

Measuring the turbulent wind vector with a weight-shift Microlight Aircraft

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- M-IFU application area and setup for fast wind measurement
- from lab- to field calibration
- performance and uncertainty
- outlook

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- what we got...
 - cruise speed 80 kmh^{-1}
 - payload max 80 kg
 - power max 60 A at 12 VDC
 - high mobility

- and what we need...
 - visual flight
 - wind at ground level $< 10 \text{ ms}^{-1}$
 - waterproof shelter for storage
 - runway minimum 200 m



setup for fast wind measurement

- 5 hole probe
 - pascaLine low pressure sensors < 6 hPa
- Omega 50 μm Ni-Cr thermocouple
 - response time < 0.05 s
- Oxford Scientific RT 3000 INS
 - groundspeed $\sigma < 0.05$ ms^{-1}
 - attitude angles $\sigma < 0.1^\circ$
- Dynamax OP-2 IRGA for H_2O & CO_2
- 4 pole hardware Butterworth filter at 20 Hz
- storage at 10 Hz; spatial resolution ~ 2.6 m



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calibration scheme

calibration range for flow angles:

- $\tan(\beta) = \text{HOR} / \text{TAS}$
- for $\text{TAS} = 28 \text{ ms}^{-1}$ and $\text{HOR} = 10 \text{ ms}^{-1}$ $\beta = \pm 20^\circ$
- low level flight ($\text{HOR} = 10 \text{ ms}^{-1}$, $u^* = 0.7 \text{ ms}^{-1}$) $\alpha, \beta = \pm 15^\circ$

