

Derivation of two-phase volume averaged conservation equations for volume-of-fluid interface tracking

M. Wörner, D.G. Cacuci, W. Sabisch, G. Grötzbach

Research Center Karlsruhe, Institute for Reactor Safety, Germany

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Problem and motivation

- **Volume-of-fluid (VOF) computations in literature:**
finite difference discretization of *local* equations

$$\frac{\partial f}{\partial t} + \nabla \cdot f \mathbf{v} = 0 \quad (0 \leq f \leq 1), \rho_m = f\rho_1 + (1-f)\rho_2, \mu_m = f\mu_1 + (1-f)\mu_2$$

$$\frac{\partial \rho_m \mathbf{v}}{\partial t} + \nabla \cdot \rho_m \mathbf{v} \mathbf{v} = -\nabla p + \nabla \cdot \mu_m (\nabla \mathbf{v} + \nabla \mathbf{v}^\top) + \rho_m \mathbf{g} + \sigma \kappa \mathbf{n} \delta_s \quad \nabla \cdot \mathbf{v} = 0$$

- **Obvious inconsistency:**
some quantities are averaged f, ρ_m, μ_m
and some are not \mathbf{v}, p

(Problem and motivation)

- Both phases are assumed to move with same velocity, namely the center-of-mass velocity
⇒ comput. grid must resolve boundary layer at interface
- Which are the additional terms if the boundary layer is not fully resolved, i.e. the phase velocities differ?
- **Goal:** Derive consistent volume-averaged equations for volume-of-fluid computations
(VA-VOF eqs. for phases of constant density)

Procedure to derive VA-VOF equations

1. local mass & momentum cons.-eqs. for phase $k=1,2$ valid in $\Omega_k(t)$
2. multiply eqs. by respective phase indicator function $X_k(\mathbf{x},t)$
3. apply to each term VA operator $\overline{\psi}_k \equiv \frac{1}{V_k} \int_V \psi_k(\mathbf{x} + \boldsymbol{\eta}, t) X_k(\mathbf{x} + \boldsymbol{\eta}, t) d\mathbf{x}$
4. apply Gauss & Leibnitz rules to obtain eqs. of two-fluid model:

$$\frac{\partial \alpha_k \rho_k}{\partial t} + \nabla \cdot \alpha_k \rho_k \overline{\mathbf{v}}_k = 0 \quad k = 1,2$$

$$\frac{\partial \alpha_k \rho_k \overline{\mathbf{v}}_k}{\partial t} + \nabla \cdot \alpha_k \rho_k \left(\overline{\mathbf{v}}_k \overline{\mathbf{v}}_k + \overline{\mathbf{v}'_k \mathbf{v}'_k} \right) = -\nabla \alpha_k \overline{p}_k + \alpha_k \rho_k \mathbf{g} + \nabla \cdot \alpha_k \overline{\mathbf{\tau}}_k + \mathbf{M}_k$$

(Procedure to derive VA-VOF equations)

5. for simplified representation of VA-VOF eqs. we introduce

- liquid volumetric fraction $f \equiv \alpha_1$

- mixture density $\rho_m \equiv \sum_{k=1}^2 \alpha_k \rho_k = f\rho_1 + (1-f)\rho_2$

- center-of-mass velocity $\mathbf{v}_m \equiv \frac{1}{\rho_m} \sum_{k=1}^2 \alpha_k \rho_k \overline{\mathbf{v}}_k = \frac{f \rho_1 \overline{\mathbf{v}}_1^{-1} + (1-f) \rho_2 \overline{\mathbf{v}}_2^{-2}}{\rho_m}$

- relative velocity $\mathbf{v}_r = \mathbf{v}_{21} \equiv \overline{\mathbf{v}}_2^{-2} - \overline{\mathbf{v}}_1^{-1}$

$$\Rightarrow \overline{\mathbf{v}}_1^{-1} = \mathbf{v}_m - \frac{\alpha_2 \rho_2}{\rho_m} \mathbf{v}_r, \quad \overline{\mathbf{v}}_2^{-2} = \mathbf{v}_m + \frac{\alpha_1 \rho_1}{\rho_m} \mathbf{v}_r$$

