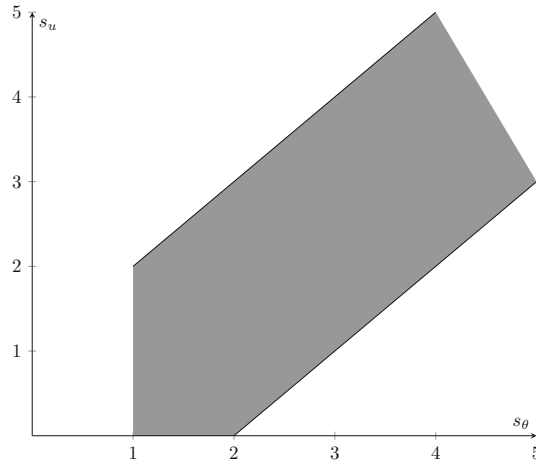


FIG. 1. Admissible regularity exponents

Furthermore, the general H^s -regularities can be propagated globally in time in the following sense: For any initial data (see the gray closed unbounded quadrangle in Fig. 1 for the admissible regularity exponent range)

$$\begin{aligned}
 (\theta_0, u_0) &\in H^{s_\theta}(\mathbb{R}^2) \times (H^{s_u}(\mathbb{R}^2))^2 \\
 &\text{with } (s_\theta, s_u) \in \{(s_\theta, s_u) \in [1, \infty) \times [0, \infty) \mid s_u - 1 \leq s_\theta \leq s_u + 2\}
 \end{aligned}
 \tag{1.15}$$

and the functions $a \in C_b^2 \cap C^{[s_\theta]+1}$, $b \in C_b^2 \cap C^{[s_u]+1}$, the unique solution (θ, u) stays in

$$C([0, \infty); H^{s_\theta}(\mathbb{R}^2) \times (H^{s_u}(\mathbb{R}^2))^2) \cap L_{loc}^2([0, \infty); H^{s_\theta+1}(\mathbb{R}^2) \times (H^{s_u+1}(\mathbb{R}^2))^2).
 \tag{1.16}$$

Theorem 1.2 will be proved in Sect. 2. The proof of the existence of weak solutions is rather standard, and we are going to sketch the proof in Sect. 2.1 for the reason of completeness, as we did not find the proof in the literature. As mentioned before, some well-posedness results have already been established for smooth data in the bounded domain case (see (1.5) above in, e.g., [15, 17, 23, 33]) or in smoother functional frameworks in the whole space case (see (1.6) above in, e.g., [41]). We are going to focus on the proofs of the uniqueness result and the global-in-time regularity result (in the low regularity regimes) in Sects. 2.2 and 2.3, respectively, where different regularity exponents for different unknowns are permitted. The commutator estimates as well as the composition estimates in Lemma 2.1 will play an important role, and the a priori estimates for a general linear parabolic equation in Lemma 2.2 will be of independent interest.

We conclude this introduction part with several remarks on the results in Theorem 1.2.

Remark 1.3. (Optimality of the regularity exponent ranges in Theorem 1.2) We are going to follow the standard procedure to show the existence of weak solutions for L^2 -initial data by use of the a priori energy (in)equalities (1.8) and (1.10) (see Sect. 2.1 below).

If we take the difference between two different weak solutions (θ_1, u_1) and (θ_2, u_2) , the difference of the nonlinear viscosity term $\operatorname{div}(\mu S u)$ in the u -equation will become

$$\operatorname{div}((\mu_1 - \mu_2) S u_1) + \operatorname{div}(\mu_2 S (u_1 - u_2)),$$

which stays in $L_{loc}^2([0, \infty); (H^{-1}(\mathbb{R}^2))^2)$ provided with

$$u_1 \text{ and } (u_1 - u_2) \in L_{loc}^2([0, \infty); (H^1(\mathbb{R}^2))^2),$$

$$\text{and } \mu_1 - \mu_2 \in L_{loc}^\infty([0, \infty); H^1(\mathbb{R}^2)) \subset L_{loc}^\infty([0, \infty); (L^1(\mathbb{R}^2))' = \operatorname{BMO}(\mathbb{R}^2)).$$

Therefore in order to ensure the L_x^2 -Estimate for the velocity difference $(u_1 - u_2)$, we require the H_x^1 -Estimate for the temperature difference in $(\mu_1 - \mu_2)$. And hence the initial condition $\theta_0 \in H_x^1$ (i.e., $s_\theta \geq 1$ above) is required for the proof of the uniqueness result (see Sect. 2.2 below).

Under the lower-regularity assumption $\theta_0 \in H_x^s$ with $0 < s < 1$, the coefficients κ, μ are not expected to be continuous uniformly in time, and hence no uniqueness or H^s -regularity results for θ or $H^{s_1}, s_1 > 0$ -regularity results for u are expected. Nevertheless with constant diffusion coefficients (e.g., $\kappa = \mu = 1$), the uniqueness result for the weak solutions holds true by virtue of the L_x^2 -energy (in)equalities (similar as the classical global-in-time well-posedness result for the classical two dimensional incompressible Navier–Stokes equations). Furthermore, if $\kappa = 1$ is a positive constant, then the $H_x^s, s \in (0, 1)$ -Estimate for θ holds true, provided with $u \in L_{\text{loc}}^4(L_x^4(\mathbb{R}^2))^2$ (or with $u_0 \in (L^2(\mathbb{R}^2))^2$), simply by an interpolation argument between (1.8) and (1.14). Similarly if $\mu = 1$ is a positive constant, then the $H_x^s, s > 0$ -Estimate for u holds true, provided with $\theta \in L_{\text{loc}}^2(H_x^{s-1}(\mathbb{R}^2))$. Thus with constant diffusion coefficients (e.g., $\kappa = \mu = 1$), the Sobolev regularities

$$(\theta_0, u_0) \in (H^s(\mathbb{R}^2)) \times (L^2(\mathbb{R}^2))^2 \text{ or } (L^2(\mathbb{R}^2)) \times (H^s(\mathbb{R}^2))^2, \quad 0 < s \leq 1$$

can be propagated globally in time, and the admissible regularity exponent set (1.15) extends itself indeed to the closed set consisting of all nonnegative admissible regularity exponents:

$$(s_\theta, s_u) \in \{(s_\theta, s_u) \in [0, \infty) \times [0, \infty) \mid s_u - 1 \leq s_\theta \leq s_u + 2\}.$$

In order to propagate the $H^{s_\theta}, s_\theta \geq 2$ -regularity of θ , we require the transport term $u \cdot \nabla \theta$ in the θ -equation to be at least in $L_{\text{loc}}^2([0, \infty); H_x^{s_\theta-1})$, which requires $u \in L_{\text{loc}}^2([0, \infty); H_x^{s_\theta-1})$ and hence the initial assumption $u_0 \in H^{s_u}$ with the restriction $s_u \geq s_\theta - 2$ (as there is a gain of regularity of order 1 when taking L^2 -norm in the time variable in general). Similarly, in order to propagate the $H^{s_u}, s_u \geq 2$ -regularity of u , we require the viscosity term $\text{div}(\mu S u)$ in the u -equation to be at least in $L_{\text{loc}}^2([0, \infty); H_x^{s_u-1})$, which requires $\mu S u \in L_{\text{loc}}^2([0, \infty); H_x^{s_u})$ and hence the initial assumption $\theta_0 \in H^{s_\theta}$ with the restriction $s_\theta \geq s_u - 1$.

Remark 1.4. (Precise H_x^s -Estimates in the high regularity regime) The global-in-time regularity in the high regularity regime (1.15)–(1.16) follows immediately from the following *borderline* a priori estimates:

- If $\theta_0 \in H^s(\mathbb{R}^2)$, $u_0 \in (L^2(\mathbb{R}^2))^2$ with $s \in (1, 2]$ and the function $a \in C_b^2(\mathbb{R})$, then for $s \in (1, 2)$ it holds

$$\begin{aligned} & \|\theta\|_{L_T^\infty H_x^s}^2 + \|\nabla \theta\|_{L_T^2 H_x^s}^2 \leq C(\kappa_*) \|\theta_0\|_{H_x^s}^2 \times \\ & \quad \times \exp\left(C(\kappa_*, s, \|a\|_{C^2}, \|\theta\|_{L_T^\infty H_x^1}) (\|\nabla u\|_{L_T^2 L_x^2}^2 + \|\nabla \theta\|_{L_T^2 H_x^1}^2)\right), \end{aligned} \quad (1.17)$$

and for $s = 2$ it holds

$$\begin{aligned} & \|\theta\|_{L_T^\infty H_x^2}^2 + \|\nabla \theta\|_{L_T^2 H_x^2}^2 \leq C(\kappa_*, \|a\|_{C^2}, \kappa^*) \|\theta_0\|_{H^2}^2 (1 + \|\nabla \theta_0\|_{L^2}^2) \\ & \quad \times \exp\left(C(\kappa_*, \|a\|_{\text{Lip}}) (\|\nabla u\|_{L_T^2 L_x^2}^2 + \|u\|_{L_T^4 L_x^4}^4 + \|\nabla \theta\|_{L_T^4 L_x^4}^4)\right). \end{aligned} \quad (1.18)$$

- If $\theta_0 \in H^1(\mathbb{R}^2)$, $u_0 \in (H^s(\mathbb{R}^2))^2$ with $s \in (0, 2]$ and the function $b \in C_b^2(\mathbb{R})$, then for $s \in (0, 2)$ it holds

$$\begin{aligned} & \|u\|_{L_T^\infty H_x^s}^2 + \|\nabla u\|_{L_T^2 H_x^s}^2 \leq C(\mu_*) (\|u_0\|_{H_x^s}^2 + T \|\theta_0\|_{L_x^2}^2 + \|\theta\|_{L_T^2 H_x^{s-1}}^2) \\ & \quad \times \exp\left(C(\mu_*, s, \|b\|_{C^2}, \|\theta\|_{L_T^\infty H_x^1}) (\|\nabla u\|_{L_T^2 L_x^2}^2 + \|\nabla \theta\|_{L_T^2 H_x^1}^2)\right), \end{aligned} \quad (1.19)$$

and for $s = 2$ it holds

$$\begin{aligned} & \|u\|_{L_T^\infty H_x^2}^2 + \|\nabla u\|_{L_T^2 H_x^2}^2 \leq (\|u\|_{L_T^\infty H_x^1}^2 + \|\nabla u\|_{L_T^2 H_x^1}^2) + C(\mu_*, \|b\|_{C^2}) \times \\ & \quad (1 + \|\Delta u_0\|_{L_x^2}^2) (1 + \|u\|_{L_T^\infty H_x^1}^2 + \|\nabla u\|_{L_T^2 H_x^1}^2)^2 (1 + \|\theta\|_{L_T^\infty H_x^1}^2 + \|\nabla \theta\|_{L_T^2 H_x^1}^2) \\ & \quad \times \exp\left(C(\mu_*, \|b\|_{C^2}) (\|(u, \nabla \theta)\|_{L_T^4 L_x^4}^4 + \|\nabla^2 \theta\|_{L_T^2 L_x^2}^2)\right). \end{aligned} \quad (1.20)$$

- If $\theta_0 \in H^s(\mathbb{R}^2)$, $u_0 \in (H^{s-2}(\mathbb{R}^2))^2$ with $s > 2$ and the function $a \in C^{[s]+1}$, then for $s \in (2, 3)$ it holds

$$\begin{aligned} \|\theta\|_{L_T^\infty H_x^s}^2 + \|\nabla\theta\|_{L_T^2 H_x^s}^2 &\leq C(\kappa_*)\|\theta_0\|_{H_x^s}^2 \times \\ &\times \exp\left(C(\kappa_*, s, a, \|\theta\|_{L_T^\infty L_x^\infty})(\|u\|_{L_T^2 H_x^{s-1}}^2 + \|\nabla\theta\|_{L_T^2 L_x^\infty}^2)\right), \end{aligned} \quad (1.21)$$

and for $s \geq 3$ it holds

$$\begin{aligned} \|\theta\|_{L_T^\infty H_x^s}^2 + \|\nabla\theta\|_{L_T^2 H_x^s}^2 &\leq C(\kappa_*, s)(\|\theta_0\|_{H_x^s}^2 + \|\nabla\theta\|_{L_T^\infty L_x^\infty}^2 \|\nabla u\|_{L_T^2 H_x^{s-2}}^2) \\ &\times \exp(C(\kappa_*, s, a, \|\theta\|_{L_T^\infty L_x^\infty})(\|\nabla u\|_{L_T^2 L_x^\infty}^2 + \|\nabla\theta\|_{L_T^2 L_x^\infty}^2)). \end{aligned} \quad (1.22)$$