I. dynamic pressure (q)



II. flow angles ($p_{\text{diff}1}, p_{\text{diff}2}$)



V. pitching: α

III. tower: static pressure (p)



IV. squares: q and β

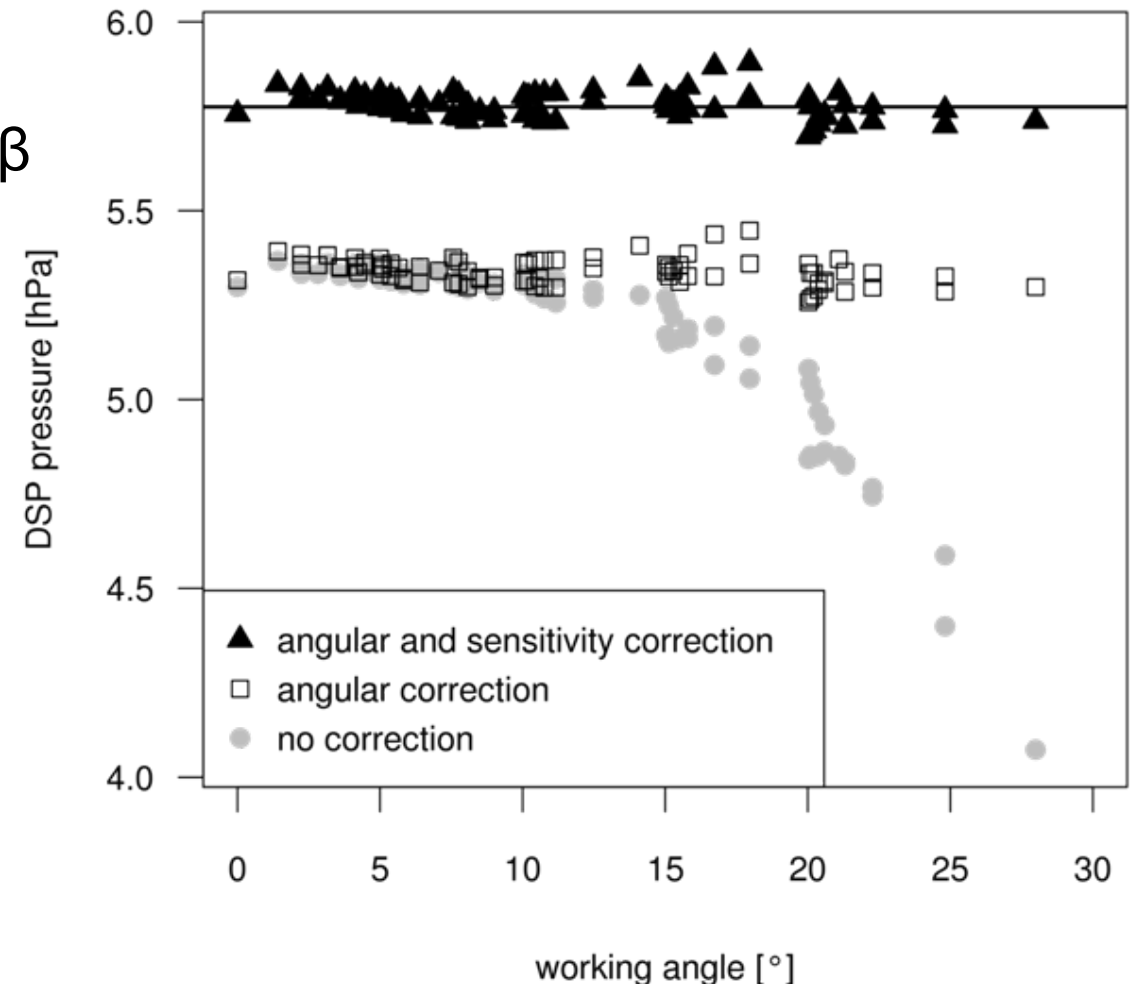


IV. racetracks: q



I & II: lab - dynamic pressure and flow angles

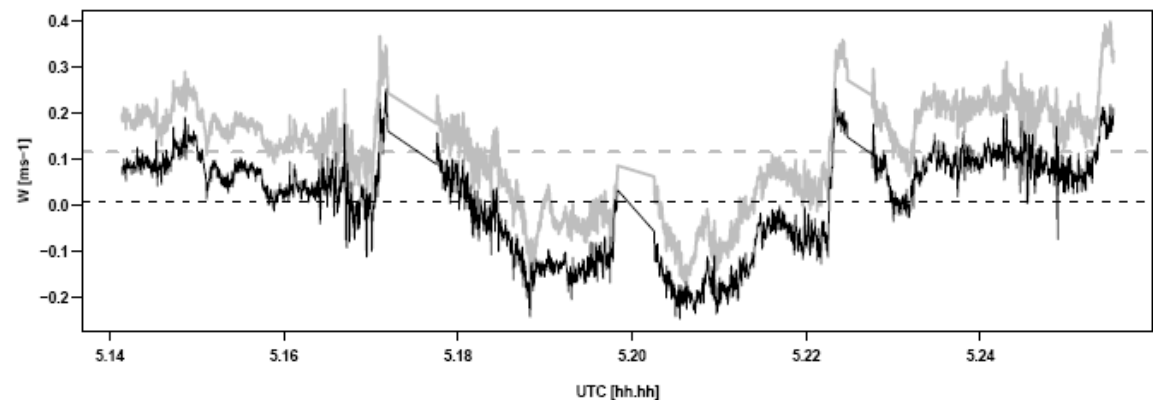
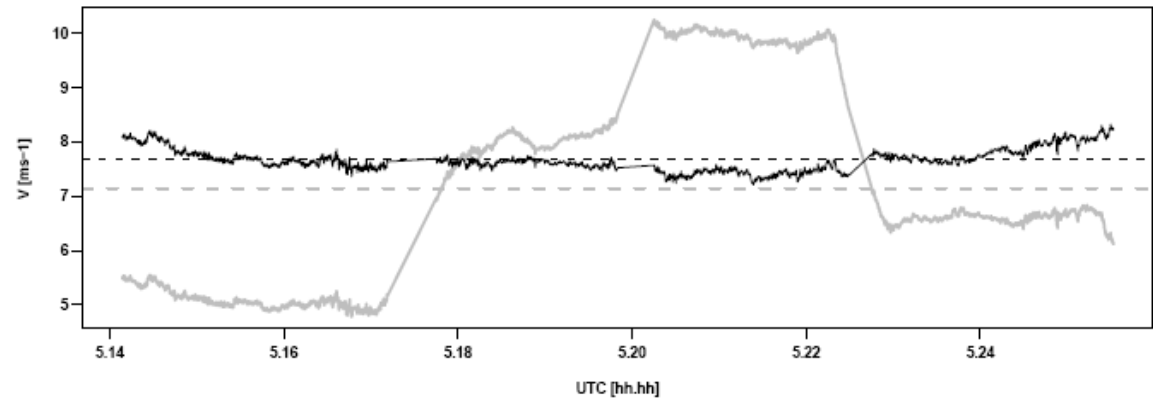