VA-VOF mass conservation equations

- two-fluid model mass conservation equations for $k=1,2$:

$$\frac{\partial f \rho_1}{\partial t} + \nabla \cdot f \rho_1 \mathbf{v}_m = \nabla \cdot f(1-f) \frac{\rho_1 \rho_2}{\rho_m} \mathbf{v}_r \quad (1)$$

$$\frac{\partial (1-f) \rho_2}{\partial t} + \nabla \cdot (1-f) \rho_2 \mathbf{v}_m = -\nabla \cdot f(1-f) \frac{\rho_1 \rho_2}{\rho_m} \mathbf{v}_r \quad (2)$$

- rearrange to yield:

$$\frac{\partial f}{\partial t} + \nabla \cdot f \mathbf{v}_m = \nabla \cdot f(1-f) \frac{\rho_2}{\rho_m} \mathbf{v}_r \quad (1)/\rho_1$$

$$\nabla \cdot \mathbf{v}_m = -\nabla \cdot f(1-f) \frac{\rho_1 - \rho_2}{\rho_m} \mathbf{v}_r \quad (1)/\rho_1 + (2)/\rho_2$$

VA single-field momentum equation

- sum of the momentum equations of the two-fluid model for phase 1 and 2 within averaging volume V

$$\begin{aligned} \frac{\partial}{\partial t} \sum_{k=1}^2 \alpha_k \rho_k \overline{\mathbf{v}_k}^k + \nabla \cdot \sum_{k=1}^2 \alpha_k \rho_k \overline{\mathbf{v}_k}^k \overline{\mathbf{v}_k}^k = \\ - \nabla \sum_{k=1}^2 \alpha_k \overline{p_k}^k + \sum_{k=1}^2 \alpha_k \rho_k \mathbf{g} + \nabla \cdot \sum_{k=1}^2 \alpha_k (\overline{\boldsymbol{\tau}_k}^k + \underline{\boldsymbol{\tau}}_{sgs}^k) + \mathbf{M}_1 + \mathbf{M}_2 \end{aligned}$$

where $\underline{\boldsymbol{\tau}}_{sgs} = - \sum_{k=1}^2 \alpha_k \rho_k \overline{\mathbf{v}'_k} \overline{\mathbf{v}'_k}^k$

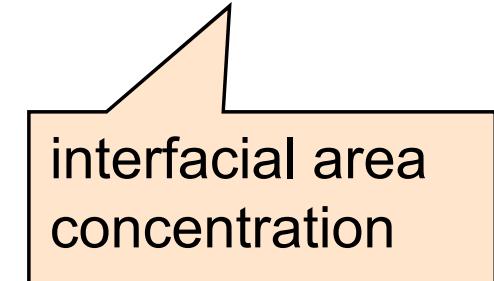
(VA single-field momentum equation)

- sum of momentum transfer terms (jump condition)

$$\mathbf{M}_1 + \mathbf{M}_2 = \frac{\sigma}{V} \int_{S_i(\mathbf{x},t)} \kappa \mathbf{n} dS \cong \sigma \bar{\kappa}^V \bar{\mathbf{n}}^V \frac{1}{V} \int_{S_i(\mathbf{x},t)} dS = \sigma \bar{\kappa}^V \bar{\mathbf{n}}^V a_{int}$$

- sum of convective terms

$$\sum_{k=1}^2 \alpha_k \rho_k \overline{\mathbf{v}_k} \overline{\mathbf{v}_k} = \rho_m \mathbf{v}_m \mathbf{v}_m + \underline{\mathbf{D}}_{int},$$



where $\underline{\mathbf{D}}_{int} \equiv \alpha_1 \alpha_2 \frac{\rho_1 \rho_2}{\rho_m} \mathbf{v}_r \mathbf{v}_r$ = "momentum drift flux term"

