

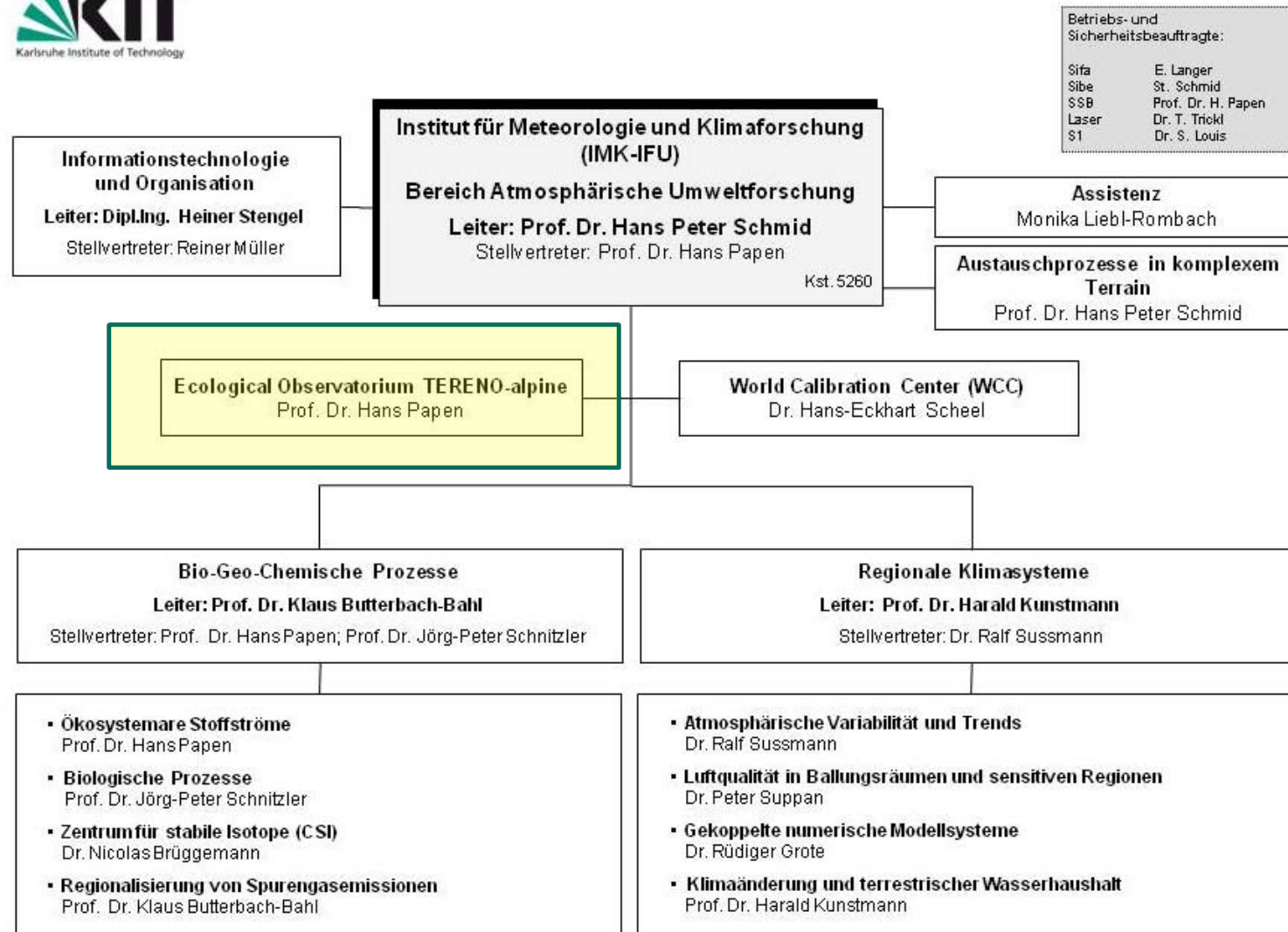
Remote sensing of mixing-layer height at ICOS and TERENO stations

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IMK-IFU

and its activities in TERENO





- 58 employees
 - 35 scientists
 - 12 engineers and technicians
 - 11 staff
- 21 PhD/Diploma students
(Italy, China, Australia, etc.)
- 5 postdoc / guests
- 7 interns, etc.

91 persons in total

IMK-IFU „Highlights“

New greenhouse (06.10.2009)



TERENO

TERRESTRIAL ENVIRONMENTAL OBSERVATORIES

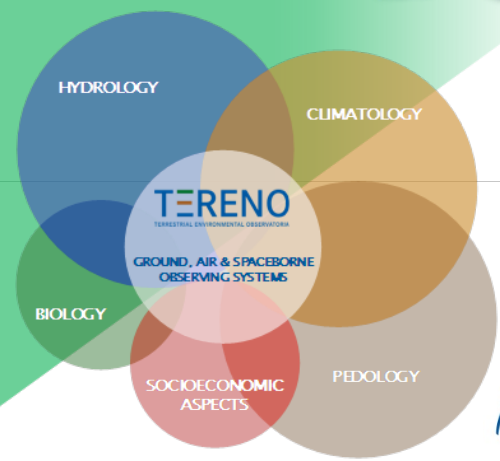
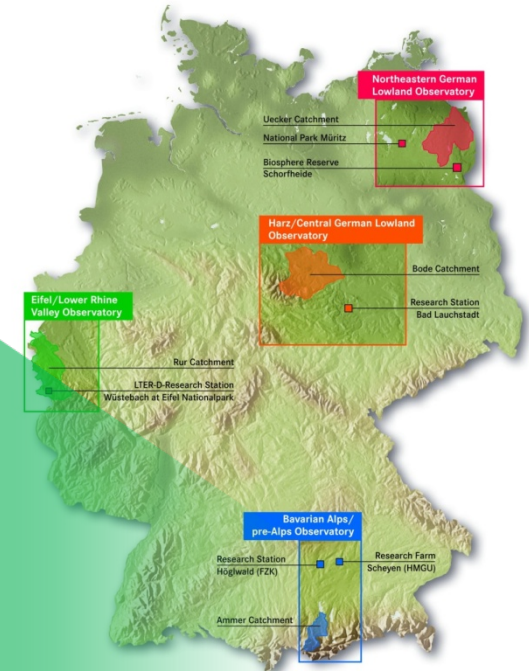
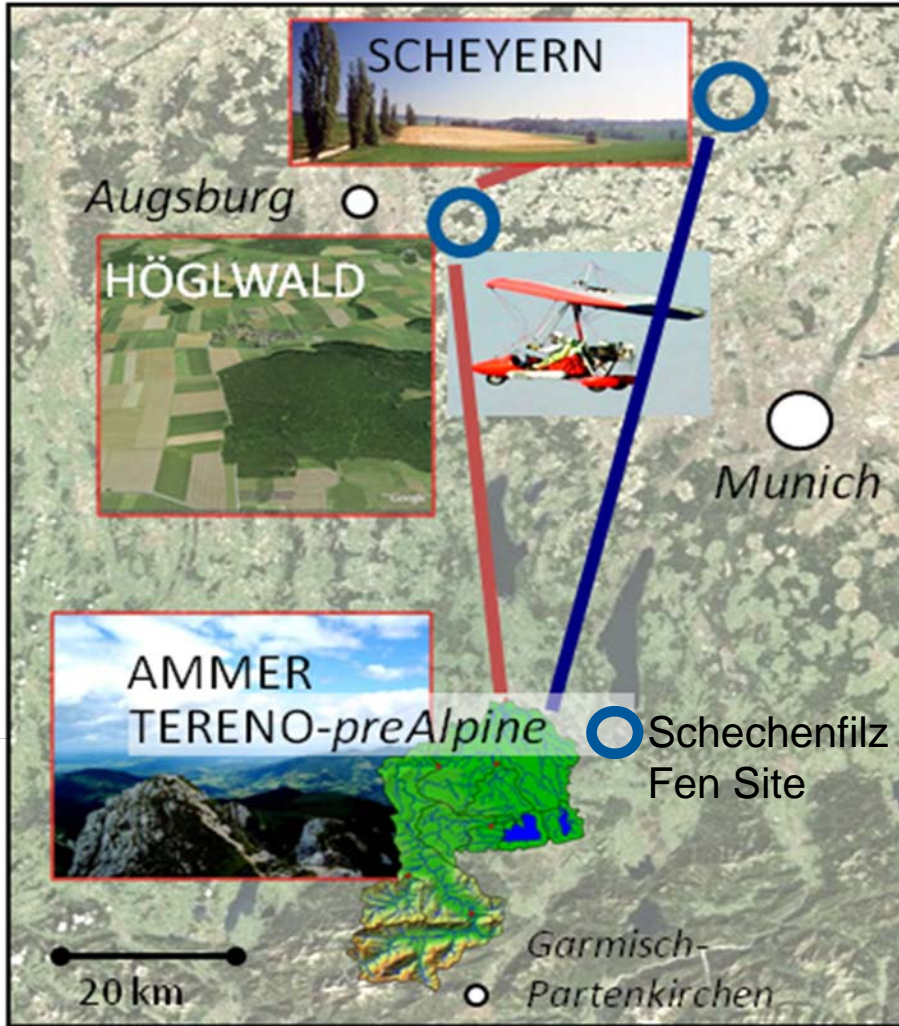
The Bavarian Prealpine Observatory

Hans Peter Schmid, Harald Kunstmann,
Hans Papen, Jean Charles Munch,
Eckart Priesack





The Bavarian Prealpine Observatory



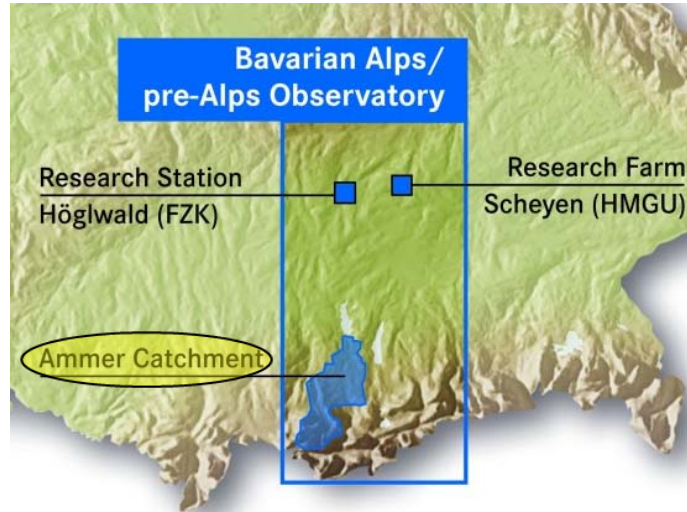


“In House” Research Goals

- Long-Term **biosphere-atmosphere exchange** (greenhouse gases, energy balance)
- Coupled **C-/N-cycles** and C-/N-storage
- **Vegetation and microbial biodiversity** (temporal dynamics, relation to matter turnover)
- **Alpine watershed hydrology** (water budget, Karst related problems, precipitation variability, floods/droughts, seepage water quality/quantity, water retention capacity)
- **Nutrient deposition** and **land use/management** (wet grasslands/fens, forests and agricultural systems).
- **Methodology development** for micrometeorological observations in complex terrain



Ammer Catchment Observatory



- area of ~710 km² (601 km² above Weilheim)
- alpine and prealpine landscape with high spatial differentiation in geology and pedology
- elevations: from 533 m (a.s.l., Ammersee) to 2185 m (Kreuzspitze)
- two dominant landscape units: the prealpine hill country and moorland and the Swabian-Upper Bavarian foothills of the Alps.
- Dominant geology: lime-alpine zone (south), flysch zone (north)

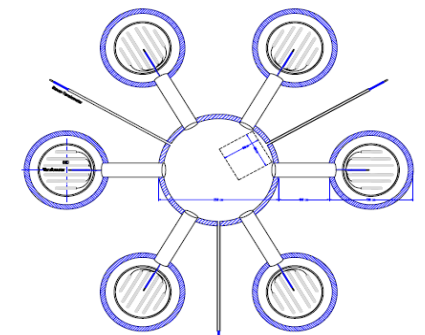
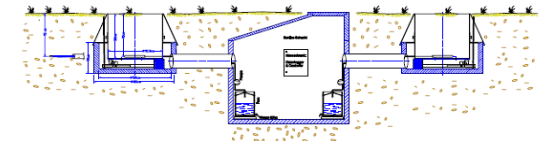
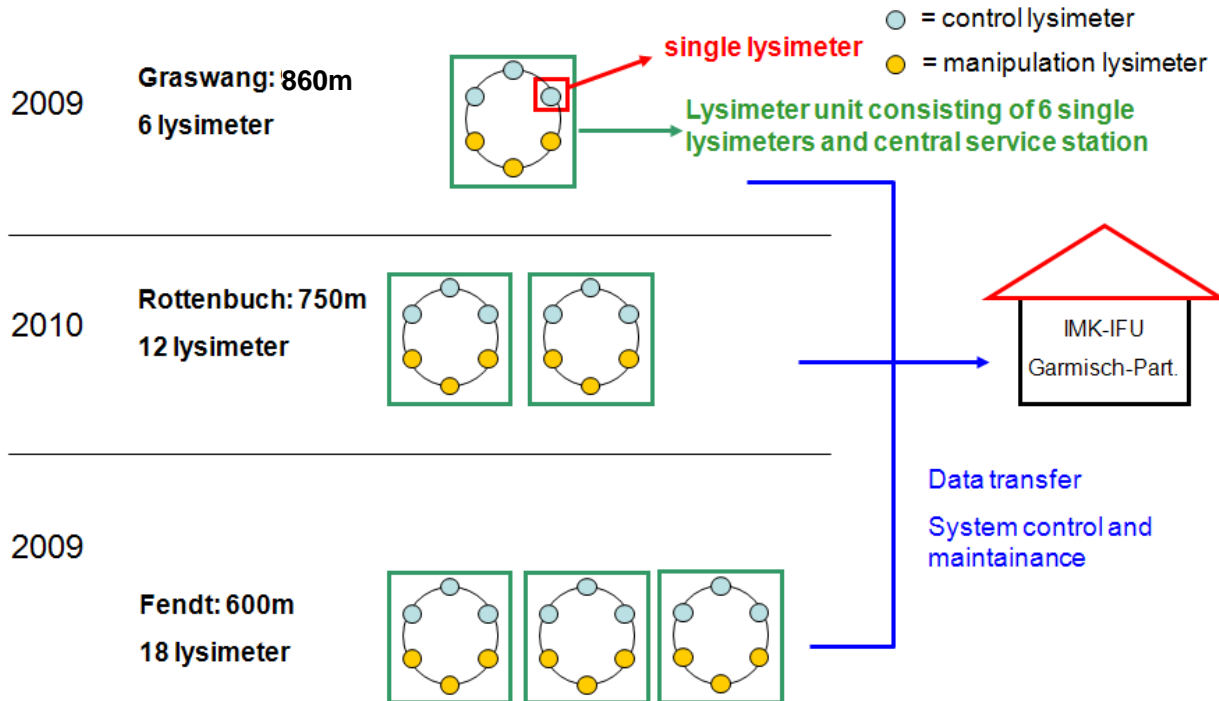
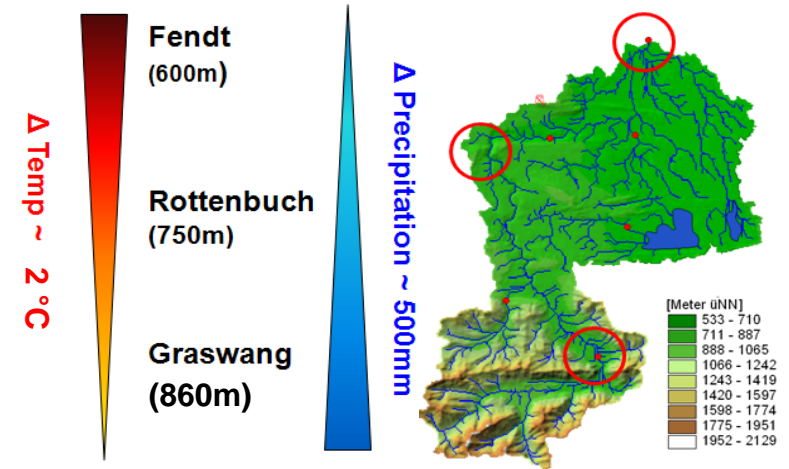
TERENO Infrastructure

- **Graswang-, Rottenbuch-, Fendt Sites**
 - 3 EC towers: momentum, heat, H₂O, CO₂, plus TERENO-ICOS: N₂O, CH₄ fluxes
 - 36 Lysimeters: soil water balance,
 - GHG (N₂O, CO₂, CH₄) measurements at lysimeters
- **Geigersau Site:** 1 X-Band precipitation radar
- **Sites to be determined:** 3 Climate stations



Climasequence: how do grassland ecosystems adapt to climate change?