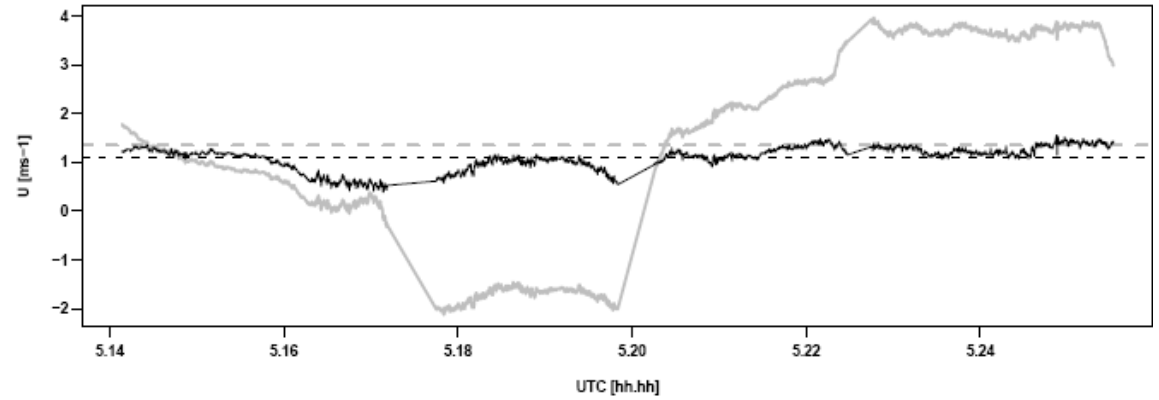
- angular correction
 - q port 6° of of half sphere
 - fourth order linear model for q
 - sensitivity for q: $K_{q11} = 1.080$
 - third order linear model for α, β
- uncertainties in residuals
 - $\sigma_q < 0.025$ hPa
 - $\sigma_{\alpha, \beta} < 0.2^\circ$
- outcome
 - q angular independent
 - q recovers input
 - flow angle reference