(VA single-field momentum equation)

- sum of diffusive terms

$$\sum_{k=1}^2 \alpha_k \underline{\tau}_k = \sum_{k=1}^2 \alpha_k \mu_k \left(\nabla \underline{v}_k + (\nabla \underline{v}_k)^T \right) \equiv \underline{\tau}_m + \underline{\tau}_{int}$$

where $\underline{\tau}_m \equiv \mu_m \left(\nabla \underline{v}_m + (\nabla \underline{v}_m)^T \right)$, $\mu_m \equiv f\mu_1 + (1-f)\mu_2$

$$\Rightarrow \underline{\tau}_{int} = \alpha_2 \mu_2 \left(\nabla \frac{\alpha_1 \rho_1}{\rho_m} \underline{v}_r + \left(\nabla \frac{\alpha_1 \rho_1}{\rho_m} \underline{v}_r \right)^T \right) - \alpha_1 \mu_1 \left(\nabla \frac{\alpha_2 \rho_2}{\rho_m} \underline{v}_r + \left(\nabla \frac{\alpha_2 \rho_2}{\rho_m} \underline{v}_r \right)^T \right)$$

$\underline{\tau}_{int}$ = "interfacial friction term"

Set of VA-VOF equations

$$\frac{\partial f}{\partial t} + \nabla \cdot f \mathbf{v}_m = \nabla \cdot f (1-f) \frac{\rho_2}{\rho_m} \mathbf{v}_r$$

$$\nabla \cdot \mathbf{v}_m = -\nabla \cdot f (1-f) \frac{\rho_1 - \rho_2}{\rho_m} \mathbf{v}_r$$

$$\frac{\partial \rho_m \mathbf{v}_m}{\partial t} + \nabla \cdot (\rho_m \mathbf{v}_m \mathbf{v}_m + \underline{\mathbf{D}}_{int}) = -\nabla \sum_{k=1}^2 \alpha_k \overline{p}_k^k + \rho_m \mathbf{g} + \sigma \bar{\kappa}^V \bar{\mathbf{n}}^V a_{int}$$

$$+ \nabla \cdot \mu_m \left(\nabla \mathbf{v}_m + (\nabla \mathbf{v}_m)^T \right) + \nabla \cdot (\underline{\boldsymbol{\tau}}_{int} + \underline{\boldsymbol{\tau}}_{sgs})$$

(Set of VA-VOF equations)

$$\frac{\partial f}{\partial t} + \nabla \cdot f \mathbf{v}_m = \nabla \cdot f(1-f) \frac{\rho_2}{\rho_m} \mathbf{v}_r = 0$$

limit $V \rightarrow 0 \Rightarrow \mathbf{v}_r = 0$
 ⇒ local VOF equations

$$\nabla \cdot \mathbf{v}_m = -\nabla \cdot f(1-f) \frac{\rho_1 - \rho_2}{\rho_m} \mathbf{v}_r = 0$$

$$\frac{\partial \rho_m \mathbf{v}_m}{\partial t} + \nabla \cdot (\rho_m \mathbf{v}_m \mathbf{v}_m + \underline{\mathbf{D}}_{int}) = -\nabla \sum_{k=1}^2 \alpha_k \bar{p}_k^{-k} + \rho_m \mathbf{g} + \sigma \bar{\kappa}^V \bar{\mathbf{n}}^V a_{int}$$

$$+ \nabla \cdot \mu_m (\nabla \mathbf{v}_m + (\nabla \mathbf{v}_m)^T) + \nabla \cdot (\underline{\boldsymbol{\tau}}_{int} + \underline{\boldsymbol{\tau}}_{sgs})$$

Closure of VA-VOF equations

- 3 equations: f -equation = liquid mass conservation eq.
divergence condition = gas mass conserv. eq.
mixture momentum equation
- 5 unknowns $f, \mathbf{v}_m, \mathbf{v}_r, \overline{p}_1, \overline{p}_2$
- 1st assumption: both phases share same pressure field
- 2nd closure relation: constitutive equation for \mathbf{v}_r
 - trivial closure: “homogenous model” $\mathbf{v}_r = \mathbf{0}$

