

Mapping forest tree species in high resolution UAV-based RGB-imagery by means of convolutional neural networks

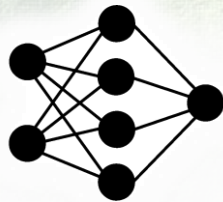
Felix Schiefer, Teja Kattenborn, Annett Frick, Julian Frey, Peter Schall, Barbara Koch, Sebastian Schmidlein

Data



- RGB-imagery from consumer-grade UAVs
- Spatial resolution < 2 cm
- Mixed coniferous and mixed deciduous forests
- 51 plots á 1 ha
- 14 classes (9 species, 3 genera, deadwood, forest floor)
- Visual interpretation based on full forest inventory data

Deep Learning



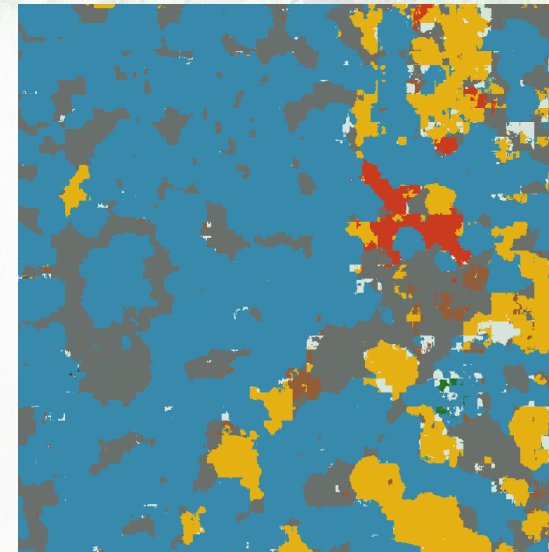
- U-Net CNN architecture
- Semantic segmentation
- Test several models
- Independent, pixel-based evaluation using F1-Score



TensorFlow



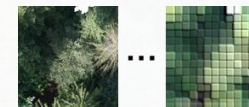
Results + Key findings



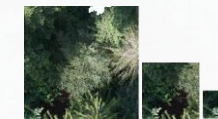
	F1
<i>Picea abies</i>	0.93
<i>Fagus sylvatica</i>	0.90
<i>Abies alba</i>	0.86
<i>Pseudotsuga menziesii</i>	0.89
<i>Pinus sylvestris</i>	0.91
<i>Acer</i> spp.	0.80
<i>Fraxinus excelsior</i>	0.87
<i>Larix decidua</i>	0.83
<i>Quercus</i> spp.	0.58
<i>Carpinus betulus</i>	0.38
<i>Tilia</i> spp.	0.50
<i>Betula pendula</i>	0.27
Forest floor	0.83
Deadwood	0.72
Mean	0.73

- ✗ LiDAR
- ✗ hyperspectral
- ✓ RGB

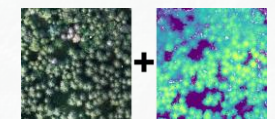
- High accuracy
- End-to-end learning



- High spatial resolution essential



- Trade-offs in tile size



- No clear benefit of additional height information



Sharing is encouraged