V & VI: field - squares and pitching

- four perpendicular legs
 - cardinal directions
 - calm conditions
- idea
 - q sensitive along-track
 - beta sensitive cross-track

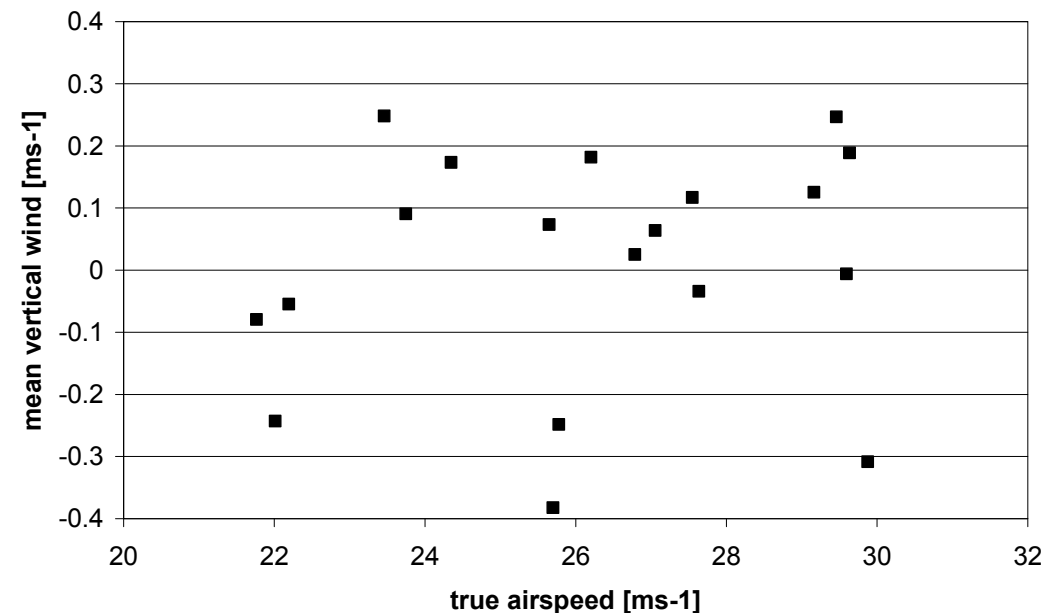
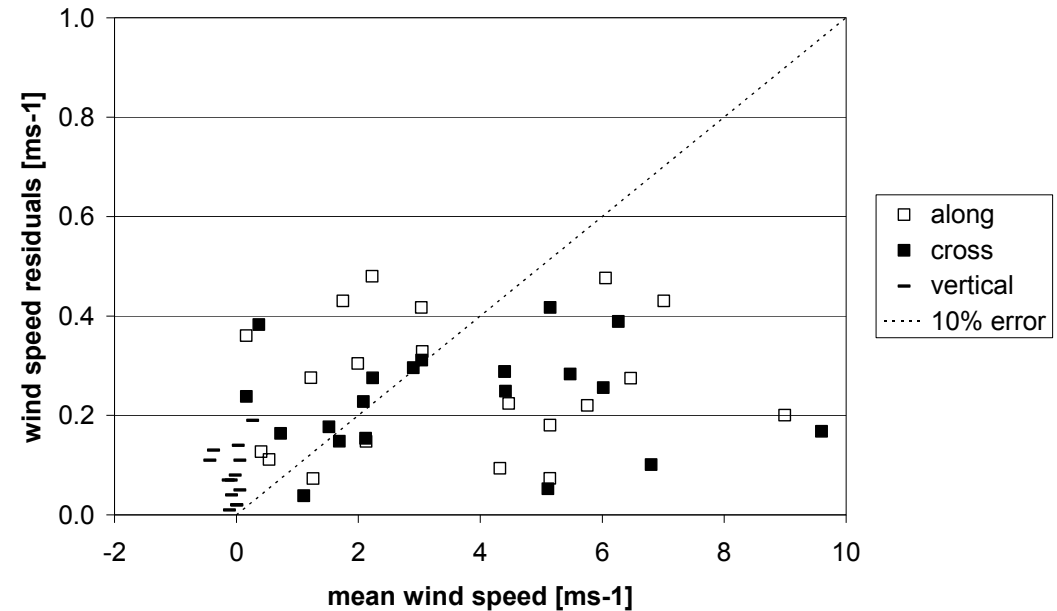
	offset	sensitivity	σ [ms ⁻¹]
p	2.12 hPa	-	0.01
q	-	1.09	0.16
α	0.26°	1.09	0.18
β	2.54°	1.21	0.18
T	-	-	0.02
e	-	-	0.01
UVWairc	-	-	0.05
ANGairc	-	-	0.09
uncorrelated Gauss error			0.32