- If $\theta_0 \in H^{s-1}(\mathbb{R}^2)$, $u_0 \in (H^s(\mathbb{R}^2))^2$ with $s > 2$ and the function $b \in C^{[s]+1}$, then for $s \in (2, 3)$ it holds

$$\begin{aligned} \|u\|_{L_T^\infty H_x^s}^2 + \|\nabla u\|_{L_T^2 H_x^s}^2 &\leq C(\mu_*)(\|u_0\|_{H_x^s}^2 + T\|\theta\|_{L_T^\infty H_x^{s-1}}^2) \\ &\times \exp(C(\mu_*, s, b, \|\theta\|_{L_T^\infty L_x^\infty})(\|\nabla u\|_{L_T^2 H_x^1}^2 + \|\nabla\theta\|_{L_T^2 H_x^{s-1}}^2)), \end{aligned} \quad (1.23)$$

and for $s \geq 3$ it holds

$$\begin{aligned} \|u\|_{L_T^\infty H_x^s}^2 + \|\nabla u\|_{L_T^2 H_x^s}^2 &\leq C(\mu_*)(\|u_0\|_{H_x^s}^2 + T\|\theta\|_{L_T^\infty H_x^{s-1}}^2 + \|\nabla u\|_{L_T^\infty L_x^\infty}^2 \|\nabla\theta\|_{L_T^2 H_x^{s-1}}^2) \times \\ &\times \exp(C(\mu_*, s, b, \|\theta\|_{L_T^\infty L_x^\infty})(\|\nabla u\|_{L_T^2 L_x^\infty}^2 + \|\nabla\theta\|_{L_T^2 L_x^\infty}^2)). \end{aligned} \quad (1.24)$$

We are going to prove the above borderline estimates one by one in Sect. 2.3 below.

Remark 1.5. (*L^2 -in time Estimate V.S. L^1 -in time Estimate*) Instead of the classical $L_t^\infty H_x^s \cap L_t^1 H_x^{s+2}$ -type estimate in the literature, we derive $L_t^\infty H_x^s \cap L_t^2 H_x^{s+1}$ -type estimate here, since, e.g., only the $L_t^2 H_x^1$ -a priori estimate for the velocity vector field is available from the energy estimates (roughly speaking, the L_t^2 -in time norm asks less spatial regularity on the coefficients). See Lemma 2.2 below for the a priori H_x^s , $s \in (0, 2)$ -Estimates for a general linear parabolic equation with divergence-free $L_t^2 H_x^1$ -velocity vector field, which is of independent interest.

It is in general not true that $\theta \in L_t^1 H_x^{s+2}$ (or $u \in L_t^1 H_x^{s+2}$) in the low regularity regime, although it holds straightforward in the high regularity regime.

Remark 1.6. (*Remarks on the smoothness assumptions on the functions a, b*) It is common to assume smooth heat conductivity law and viscosity law [37, I] in fluid models.

The Lipschitz continuity assumption $a, b \in \text{Lip}$ is enough for the $H^1 \times L^2$ -Estimates (1.13)–(1.14) in Theorem 1.2. As for the uniqueness result, due to the following \dot{H}_x^1 -Estimate for the difference of the diffusion coefficients

$$\begin{aligned} \|\nabla(a(\theta_1) - a(\theta_2))\|_{L_x^2} &\leq \|(a'(\theta_1) - a'(\theta_2))\nabla\theta_1\|_{L_x^2} + \|a(\theta_2)\nabla(\theta_1 - \theta_2)\|_{L_x^2} \\ &\leq \|a'\|_{\text{Lip}}\|\nabla\theta_1\|_{L_x^4}\|\theta_1 - \theta_2\|_{L_x^4} + \|a\|_{L^\infty}\|\nabla(\theta_1 - \theta_2)\|_{L_x^2}, \end{aligned}$$

the Lipschitz continuity assumptions $a', b' \in \text{Lip}$ are required.

The dependence on the function a of the constants C in (1.21)–(1.22) reads precisely as [similarly for the constants in (1.23)–(1.24)]

$$\sup_{k=0, \dots, [s]+1} \sup_{|y| \leq c\|\theta\|_{L_T^\infty L_x^\infty}} \left| \frac{d}{dy^k} a(y) \right|,$$

and hence only $a \in C^{[s]+1}$ (instead of $a \in C_b^{[s]+1}$) is required.

For the integer regularity exponents, we can simply derive the energy estimates by integration by parts (instead of the application of the commutator estimates or the composition estimates in Lemma 2.1 below), such that the requirement for $a \in C^{[s_\theta]+1}$ and $b \in C^{[s_u]+1}$ can be relaxed, see, e.g., (1.18), (1.20).

2. Proofs

Recall the Cauchy problem for the two-dimensional Boussinesq equations (1.1)–(1.3)

$$\begin{cases} \partial_t \theta + u \cdot \nabla \theta - \operatorname{div}(\kappa \nabla \theta) = 0, \\ \partial_t u + u \cdot \nabla u - \operatorname{div}(\mu S u) + \nabla \Pi = \theta \vec{e}_2, \\ \operatorname{div} u = 0, \\ (\theta, u) |_{t=0} = (\theta_0, u_0), \end{cases} \tag{2.1}$$

where $\kappa = a(\theta) \in L^\infty(\mathbb{R}; [\kappa_*, \kappa^*])$, $\mu = b(\theta) \in L^\infty(\mathbb{R}; [\mu_*, \mu^*])$ with $\kappa_*, \kappa^*, \mu_*, \mu^*$ four positive constants.

We are going to show the existence, uniqueness as well as the global-in-time regularity results in Theorem 1.2 in Sects. 2.1, 2.2 and 2.3, respectively.

Recall the definition of the $\|\cdot\|_{L_T^q X_x}$ -norm in (1.12). The Gagliardo–Nirenberg’s inequality

$$\|f\|_{L_T^4 L_x^4(\mathbb{R}^2)} \leq C \|f\|_{L_T^2 L_x^2(\mathbb{R}^2)}^{\frac{1}{2}} \|\nabla f\|_{L_T^2 L_x^2(\mathbb{R}^2)}^{\frac{1}{2}} \tag{2.2}$$

as well as the equivalence relations between the norms

$$\begin{aligned} \|S u\|_{L_x^2(\mathbb{R}^2)}^2 &= 2 \|\nabla u\|_{L_x^2(\mathbb{R}^2)}^2 \text{ if } \operatorname{div} u = 0, \\ \|\Delta \eta\|_{L_x^2(\mathbb{R}^2)} &\sim \|\nabla^2 \eta\|_{L_x^2(\mathbb{R}^2)} \end{aligned} \tag{2.3}$$

will be used freely in the proof.

2.1. Existence of weak solutions if $(\theta_0, u_0) \in (L^2(\mathbb{R}^2))^3$

We will follow the standard procedure to show the existence of the weak solutions under the initial condition

$$(\theta_0, u_0) \in L^2(\mathbb{R}^2) \times (L^2(\mathbb{R}^2))^2,$$

namely

Step 1 We construct a sequence of approximate solutions, which satisfy the energy estimates uniformly.

Step 2 We show the convergence of this approximate solution sequence to a weak solution and study the property of the weak solution.

We are going to sketch the proof and pay attention to the low-regularity assumptions.

Step 1: Construction of approximate solutions with uniform bounds

We use the Friedrich’s method to construct a sequence of approximate solutions. We consider the following system of (θ_n, u_n)

$$\begin{cases} \partial_t \theta_n + P_n(u_n \cdot \nabla \theta_n) - P_n \operatorname{div}(\kappa_n \nabla \theta_n) = 0, \\ \partial_t u_n + P_n \mathbb{P}(u_n \cdot \nabla u_n) - P_n \mathbb{P} \operatorname{div}(\mu_n S u_n) = \mathbb{P}(\theta_n \vec{e}_2), \\ u_n(0, x) = P_n u_0(x), \quad \theta_n(0, x) = P_n \theta_0(x), \end{cases} \tag{2.4}$$

where $\kappa_n = a(\theta_n)$ and $\mu_n = b(\theta_n)$. The operator P_n , $n \in \mathbb{N}$, is the low-frequency cutoff operator which is defined as follows

$$P_n f(x) = \mathcal{F}^{-1}(\mathbb{1}_{B_n}(\xi) \mathcal{F} f(\xi))(x),$$

where $B_n \subset \mathbb{R}^2$ is the disk with center at 0 and radius n , and $\mathcal{F}, \mathcal{F}^{-1}$ are the standard Fourier and inverse Fourier transformations. The operator \mathbb{P} in (2.4) denotes the Leray–Helmholtz projector on \mathbb{R}^2 , which decomposes the tempered distributions $v \in \mathcal{S}'(\mathbb{R}^2; \mathbb{R}^2)$ into div-free and curl-free parts as follows

$$v = \nabla^\perp V_1 + \nabla V_2, \tag{2.5}$$

where

$$\nabla^\perp V_1 = -\nabla^\perp(-\Delta)^{-1}\nabla^\perp \cdot v =: \mathbb{P}v, \quad \nabla V_2 = -\nabla(-\Delta)^{-1}\nabla \cdot v = (1 - \mathbb{P})v$$

with $\nabla^\perp = (\partial_{x_2}, -\partial_{x_1})^T$. Notice that \mathbb{P} maps $L^p(\mathbb{R}^2; \mathbb{R}^2)$ into itself for any $p \in (1, \infty)$ and it is commutative with the projection operator P_n .

We define the Banach spaces L_n^2 and $L_n^{2,\sigma}$ as following

$$\begin{aligned} L_n^2(\mathbb{R}^2) &= \{f \in L^2(\mathbb{R}^2) \mid f = P_n f\}, \\ L_n^{2,\sigma}(\mathbb{R}^2) &= \{f \in (L_n^2(\mathbb{R}^2))^2 \mid \operatorname{div}_x(f) = 0\}. \end{aligned}$$

The system (2.4) turns out to be an ordinary differential equation system in $L_n^2(\mathbb{R}^2) \times L_n^{2,\sigma}(\mathbb{R}^2)$. Indeed, the following estimates hold

$$\begin{aligned} \|P_n(u_n \cdot \nabla \theta_n) - P_n \operatorname{div}(\kappa_n \nabla \theta_n)\|_{L_x^2} &\leq Cn^3(\|u_n\|_{L_x^2} + \kappa^*)\|\theta_n\|_{L_x^2}, \\ \|P_n \mathbb{P}(u_n \cdot \nabla u_n) - P_n \mathbb{P} \operatorname{div}(\mu_n S u_n)\|_{L_x^2} &\leq Cn^3(\|u_n\|_{L_x^2} + \mu^*)\|u_n\|_{L_x^2}. \end{aligned}$$

Hence, for any $n \in \mathbb{N}$, there exists $T_n > 0$ such that the system (2.4) has a solution $(\theta_n, u_n) \in C([0, T_n]; L_n^2(\mathbb{R}^2)) \times C([0, T_n]; L_n^{2,\sigma}(\mathbb{R}^2))$.