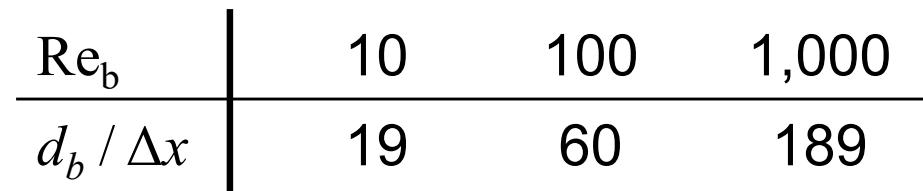
Relevance of modelling v_r

- estimate for thickness of boundary layer

$$\delta \approx \frac{d_b/2}{\sqrt{\text{Re}_b}}, \quad \text{where} \quad \text{Re}_b = \frac{d_b U_\infty}{v_l}$$

- resolve boundary layer by 3 mesh cells

$$\Rightarrow \frac{d_b}{\Delta x} = 6\sqrt{\text{Re}_b}$$



- current 3D VOF computations: $\text{Re}_b \leq O(100)$, $d_b/\Delta x \leq 50$

Order of magnitude estimation

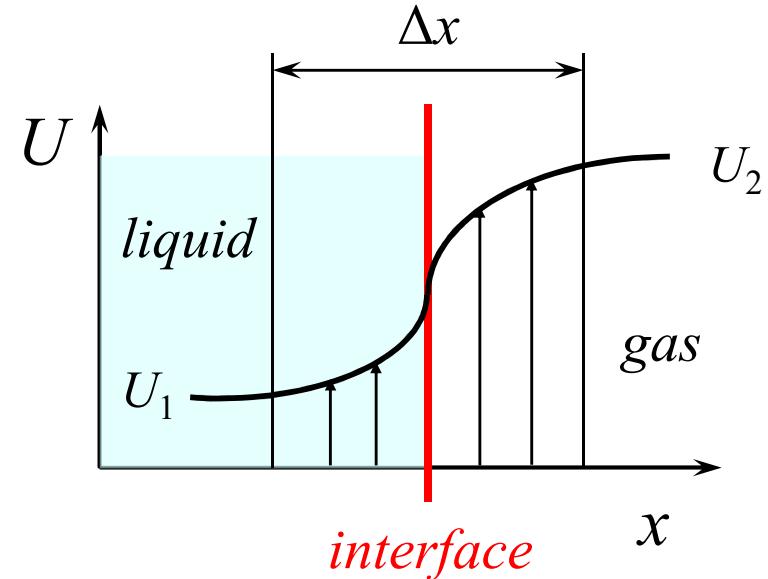
- momentum drift flux term

$$\frac{D_{int}}{\rho_m U_m U_m} = q(f, \rho_1, \rho_2, U_1, U_2)$$

$$\frac{f}{1-f} = \frac{\rho_1}{\rho_2} \Rightarrow q = q_{max} \cong \frac{1}{2} \frac{U_2 - U_1}{U_1 + U_2}$$

- interfacial friction term

$$\rho_1 = \rho_2, \mu_1 = \mu_2 \Rightarrow \frac{\tau_{int}}{\tau_m} \propto \frac{(U_2 - U_1) \frac{\partial f}{\partial x}}{\frac{\partial U_m}{\partial x}} \cong \frac{(U_2 - U_1)^{1-0}}{\frac{U_2 - U_1}{\Delta x}} = 1$$