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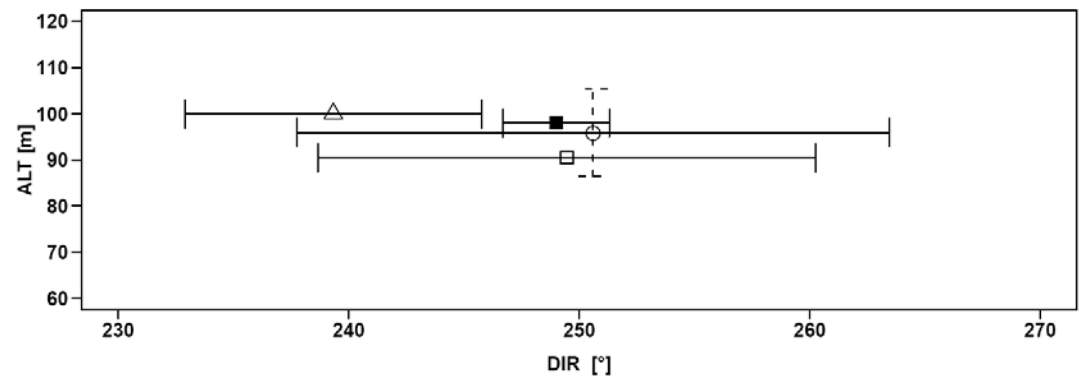
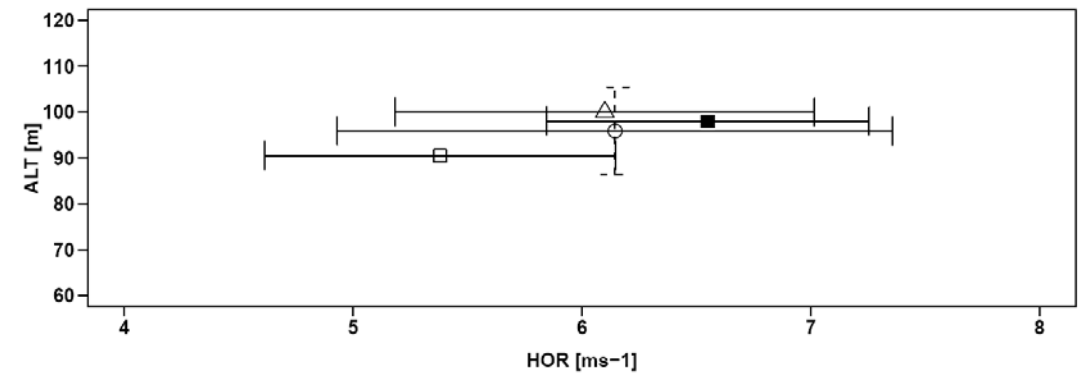
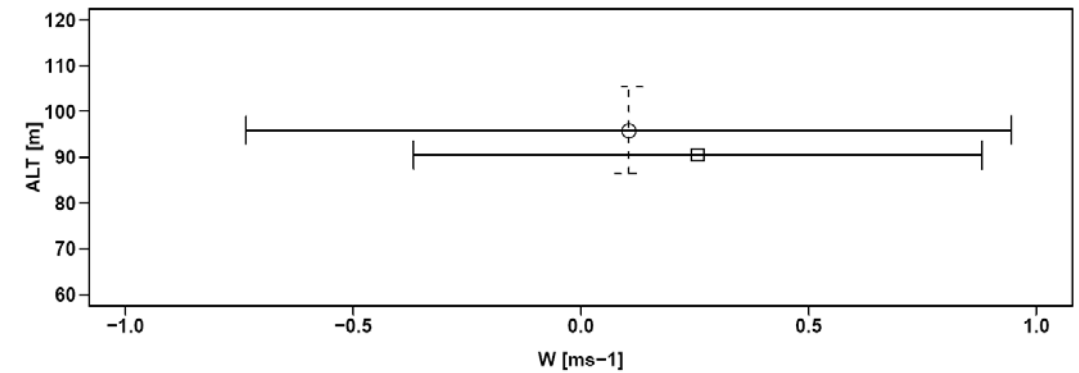
free atmosphere: final wind uncertainty

- 20 flights in cardinal directions
- horizontal wind components
 - $\sigma_{UV} = 0.24 \pm 0.12 \text{ ms}^{-1}$
 - $\sigma_W = 0.08 \pm 0.05 \text{ ms}^{-1}$
- vertical wind
 - independent from TAS
 - $W = 0.02 \pm 0.19 \text{ ms}^{-1}$