We take the $L^2(\mathbb{R}^2)$ -inner product of Eq. (2.4)₁ and θ_n to derive

$$\frac{1}{2} \frac{d}{dt} \int_{\mathbb{R}^2} \theta_n^2 + \int_{\mathbb{R}^2} \kappa_n |\nabla \theta_n|^2 = 0.$$

Then, the following uniform estimate for (θ_n) holds

$$\frac{1}{2} \|\theta_n\|_{L_T^\infty L_x^2}^2 + \kappa_* \|\nabla \theta_n\|_{L_T^2 L_x^2}^2 dt \leq \frac{1}{2} \|P_n \theta_0\|_{L_x^2}^2 \leq \frac{1}{2} \|\theta_0\|_{L_x^2}^2, \quad \forall T > 0. \tag{2.6}$$

Similarly, we take the $L^2(\mathbb{R}^2)$ -inner product of Eq. (2.4)₂ and u_n to derive

$$\frac{1}{2} \frac{d}{dt} \|u_n\|_{L_x^2}^2 + \frac{1}{2} \|\mu_n S u_n\|_{L_x^2}^2 \leq \|\theta_n\|_{L_x^2} \|u_n\|_{L_x^2} \leq \frac{1}{2} \left(T \|\theta_n\|_{L_x^2}^2 + \frac{1}{T} \|u_n\|_{L_x^2}^2 \right),$$

for all positive times $T > 0$, and thus by Gronwall's inequality we arrive at the following uniform estimate for (u_n) (noticing $\|S u_n\|_{L_x^2}^2 = 2\|\nabla u_n\|_{L_x^2}^2$)

$$\frac{1}{2} \|u_n\|_{L_T^\infty L_x^2}^2 + \mu_* \|\nabla u_n\|_{L_T^2 L_x^2}^2 \leq \frac{e}{2} (T \|\theta_0\|_{L_x^2}^2 + \|u_0\|_{L_x^2}^2), \quad \forall T > 0. \tag{2.7}$$

Thus, the approximate solutions (θ_n, u_n) exist for all positive times.

Step 2: Passing to the limit

By the above uniform bounds (2.6)–(2.7), there exists a subsequence, still denote by (θ_n, u_n) , converging weakly to a limit $(\theta, u) \in L_{\text{loc}}^\infty([0, \infty); (L_x^2)^3) \cap L_{\text{loc}}^2([0, \infty); (H_x^1)^3)$:

$$\begin{aligned} \theta_n &\overset{*}{\rightharpoonup} \theta \quad \text{in } L_{\text{loc}}^\infty([0, \infty); L^2(\mathbb{R}^2)), \quad \nabla \theta_n \rightharpoonup \nabla \theta \quad \text{in } L_{\text{loc}}^2([0, \infty); (L^2(\mathbb{R}^2))^2), \\ u_n &\overset{*}{\rightharpoonup} u \quad \text{in } L_{\text{loc}}^\infty([0, \infty); (L^2(\mathbb{R}^2))^2), \quad \nabla u_n \rightharpoonup \nabla u \quad \text{in } L_{\text{loc}}^2([0, \infty); (L^2(\mathbb{R}^2))^4). \end{aligned}$$

Since by the Gagliardo–Nirenberg's inequality (θ_n, u_n) is a bounded sequence in $L_T^4 L_x^4$ for any $T > 0$, the sequence of the time derivatives $(\partial_t \theta_n, \partial_t u_n)$ is bounded in $L_T^2(H_x^{-1})$ [by use of the equations in (2.4)], and hence $\{(\theta_n, u_n)\}$ is relatively compact in $L_T^p L_x^p(B_R)$ for any fixed disk $B_R \subset \mathbb{R}^2$ and $p \in [1, \infty)$, which implies the pointwise convergence (up to a subsequence)

$$\theta_n \rightarrow \theta, \quad u_n \rightarrow u \text{ for almost every } t \in \mathbb{R}^+, \quad x \in \mathbb{R}^2,$$

as well as the convergence of the nonlinear terms (noticing, e.g., $u_n \varphi \rightarrow u \varphi$ in $L_T^4 L_x^4$ for fixed $\varphi \in C_c^\infty((0, T) \times \mathbb{R}^2)$)

$$u_n \theta_n \rightarrow u \theta, \quad u_n \otimes u_n \rightarrow u \otimes u \text{ in } \mathcal{D}'((0, T) \times \mathbb{R}^2) \text{ and hence weakly in } L_T^2 L_x^2.$$

Consequently, $\kappa_n = a(\theta_n) \rightarrow \kappa = a(\theta)$ and $\mu_n = b(\theta_n) \rightarrow \mu = b(\theta)$ almost everywhere and

$$\kappa_n \nabla \theta_n \rightharpoonup \kappa \nabla \theta, \quad \mu_n S u_n \rightharpoonup \mu S u \text{ in } L_T^2 L_x^2.$$

Thus, the equation (noticing $P_n \rightarrow \text{Id}$ as an operator from $H^s(\mathbb{R}^2)$ to itself)

$$\partial_t \theta + \text{div}(u\theta) - \text{div}(\kappa \nabla \theta) = 0 \text{ holds in } L_{\text{loc}}^2((0, \infty); H_x^{-1}(\mathbb{R}^2)),$$

and we can test it by $\theta \in L_{\text{loc}}^2([0, \infty); H_x^1)$ to arrive at the energy equality (1.8) for θ , such that $\theta|_{t=0} = \theta_0$ and $\theta \in C([0, \infty); L_x^2)$ hold true.

Similarly, the equation

$$\partial_t u + \mathbb{P} \text{div}(u \otimes u - \mu S u) = \mathbb{P}(\theta \vec{e}_2) \text{ holds in } L_{\text{loc}}^2((0, \infty); (H_x^{-1}(\mathbb{R}^2))^2), \quad (2.8)$$

and we can test it by the divergence-free velocity field $u \in L_{\text{loc}}^2((0, \infty); (H_x^1(\mathbb{R}^2))^2)$ to arrive at the energy equality (1.10), which implies $u \in C([0, \infty); (L_x^2(\mathbb{R}^2))^2)$ and $u|_{t=0} = u_0$. We take the solution Π of the Poisson equation

$$\Delta \Pi = \text{div}(1 - \mathbb{P})(\theta \vec{e}_2 - \text{div}(u \otimes u - \mu S u)) \quad (2.9)$$

under the renormalization condition $\int_{B_1} \Pi dx = 0$, such that

$$\nabla \Pi = (1 - \mathbb{P})(\theta \vec{e}_2 - \text{div}(u \otimes u - \mu S u)) \in L_{\text{loc}}^2((0, \infty); (H_x^{-1}(\mathbb{R}^2))^2),$$

and the equation (1.11) holds in $L_{\text{loc}}^2((0, \infty); (H_x^{-1}(\mathbb{R}^2))^2)$.

2.2. Energy estimates and uniqueness of the weak solutions if $(\theta_0, u_0) \in H^1(\mathbb{R}^2) \times (L^2(\mathbb{R}^2))^2$

We first introduce a scalar function η , which is given in terms of the temperature function as follows (recalling now $\kappa = a(\theta) \in C_b^2(\mathbb{R}; [\kappa_*, \kappa^*])$)

$$\eta = A(\theta), \text{ with } A(z) := \int_0^z a(\alpha) d\alpha \text{ the primitive function of } a. \quad (2.10)$$

As $A'(\theta) = a(\theta) \geq \kappa_* > 0$, the function A is invertible and we can write

$$\theta = A^{-1}(\eta), \quad (2.11)$$

where $(A^{-1})'(\eta) = \frac{1}{a(A^{-1}(\eta))} \leq \frac{1}{\kappa_*}$. We have the following equivalence relations³

$$\begin{aligned} \kappa_* \|\theta\|_{L_x^2} &\leq \|\eta\|_{L_x^2} \leq \kappa^* \|\theta\|_{L_x^2}, \\ \kappa_* \|\nabla \theta\|_{L_x^2} &\leq \|\nabla \eta\|_{L_x^2} = \|a(\theta) \nabla \theta\|_{L_x^2} \leq \kappa^* \|\nabla \theta\|_{L_x^2}, \\ \kappa_* \|\partial_t \theta\|_{L_x^2} &\leq \|\partial_t \eta\|_{L_x^2} = \|a(\theta) \partial_t \theta\|_{L_x^2} \leq \kappa^* \|\partial_t \theta\|_{L_x^2}, \\ \|\nabla^2 \eta\|_{L_x^2} &\leq \|a\|_{\text{Lip}} \|\nabla \theta\|_{L_x^4}^2 + \kappa^* \|\nabla^2 \theta\|_{L_x^2} \leq (C \|a\|_{\text{Lip}} \|\nabla \theta\|_{L_x^2} + \kappa^*) \|\nabla^2 \theta\|_{L_x^2}, \\ \|\nabla^2 \theta\|_{L_x^2} &\leq \frac{\|a\|_{\text{Lip}}}{\kappa_*^3} \|\nabla \eta\|_{L_x^4}^2 + \frac{1}{\kappa_*} \|\nabla^2 \eta\|_{L_x^2} \leq \left(C \frac{\|a\|_{\text{Lip}}}{\kappa_*^3} \|\nabla \eta\|_{L_x^2} + \frac{1}{\kappa_*} \right) \|\nabla^2 \eta\|_{L_x^2}. \end{aligned} \quad (2.12)$$

³We can easily compute

$$\begin{aligned} \nabla \eta &= a(\theta) \nabla \theta, \quad \nabla \theta = \frac{1}{a(A^{-1}(\eta))} \nabla \eta, \\ \nabla^2 \eta &= a'(\theta) \nabla \theta \otimes \nabla \theta + a(\theta) \nabla^2 \theta, \quad \nabla^2 \theta = -\frac{a'(A^{-1}(\eta))}{a^3(A^{-1}(\eta))} \nabla \eta \otimes \nabla \eta + \frac{1}{a(A^{-1}(\eta))} \nabla^2 \eta. \end{aligned}$$

That is,

$$\theta(t, \cdot) \in H_x^k(\mathbb{R}^2) \Leftrightarrow \eta(t, \cdot) \in H_x^k(\mathbb{R}^2), \quad k = 0, 1, 2. \tag{2.13}$$

Let $(\theta, u) \in C([0, \infty); (L^2(\mathbb{R}^2))^3) \cap L_{\text{loc}}^2([0, \infty); (H^1(\mathbb{R}^2))^3)$ be a weak solution of the Cauchy problem (2.1) in the sense of Definition 1.1 with

$$\partial_t \theta + u \cdot \nabla \theta - \operatorname{div}(\kappa \nabla \theta) = 0 \text{ holding in } L_{\text{loc}}^2([0, \infty); H_x^{-1}(\mathbb{R}^2)). \tag{2.14}$$

Since $Y := L_{t,x}^\infty([0, \infty) \times \mathbb{R}^2) \cap L_{\text{loc}}^2([0, \infty); H_x^1(\mathbb{R}^2))$ is an algebra (in the sense that the product of any two elements in Y still belongs to Y), we can multiply the above θ -equation by $\kappa = a(\theta)$ (with $a(\theta) - a(0) \in Y$), to arrive at the parabolic equation for $\eta = A(\theta) \in C([0, \infty); L^2(\mathbb{R}^2)) \cap L_{\text{loc}}^2([0, \infty); H^1(\mathbb{R}^2))$:

$$\partial_t \eta + u \cdot \nabla \eta - \kappa \Delta \eta = 0 \text{ holding in the dual space } Y'. \tag{2.15}$$

We are going to derive the H^1 -Estimate for η (and hence for θ^4) as well as the L^2 -Estimate for u first. Then, we will show the uniqueness result of the weak solutions by considering the difference of two possible weak solutions. The procedure is standard (see, e.g., Sect. 2 [29]) and we are going to sketch the proof.