- grassland soil monoliths transplanted along the natural gradient in temperature and precipitation
- climate change effects on C/N cycles
- associated plant and microbial processes/populations/biodiversity
- terrestrial hydrology and water quality





TERENO Lysimeter experiment: construction phase



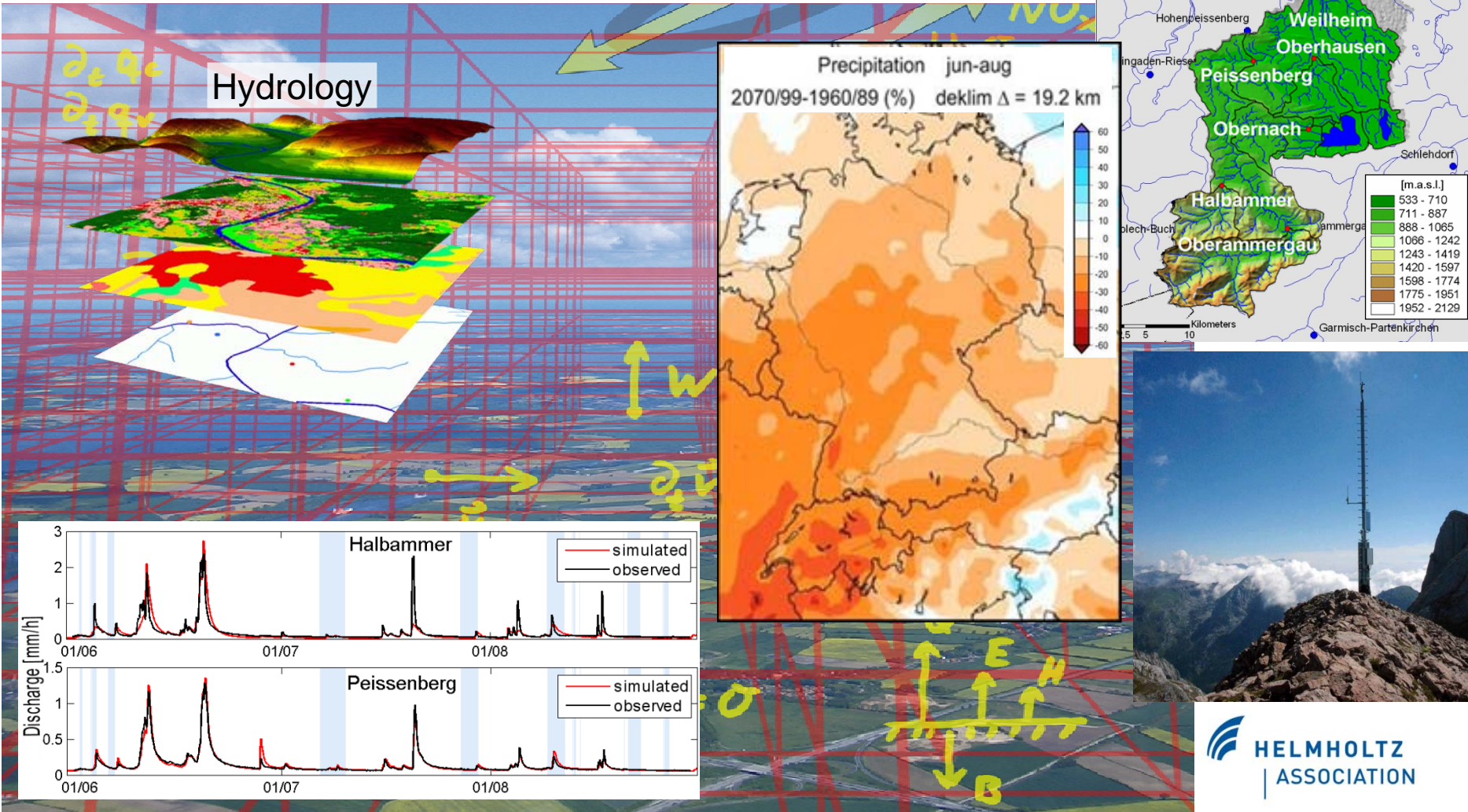


TERENO rain RADAR Geigersau



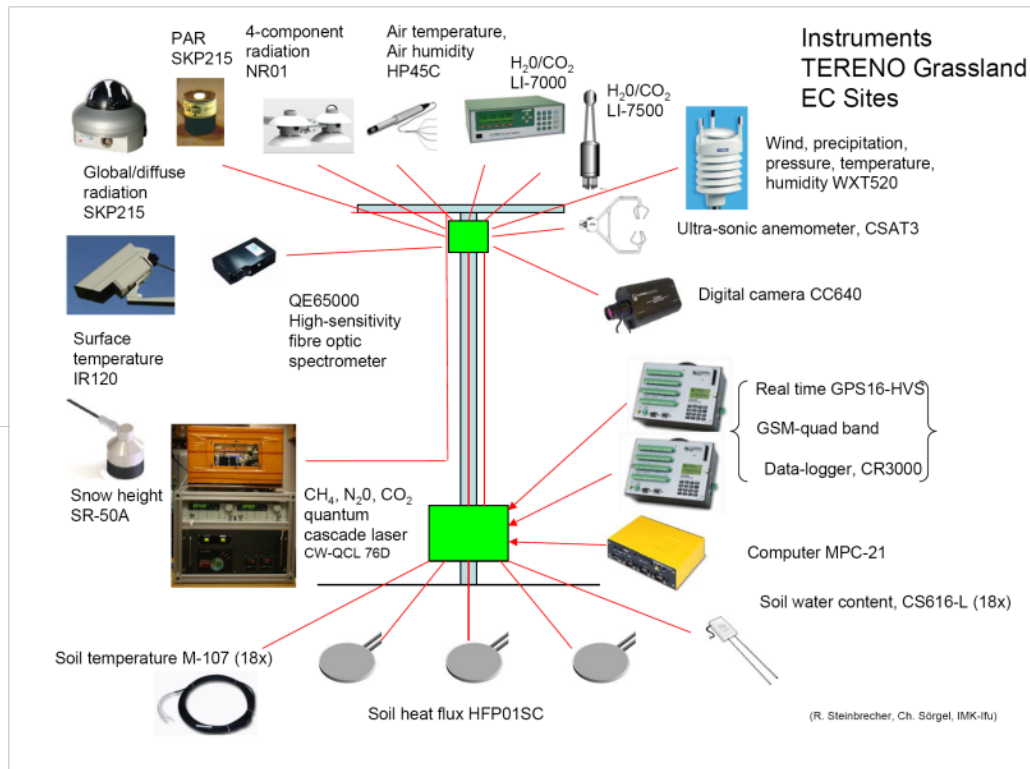


Observations and Meso-Scale Modelling of Alpine Watershed Hydrology





- ICOS mission: “To provide the long-term observations required to understand the present state and predict future behavior of the global carbon cycle and greenhouse gas emissions.”
- 5 EC-sites at TERENO-prealpine, -Harz, and –Eifel received additional funding to expand instrumentation to include fluxes of CH₄ and N₂O and upgrade to ICOS standard

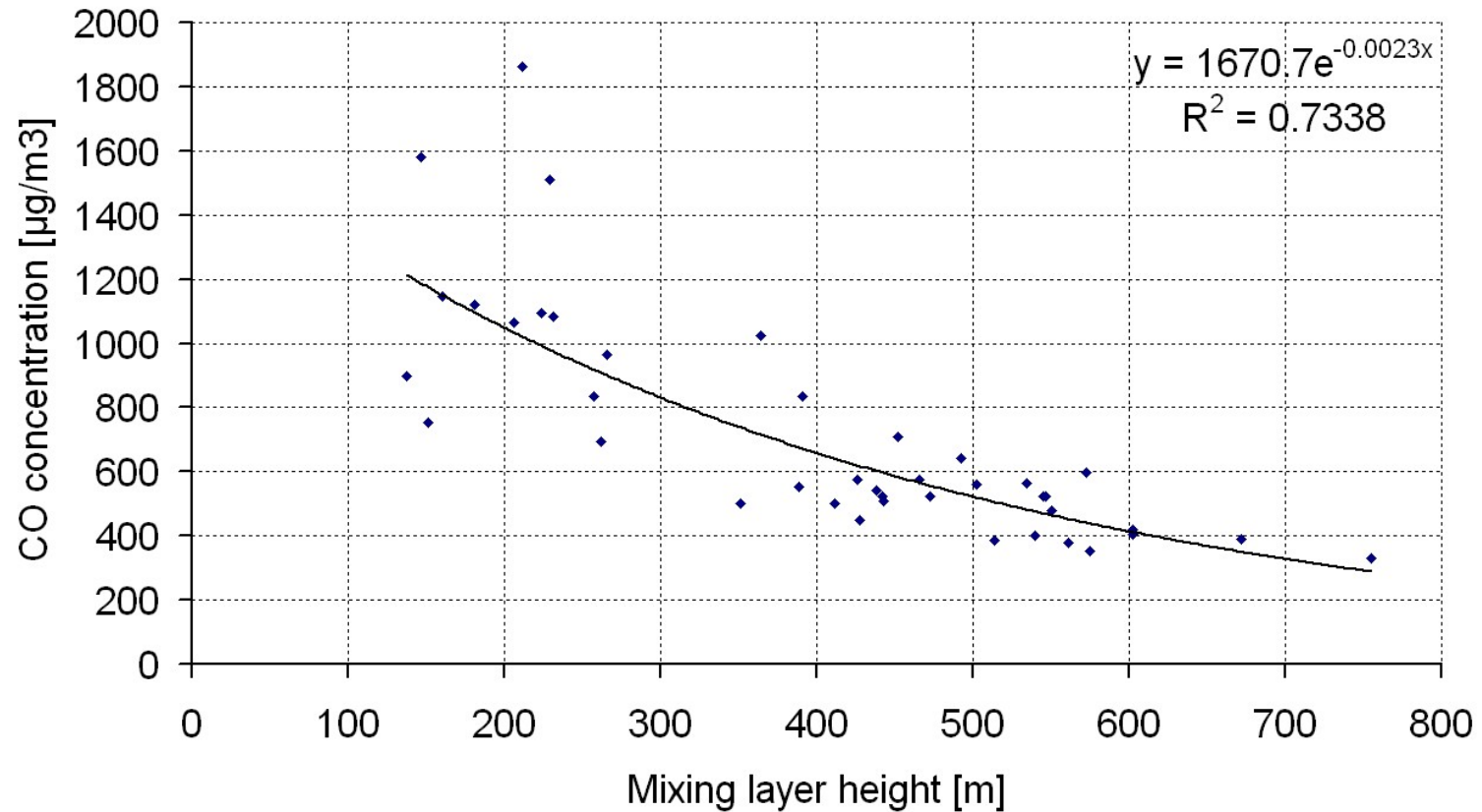


Remote sensing

of the vertical structure of the atmospheric boundary layer

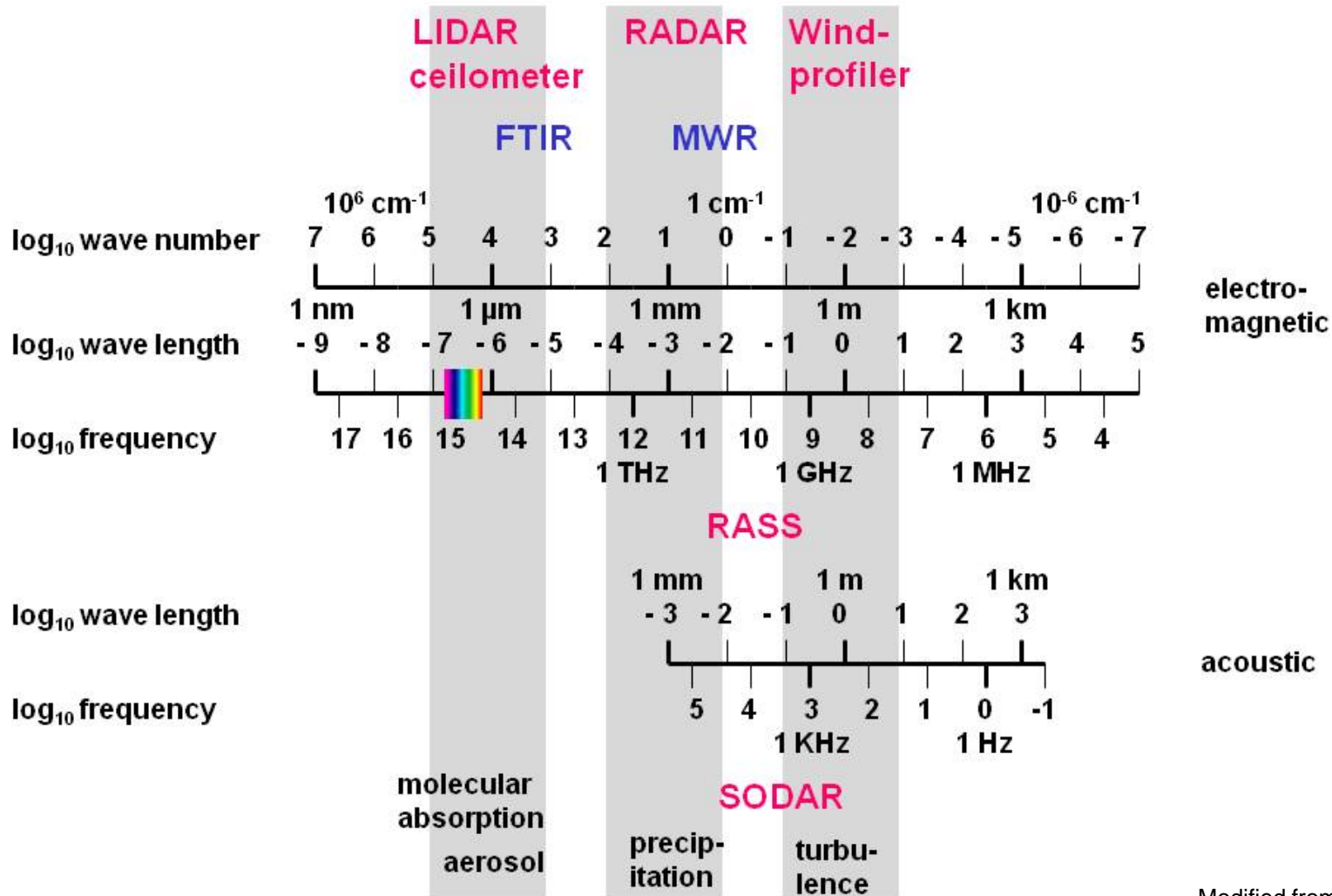
Motivation

correlation at street level pollutant - MLH



Schäfer, K., S. Emeis, H. Hoffmann, C. Jahn, 2006: Influence of mixing layer height upon air pollution in urban and sub-urban areas. Meteorol. Z., 15, 647-658.