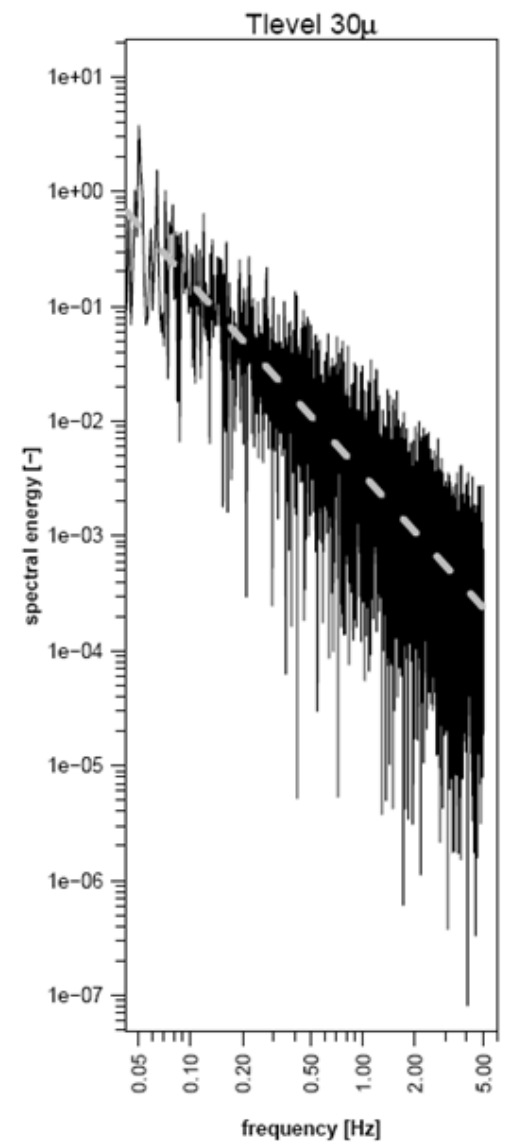
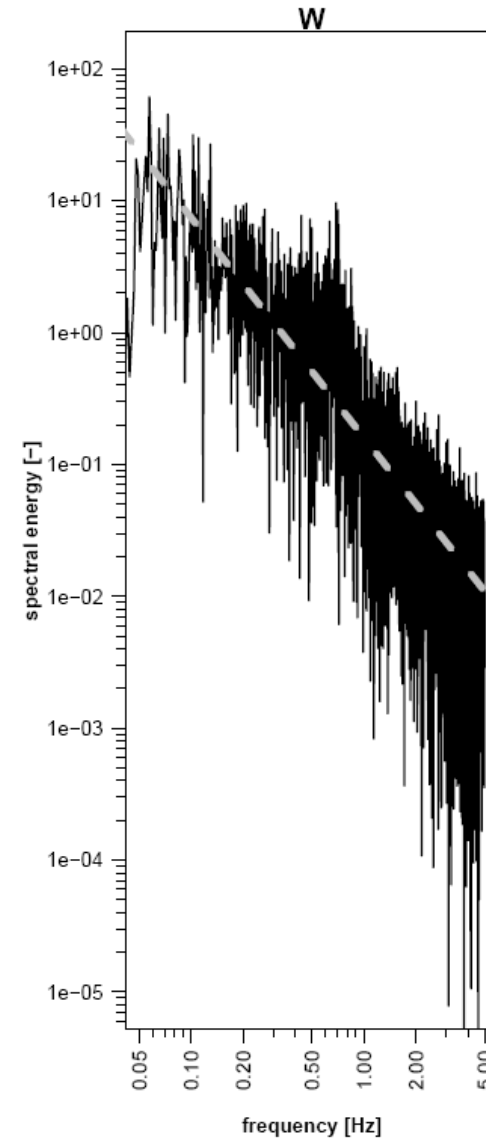