$H^1 \times L^2$ -Estimate for (θ, u)

By virtue of the energy equalities (1.8) and (1.10) and the derivation of the uniform estimates (2.6) and (2.7), we have the L^2 -Estimate

$$\|\theta\|_{L_T^\infty L_x^2}^2 + \|\nabla \theta\|_{L_T^2 L_x^2}^2 \leq C(\kappa_*) \|\theta_0\|_{L^2}^2, \tag{2.16}$$

and the L^2 -Estimate (1.13) for u . By Gagliardo–Nirenberg’s inequality (2.2) it holds

$$\|u\|_{L_T^4 L_x^4} \leq C(\mu_*) (\sqrt{T} \|\theta_0\|_{L^2} + \|u_0\|_{L^2}). \tag{2.17}$$

We assume a priori that the function η is smooth and decay sufficiently fast at infinity. We test the η -equation (2.15) by $\Delta \eta$ to derive by integration by parts that

$$\frac{1}{2} \frac{d}{dt} \int_{\mathbb{R}^2} |\nabla \eta|^2 dx + \int_{\mathbb{R}^2} \kappa |\Delta \eta|^2 dx = \int_{\mathbb{R}^2} u \cdot \nabla \eta \Delta \eta dx \leq \|u\|_{L_x^4} \|\nabla \eta\|_{L_x^4} \|\Delta \eta\|_{L_x^2}.$$

By Gagliardo–Nirenberg’s inequality (2.2), the equivalence $\|\Delta \eta\|_{L_x^2(\mathbb{R}^2)} \sim \|\nabla^2 \eta\|_{L_x^2(\mathbb{R}^2)}$ and Young’s inequality we arrive at

$$\frac{1}{2} \frac{d}{dt} \int_{\mathbb{R}^2} |\nabla \eta|^2 dx + \frac{\kappa_*}{2} \int_{\mathbb{R}^2} |\Delta \eta|^2 dx \leq C(\kappa_*) \|u\|_{L_x^4}^4 \|\nabla \eta\|_{L_x^2}^2.$$

Gronwall’s inequality gives

$$\|\nabla \eta(T)\|_{L_x^2}^2 + \|\nabla^2 \eta\|_{L_T^2 L_x^2}^2 \leq C(\kappa_*) \|\nabla \eta_0\|_{L_x^2}^2 \exp\left(C(\kappa_*) \|u\|_{L_T^4 L_x^4}^4\right)$$

for any positive time $T > 0$. Thus by the η -equation

$$\begin{aligned} \|\partial_t \eta\|_{L_T^2 L_x^2} &= \|u \cdot \nabla \eta - \kappa \Delta \eta\|_{L_T^2 L_x^2} \leq \|u\|_{L_T^4 L_x^4} \|\nabla \eta\|_{L_T^4 L_x^4} + \kappa^* \|\Delta \eta\|_{L_T^2 L_x^2} \\ &\leq C(\kappa_*, \kappa^*) \|\nabla \eta_0\|_{L_x^2} \exp\left(C(\kappa_*) \|u\|_{L_T^4 L_x^4}^4\right). \end{aligned}$$

By virtue of the equivalence relation (2.12):

$$\|\nabla \theta\|_{L_T^\infty L_x^2}^2 + \|\nabla^2 \theta\|_{L_T^2 L_x^2}^2 \leq C(\kappa_*, \|a\|_{\text{Lip}}) \left(\|\nabla \eta\|_{L_T^\infty L_x^2}^2 + \left(1 + \|\nabla \eta\|_{L_T^\infty L_x^2}^2\right) \|\nabla^2 \eta\|_{L_T^2 L_x^2}^2 \right)$$

⁴The introduction of the η -function makes the derivation of the H^1 -Estimate for θ straightforward (and possible).

and (2.16)-(2.17), we have the a priori H^1 -Estimate (1.14) for θ :

$$\begin{aligned} & \|\theta\|_{L_T^\infty H_x^1}^2 + \|\nabla\theta\|_{L_T^2 H_x^1}^2 + \|\partial_t\theta\|_{L_T^2 L_x^2}^2 \\ & \leq C(\kappa_*, \|a\|_{\text{Lip}}, \kappa^*) \|\theta_0\|_{H^1}^2 (1 + \|\nabla\theta_0\|_{L^2}^2) \exp\left(C(\kappa_*) \|u\|_{L_T^4 L_x^4}^4\right). \end{aligned} \quad (2.18)$$

Therefore, both the parabolic equations (2.14) and (2.15) for θ and η hold in $L_{\text{loc}}^2([0, \infty); L^2(\mathbb{R}^2))$. A standard density argument ensures the H^1 -Estimate (1.14) for θ , and hence $\theta \in C([0, \infty); H_x^1(\mathbb{R}^2))$.

Proof of the uniqueness

Let (θ_1, u_1, Π_1) and (θ_2, u_2, Π_2) be two weak solutions of the Cauchy problem (2.1) with the same initial data $(\theta_0, u_0) \in H^1(\mathbb{R}^2) \times (L^2(\mathbb{R}^2))^2$, which satisfy the energy estimates (1.13)-(1.14). Recall (2.10) for the definition of the function A , and we set

$$\eta_1 = A(\theta_1), \quad \eta_2 = A(\theta_2).$$

We consider the difference

$$(\dot{\eta}, \dot{u}, \nabla\dot{\Pi}) = (\eta_1 - \eta_2, u_1 - u_2, \nabla\Pi_1 - \nabla\Pi_2),$$

which lies in

$$\begin{aligned} & (C([0, \infty); H^1(\mathbb{R}^2)) \cap L_{\text{loc}}^2([0, \infty); H^2(\mathbb{R}^2))) \\ & \times (C([0, \infty); (L^2(\mathbb{R}^2))^2) \cap L_{\text{loc}}^2([0, \infty); (H^1(\mathbb{R}^2))^2)) \times L_{\text{loc}}^2([0, \infty); (H^{-1}(\mathbb{R}^2))^2). \end{aligned}$$

It satisfies the following Cauchy problem

$$\begin{cases} \partial_t \dot{\eta} + u_1 \cdot \nabla \dot{\eta} - \kappa_1 \Delta \dot{\eta} = \dot{\kappa} \Delta \eta_2 - \dot{u} \cdot \nabla \eta_2, \\ \partial_t \dot{u} + u_1 \cdot \nabla \dot{u} - \text{div}(\mu_1 S \dot{u}) + \nabla \dot{\Pi} = \dot{\theta} e_2^* - \dot{u} \cdot \nabla u_2 + \text{div}(\dot{\mu} S u_2), \\ \text{div} \dot{u} = 0, \\ (\dot{\eta}_0, \dot{u}_0) = (0, 0), \end{cases} \quad (2.19)$$

where

$$\kappa_1 = a(\theta_1), \quad \mu_1 = b(\theta_1), \quad \dot{\theta} = \theta_1 - \theta_2, \quad \dot{\kappa} = a(\theta_1) - a(\theta_2), \quad \dot{\mu} = b(\theta_1) - b(\theta_2).$$

Similarly as in (2.12) we have the following equivalence relationships

$$\begin{aligned} \kappa_* \|\dot{\theta}\|_{L_x^2} & \leq \|\dot{\eta}\|_{L_x^2} \leq \kappa^* \|\dot{\theta}\|_{L_x^2}, \\ \|\nabla \dot{\eta}\|_{L_x^2} & \leq \|a\|_{\text{Lip}} \|\nabla \theta_1\|_{L_x^4} \|\dot{\theta}\|_{L_x^4} + \kappa^* \|\nabla \dot{\theta}\|_{L_x^2}, \\ \|\nabla \dot{\theta}\|_{L_x^2} & \leq \frac{\|a\|_{\text{Lip}}}{\kappa_*^3} \|\nabla \eta_1\|_{L_x^4} \|\dot{\eta}\|_{L_x^4} + \frac{1}{\kappa_*} \|\nabla \dot{\eta}\|_{L_x^2}, \end{aligned} \quad (2.20)$$

and correspondingly we have

$$\begin{aligned} \|(\dot{\kappa}, \dot{\mu})\|_{H_x^1} & \leq C(\|(a, b)\|_{\text{Lip}}, \|(a', b')\|_{\text{Lip}}, \kappa_*) (\|\nabla \eta_1\|_{L_x^4} \|\dot{\eta}\|_{L_x^4} + \|\dot{\eta}\|_{H_x^1}) \\ & \leq C(\|(a, b)\|_{\text{Lip}}, \|(a', b')\|_{\text{Lip}}, \kappa_*) (1 + \|\nabla \eta_1\|_{L_x^4}) \|\dot{\eta}\|_{H_x^1}. \end{aligned} \quad (2.21)$$

We are going to sketch the derivation of the $H^1 \times L^2$ -Estimate for $(\dot{\eta}, \dot{u})$.

(i) L^2 estimate of $\dot{\eta}$. We take the $L^2(\mathbb{R}^2)$ -inner product between (2.19)₁ and $\dot{\eta}$ to derive

$$\frac{1}{2} \frac{d}{dt} \int_{\mathbb{R}^2} |\dot{\eta}|^2 + \int_{\mathbb{R}^2} \kappa_1 |\nabla \dot{\eta}|^2 \leq \int_{\mathbb{R}^2} |\dot{\eta} \nabla \kappa_1 \cdot \nabla \dot{\eta}| + |\dot{\eta} \dot{u} \cdot \nabla \eta_2| + |\dot{\kappa} \Delta \eta_2 \dot{\eta}|. \quad (2.22)$$

The right hand side can be bounded by

$$\begin{aligned} & \|\dot{\eta}\|_{L_x^4} \|\nabla \kappa_1\|_{L_x^4} \|\nabla \dot{\eta}\|_{L_x^2} + \|\nabla \eta_2\|_{L_x^2} \|\dot{u}\|_{L_x^4} \|\dot{\eta}\|_{L_x^4} + \|\Delta \eta_2\|_{L_x^2} \|\dot{\kappa}\|_{L_x^4} \|\dot{\eta}\|_{L_x^4} \\ & \leq C(\|a\|_{\text{Lip}}) \left(\|\nabla \theta_1\|_{L_x^4} \|\dot{\eta}\|_{L_x^2}^{\frac{1}{2}} \|\nabla \dot{\eta}\|_{L_x^2}^{\frac{3}{2}} + \|\nabla \eta_2\|_{L_x^2} \|\dot{u}\|_{L_x^2}^{\frac{1}{2}} \|\nabla \dot{u}\|_{L_x^2}^{\frac{1}{2}} \|\dot{\eta}\|_{L_x^2}^{\frac{1}{2}} \|\nabla \dot{\eta}\|_{L_x^2}^{\frac{3}{2}} \right) \end{aligned}$$

$$\begin{aligned}
& + \|\Delta\eta_2\|_{L_x^2} \|\dot{\theta}\|_{L_x^2}^{\frac{1}{2}} \|\nabla\dot{\theta}\|_{L_x^2}^{\frac{1}{2}} \|\dot{\eta}\|_{L_x^2}^{\frac{1}{2}} \|\nabla\dot{\eta}\|_{L_x^2}^{\frac{1}{2}} \\
\leq & \frac{\kappa_*}{2} \|\nabla\dot{\eta}\|_{L_x^2}^2 + \frac{\mu_*}{4} \|\nabla\dot{u}\|_{L_x^2}^2 \\
& + C(\|a\|_{\text{Lip}}, \kappa_*, \mu_*) \left(\|\nabla\theta_1\|_{L_x^4}^4 + \|\nabla\eta_2\|_{L_x^2}^2 + \|\Delta\eta_2\|_{L_x^2}^2 \right) \times (\|\dot{\eta}\|_{L_x^2}^2 + \|\dot{u}\|_{L_x^2}^2).
\end{aligned}$$

(ii) L^2 estimate of \dot{u} .

We take the L^2 inner product of the equation (2.19)₂ and \dot{u} to derive

$$\frac{1}{2} \frac{d}{dt} \int_{\mathbb{R}^2} |\dot{u}|^2 + \frac{1}{2} \int_{\mathbb{R}^2} \mu_1 |S\dot{u}|^2 \leq \int_{\mathbb{R}^2} |\dot{\theta}\dot{u}| + |\dot{u}|^2 |\nabla u_2| + |\dot{\mu} S u_2 : \nabla \dot{u}|. \quad (2.23)$$

The right hand side can be bounded by

$$\|\dot{u}\|_{L_x^2} \|\dot{\theta}\|_{L_x^2} + \|\dot{u}\|_{L_x^4}^2 \|\nabla u_2\|_{L_x^2} + \|\dot{\mu}\|_{H_x^1} \|S u_2 : \nabla \dot{u}\|_{H_x^{-1}}$$

which, by use of the Sobolev embedding $L^1(\mathbb{R}^2) \hookrightarrow H^{-1}(\mathbb{R}^2)$, is bounded by

$$\begin{aligned}
& \frac{\mu_*}{4} \|\nabla\dot{u}\|_{L_x^2}^2 + C(\|a\|_{\text{Lip}}, \kappa_*, \mu_*) (1 + \|\nabla u_2\|_{L_x^2}^2) (\|\dot{u}\|_{L_x^2}^2 + \|\dot{\eta}\|_{L_x^2}^2) \\
& + C(\mu_*) \|\nabla u_2\|_{L_x^2}^2 \|\dot{\mu}\|_{H_x^1}^2.
\end{aligned}$$

(iii) L^2 estimate of $\nabla\dot{\eta}$.