Typical frequency bands for remote sensing of the atmosphere



Modified from Fig. 8.1 in „
Meteorologie in Stichworten“,
Borntraeger, Berlin Stuttgart 2000

Basic remote sensing techniques

name	principle	spatial resolution	direction	type
RADAR	backscatter, electro-magnetic pulses, fixed wave length	profiling	scanning, slanted	active, monostatic
SODAR	backscatter, acoustic pulses, fixed wave length	profiling	fixed, slanted, vertical	active, usually monostatic
LIDAR	backscatter, optical pulses, fixed wave length(s)	profiling	scanning, fixed, horizontal, slanted, vertical	active, monostatic
RASS	backscatter, acoustic, electro-magnetic, fixed wave length	profiling	fixed, vertical	active, monostatic
	absorption, infrared, spectrum	path-averaging	fixed, horizontal, slanted	active, bistatic or passive
FTIR	emission, infrared, spectrum	path-averaging	fixed, horizontal, slanted	passive
DOAS	absorption, optical, fixed wave lengths	path-averaging	fixed, horizontal	active, bistatic
radiometry	electro-magnetic, fixed wave length(s)	averaging, profiling	fixed, scanning, slanted, vertical	passive
tomography	travel time, acoustic, fixed wave length	horizontal distribution	fixed, horizontal	active, multiple emitters and receivers

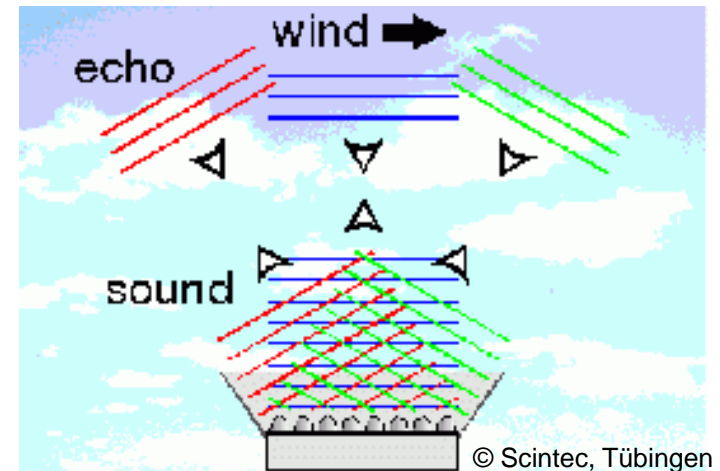
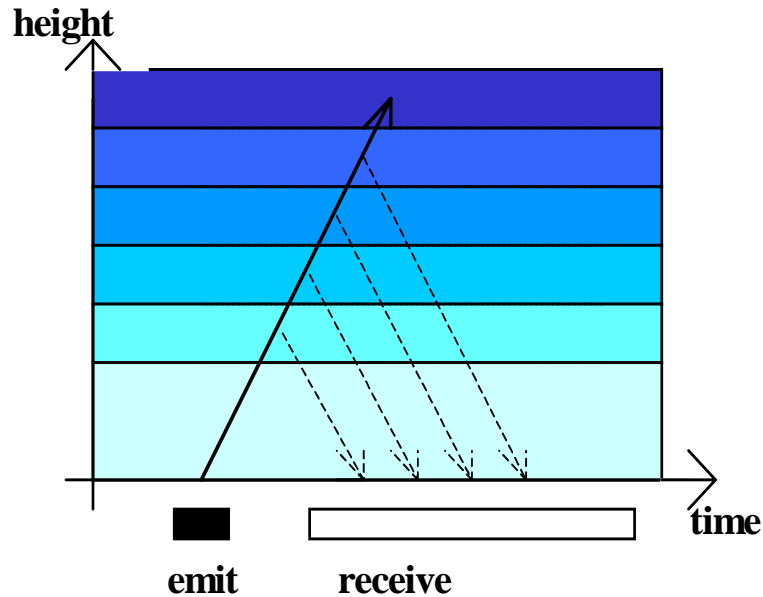
subject of this talk

subject of this talk

SODAR

algorithms for mixing-layer height

monostatic SODAR: measuring principles



deduction:

sound travel time	=	height
backscatter intensity	=	turbulence
Doppler-shift	=	wind speed

Emission of sound waves
into three directions:

in order to measure all three
components of the wind
(horizontal and vertical)



three-antenna SODAR
range: roughly 1 km



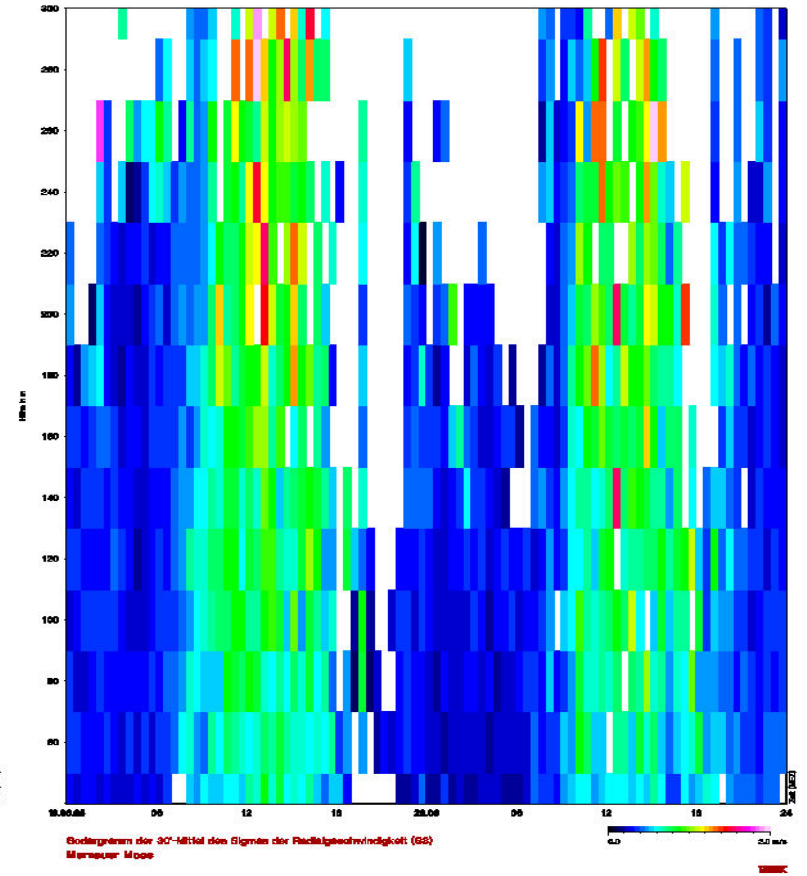
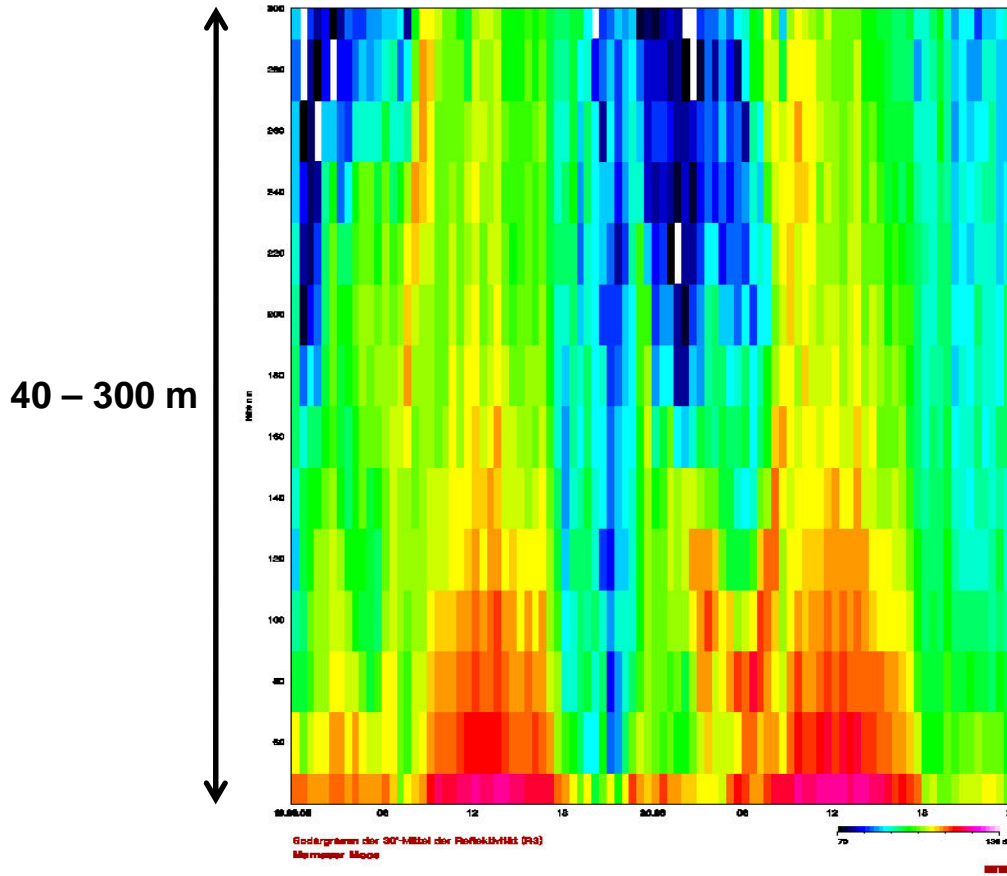
phased-array SODAR
range: roughly 600 m



Sample plot SODAR (convective BL at daytime)

acoustic backscatter intensity

sigma w

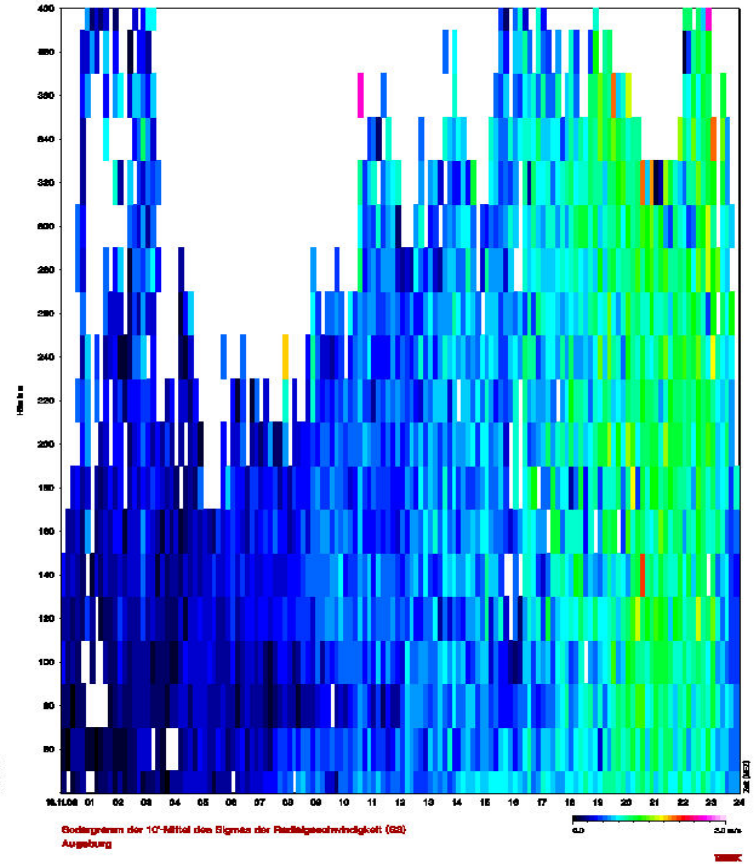
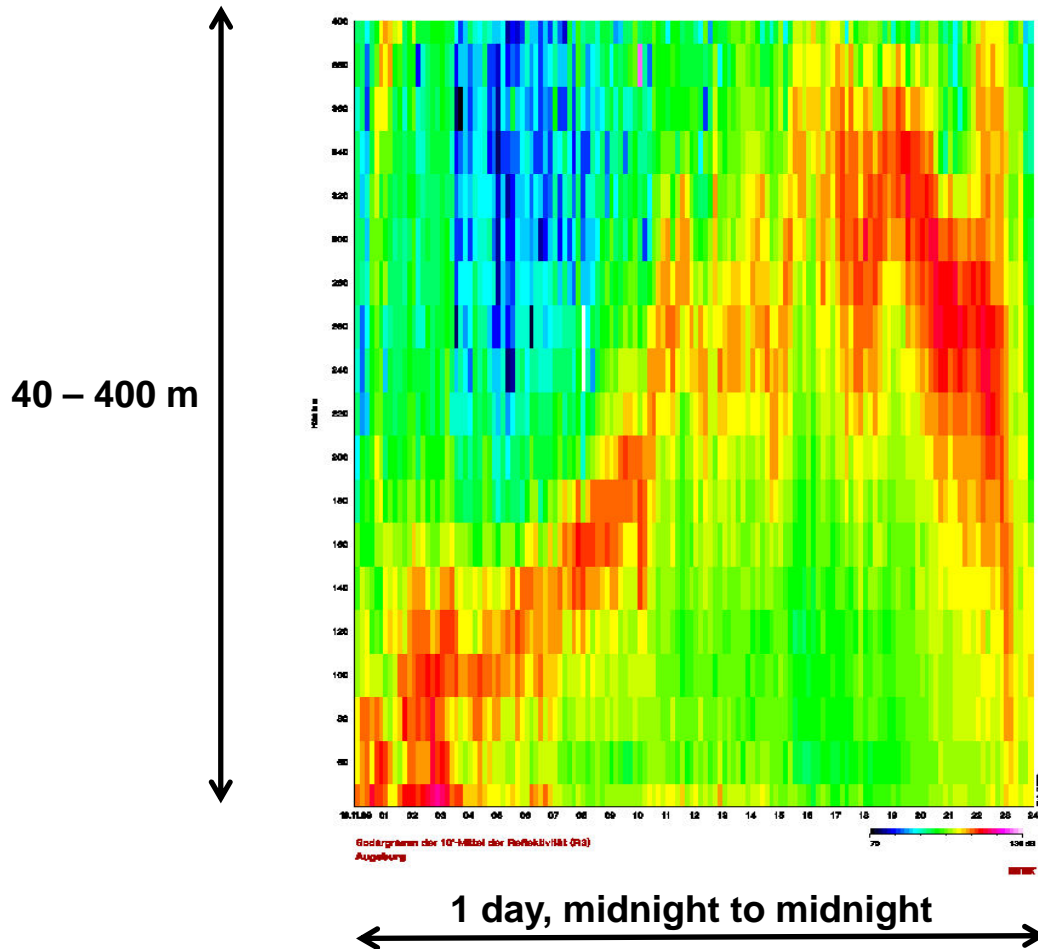


2 days, midnight to midnight

Sample plot SODAR (lifted inversion)

acoustic backscatter intensity

sigma w

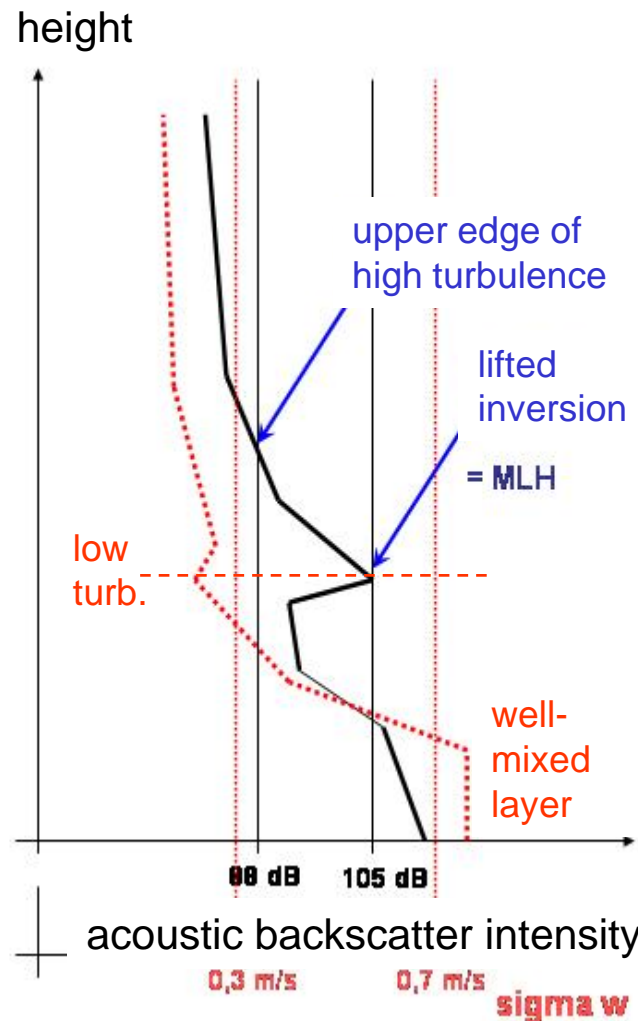


Algorithms to detect MLH from SODAR data

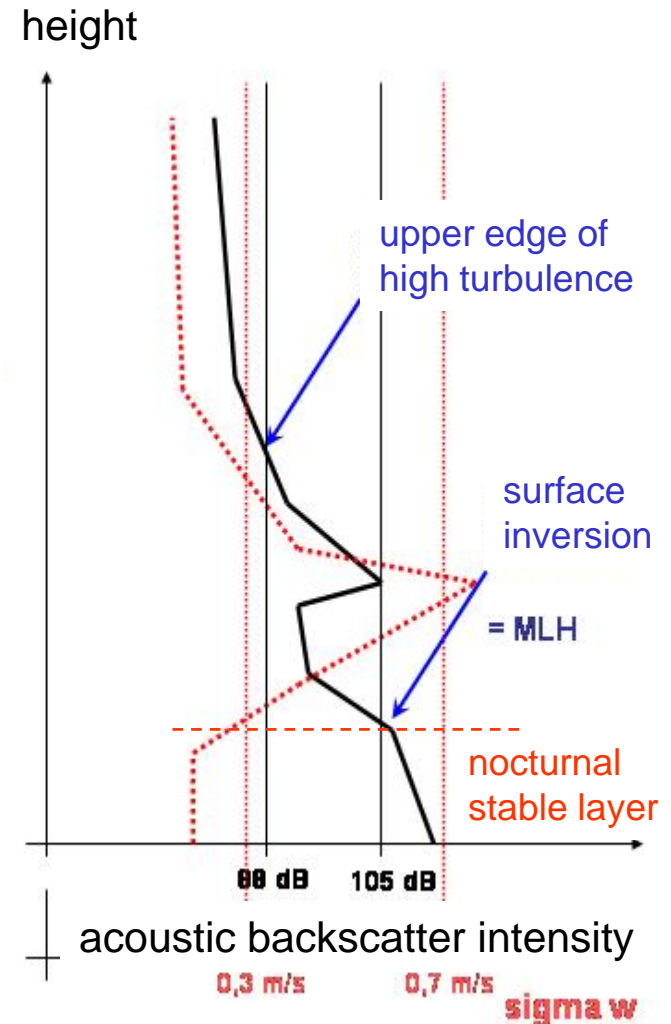
criterion 1:
 upper edge of high turbulence

criterion 2:
 surface and lifted inversions

$MLH = \text{Min}(C1, C2)$



example 1: daytime

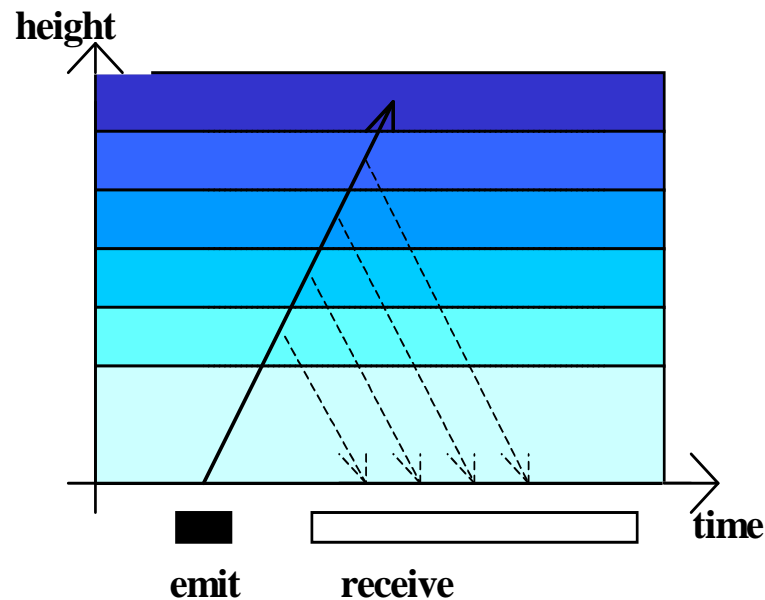


example 2: night-time

Ceilometer

algorithms for mixing-layer height

Ceilometer/LIDAR measuring principle



detection:

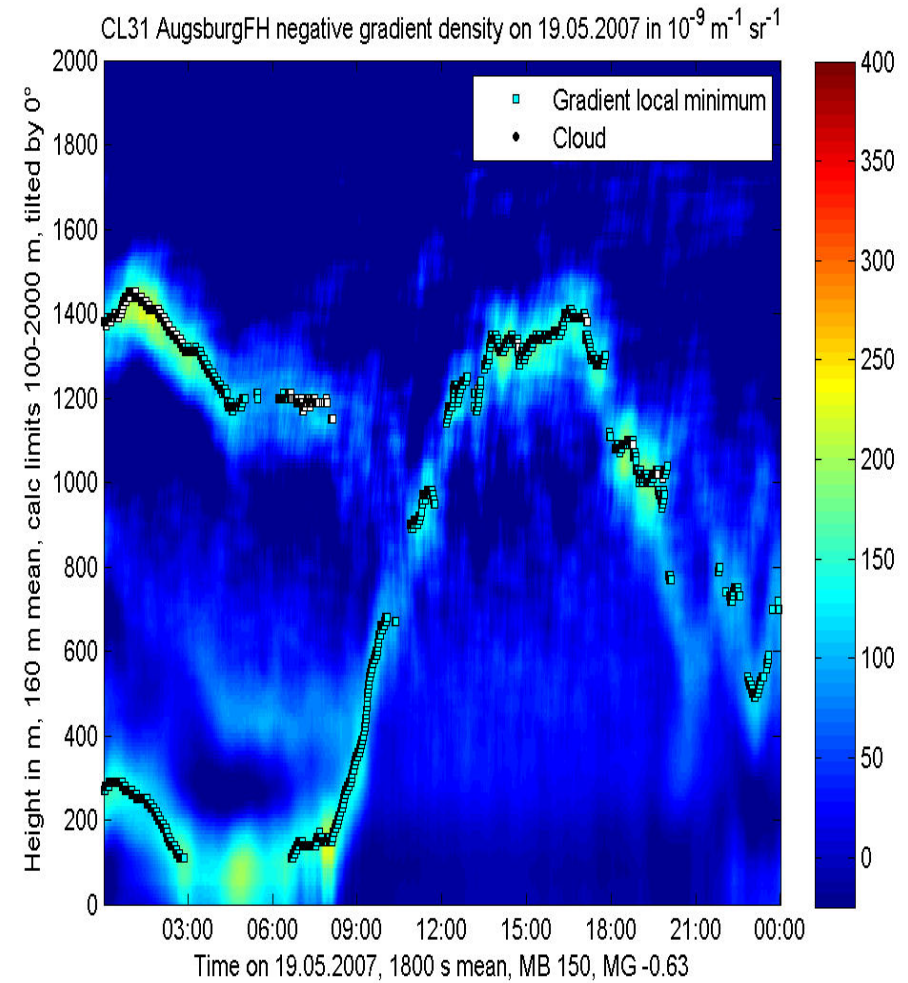
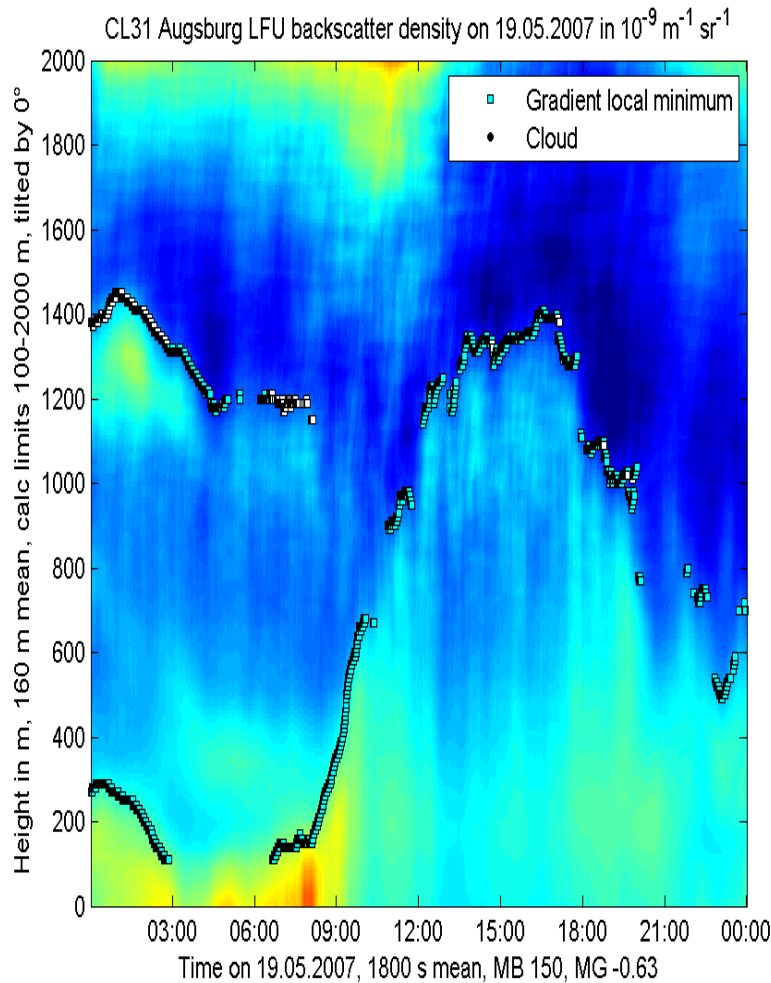
- travel time of signal = height
- backscatter intensity = particle size and number distribution
- Doppler-shift = cannot be analyzed from ceilometer data
(only from Wind-LIDAR: velocity component in line of sight)



Sample plot ceilometer (convective BL at daytime)

optical backscatter intensity

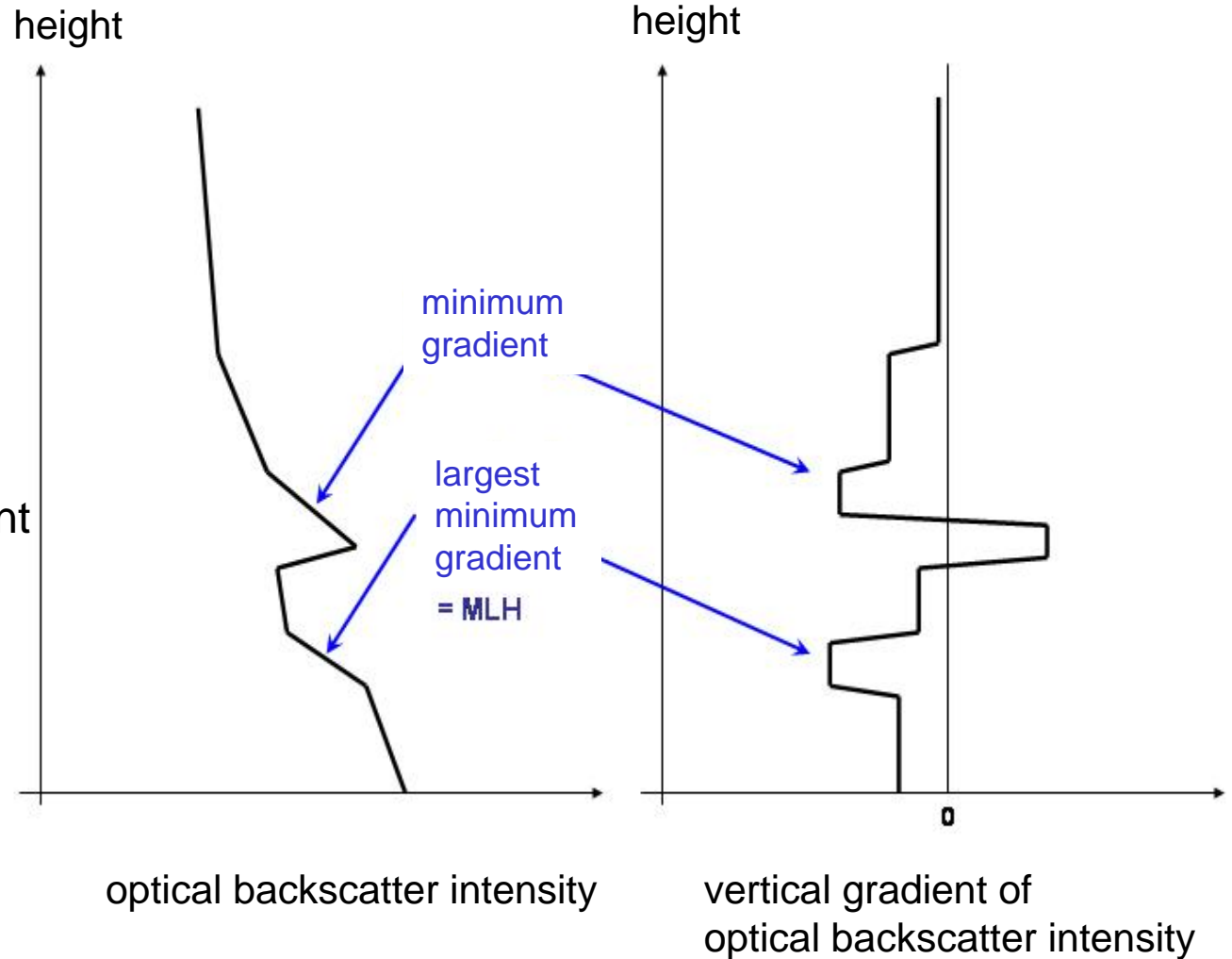
negative vertical gradient of optical backscatter intensity



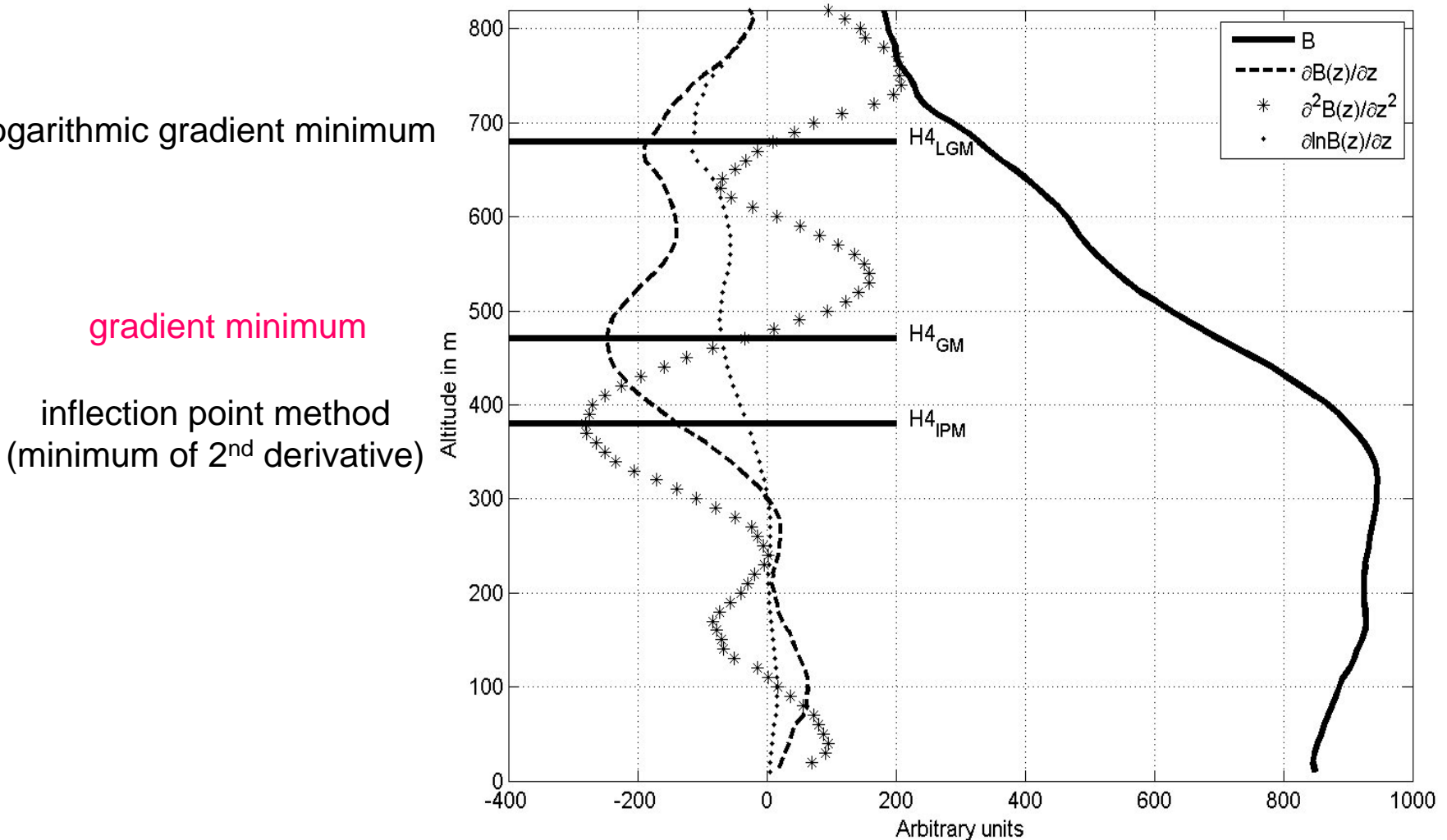
Algorithms to detect MLH from Ceilometer-Daten

criterion

minimal vertical gradient of backscatter intensity (the most negative gradient)



Different gradient methods (see Sicard et al. 2006, BLM 119, 135-157)

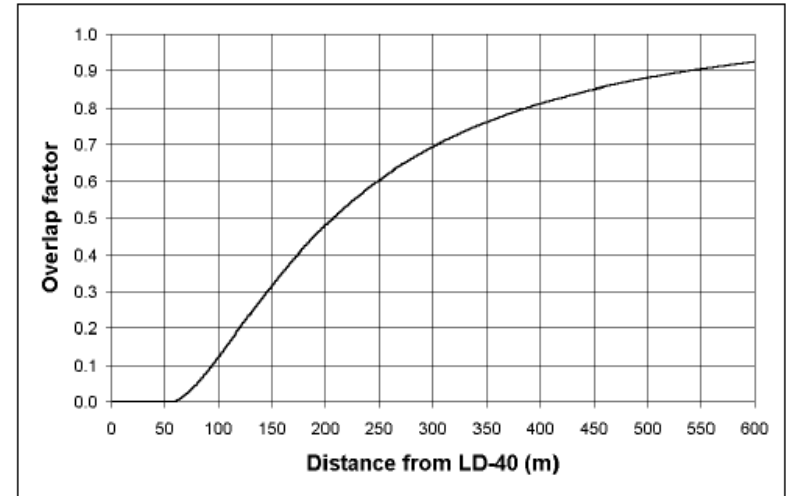
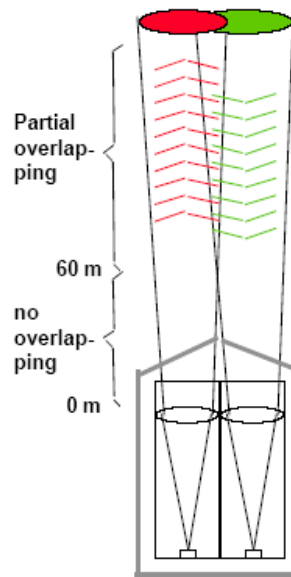


comparison of two different ceilometers

LD40

two optical axes

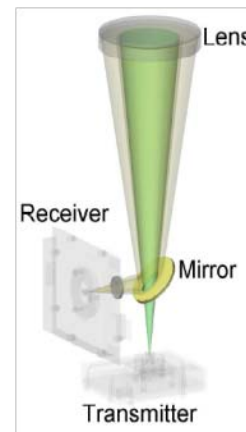
wave length: 855 nm
 height resolution: 7.5 m
 max. range: 13000 m