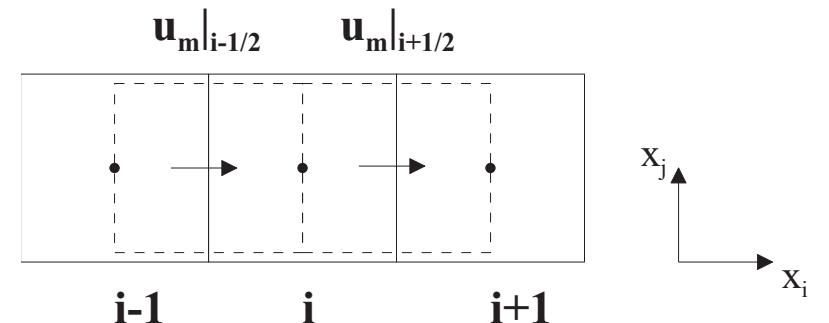
A first model proposal for \mathbf{v}_r

- local algebraic model for $\mathbf{v}_r = (u_r, v_r, w_r)^T$
- for conservative discretization of D_{int} on staggered grid \mathbf{v}_r must be formulated cell-centered, e.g. $u_{r;i} = u_{2;i} - u_{1;i}$
- 2 equations from definitions:

$$u_{m,i\pm 1/2} = \frac{f_{i\pm 1/2}\rho_1 u_{1,i\pm 1/2} + (1-f_{i\pm 1/2})\rho_2 u_{2,i\pm 1/2}}{\rho_{m,i\pm 1/2}}$$

- 6 unknowns:

$$u_{1,i+1/2}, \quad u_{1,i-1/2}, \quad u_{1,i}, \quad u_{2,i+1/2}, \quad u_{2,i-1/2}, \quad u_{2,i}$$



(A first model proposal for v_r)

- assumption: $u_{1,i+1/2} = u_{1,i-1/2} = u_{1,i}$, $u_{2,i+1/2} = u_{2,i-1/2} = u_{2,i}$

Local Uniform Relative Velocity model (LURV)

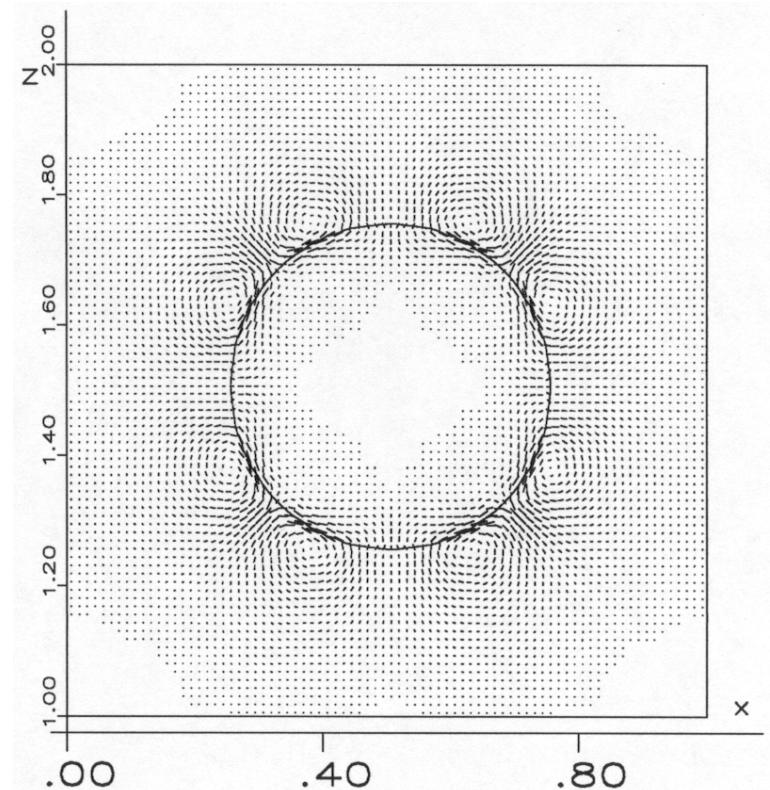
- after some algebraic manipulations we obtain:

$$u_{r,i} = - \left(1 + \frac{\rho_1 - \rho_2}{\rho_2} f_{i-1/2} \right) \left(1 + \frac{\rho_1 - \rho_2}{\rho_2} f_{i+1/2} \right) \frac{\rho_2}{\rho_1} \frac{u_{m,i+1/2} - u_{m,i-1/2}}{f_{i+1/2} - f_{i-1/2}}$$