We take the L^2 inner product of Eq. (2.19)₁ and $\Delta\dot{\eta}$ to derive

$$\frac{1}{2} \frac{d}{dt} \int_{\mathbb{R}^2} |\nabla\dot{\eta}|^2 + \int_{\mathbb{R}^2} \kappa_1 |\Delta\dot{\eta}|^2 \leq \int_{\mathbb{R}^2} |u_1 \cdot \nabla\dot{\eta}\Delta\dot{\eta}| + |\dot{u} \cdot \nabla\eta_2\Delta\dot{\eta}| + |\dot{\kappa}\Delta\eta_2\Delta\dot{\eta}|$$

By $L^1(\mathbb{R}^2) \hookrightarrow H^{-1}(\mathbb{R}^2)$ again, the right hand side is bounded similarly by

$$\begin{aligned}
& \frac{\kappa_*}{2} \|\Delta\dot{\eta}\|_{L_x^2}^2 + \frac{\mu_*}{4} \|\nabla\dot{u}\|_{L_x^2}^2 + C(\kappa_*, \mu_*) \left(\|u_1\|_{L_x^4}^4 + \|\nabla\eta_2\|_{L_x^4}^4 \right) \left(\|\dot{u}\|_{L_x^2}^2 + \|\nabla\dot{\eta}\|_{L_x^2}^2 \right) \\
& + C(\kappa_*) \|\Delta\eta_2\|_{L_x^2}^2 \|\dot{\kappa}\|_{H_x^1}^2.
\end{aligned}$$

To conclude, by virtue of the above estimates and (2.21), we have the following inequality

$$\begin{aligned}
& \frac{d}{dt} \left(\|\dot{\eta}\|_{H_x^1}^2 + \|\dot{u}\|_{L_x^2}^2 \right) + \|\nabla\dot{u}\|_{L_x^2}^2 + \|\nabla\dot{\eta}\|_{H_x^1}^2 \\
& \leq C(\|(a, b)\|_{\text{Lip}}, \|(a', b')\|_{\text{Lip}}, \kappa_*, \mu_*) B(t) \left(\|\dot{u}\|_{L_x^2}^2 + \|\dot{\eta}\|_{H_x^1}^2 \right),
\end{aligned}$$

where

$$\begin{aligned}
B(t) = & \left(\|\nabla\theta_1\|_{L_x^4}^4 + \|\nabla\eta_2\|_{L_x^2}^2 + \|\Delta\eta_2\|_{L_x^2}^2 + 1 + \|\nabla u_2\|_{L_x^2}^2 + \|u_1\|_{L_x^4}^4 + \|\nabla\eta_2\|_{L_x^4}^4 \right) \\
& \times (1 + \|\nabla\eta_1\|_{L_x^4}) \in L_{\text{loc}}^1([0, \infty)).
\end{aligned}$$

Gronwall's inequality implies then $\dot{\eta} = 0$ and $\dot{u} = 0$. The uniqueness of the weak solutions follows.

2.3. Propagation of the general H^s -regularities

After the derivation of the a priori H_x^s , $s \in (0, 2)$ -Estimate for a general linear parabolic equation in Sect. 2.3.1, we are going to derive the precise H_x^s -Estimates (1.17)–(1.24) in Remark 1.4 in the subsequent subsections:

- In Sect. 2.3.2 the global-in-time $H_x^s(\mathbb{R}^2) \times (L_x^2(\mathbb{R}^2))^2$, $s \in (1, 2)$ -regularities [i.e., (1.17)] will be established, where the endpoint case $s = 2$ [i.e., (1.18)] will be treated separately.
- In Sect. 2.3.3, the global-in-time $H_x^1(\mathbb{R}^2) \times (H_x^s(\mathbb{R}^2))^2$, $s \in (0, 2)$ -regularities [i.e., (1.19)] will be established, where the endpoint case $s = 2$ [i.e., (1.20)] will be treated separately.

- In Sect. 2.3.4 the global-in-time $H_x^s(\mathbb{R}^2) \times (H_x^{s-2}(\mathbb{R}^2))^2$ [i.e., (1.21)–(1.22)] and $H_x^{s-1} \times (H_x^s(\mathbb{R}^2))^2$, $s > 2$ -regularities [i.e., (1.23)–(1.24)] will be established, respectively.

As far as the borderline estimates (1.17)–(1.24) are established, the global-in-time regularity (1.16) follows immediately.

For readers’ convenience, we recall here briefly the Littlewood–Paley dyadic decomposition and the definition of the $H^s(\mathbb{R}^n)$ -norms (see, e.g., Chapter 2 in the book [4] for more details). We fix a nonincreasing radial function $\chi \in C_c^\infty(B_{\frac{3}{4}})$ with $\chi(x) = 1$ for $x \in B_1$, where $B_r \subset \mathbb{R}^n$ denotes the ball centered at 0 with radius r . We define the function $\varphi(\xi) = \chi(\frac{\xi}{2}) - \chi(\xi)$ and $\varphi_j(\xi) = \varphi(2^{-j}\xi)$ with $j \geq 0$. We do the Littlewood–Paley decomposition in the following way

$$g = \Delta_{-1}g + \sum_{j \geq 0} \Delta_j g, \tag{2.24}$$

where

$$\mathcal{F}(\Delta_{-1}g)(\xi) = \chi(\xi)\mathcal{F}(g)(\xi), \quad \mathcal{F}(\Delta_j g)(\xi) = \varphi_j(\xi)\mathcal{F}(g)(\xi), \quad j \geq 0,$$

and \mathcal{F} denotes the Fourier transform. We have the following Bernstein’s inequalities for some universal constant C (depending only on n)

$$\begin{aligned} \|\Delta_{-1}g\|_{L^2(\mathbb{R}^n)} &\leq C\|g\|_{L^2(\mathbb{R}^n)}, \\ C^{-1}2^j\|\Delta_j g\|_{L^2(\mathbb{R}^n)} &\leq \|\nabla(\Delta_j g)\|_{L^2(\mathbb{R}^n)} \leq C2^j\|\Delta_j g\|_{L^2(\mathbb{R}^n)}, \quad \forall j \geq 0. \end{aligned} \tag{2.25}$$

Let $s \geq 0$ and $p, r \geq 1$. We define the nonhomogeneous Besov spaces $B_{p,r}^s(\mathbb{R}^n)$ as the spaces consisting of all tempered distributions $g \in \mathcal{S}'(\mathbb{R}^n)$ satisfying

$$\|g\|_{B_{p,r}^s(\mathbb{R}^n)} = \left\| \left(2^{js} \|\Delta_j g\|_{L^p(\mathbb{R}^n)} \right)_{j \geq -1} \right\|_{l^r} < \infty.$$

The inhomogeneous Sobolev spaces $H^s(\mathbb{R}^n) = B_{2,2}^s(\mathbb{R}^n)$ can be defined by

$$H^s(\mathbb{R}^n) = \left\{ g \in \mathcal{S}'(\mathbb{R}^n) \mid \|g\|_{H^s(\mathbb{R}^n)} = \left(\int_{\mathbb{R}^n} (1 + |\xi|^2)^{\frac{s}{2}} |\mathcal{F}(g)(\xi)|^2 d\xi \right)^{1/2} < \infty \right\},$$

where the $H^s(\mathbb{R}^n)$ -norm reads in terms of Littlewood–Paley decomposition as follows

$$\|g\|_{H^s(\mathbb{R}^n)} \sim \|g\|_{L^2(\mathbb{R}^n)} + \left(\sum_{j \geq 0} 2^{2js} \|\Delta_j g\|_{L^2(\mathbb{R}^n)}^2 \right)^{\frac{1}{2}}. \tag{2.26}$$

It is straightforward to derive the following interpolation inequality

$$\|u\|_{H^{t_\sigma}} \leq C \|u\|_{H^{t_0}}^{1-\sigma} \|u\|_{H^{t_1}}^\sigma, \quad \text{where } t_\sigma = (1 - \sigma)t_0 + \sigma t_1, \sigma \in [0, 1]. \tag{2.27}$$

We are going to use the following known estimates to control the nonlinear terms in the Boussinesq system (1.1).

Lemma 2.1. *We have the following commutator, product, and composition estimates.*

- (1) [12, Proposition 2.4] *In the low regularity regime where $(s, \nu) \in \mathbb{R}^2$ satisfy*

$$-1 < s < \nu + 1, \quad \text{and} \quad -1 < \nu < 1,$$

the following commutator estimate holds true (in \mathbb{R}^2):

$$\| (2^{js} \| [\phi, \Delta_j] \nabla \psi \|_{L^2(\mathbb{R}^2)})_{j \geq 1} \|_{l^1} \leq C \| \nabla \phi \|_{H^\nu(\mathbb{R}^2)} \| \nabla \psi \|_{H^{s-\nu}(\mathbb{R}^2)}, \tag{2.28}$$

where C is a constant depending only on s, ν .

(2) [4, Lemma 2.100] For any $s > 0$, the following commutator estimate holds true

$$\begin{aligned} & \| (2^{js} \| [\phi, \Delta_j] \nabla \psi \|_{L^2(\mathbb{R}^n)})_{j \geq 1} \|_{l^2} \\ & \leq C (\| \nabla \phi \|_{L^\infty(\mathbb{R}^n)} \| \nabla \psi \|_{H^{s-1}(\mathbb{R}^n)} + \| \nabla \phi \|_{H^{s-1}(\mathbb{R}^n)} \| \nabla \psi \|_{L^\infty(\mathbb{R}^n)}). \end{aligned} \tag{2.29}$$

(3) [4, Corollary 2.86] For any $s > 0$, the following product estimate holds true

$$\| \phi \psi \|_{H^s(\mathbb{R}^n)} \leq C (\| \phi \|_{L^\infty(\mathbb{R}^n)} \| \psi \|_{H^s(\mathbb{R}^n)} + \| \phi \|_{H^s(\mathbb{R}^n)} \| \psi \|_{L^\infty(\mathbb{R}^n)}). \tag{2.30}$$

(4) [4, Theorems 2.87 and Theorem 2.89] For any $s > 0$ and $g \in C^{k+1}$ with $k = [s] \in \mathbb{N}$, the following composition estimate holds true

$$\| \nabla (g \circ \theta) \|_{H^{s-1}(\mathbb{R}^n)} \leq C (g, \| \theta \|_{L^\infty(\mathbb{R}^n)}) \| \nabla \theta \|_{H^{s-1}(\mathbb{R}^n)}. \tag{2.31}$$

If $g \in C_b^{k+1}$ with $k = [s] \in \mathbb{N}$, then the above estimate can be improved in the spatial dimension two as follows

$$\| \nabla (g \circ \theta) \|_{H^{s-1}(\mathbb{R}^2)} \leq C (\| g \|_{C^{k+1}}, \| \theta \|_{H^1(\mathbb{R}^2)}) \| \nabla \theta \|_{H^{s-1}(\mathbb{R}^2)}. \tag{2.32}$$

The commutator estimate (2.28) will present its power in the low regularity regime (see Sects. 2.3.1–2.3.3 below), and the classical commutator estimate (2.29) will help in the high regularity regime (see Sect. 2.3.4 below).

The composition estimate (2.32) will help to bound the diffusion coefficients κ, μ in terms of θ in the low regularity regime, where only $H^1(\mathbb{R}^2)$ -norm (instead of L^∞ -norm) of θ is available.

2.3.1. Estimates for the general parabolic equations. We derive in this paragraph a priori H^s , $s \in (0, 2)$ -Estimates for a general linear parabolic equation, which should be of independent interest.

Lemma 2.2. Let $\psi = \psi(t, x) : [0, \infty) \times \mathbb{R}^2 \mapsto \mathbb{R}^m$, $m \geq 1$ be a smooth solution with sufficiently decay of the following linear parabolic equation

$$\begin{cases} \partial_t \psi + u \cdot \nabla_x \psi - \operatorname{div}_x (\kappa \nabla_x \psi) = f, \\ \psi|_{t=0} = \psi_0, \end{cases} \tag{2.33}$$

where

- $u = u(t, x) : \mathbb{R}^+ \times \mathbb{R}^2 \mapsto \mathbb{R}^2$ is a given divergence-free vector field: $\operatorname{div}_x u = 0$;
- $\kappa = \kappa(t, x) : \mathbb{R}^+ \times \mathbb{R}^2 \rightarrow [\kappa_*, \kappa^*]$ with $\kappa_*, \kappa^* \in (0, \infty)$;
- $f = f(t, x) : \mathbb{R}^+ \times \mathbb{R}^2 \mapsto \mathbb{R}^m$ denotes the given external force.