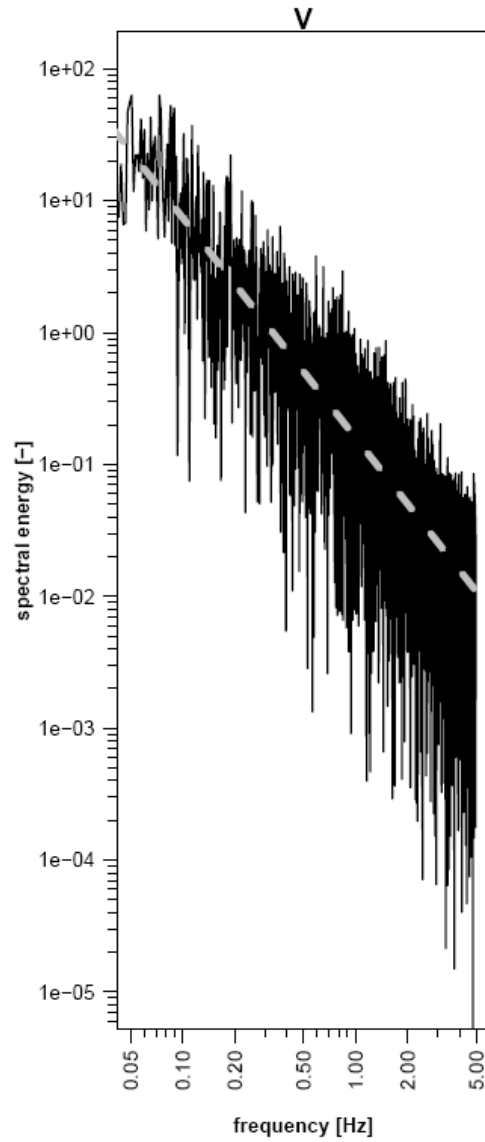
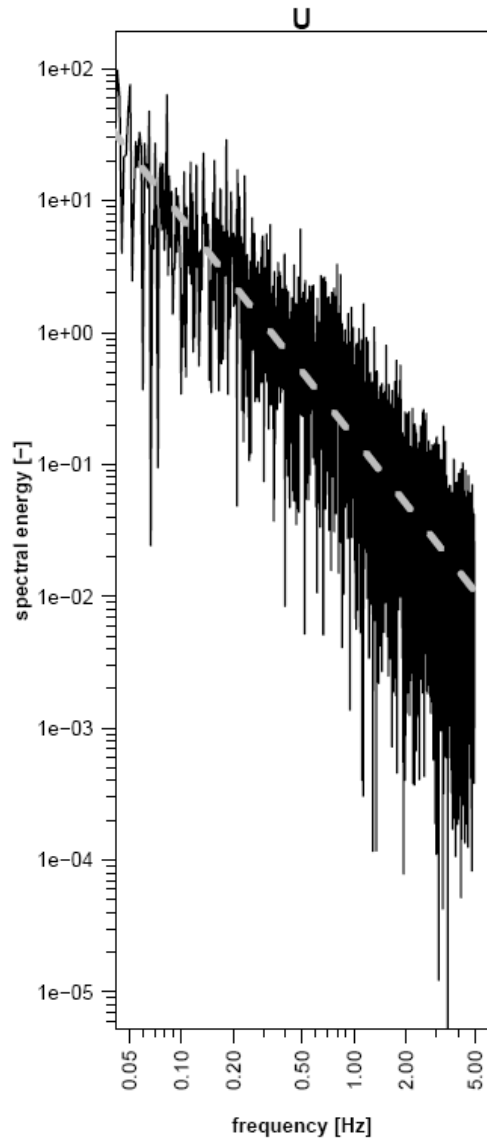