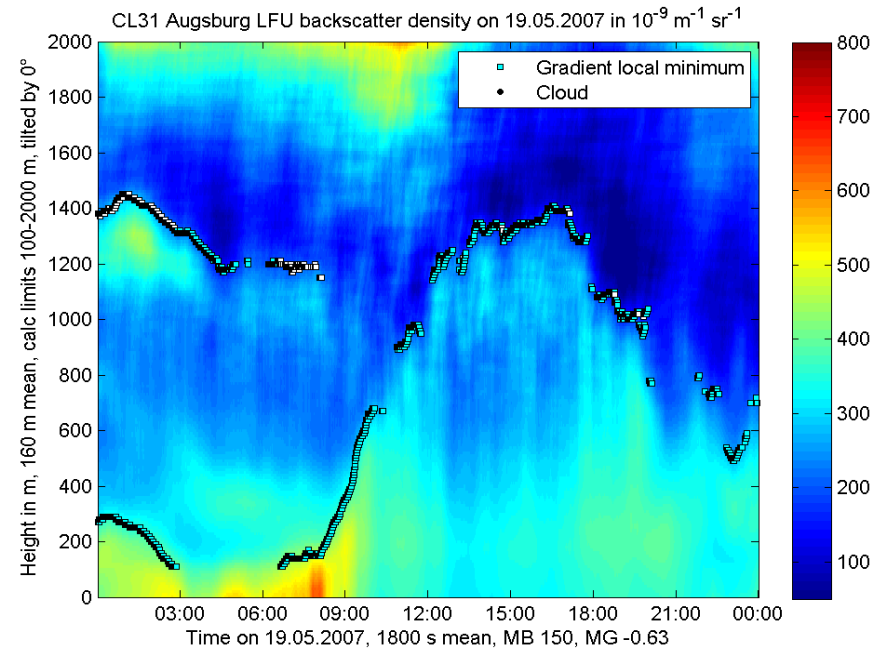
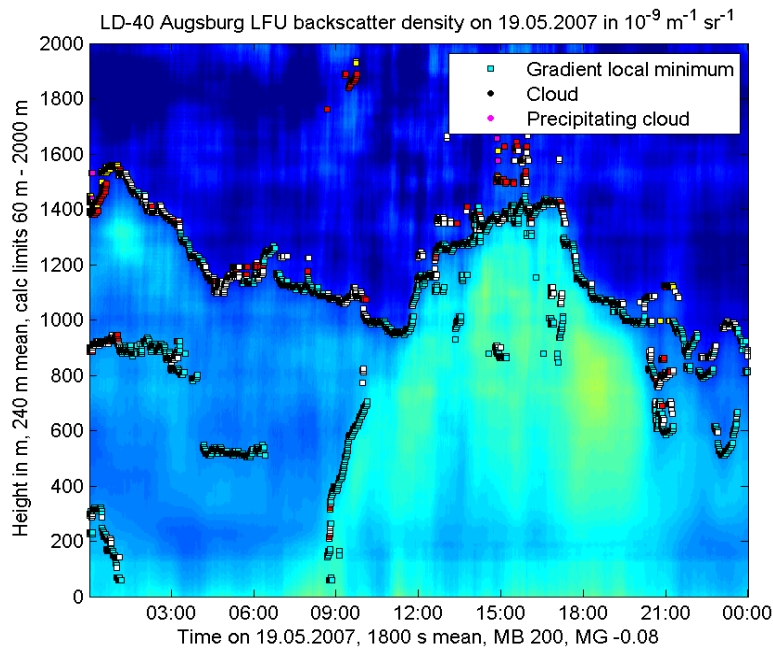
CL31

one optical axis

wave length: 905 nm
 height resolution: 5 m
 max. range: 7500 m



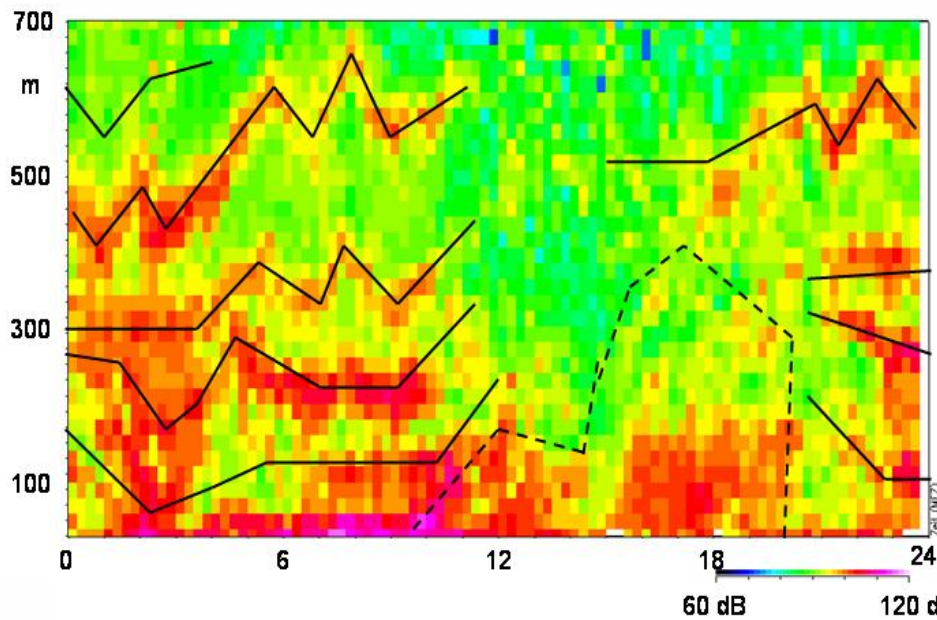
19 May 2007: ceilometer LD40 and CL31



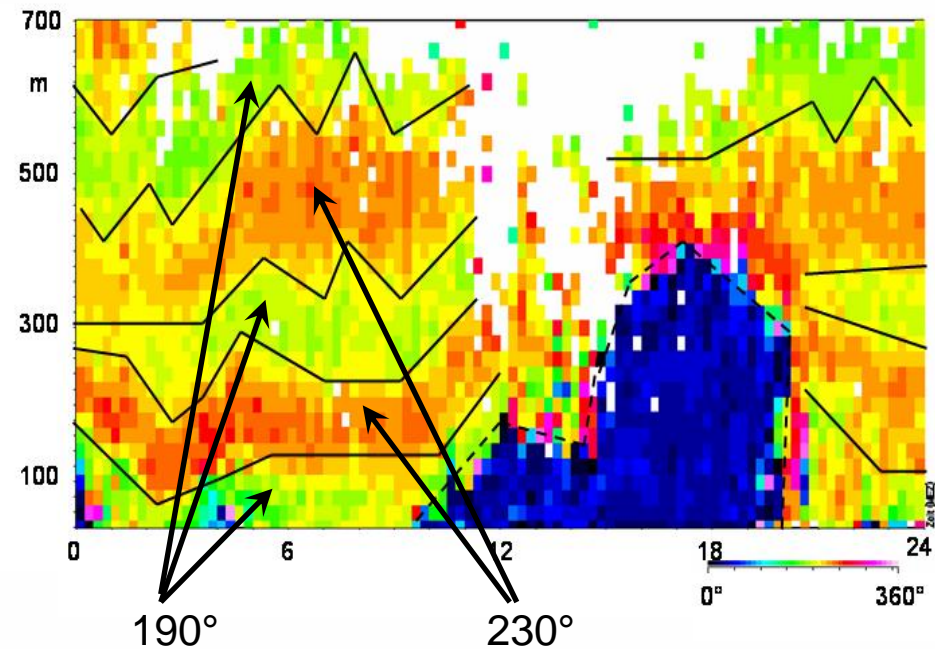
Application examples for SODAR and Ceilometer

SODAR measurements in a wintry Alpine valley

29 January 2006

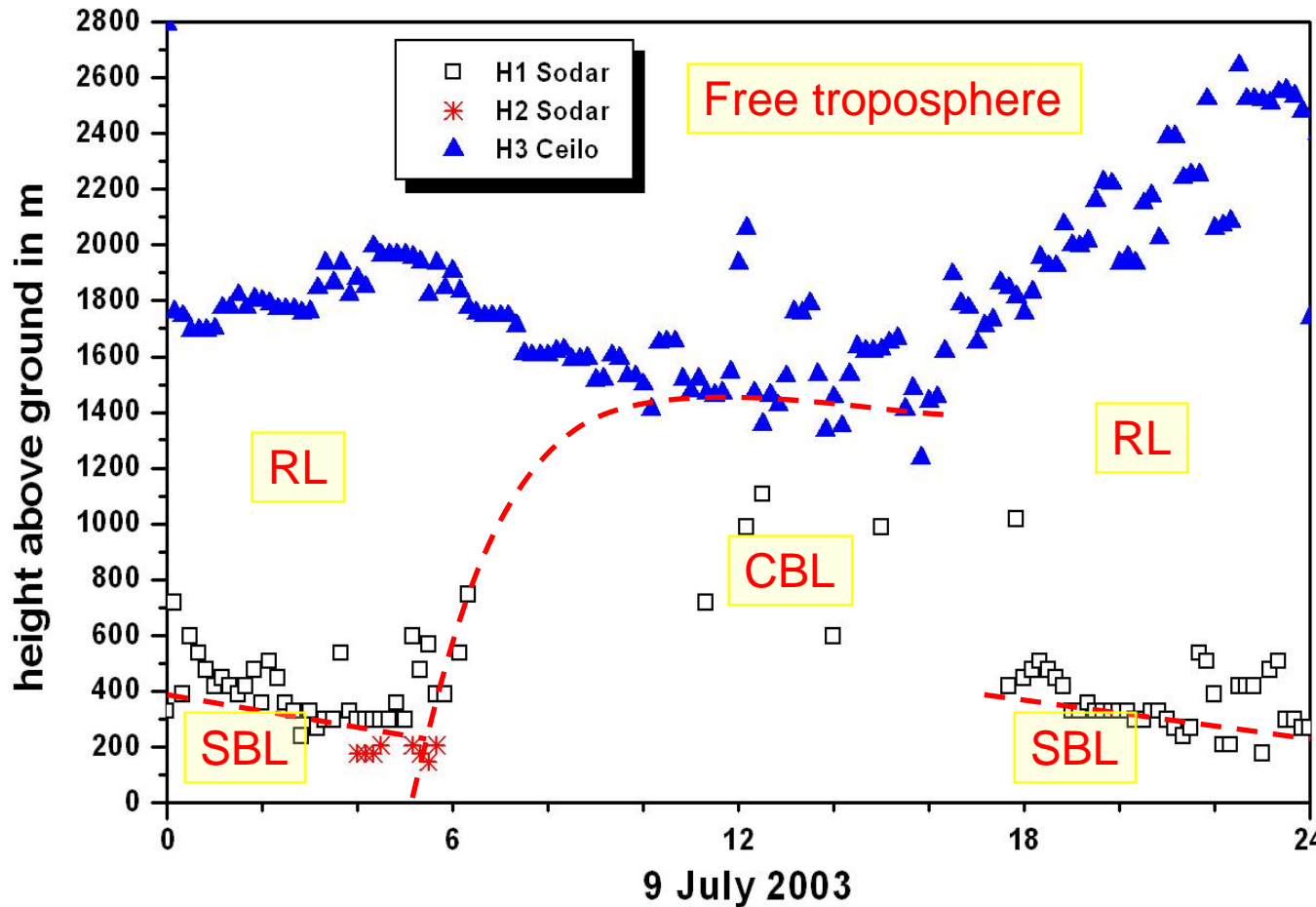


backscatter intensity



wind direction

Diurnal variation of mixing-layer height from SODAR and Ceilometer data (Budapest)



SBL:

stable boundary layer (usually at night and in winter)

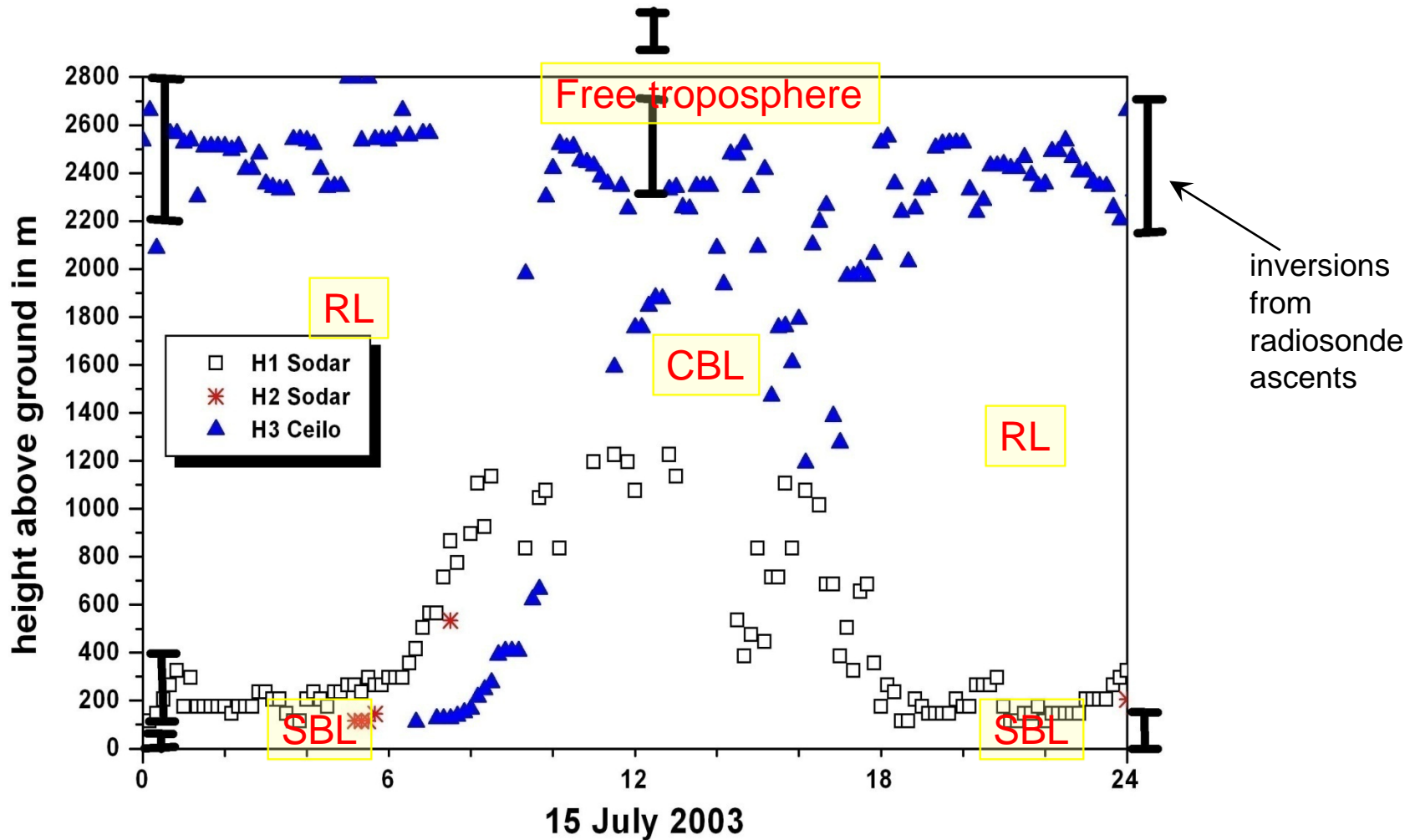
CBL:

convective boundary layer (usually at daytime due to strong insolation)

RL:

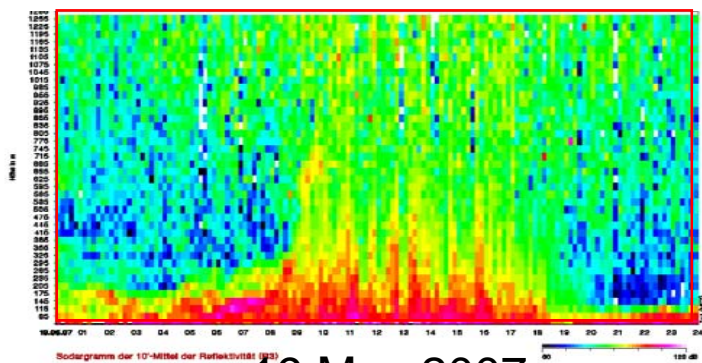
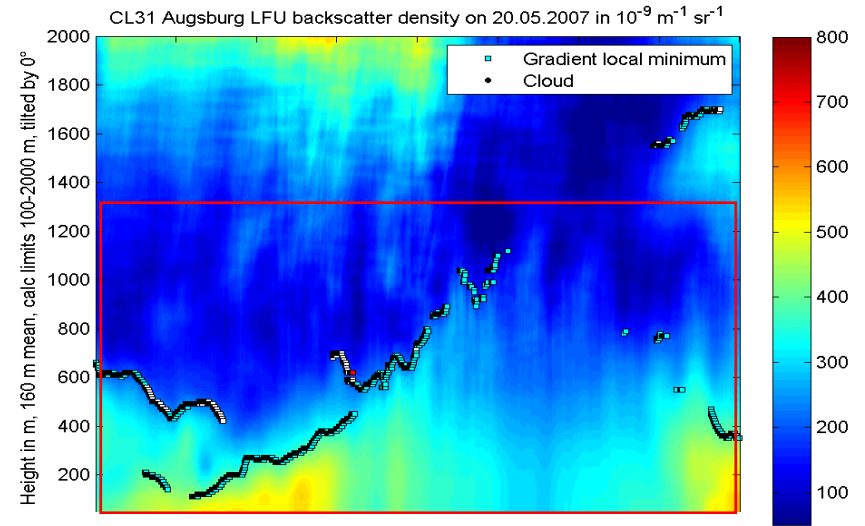
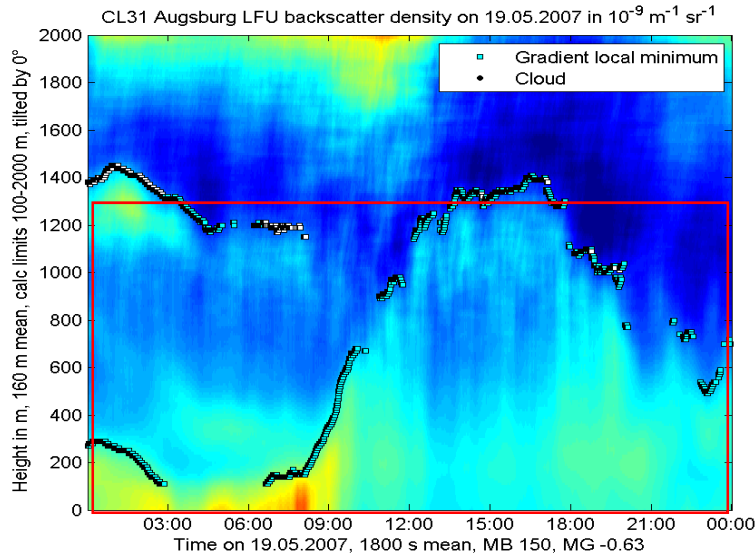
residual layer (usually at night-time)

Simultaneous operation SODAR-Ceilometer: examples for summer days

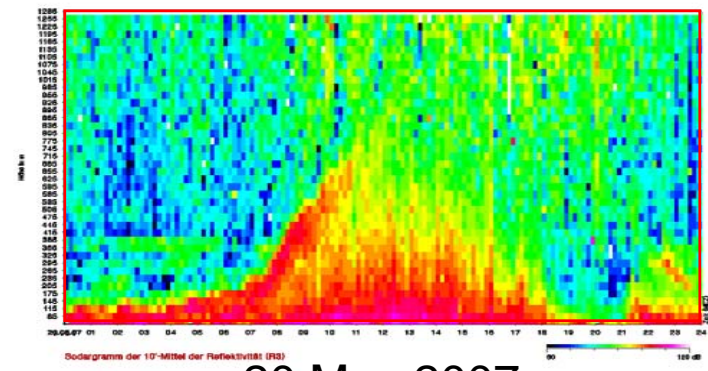


Emeis, S., K. Schäfer, 2006: Remote sensing methods to investigate boundary-layer structures relevant to air pollution in cities. Bound.-Lay Meteorol., 121, 377-385,

comparison of optical (top) and acoustic (below) backscatter intensity

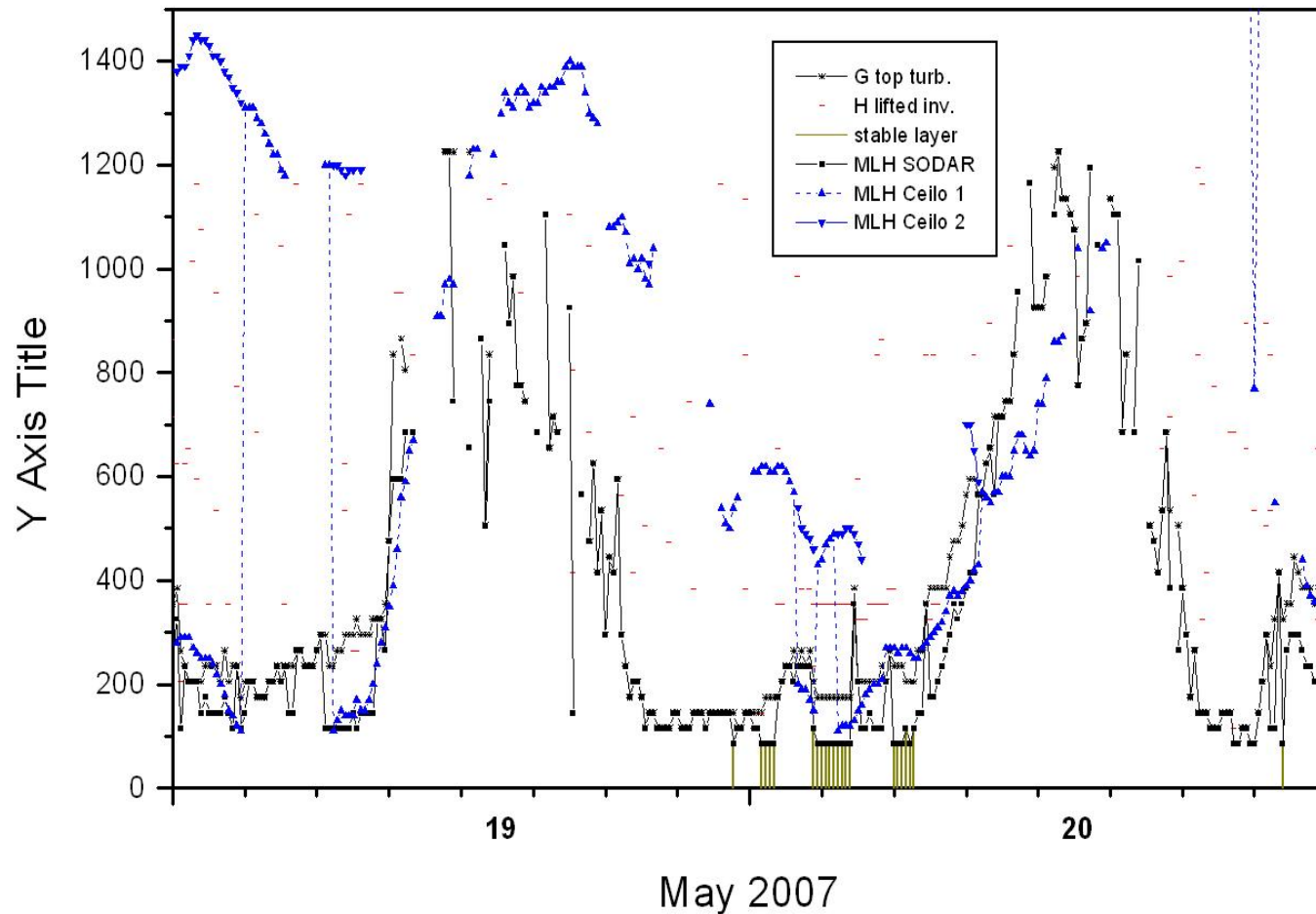


19 May 2007



20 May 2007

comparison of MLH from Sodar and CL31 data



RASS

principles of operation

examples

RASS (radio-acoustic remote sensing)

measures vertical temperature profiles

Bragg-RASS: windprofiler plus acoustic component

Doppler-RASS: SODAR plus electro-magnetic component

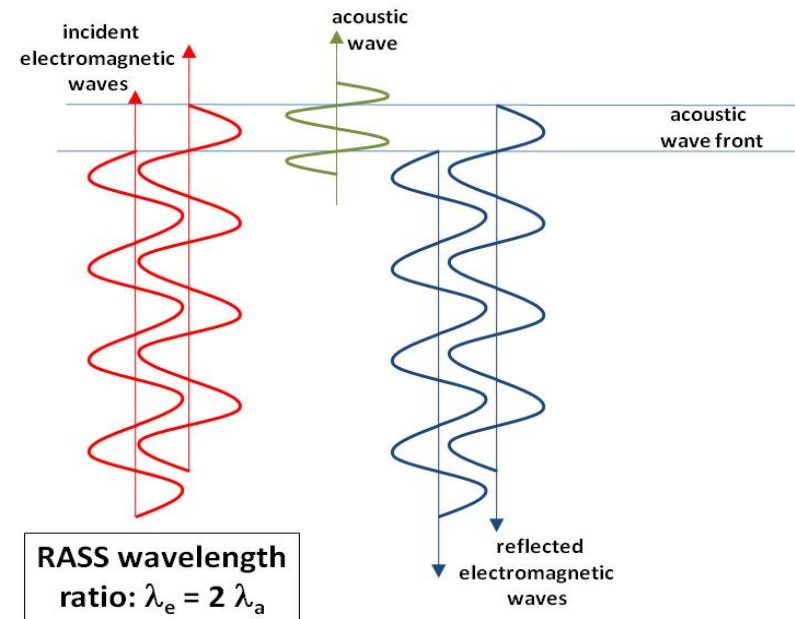
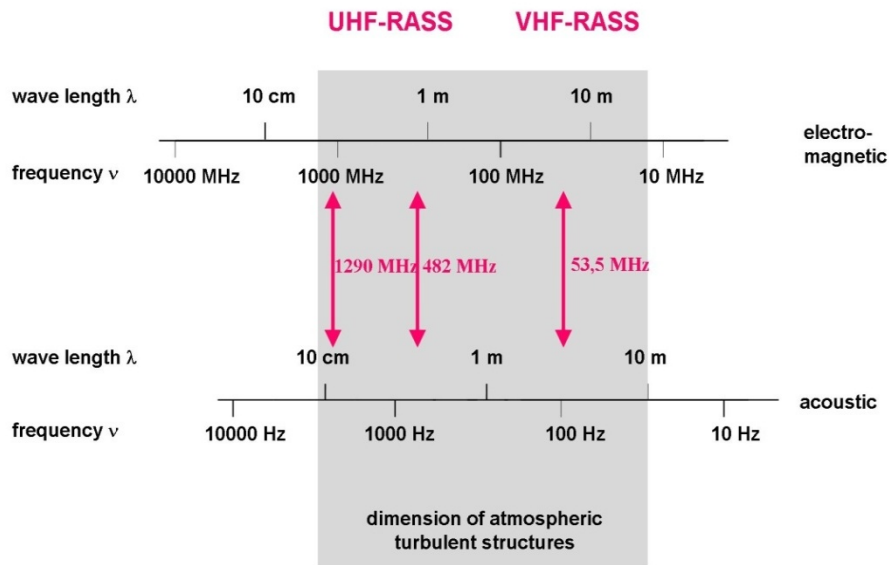
UHF RASS (boundary layer)

VHF RASS (troposphere)

RASS: frequencies

Bragg condition:
 acoustic wavelength = $\frac{1}{2}$ electro-magnetic wavelength

electro-magnetic - acoustic frequency pairs for RASS devices





SODAR-RASS (Doppler-RASS)

(METEK)

acoustic frequ.: 1500 – 2200 Hz

radio frequ.: 474 MHz

resolution: 20 m

lowest

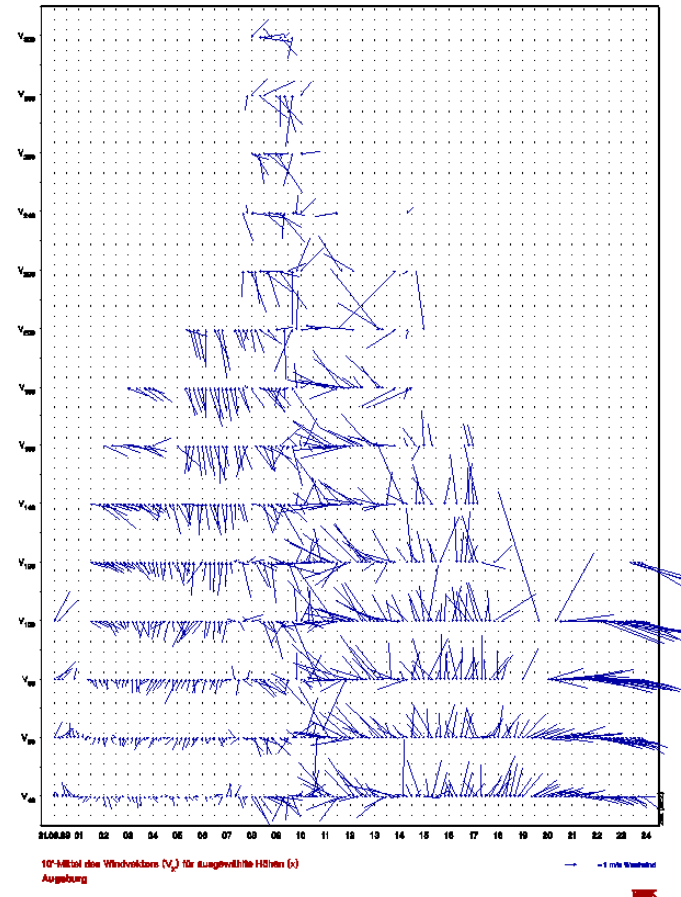
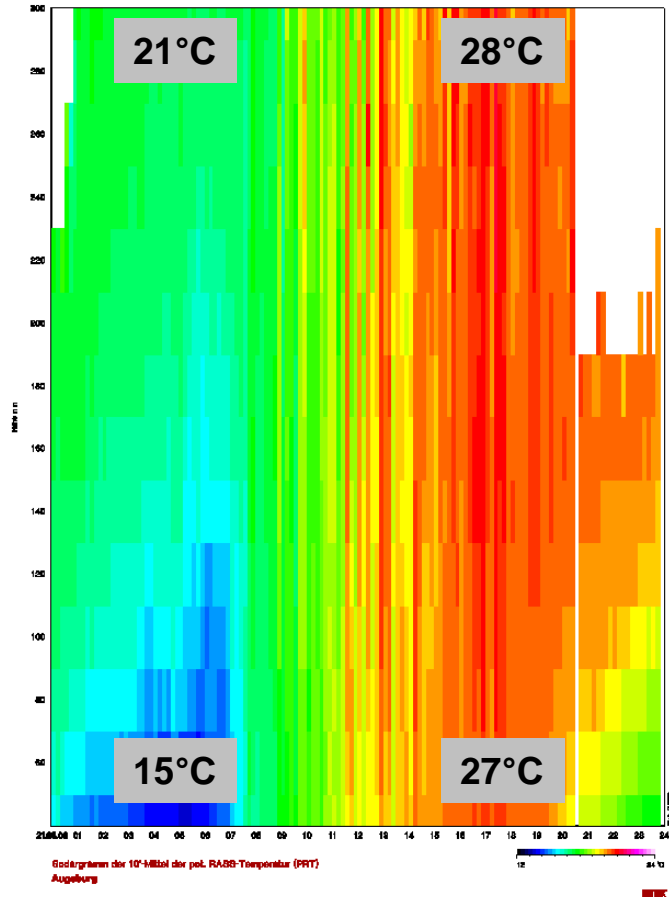
range gate: ca. 40 m

vertical range: 540 m

temperature profile and dynamics

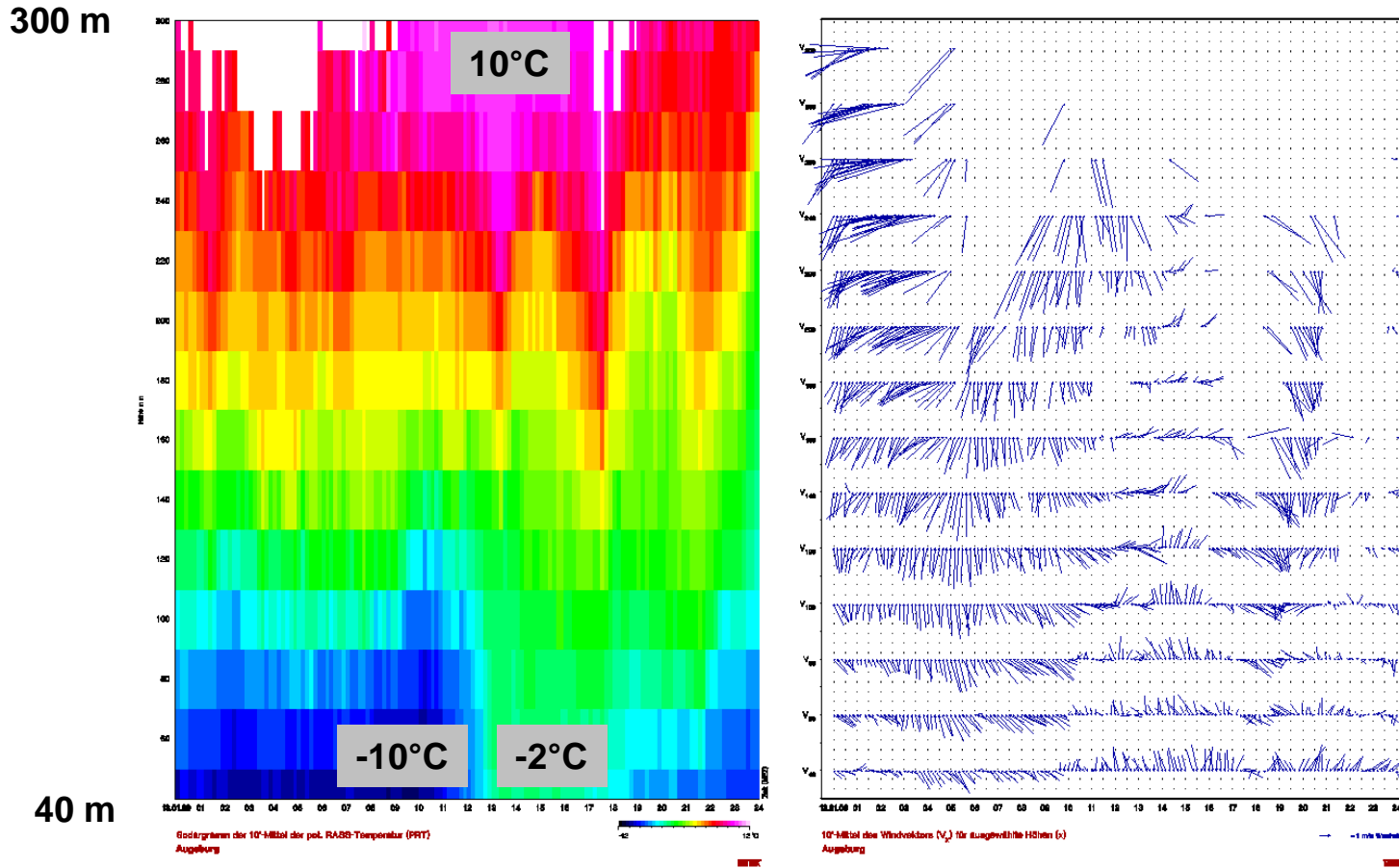
example RASS data: summer day
potential temperature (left), horizontal wind (right)