Then, the following a priori H_x^s -Estimates for (2.33) holds true:

$$\begin{aligned} & \| \psi \|_{L_T^\infty H_x^s}^2 + \| \nabla \psi \|_{L_T^2 H_x^s}^2 \leq C(\kappa_*) \left(\| \psi_0 \|_{H_x^s}^2 + \| f \|_{L_T^2 H_x^{s-1}}^2 \right) \\ & \quad \times \exp \left(C(\kappa_*, s, \nu) (\| \nabla u \|_{L_T^2 L_x^2}^2 + \| \nabla \kappa \|_{L_T^{\frac{2}{\nu}} H_x^\nu}^{2/\nu} + \| f \|_{L_T^1 H_x^{-s}}) \right) \\ & \quad \text{for any } s \in (0, 2) \text{ and } \nu \in (s - 1, 1) \subset (-1, 1). \end{aligned} \tag{2.34}$$

Proof. It is straightforward to derive the following L_x^2 -Estimate by simply taking the $L^2(\mathbb{R}^2)$ inner product of the equation (2.33) and ψ itself

$$\| \psi \|_{L_T^\infty L_x^2}^2 + \| \nabla \psi \|_{L_T^2 L_x^2}^2 \leq C(\kappa_*) \left(\| \psi_0 \|_{L_x^2}^2 + \int_0^T \langle \psi, f \rangle_{H_x^s, H_x^{-s}} dt \right), \quad \forall s \in \mathbb{R}. \tag{2.35}$$

We next consider the a priori estimates for the $H^s(\mathbb{R}^2)$ -norm. By virtue of the description (2.26) of the $H^s(\mathbb{R}^2)$ -norm, we consider the dyadic piece of ψ :

$$\psi_j := \Delta_j \psi, \quad j \geq 0. \tag{2.36}$$

where the operator Δ_j is defined in (2.24). We apply Δ_j to the linear ψ -equation to derive the equation for ψ_j :

$$\partial_t \psi_j + u \cdot \nabla \psi_j - \operatorname{div}(\kappa \nabla \psi_j) = [u, \Delta_j] \cdot \nabla \psi - \operatorname{div}([\kappa, \Delta_j] \nabla \psi) + f_j, \quad j \geq 0. \quad (2.37)$$

We take the L^2 inner product of the equation (2.37) and ψ_j and make use of $\operatorname{div} u = 0$ and $\kappa \geq \kappa_*$ to derive

$$\begin{aligned} \frac{1}{2} \frac{d}{dt} \|\psi_j\|_{L_x^2}^2 + \kappa_* \|\nabla \psi_j\|_{L_x^2}^2 &\leq \|\psi_j\|_{L_x^2} \|[u, \Delta_j] \cdot \nabla \psi\|_{L_x^2} \\ &\quad + \|\nabla \psi_j\|_{L_x^2} \|[\kappa, \Delta_j] \nabla \psi\|_{L_x^2} + \|f_j\|_{L_x^2} \|\psi_j\|_{L_x^2}, \quad j \geq 0. \end{aligned}$$

By use of Bernstein's inequality (2.25), we have

$$\begin{aligned} \frac{d}{dt} \|\psi_j\|_{L_x^2}^2 + 2^{2j} \|\psi_j\|_{L_x^2}^2 \\ \leq C(\kappa_*) \|\psi_j\|_{L_x^2} \left(\|[u, \Delta_j] \cdot \nabla \psi\|_{L_x^2} + 2^j \|[\kappa, \Delta_j] \nabla \psi\|_{L_x^2} + \|f_j\|_{L_x^2} \right), \end{aligned}$$

that is,

$$\begin{aligned} \frac{d}{dt} \|\psi_j\|_{L_x^2} + 2^{2j} \|\psi_j\|_{L_x^2} \\ \leq C(\kappa_*) \left(\|[u, \Delta_j] \cdot \nabla \psi\|_{L_x^2} + 2^j \|[\kappa, \Delta_j] \nabla \psi\|_{L_x^2} + \|f_j\|_{L_x^2} \right), \quad j \geq 0. \end{aligned} \quad (2.38)$$

We make use of the commutator estimate (2.28) in Lemma 2.1 to estimate the commutators $\|[u, \Delta_j] \cdot \nabla \psi\|_{L_x^2}$ and $2^j \|[\kappa, \Delta_j] \nabla \psi\|_{L_x^2}$ in the above inequality in the following way. Let $(l_j)_{j \geq 0}$ be a normalized sequence in $\ell^1(\mathbb{N})$ such that $l_j \geq 0$ and $\sum_{j \geq 0} l_j = 1$. Then, we have

$$\begin{aligned} \|[u, \Delta_j] \nabla \psi\|_{L^2} &\leq C(s) l_j 2^{j(1-s)} \|\nabla u\|_{L_x^2} \|\nabla \psi\|_{H_x^{s-1}}, \quad \text{for } s \in (0, 2), \\ 2^j \|[\kappa, \Delta_j] \nabla \psi\|_{L_x^2} &\leq C(s, \nu) l_j 2^{j(1-s)} \|\nabla \kappa\|_{H_x^\nu} \|\nabla \psi\|_{H_x^{s-\nu}} \\ &\quad \text{for } \nu \in (-1, 1), s \in (-1, \nu + 1). \end{aligned} \quad (2.39)$$

Therefore, we have

$$\begin{aligned} \frac{d}{dt} \|\psi_j\|_{L_x^2} + 2^{2j} \|\psi_j\|_{L_x^2} \\ \leq C(\kappa_*, s, \nu) l_j 2^{j(1-s)} \left(\|\nabla u\|_{L_x^2} \|\nabla \psi\|_{H_x^{s-1}} + \|\nabla \kappa\|_{H_x^\nu} \|\nabla \psi\|_{H_x^{s-\nu}} \right) + C(\kappa_*) \|f_j\|_{L_x^2} \\ \text{for } \nu \in (-1, 1), s \in (0, \nu + 1), j \geq 0. \end{aligned}$$

We use Duhamel's Principle to derive

$$\begin{aligned} \|\psi_j\|_{L_x^2} &\leq e^{-t2^{2j}} \|(\psi_0)_j\|_{L_x^2} + C(\kappa_*) \int_0^t e^{-(t-\tau)2^{2j}} \|f_j(\tau)\|_{L_x^2} d\tau \\ &\quad + C(\kappa_*, s, \nu) 2^{j(1-s)} l_j \int_0^t e^{-(t-\tau)2^{2j}} \left(\|\nabla u(\tau)\|_{L_x^2} \|\nabla \psi(\tau)\|_{H_x^{s-1}} \right. \\ &\quad \left. + \|\nabla \kappa(\tau)\|_{H_x^\nu} \|\nabla \psi(\tau)\|_{H_x^{s-\nu}} \right) d\tau, \quad j \geq 0. \end{aligned} \quad (2.40)$$

We multiply the inequality (2.40) by 2^{js} to derive

$$\begin{aligned}
2^{js} \|\psi_j\|_{L_x^2} &\leq 2^{js} e^{-t2^{2j}} \|(\psi_0)_j\|_{L_x^2} + C(\kappa_*) 2^{js} \int_0^t e^{-(t-\tau)2^{2j}} \|f_j\|_{L_x^2} d\tau \\
&+ C(\kappa_*, s, \nu) 2^j l_j \int_0^t e^{-(t-\tau)2^{2j}} (\|\nabla u(\tau)\|_{L_x^2} \|\nabla \psi(\tau)\|_{H_x^{s-1}} \\
&+ \|\nabla \kappa(\tau)\|_{H_x^\nu} \|\nabla \psi(\tau)\|_{H_x^{s-\nu}}) d\tau, \quad j \geq 0.
\end{aligned} \tag{2.41}$$

We take $L^\infty([0, T])$ -norm in t of (2.41) and the $L^2([0, T])$ -norm in t of $2^j \cdot$ (2.41), to derive by use of Young's inequality that

$$\begin{aligned}
2^{js} \|\psi_j\|_{L_T^\infty L_x^2} + 2^{j(s+1)} \|\psi_j\|_{L_T^2 L_x^2} &\leq 2^{js} \|(\psi_0)_j\|_{L_x^2} + C(\kappa_*) 2^{j(s-1)} \|f_j\|_{L_T^2 L_x^2} \\
&+ C(\kappa_*, s, \nu) l_j \left\| \|\nabla u\|_{L_x^2} \|\nabla \psi\|_{H_x^{s-1}} + \|\nabla \kappa\|_{H_x^\nu} \|\nabla \psi\|_{H_x^{s-\nu}} \right\|_{L_T^2}.
\end{aligned} \tag{2.42}$$

We take square of (2.42) and sum them up for $j \in \mathbb{N}$ to derive

$$\begin{aligned}
&\sum_{j \geq 0} \left(2^{2js} \|\psi_j\|_{L_T^\infty L_x^2}^2 + 2^{2j(s+1)} \|\psi_j\|_{L_T^2 L_x^2}^2 \right) \\
&\lesssim_{\kappa_*, s, \nu} \sum_{j \geq 0} \left(2^{2js} \|(\psi_0)_j\|_{L_x^2}^2 + 2^{2j(s-1)} \|f_j\|_{L_T^2 L_x^2}^2 \right) \\
&+ \int_0^T \|\nabla u\|_{L_x^2}^2 \|\nabla \psi\|_{H_x^{s-1}}^2 + \|\nabla \kappa\|_{H_x^\nu}^2 \|\nabla \psi\|_{H_x^{s-\nu}}^2 dt, \quad j \geq 0,
\end{aligned}$$

that is, by virtue of the L^2 -Estimate (2.35),

$$\begin{aligned}
\|\psi\|_{L_T^\infty H_x^s}^2 + \|\nabla \psi\|_{L_T^2 H_x^s}^2 &\lesssim_{\kappa_*, s, \nu} \left(\|\psi_0\|_{H_x^s}^2 + \|f\|_{L_T^2 H_x^{s-1}}^2 + \int_0^T \|\psi\|_{H_x^s} \|f\|_{H_x^{-s}} dt \right. \\
&+ \left. \int_0^T \|\nabla u\|_{L_x^2}^2 \|\nabla \psi\|_{H_x^{s-1}}^2 + \|\nabla \kappa\|_{H_x^\nu}^2 \|\nabla \psi\|_{H_x^{s-\nu}}^2 dt \right).
\end{aligned}$$

We next consider the norm $\|\nabla \psi\|_{H_x^{s-\nu}}$. By the interpolation inequality (2.27), we have

$$\|\nabla \psi\|_{H_x^{s-\nu}} \leq C \|\nabla \psi\|_{H_x^{s-1}}^\nu \|\nabla \psi\|_{H_x^s}^{1-\nu}, \quad \nu \in (0, 1),$$

which implies by Young's inequality that

$$\begin{aligned}
\int_0^T \|\nabla \kappa\|_{H_x^\nu}^2 \|\nabla \psi\|_{H_x^{s-\nu}}^2 dt &\leq \int_0^T \|\nabla \kappa\|_{H_x^\nu}^2 \|\nabla \psi\|_{H_x^{s-1}}^{2\nu} \|\nabla \psi\|_{H_x^s}^{2(1-\nu)} dt \\
&\leq \varepsilon \|\nabla \psi\|_{L_T^2 H_x^s}^2 + C_\varepsilon \int_0^T \|\nabla \kappa\|_{H_x^\nu}^{2/\nu} \|\nabla \psi\|_{H_x^{s-1}}^2 dt.
\end{aligned}$$

To conclude, by taking ε small enough and Gronwall's inequality, we derive the H^s -Estimate (2.34). \square

2.3.2. Case $(\theta_0, u_0) \in H^s(\mathbb{R}^2) \times (L^2(\mathbb{R}^2))^2$, $s \in (1, 2]$. In this subsection, we are going to prove the H^s -Estimates (1.17) for the unique solution (θ, u) of the Boussinesq equations (1.1) with the initial data $(\theta_0, u_0) \in H^s(\mathbb{R}^2) \times (L^2(\mathbb{R}^2))^2$, $s \in (1, 2)$, following exactly the procedure in Sect. 2.3.1. We will pay more attention on the “nonlinearities” in the equations such as $\kappa = a(\theta)$, $u \cdot \nabla u$ when using the commutator estimates and will sketch the proof.