surface layer: ground truth DWD Lindenberg

- aircraft (o) compared to
 - SODAR (Δ)
 - tower sonic (\square)
 - tower cup and vain (\blacksquare)
- vertical wind
 - within 0.2 ms^{-1}
- horizontal wind
 - SODAR and tower sonic ambiguous
 - aircraft well centered

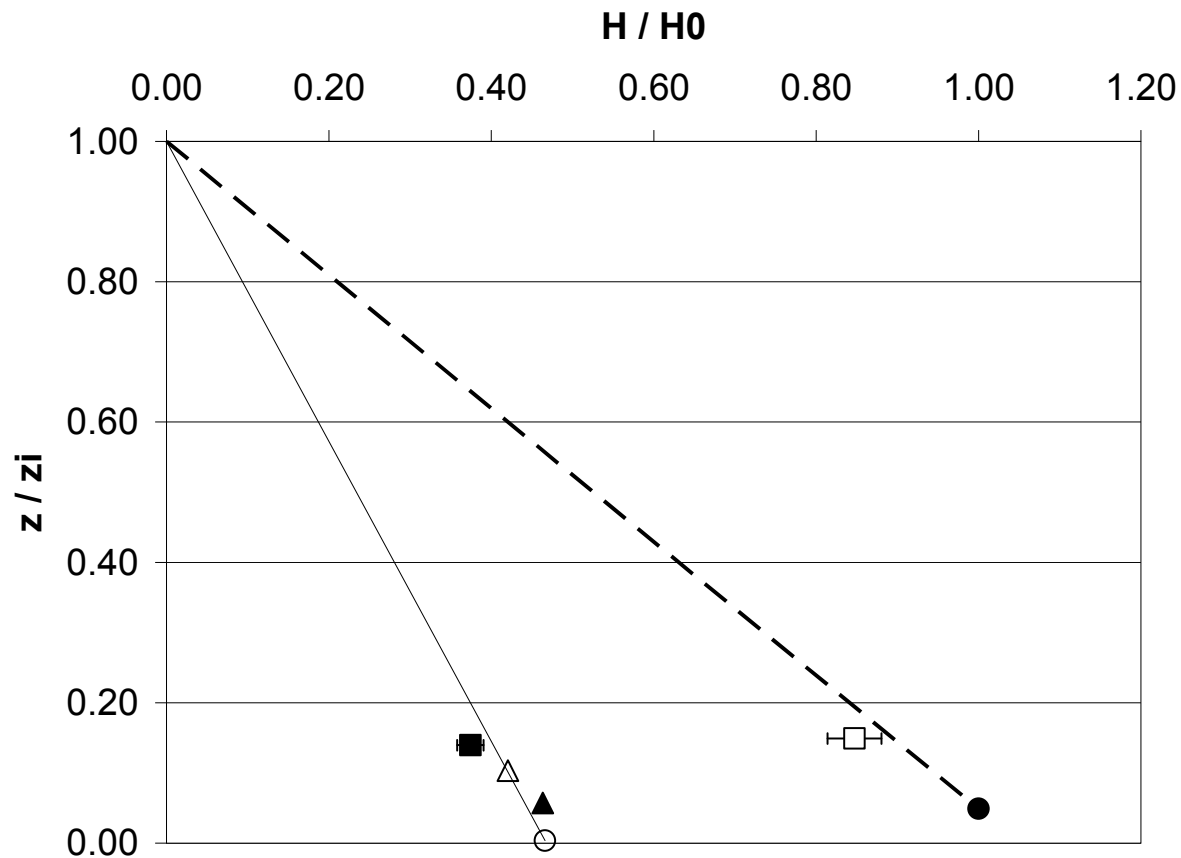


frequency response



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sensible heat: LAS comparison DWD Lindenberg



- PBL 875 m
- H_0 45 Wm^{-2}

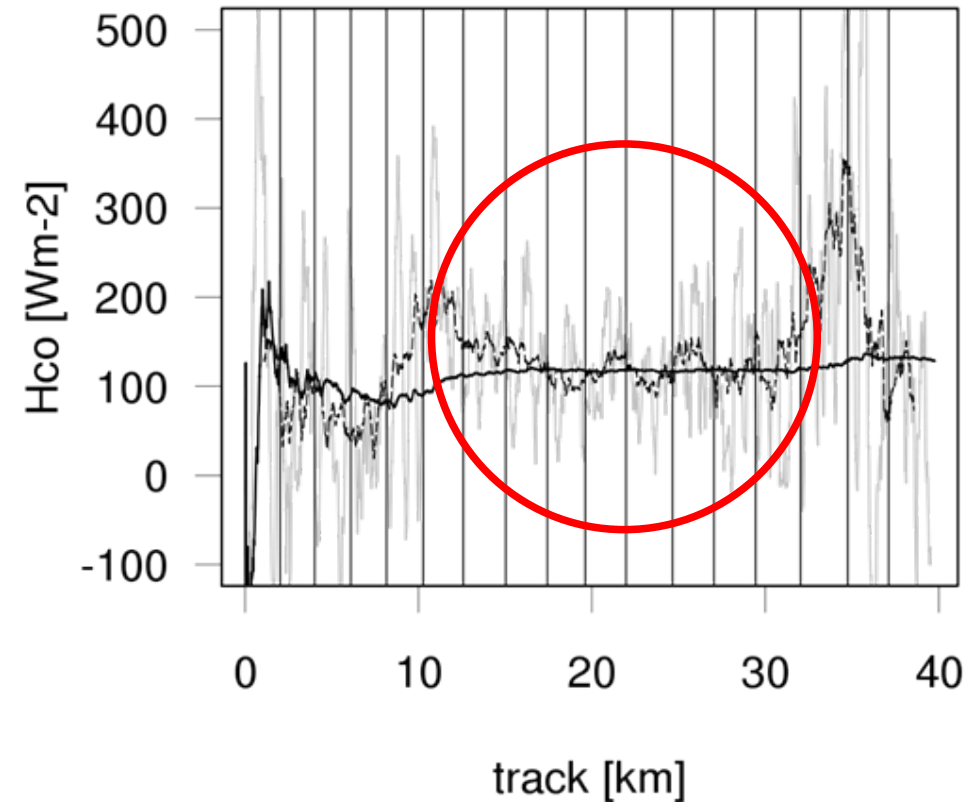
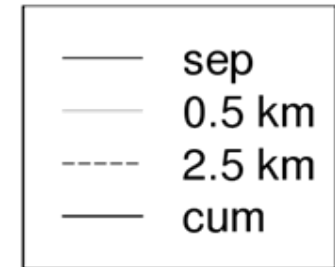
- M-IFU leg 2
- M-IFU leg las
- scintillometer
- eddy 3m
- ▲ eddy 50m
- △ eddy 90m

- propagation of wind measurement uncertainties
 - 4.3% for leg las (4.7 km)
 - 3.9% for leg 2 (20 km)



spatial resolution: landuse change Inner Mongolia

- altitude < 50 m
- 2 km legs, 1 km inhomogeneity
- resolved during stationary condition



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