300 m



temperature profile and dynamics

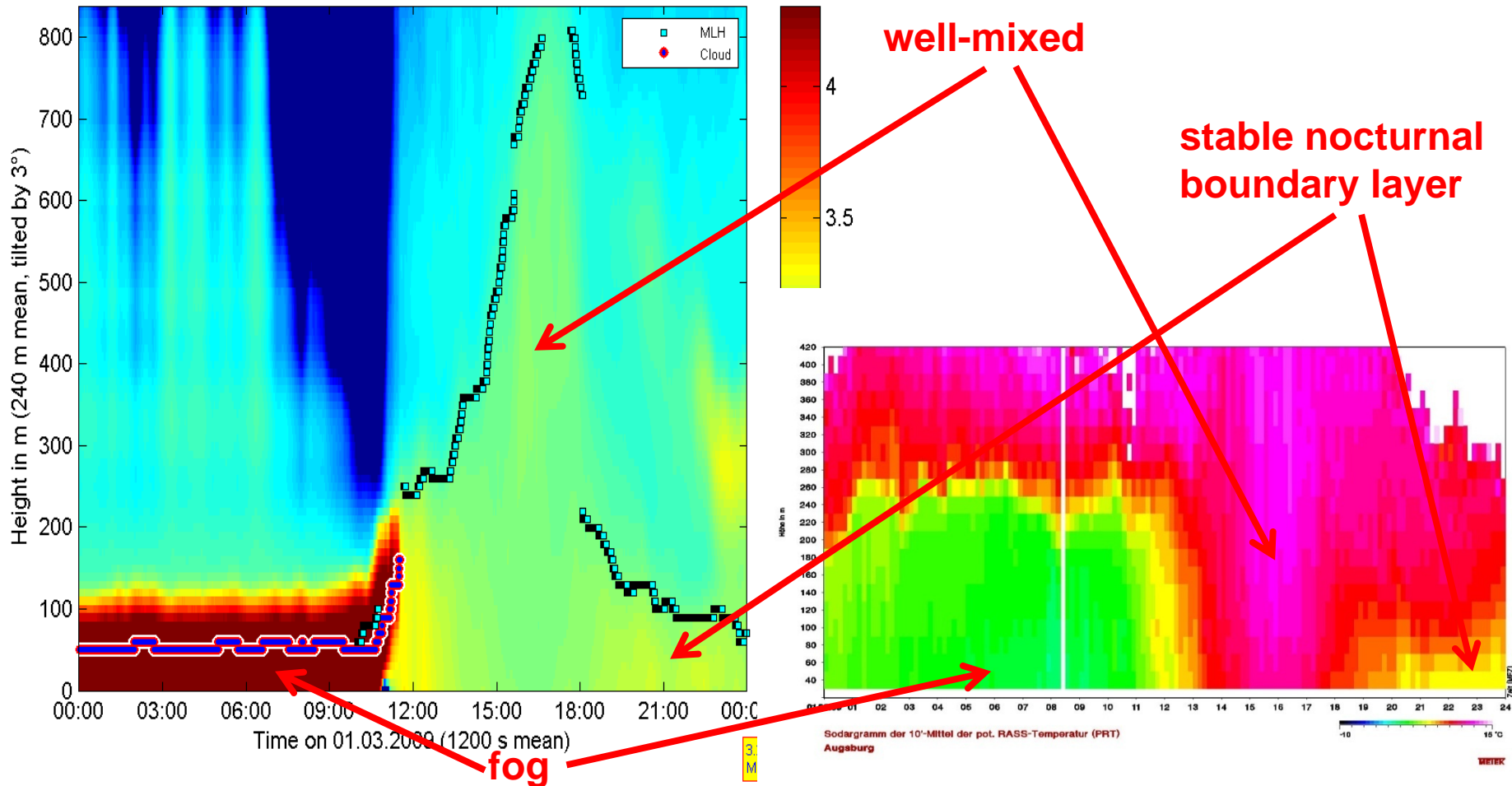
example RASS data: winter day
 potential temperature (left), horizontal wind (right)



temperature profile and pollution

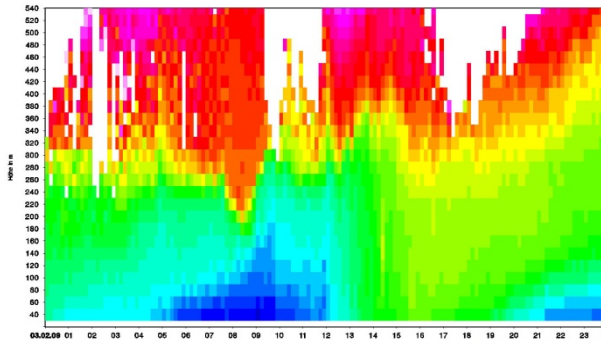
comparison of RASS data (potential temperature, right)
with aerosol backscatter from a ceilometer (left)

CL31 Augsburg AVA \log_{10} of backscatter with MLH on 01.03.2009 in $10^{-9} \text{ m}^{-1} \text{ sr}^{-1}$

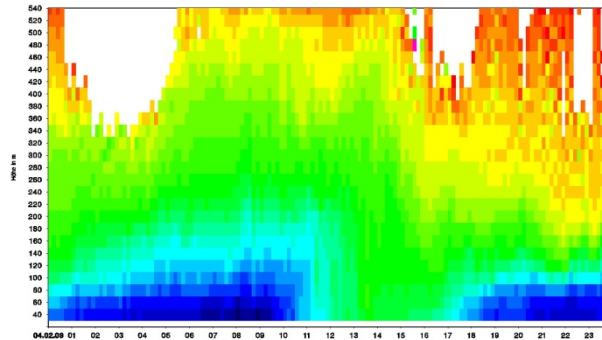


RASS data Augsburg February 2009

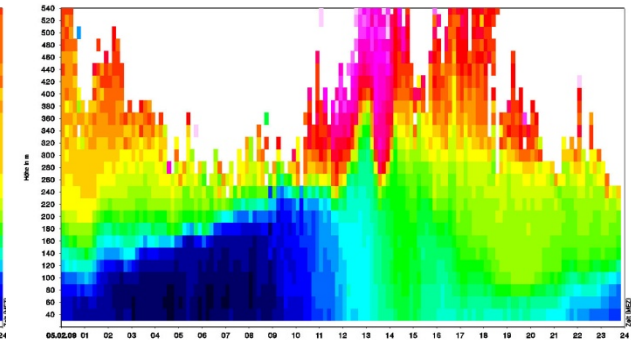
potential temperature (top), backscatter SODAR (middle), Ceilometer (bottom)



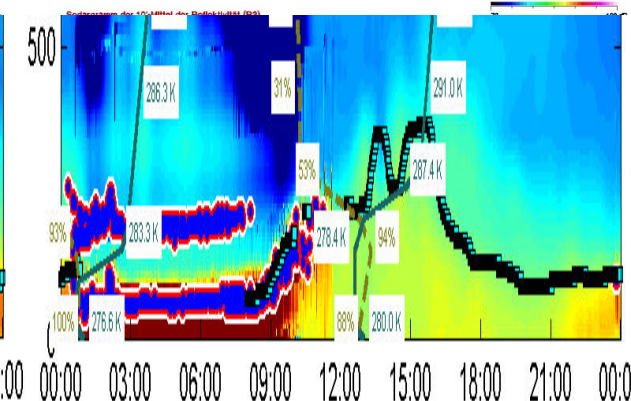
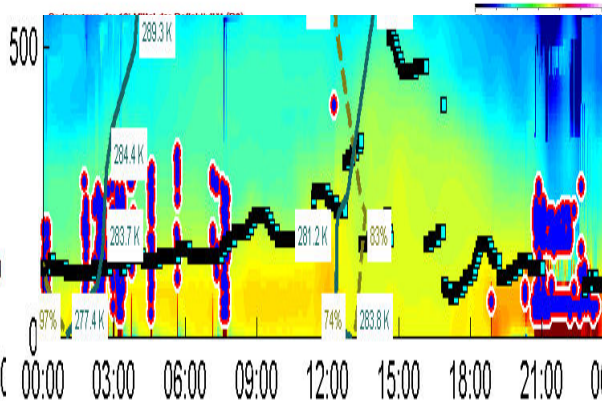
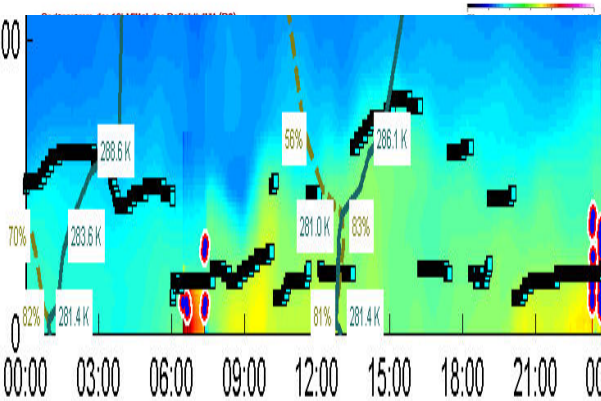
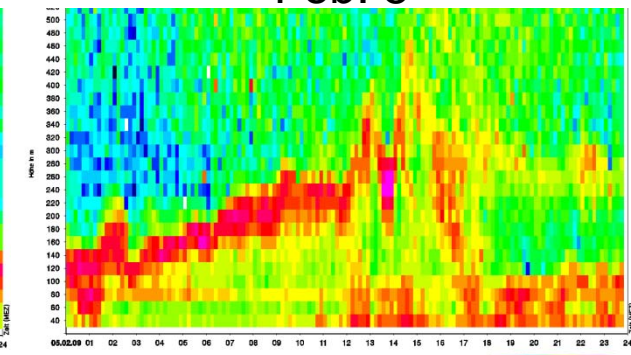
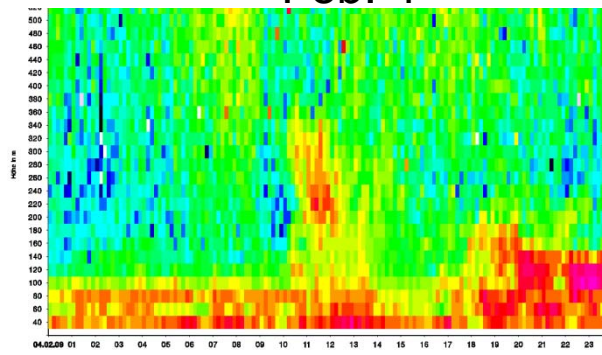
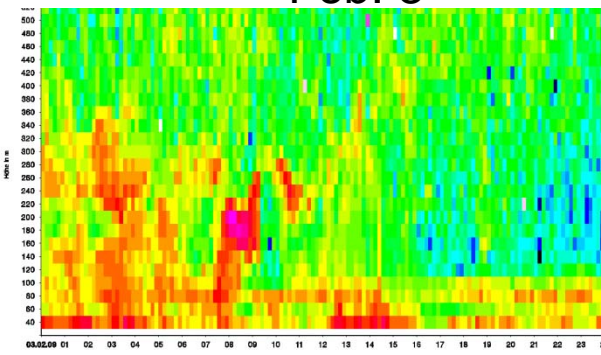
Feb. 3



Feb. 4

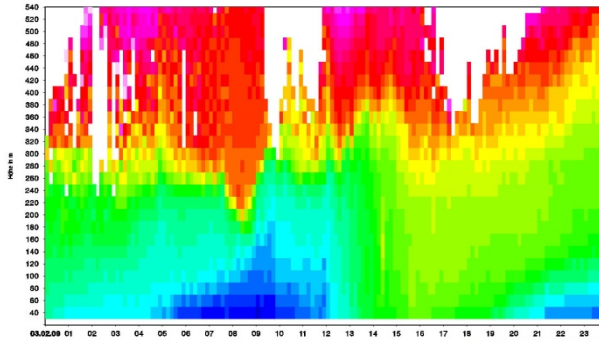


Feb. 5

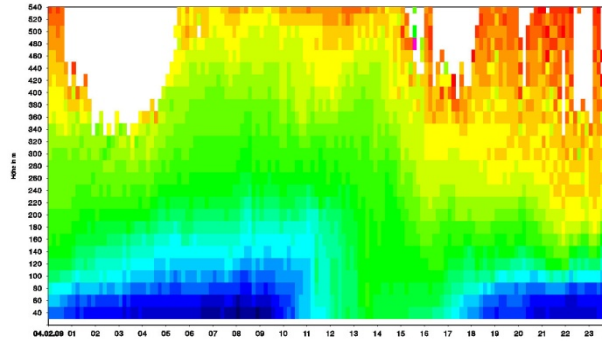


RASS data Augsburg February 2009

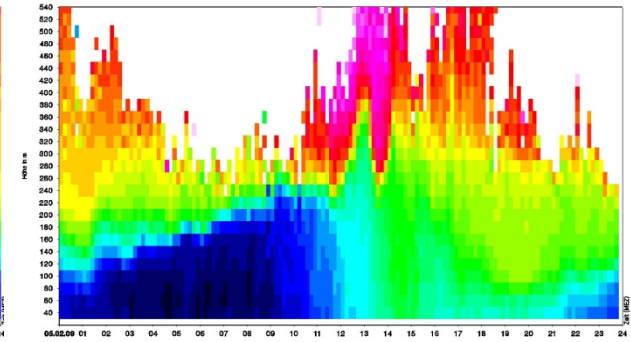
potential temperature (top), MLH RASS (middle), MHL SODAR/Ceilo (bottom)