The endpoint estimate (1.18) for $(\theta_0, u_0) \in H^2(\mathbb{R}^2) \times (L^2(\mathbb{R}^2))^2$ follows similarly as in the proof for the H^1 -Estimate for θ in Sect. 2.2 and we will sketch the proof.

Case $(\theta_0, u_0) \in H^s(\mathbb{R}^2) \times (L^2(\mathbb{R}^2))^2$, $s \in (1, 2)$

Similarly as (2.38), we have the following preliminary estimate for $\theta_j = \Delta_j \theta$:

$$\frac{d}{dt} \|\theta_j\|_{L_x^2} + 2^{2j} \|\theta_j\|_{L_x^2} \leq C(\kappa_*) (\|[u, \Delta_j] \cdot \nabla \theta\|_{L_x^2} + 2^j \|\kappa, \Delta_j\| \|\nabla \theta\|_{L_x^2}), \quad j \geq 0. \quad (2.43)$$

By use of the commutator estimates (2.39) and the action estimate (2.32):

$$\|\nabla \kappa\|_{H^\nu} \leq C(\|a\|_{C^2}, \|\theta\|_{H^1}) \|\nabla \theta\|_{H^\nu} \text{ for } \nu \in (0, 1),$$

we derive similar as (2.42)

$$\begin{aligned} 2^{2js} \|\theta_j\|_{L_T^\infty L_x^2}^2 + 2^{2j(s+1)} \|\theta_j\|_{L_T^2 L_x^2}^2 &\leq 2^{2js} \|(\theta_0)_j\|_{L_x^2}^2 \\ &+ C(\kappa_*, s, \nu, \|a\|_{C^2}, \|\theta\|_{L_T^\infty H_x^1}) (l_j)^2 \int_0^T \left(\|\nabla u\|_{L_x^2}^2 \|\nabla \theta\|_{H_x^{s-1}}^2 \right. \\ &\left. + \|\nabla \theta\|_{H_x^\nu}^2 \|\nabla \theta\|_{H_x^{s-\nu}}^2 \right) dt, \quad 1 < s < \nu + 1 < 2. \end{aligned} \quad (2.44)$$

By using the interpolation inequality (2.27), we have

$$\|\nabla \theta\|_{H_x^\nu} \|\nabla \theta\|_{H_x^{s-\nu}} \leq C \|\nabla \theta\|_{L_x^2}^{1-\nu} \|\nabla \theta\|_{H_x^1}^\nu \|\nabla \theta\|_{H_x^{s-1}}^\nu \|\nabla \theta\|_{H_x^s}^{1-\nu}, \quad 0 < \nu < 1.$$

Recall the L^2 -Estimate (2.16) for θ :

$$\|\theta\|_{L_T^\infty L_x^2}^2 + \|\nabla \theta\|_{L_T^2 L_x^2}^2 \leq C(\kappa_*) \|\theta_0\|_{L_x^2}^2. \quad (2.45)$$

Therefore by Young’s inequality, we arrive at

$$\begin{aligned} \|\theta\|_{L_T^\infty H_x^s}^2 + \|\nabla \theta\|_{L_T^2 H_x^s}^2 &\leq C(\kappa_*) \|\theta_0\|_{H_x^s}^2 \\ &+ C(\kappa_*, s, \nu, \|a\|_{C^2}, \|\theta\|_{L_T^\infty H_x^1}) \int_0^T \left(\|\nabla u\|_{L_x^2}^2 + \|\nabla \theta\|_{H_x^1}^2 \right) \|\nabla \theta\|_{H_x^{s-1}}^2 dt, \end{aligned}$$

which, together with Gronwall’s inequality, implies (1.17).

Endpoint case $(\theta_0, u_0) \in H^2(\mathbb{R}^2) \times (L^2(\mathbb{R}^2))^2$

We recall the function $\eta = A^{-1}(\theta)$ defined in (2.11), and the parabolic η -equation (2.15):

$$\partial_t \eta + u \cdot \nabla \eta - \kappa \Delta \eta = 0. \quad (2.46)$$

We are going to derive the a priori H^2 -Estimate for η under the conditions

$$\operatorname{div} u = 0, \quad \nabla u \in L_{\text{loc}}^2([0, \infty); (L^2(\mathbb{R}^2))^4) \text{ and } \nabla \kappa \in L_{\text{loc}}^4([0, \infty); (L^4(\mathbb{R}^2))^2).$$

We test the above η -equation (2.46) by $\Delta^2 \eta$, to arrive at

$$\frac{1}{2} \frac{d}{dt} \int_{\mathbb{R}^2} |\Delta \eta|^2 dx + \int_{\mathbb{R}^2} \kappa |\nabla \Delta \eta|^2 dx = - \int_{\mathbb{R}^2} \left(u \cdot \nabla \eta \Delta^2 \eta + \nabla \kappa \cdot \nabla \Delta \eta \Delta \eta \right) dx.$$

By integration by parts, $\operatorname{div} u = 0$ and the embedding $L^1(\mathbb{R}^2) \hookrightarrow H^{-1}(\mathbb{R}^2)$, we derive

$$\begin{aligned} - \int_{\mathbb{R}^2} u \cdot \nabla \eta \Delta^2 \eta dx &= \int_{\mathbb{R}^2} \nabla \Delta \eta \cdot \nabla u \cdot \nabla \eta - \nabla u : \nabla^2 \eta \Delta \eta dx \\ &\leq 4 \|\nabla u\|_{L_x^2} \left(\|\nabla \Delta \eta\|_{L_x^2} \|\nabla \eta\|_{H_x^1} + \|\nabla^2 \eta\|_{L_x^4}^2 \right) \\ &\leq \frac{\kappa_*}{4} \|\nabla \Delta \eta\|_{L_x^2}^2 + C(\kappa_*) \|\nabla u\|_{L_x^2}^2 \|\nabla \eta\|_{H_x^1}^2. \end{aligned}$$

Similarly, we have

$$\begin{aligned} - \int_{\mathbb{R}^2} \nabla \kappa \cdot \nabla \Delta \eta \Delta \eta dx &\leq \|\nabla \kappa\|_{L_x^4} \|\nabla \Delta \eta\|_{L_x^2} \|\Delta \eta\|_{L_x^4} \\ &\leq \frac{\kappa_*}{4} \|\nabla \Delta \eta\|_{L_x^2}^2 + C(\kappa_*) \|\nabla \kappa\|_{L_x^4}^4 \|\Delta \eta\|_{L_x^2}^2. \end{aligned}$$

To conclude, we have the following a priori \dot{H}_x^2 -Estimate for η and any positive time $T > 0$ by Gronwall's inequality

$$\begin{aligned} \|\Delta \eta(T)\|_{L_x^2}^2 + \|\nabla \Delta \eta\|_{L_T^2 L_x^2}^2 &\leq C(\kappa_*) \left(\|\Delta \eta_0\|_{L_x^2}^2 + \|\nabla u\|_{L_T^2 L_x^2}^2 \|\nabla \eta\|_{L_T^\infty L_x^2}^2 \right) \\ &\quad \times \exp \left(C(\kappa_*) \left(\|\nabla u\|_{L_T^2 L_x^2}^2 + \|\nabla \kappa\|_{L_T^4 L_x^4}^4 \right) \right). \end{aligned}$$

By view of the equivalence relation (2.12) as well as⁵

$$\|\nabla^3 \theta\|_{L_T^2 L_x^2} \leq C(\kappa_*, \|a\|_{C^2}) \left(\|\nabla \eta\|_{L_T^4 L_x^4}^2 + \|\nabla^2 \eta\|_{L_T^2 L_x^2} \|\nabla \eta\|_{L_T^\infty L_x^2} + \|\nabla^3 \eta\|_{L_T^2 L_x^2} \right),$$

we derive the H^2 -Estimate (1.18) for θ by virtue of the H^1 -Estimate (2.18):

$$\begin{aligned} \|\theta\|_{L_T^\infty H_x^2}^2 + \|\nabla \theta\|_{L_T^2 H_x^2}^2 &\leq C \left(\kappa_*, \|a\|_{C^2}, \kappa^* \right) \|\theta_0\|_{H^2}^2 \left(1 + \|\nabla \theta_0\|_{L^2}^2 \right)^2 \\ &\quad \times \exp \left(C(\kappa_*, \|a\|_{C^1}) \left(\|\nabla u\|_{L_T^2 L_x^2}^2 + \|u\|_{L_T^4 L_x^4}^4 + \|\nabla \theta\|_{L_T^4 L_x^4}^4 \right) \right). \end{aligned}$$

2.3.3. Case $(\theta_0, u_0) \in H^1(\mathbb{R}^2) \times (H^s(\mathbb{R}^2))^2$, $s \in (0, 2]$. In this subsection we are going to sketch the proof of the H^s , $s \in (0, 2)$ -Estimate (1.19) for the divergence-free vector field u of the unique solution (θ, u) to the Boussinesq equations (1.1), under the assumption that $\theta_0 \in H^1(\mathbb{R}^2)$, following the procedure in Sect. 2.3.1.

We deal with the endpoint case $(\theta_0, u_0) \in H^1(\mathbb{R}^2) \times (H^2(\mathbb{R}^2))^2$ similarly as for the endpoint case above.

Case $(\theta_0, u_0) \in H^1(\mathbb{R}^2) \times (H^s(\mathbb{R}^2))^2$, $s \in (0, 2)$

Recall (2.5) for the definition of the Leray–Helmholtz projector \mathbb{P} such that

$$\mathbb{P}u = u, \quad \mathbb{P}\nabla\Pi = 0.$$

We apply \mathbb{P} to the velocity equation (1.1)₂ to arrive at

$$\partial_t u + \mathbb{P}(u \cdot \nabla u) - \mathbb{P} \operatorname{div}(\mu S u) = \mathbb{P}(\theta \vec{e}_2). \quad (2.47)$$

⁵It is also straightforward to calculate

$$\begin{aligned} \partial_{jkl}\eta &= a''(\theta)(\partial_j\theta\partial_k\theta\partial_l\theta) + a'(\theta)(\partial_{jk}\theta\partial_l\theta + \partial_{ji}\partial_k\theta + \partial_{kl}\theta\partial_j\theta) + a(\theta)\partial_{jkl}\theta, \\ \partial_{jkl}\theta &= \left(-\frac{a''(A^{-1}(\eta))}{a^4(A^{-1}(\eta))} + \frac{3(a'(A^{-1}(\eta)))^2}{a^5(A^{-1}(\eta))} \right) \partial_j\eta\partial_k\eta\partial_l\eta \\ &\quad - \frac{a'(A^{-1}(\eta))}{a^3(A^{-1}(\eta))} \left(\partial_{jk}\eta\partial_l\eta + \partial_{ji}\eta\partial_k\eta + \partial_{kl}\eta\partial_j\eta \right) + \frac{1}{a(A^{-1}(\eta))} \partial_{jkl}\eta. \end{aligned}$$

We apply Δ_j to the above equation (2.47) to arrive at the equation for $u_j := \Delta_j u$

$$\partial_t u_j + \mathbb{P}u \cdot \nabla u_j - \mathbb{P} \operatorname{div}(\mu S u_j) = \mathbb{P}[u, \Delta_j] \cdot \nabla u - \mathbb{P} \operatorname{div}([\mu, \Delta_j] S u) + \mathbb{P}(\theta_j \vec{e}_2). \quad (2.48)$$

We take the $L^2(\mathbb{R}^2)$ -inner product between (2.48) and the divergence-free dyadic piece $u_j = \mathbb{P}u_j$ and follow the similar argument as to arrive at (2.38), to deduce

$$\frac{d}{dt} \|u_j\|_{L_x^2} + 2^{2j} \|u_j\|_{L_x^2} \leq C(\mu_*) \left(\|[u, \Delta_j] \cdot \nabla u\|_{L_x^2} + 2^j \|[\mu, \Delta_j] \nabla u\|_{L_x^2} + \|\theta_j\|_{L_x^2} \right). \quad (2.49)$$

