

SEE ME, HEAR ME: INTEGRATING AUTOMATIC SPEECH RECOGNITION AND LIP-READING

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ABSTRACT

Recent work on integration of visual informa-
tion with acoustic speech for lip-

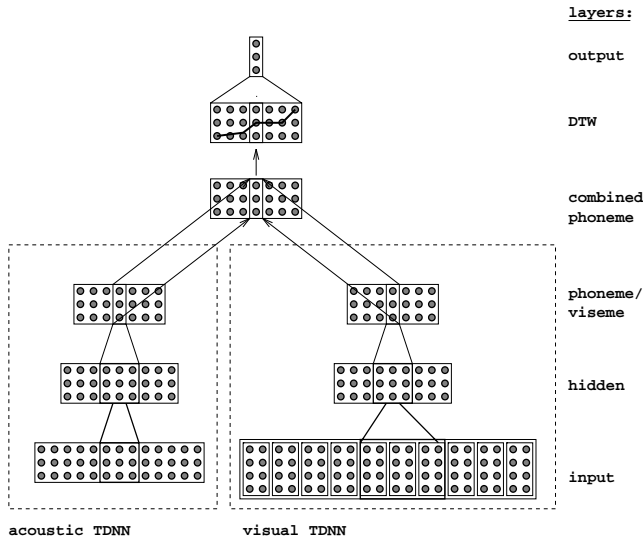


Figure 1. Original recognition network architecture (Net-P).

data, respectively. Weighted sums of the phone and corresponding viseme activations are entered in the combined layer and a one stage DTW algorithm finds the optimal path through the phone states that decodes the recognized letter sequence. The weights in the parallel networks are trained by backpropagation. There are 15 hidden units in both sub-nets. The combination weights are computed dynamically during recognition to reflect the estimated reliability of each modality. These “entropy weights” [2], λ_A for the acoustic side and λ_V for the visual are given by:

$$\begin{aligned} \lambda_A &= b + \frac{S_V - S_A}{\Delta S_{max-over-data}} \\ \lambda_V &= 1 - \lambda_A \end{aligned} \quad (1)$$

The entropy quantities S_A and S_V are computed for the acoustic and visual phone/viseme activations by normalizing these to sum to one and treating them as probability mass functions. High entropy is found when activations are evenly spread over the units which indicates high ambiguity of the decision from that particular modality. The bias b pre-skews the weights to favor one of the modalities.

2.2. Visual Data Representation

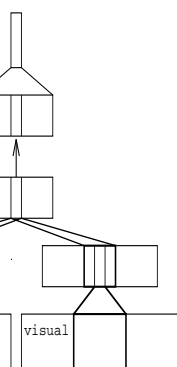
Unlike for acoustic speech data, there are no generally agreed-upon parameterization strategies for the visual lip images. Since we are using a connectionist algorithm for recognition we have followed the philosophy of avoiding explicit feature extraction and segmentation of the image. Instead, we have let the network develop appropriate intermediate higher level features. We have been using the following visual data representations

pixel vector is quite
input vec-
o

Input	Visual Count		Parameter		Word Accuracy (%)	
	mm1-2	mm1-10	mm1-2	mm1-10	mm1-2	mm1-10
Gray Levels	384	55	44			
	32	52	45			
	29	53	52			
	50	38				

ly recognition rates for different data repre-

ents the recognizer from taking advantage of
 ons between acoustic and visual events
 ationships. There is evidence
 inputs to take advan-



Net H

ic and visual combi-

erated in Figure 2.
 y be con-

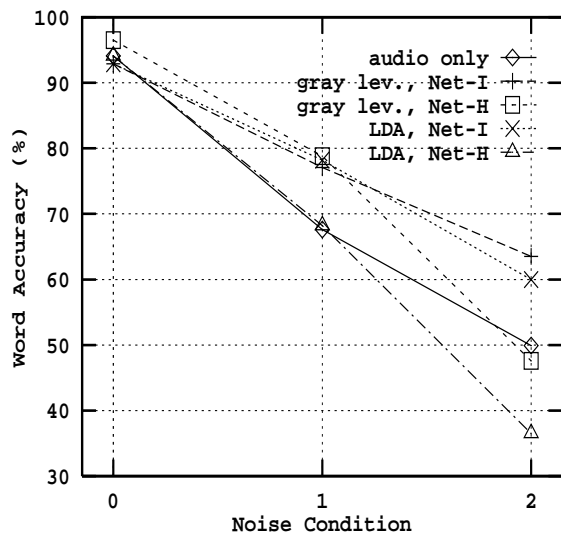


Figure 4. Combination results for Net-I and Net-H.

Comparison of different net structures yields more equivocal conclusions. All three are clearly capable of improving recognition with the addition of visual information. However, Net-P combination of the modalities *always* yields a better result than either modality alone which is not true of Net-I and Net-H. On the other hand, neither Net-I nor Net-H at this time (for instance, Net-I is outperformed by Net-P). This is especially true for