(valid only for $f_{i+1/2} \neq f_{i-1/2}$)

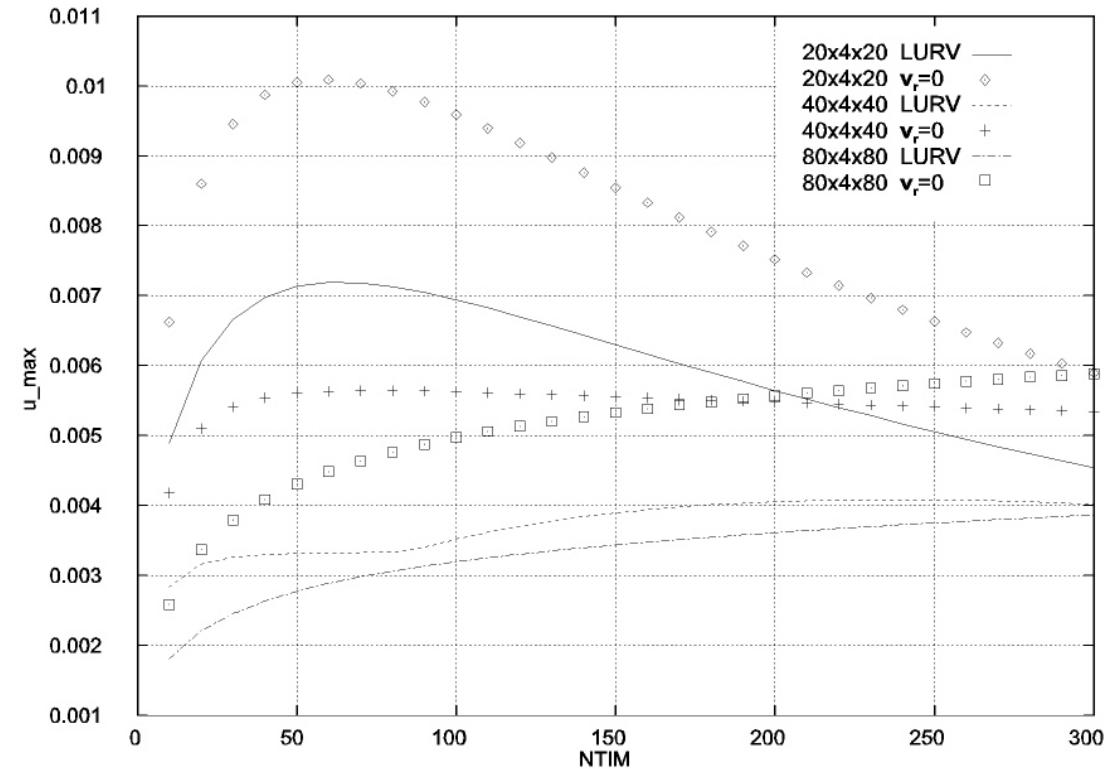
Preliminary results

- LURV model only in momentum equation
- “homogeneous model” in f -equation and in divergence equation
- static 2D interface \Rightarrow pressure jump correctly computed but unphysical “spurious currents”



(Preliminary results)

- amplitude of *unphysical* “spurious currents” may be slightly reduced or slightly increased
⇒ LURV model will be tested for *physical* flow fields



Conclusions and outlook

- Derivation of volume-averaged VOF equations
 - phase velocities may differ from center-of-mass velocity
⇒ additional terms in interface cells as compared to local VOF eqs.
 - closure assumption for relative phase velocity v_r is required
⇒ suitable models for v_r must be developed and tested
 - perspective of “low bubble resolution” VOF simulations for high Re_b
 - VA momentum eq. applies also to level-set and front-tracking method
- Two-phase “large-eddy simulation” with interface tracking
 - SGS model for unresolved velocity fluctuations in single phase cells
 - model for v_r to account for unresolved boundary layer