By use of the commutator estimate (2.28) in Lemma 2.1 again, we have the following commutator estimates as in (2.39):

$$\begin{aligned} \|[u, \Delta_j] \nabla u\|_{L_x^2} &\leq C l_j 2^{j(1-s)} \|\nabla u\|_{L_x^2} \|\nabla u\|_{H_x^{s-1}}, \text{ for } s \in (0, 2), \\ 2^j \|[\mu, \Delta_j] \nabla u\|_{L_x^2} &\leq C l_j 2^{j(1-s)} \|\nabla \mu\|_{H_x^\nu} \|\nabla u\|_{H_x^{s-\nu}}, \text{ for } \nu \in (-1, 1), s \in (-1, \nu + 1). \end{aligned}$$

By virtue of the composition estimate (2.32) in Lemma 2.1:

$$\|\nabla \mu\|_{H_x^\nu} \leq C(\|b\|_{C^{[\nu]+2}}, \|\theta\|_{H^1}) \|\nabla \theta\|_{H_x^\nu},$$

we derive similar as (2.42) that, for $0 < s < \nu + 1 < 2$,

$$\begin{aligned} 2^{2js} \|u_j\|_{L_T^\infty L_x^2}^2 + 2^{2j(s+1)} \|u_j\|_{L_T^2 L_x^2}^2 &\leq 2^{2js} \|(u_0)_j\|_{L_x^2}^2 \\ &+ C(\mu_*) \int_0^T 2^{2j(s-1)} \|\theta_j\|_{L_x^2}^2 dt + C(\mu_*, s, \nu, \|b\|_{C^{[\nu]+2}}, \|\theta\|_{L_T^\infty H_x^1})(l_j)^2 \\ &\times \int_0^T \left(\|\nabla u\|_{L_x^2}^2 \|\nabla u\|_{H_x^{s-1}}^2 + \|\nabla \theta\|_{H_x^\nu}^2 \|\nabla u\|_{H_x^{s-\nu}}^2 \right) dt. \end{aligned} \quad (2.50)$$

By the interpolation inequality (2.27):

$$\|\nabla \theta\|_{H_x^\nu} \|\nabla u\|_{H_x^{s-\nu}} \leq C \|\nabla \theta\|_{L_x^2}^{1-\nu} \|\nabla \theta\|_{H_x^1}^\nu \|\nabla u\|_{H_x^{s-1}}^\nu \|\nabla u\|_{H_x^s}^{1-\nu}, \quad \text{for } \nu \in (0, 1),$$

and the L^2 -Estimate (1.13):

$$\|u\|_{L_T^\infty L_x^2}^2 + \|\nabla u\|_{L_T^2 L_x^2}^2 \leq C(\mu_*) \left(\|u_0\|_{L_x^2}^2 + T \|\theta_0\|_{L_x^2}^2 \right), \quad (2.51)$$

we arrive at the following by Young's inequality

$$\begin{aligned} \|u\|_{L_T^\infty H_x^s}^2 + \|\nabla u\|_{L_T^2 H_x^s}^2 &\leq C(\mu_*) \left(\|u_0\|_{H_x^s}^2 + T \|\theta_0\|_{L_x^2}^2 + \|\theta\|_{L_T^2 H_x^{s-1}}^2 \right) \\ &+ C(\mu_*, s, \nu, \|b\|_{C^2}, \|\theta\|_{L_T^\infty H_x^1}) \int_0^T \left(\|\nabla u\|_{L_x^2}^2 + \|\nabla \theta\|_{H_x^1}^2 \right) \|\nabla u\|_{H_x^{s-1}}^2 dt, \end{aligned}$$

which, together with Gronwall's inequality, implies (1.19).

Endpoint case $(\theta_0, u_0) \in H^1(\mathbb{R}^2) \times (H^2(\mathbb{R}^2))^2$

We recall the u -equation (2.47) where

$$\operatorname{div}(\mu S u) = \mu \Delta u + \nabla \mu \cdot S u.$$

We test (2.47) by the divergence-free vector field $\Delta^2 u$, to arrive at

$$\begin{aligned} \frac{1}{2} \frac{d}{dt} \int_{\mathbb{R}^2} |\Delta u|^2 dx + \int_{\mathbb{R}^2} \mu |\nabla \Delta u|^2 dx \\ = \int_{\mathbb{R}^2} \left(-u \cdot \nabla u \Delta^2 u + \nabla \mu \cdot S u \cdot \Delta^2 u - \nabla \mu \cdot \nabla \Delta u \cdot \Delta u + \Delta \theta \Delta u_2 \right) dx. \end{aligned}$$

By use of the embedding $L^1(\mathbb{R}^2) \hookrightarrow H^{-1}(\mathbb{R}^2)$ again, the right hand side can be bounded by

$$C \left(\|\nabla u\|_{L_x^4}^2 + \|u\|_{L_x^4} \|\nabla^2 u\|_{L_x^4} + \|\nabla^2 \mu\|_{L_x^2} \|\nabla u\|_{H_x^1} + \|\nabla \mu\|_{L_x^4} \|\nabla^2 u\|_{L_x^4} \right) \|\nabla \Delta u\|_{L_x^2} + \|\Delta \theta\|_{L_x^2} \|\Delta u\|_{L_x^2}.$$

Thus, we have the following a priori \dot{H}_x^2 -Estimate for u and any positive time $T > 0$ by Young's inequality and Gronwall's inequality

$$\begin{aligned} & \|\Delta u(T)\|_{L_x^2}^2 + \|\nabla \Delta u\|_{L_T^2 L_x^2}^2 \\ & \leq C(\mu_*) \left(\|\Delta u_0\|_{L_x^2}^2 + \|\nabla u\|_{L_T^4 L_x^4}^4 + \|\nabla^2 \mu\|_{L_T^2 L_x^2}^2 \|\nabla u\|_{L_T^\infty L_x^2}^2 + \|\Delta \theta\|_{L_T^2 L_x^2} \|\Delta u\|_{L_T^2 L_x^2} \right) \\ & \quad \times \exp \left(C(\mu_*) (\|u, \nabla \mu\|_{L_T^4 L_x^4}^4 + \|\nabla^2 \mu\|_{L_T^2 L_x^2}^2) \right), \end{aligned}$$

which gives (1.20).

2.3.4. Case $(\theta_0, u_0) \in H^s(\mathbb{R}^2) \times (H^{s-2}(\mathbb{R}^2))^2$ or $H^{s-1} \times (H^s(\mathbb{R}^2))^2$, $s > 2$. We are going to use the estimates in the high regularity regime in Lemma 2.1 to derive the H^s -Estimates (1.21)–(1.22)–(1.23)–(1.24) in Remark 1.4. Let $(l'_j)_{j \geq 0}$ be a normalized sequence in $\ell^2(\mathbb{N})$ such that $l'_j \geq 0$ and $\sum_{j \geq 0} (l'_j)^2 = 1$.

Case $(\theta_0, u_0) \in H^s(\mathbb{R}^2) \times (H^{s-2}(\mathbb{R}^2))^2$, $s > 2$

We can view the transport term $u \cdot \nabla \theta$ simply as a source term of the θ -equation:

$$\partial_t \theta - \operatorname{div}(\kappa \nabla \theta) = -u \cdot \nabla \theta$$

Then, the preliminary estimate for $\theta_j = \Delta_j \theta$ in (2.43) can be replaced by

$$\frac{d}{dt} \|\theta_j\|_{L_x^2} + 2^{2j} \|\theta_j\|_{L_x^2} \leq C(\kappa_*) (\|u \cdot \nabla \theta\|_{L_x^2} + 2^j \|[\kappa, \Delta_j] \nabla \theta\|_{L_x^2}), \quad j \geq 0.$$

We apply Lemma 2.1 to derive the following estimates for $s > 1$:

$$\begin{aligned} \|(u \cdot \nabla \theta)_j\|_{L_x^2} & \leq C l'_j 2^{j(1-s)} (\|u\|_{L_x^\infty} \|\nabla \theta\|_{H_x^{s-1}} + \|u\|_{H_x^{s-1}} \|\nabla \theta\|_{L_x^\infty}), \\ 2^j \|[\kappa, \Delta_j] \nabla \theta\|_{L_x^2} & \leq C l'_j 2^{j(1-s)} (\|\nabla \kappa\|_{L_x^\infty} \|\nabla \theta\|_{H_x^{s-1}} + \|\nabla \kappa\|_{H_x^{s-1}} \|\nabla \theta\|_{L_x^\infty}). \end{aligned}$$

Therefore, we have the following estimate similarly as in (2.44) for $s \in (2, 3)$ by virtue of $H^{s-1}(\mathbb{R}^2) \hookrightarrow L^\infty(\mathbb{R}^2)$:

$$\begin{aligned} & 2^{2js} \|\theta_j\|_{L_T^\infty L_x^2}^2 + 2^{2j(s+1)} \|\theta_j\|_{L_T^2 L_x^2}^2 \leq 2^{2js} \|(\theta_0)_j\|_{L_x^2}^2 \\ & \quad + C(\kappa_*, s) (l'_j)^2 \int_0^T \|u\|_{H_x^{s-1}}^2 \|\nabla \theta\|_{H_x^{s-1}}^2 dt \\ & \quad + C(\kappa_*, a, \|\theta\|_{L_T^\infty L_x^\infty}) (l'_j)^2 \int_0^T \|\nabla \theta\|_{L_x^\infty}^2 \|\nabla \theta\|_{H_x^{s-1}}^2 dt, \quad j \geq 0, \end{aligned}$$

which, together with the L^2 -Estimate (2.45) and the Gronwall's inequality, implies (1.21).

For $s \geq 3$, we make use of the following commutator estimate

$$\|[u, \Delta_j] \nabla \theta\|_{L_x^2} \leq C l'_j 2^{j(1-s)} (\|\nabla u\|_{L_x^\infty} \|\nabla \theta\|_{H_x^{s-2}} + \|\nabla u\|_{H_x^{s-2}} \|\nabla \theta\|_{L_x^\infty}), \quad (2.52)$$

such that the estimate (1.22) follows.

Case $(\theta_0, u_0) \in H^{s-1}(\mathbb{R}^2) \times (H^s(\mathbb{R}^2))^2$, $s > 2$

We recall the preliminary estimate for u_j in (2.49). We apply Lemma 2.1 to derive the following commutator estimates for $s \in (2, 3)$ and $\nu \in (s-2, 1) \subset (0, 1)$

$$\begin{aligned} \|[u, \Delta_j] \nabla u\|_{L_x^2} &\leq Cl_j 2^{j(1-s)} \|\nabla u\|_{H_x^\nu} \|\nabla u\|_{H_x^{s-1-\nu}}, \\ 2^j \|[\mu, \Delta_j] \nabla u\|_{L_x^2} &\leq Cl'_j 2^{j(1-s)} (\|\nabla \mu\|_{L_x^\infty} \|\nabla u\|_{H_x^{s-1}} + \|\nabla \mu\|_{H_x^{s-1}} \|\nabla u\|_{L_x^\infty}), \end{aligned}$$

which implies then

$$\begin{aligned} 2^{2js} \|u_j\|_{L_T^\infty L_x^2}^2 + 2^{2j(s+1)} \|u_j\|_{L_T^2 L_x^2}^2 &\leq 2^{2js} \|(u_0)_j\|_{L_x^2}^2 + C(\mu_*) \int_0^T 2^{2j(s-1)} \|\theta_j\|_{L_x^2}^2 dt \\ &+ C(\mu_*, s, \nu) (l_j)^2 \int_0^T \|\nabla u\|_{H_x^\nu}^2 \|\nabla u\|_{H_x^{s-1-\nu}}^2 dt \\ &+ C(\mu_*, s, \|b\|_{C^{[s]+1}}, \|\theta\|_{L_T^\infty H_x^1}) (l'_j)^2 \int_0^T \|\nabla \theta\|_{L_x^\infty}^2 \|\nabla u\|_{H_x^{s-1}}^2 + \|\nabla \theta\|_{H_x^{s-1}}^2 \|\nabla u\|_{L_x^\infty}^2 dt, \quad j \geq 0. \end{aligned}$$

This, together with the L^2 -Estimate (2.51) and Sobolev's embedding $H^{s-1}(\mathbb{R}^2) \hookrightarrow L^\infty(\mathbb{R}^2)$, implies (1.23) where $\nu \in (0, 1)$ is taken to be a small constant bigger than $s-2$.

For $s \geq 3$, we use the commutator estimate (2.52) with θ replaced by u , to arrive at (1.24).

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