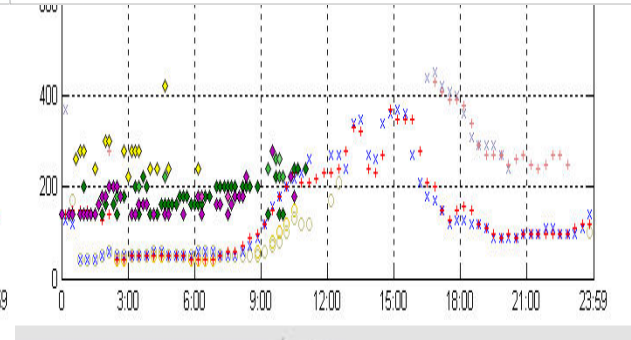
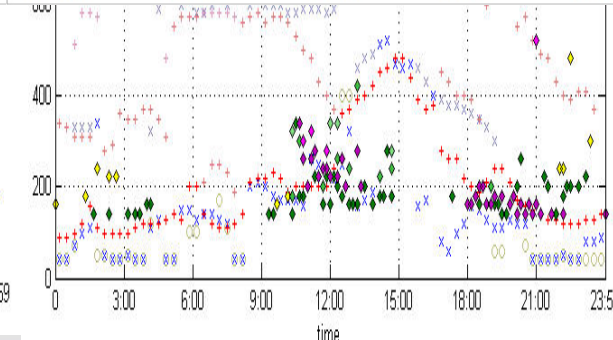
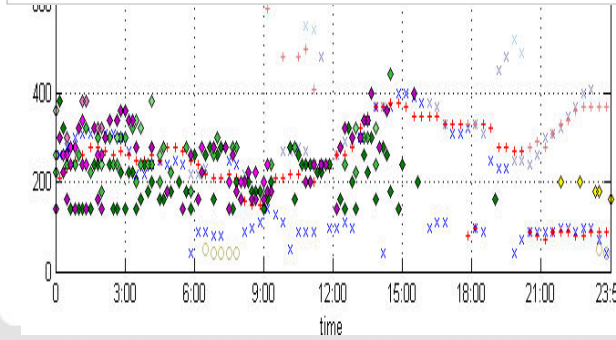
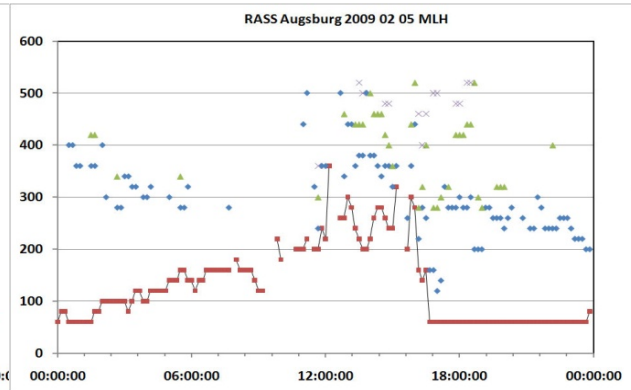
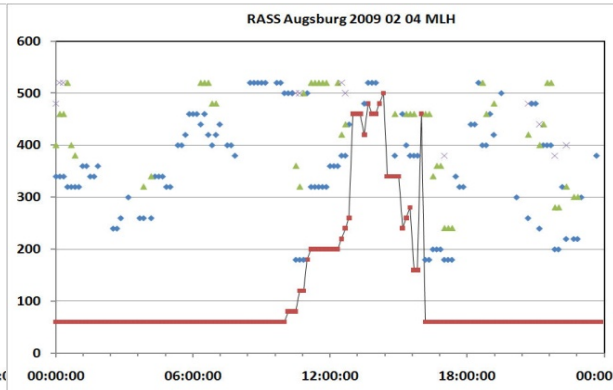
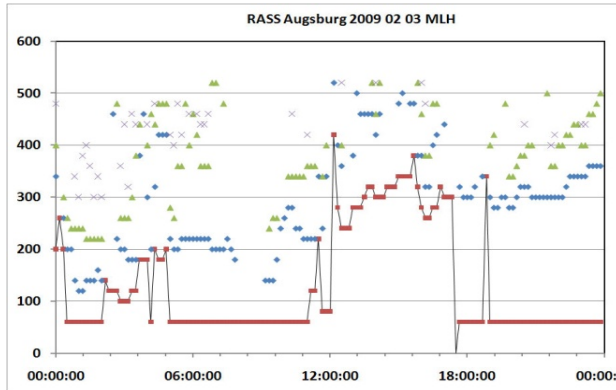
Feb. 3



Feb. 4



Feb. 5



Application

Determination of regional surface emission fluxes of a substance e

Assumptions:

- horizontal homogeneity
- no fluxes through the upper boundary (inversion)
- no sources and sinks within the volume of interest

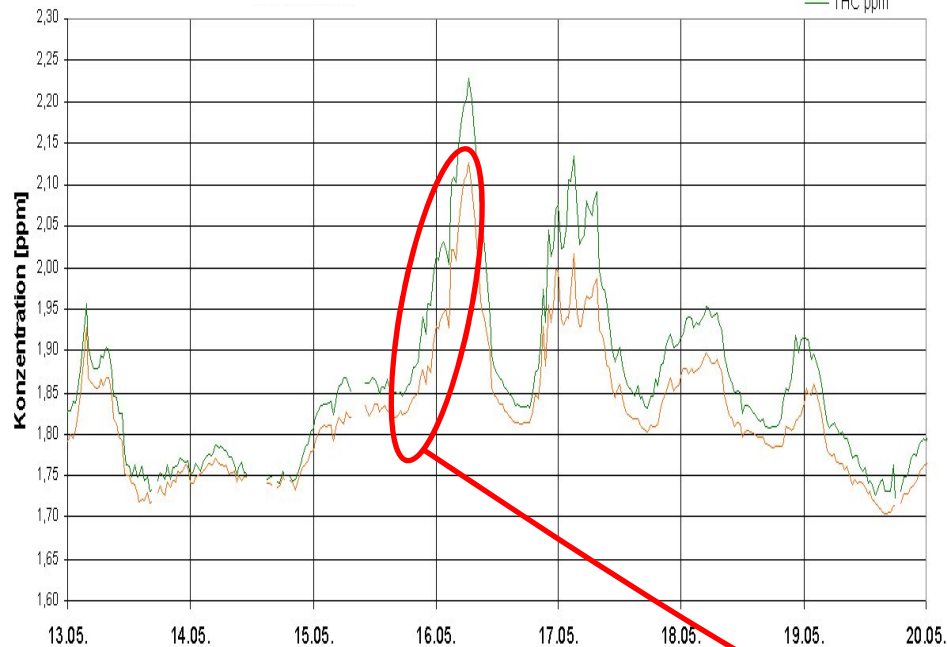
$$\int_{S_{surf}} \overline{e'w'} \cdot dS = \int_V \frac{de}{dt} dV$$

simultaneous measurement of concentration and MLH

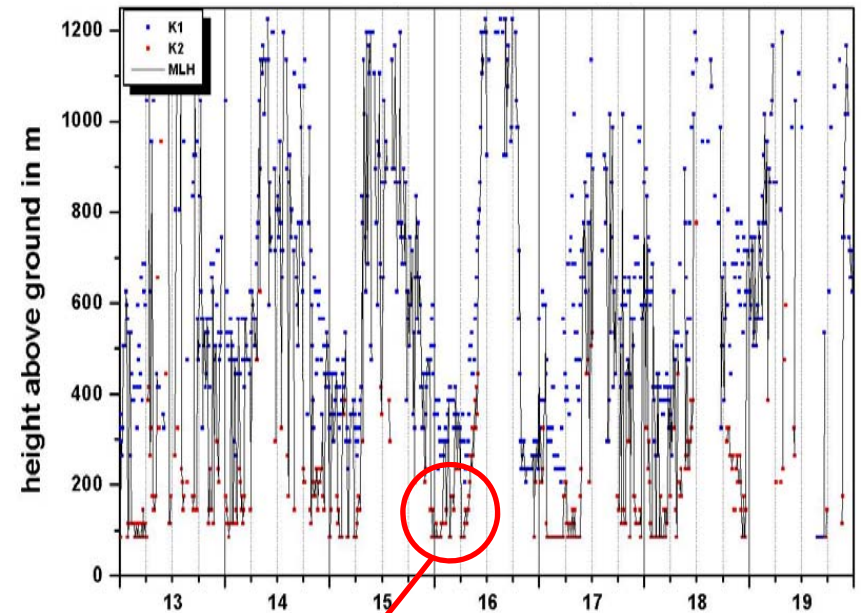
(inverse method)

C_{CH4}

— CH4 ppm
 — NMHC ppm
 — THC ppm



MLH

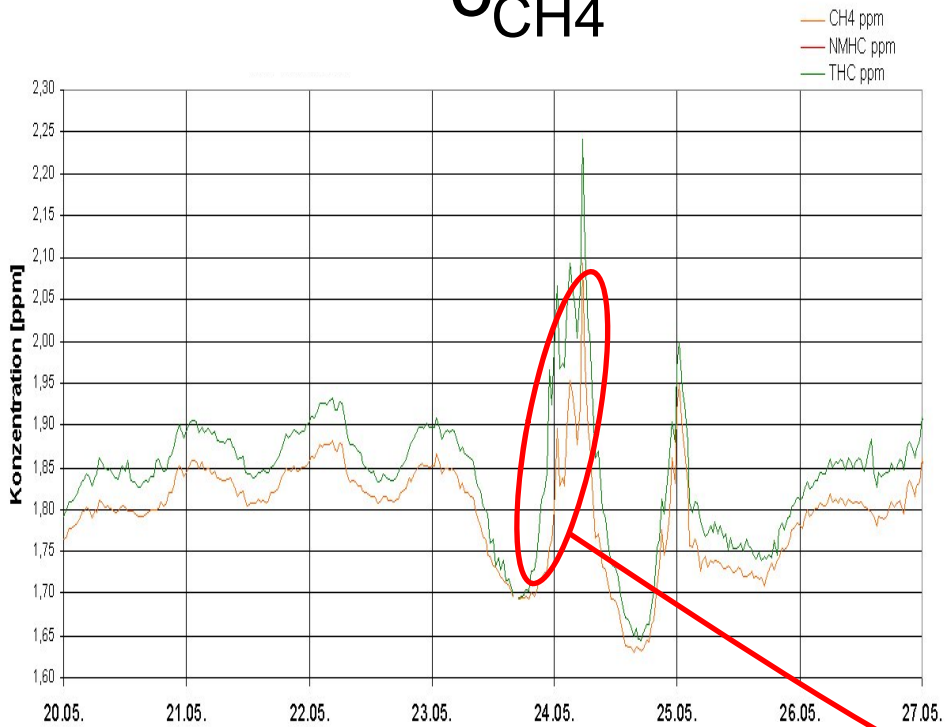


13.-19.05.2003

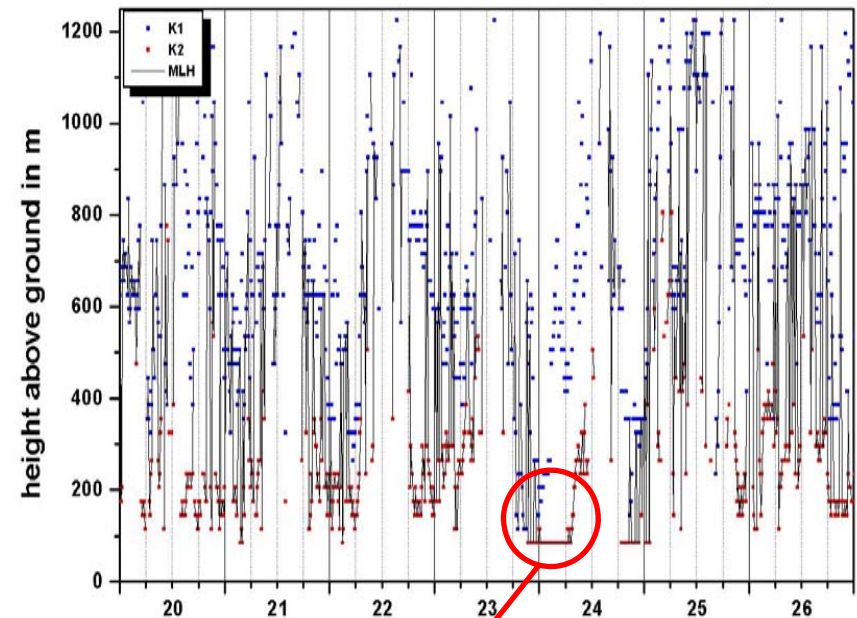
simultaneous measurement of concentration and MLH

(inverse method)

C_{CH4}

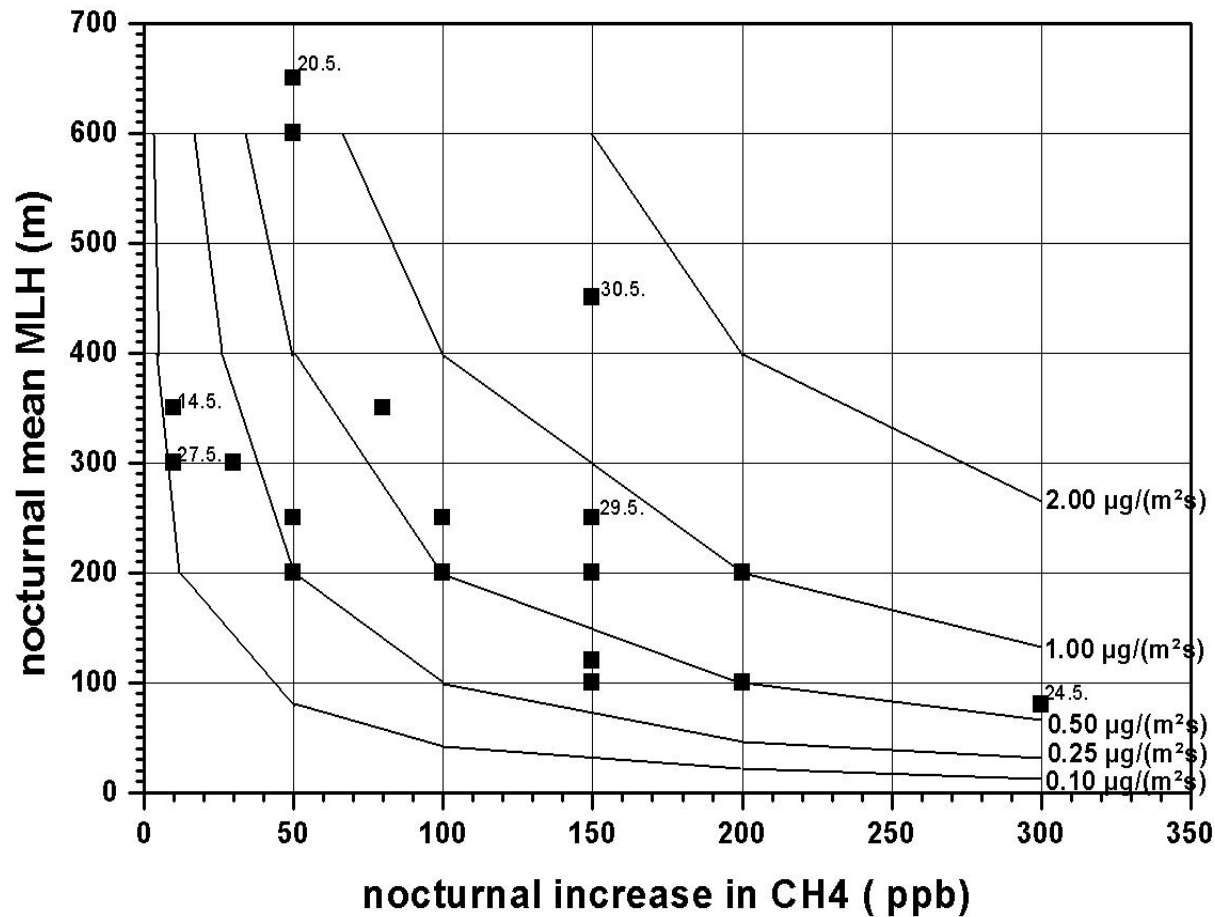


MLH



20.-26.05.2003

determination of regional $[C_{CH_4} 'w']_{surf}$ (curves) from concentration changes (x-axis) and MLH (y-axis)



determination of regional $[C_{CH_4} \cdot W]_{surf}$ (curves) from concentration changes and remotely sensed MLH

methane emissions:

typical values obtained here:

span: 0.10 to 2.00 $\mu\text{g}/(\text{m}^2 \text{ s})$

mean value: 0.50 $\mu\text{g}/(\text{m}^2 \text{ s})$

average values from national reporting (Kyoto protocol):

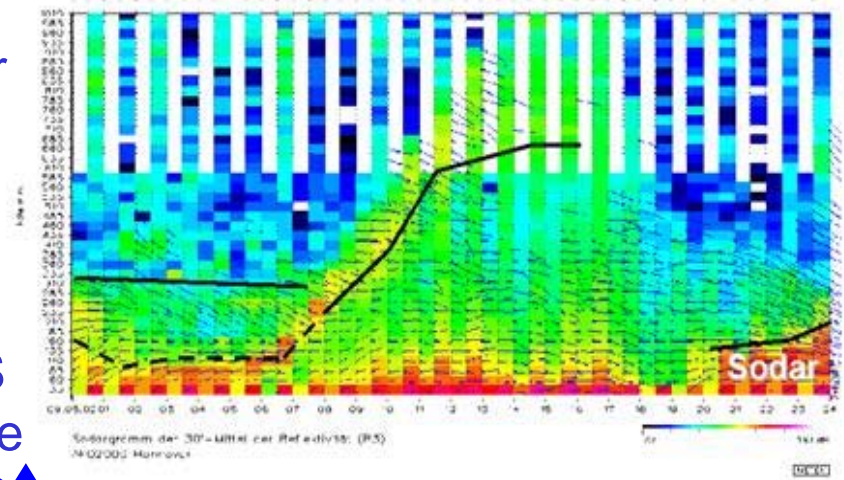
for entire Germany: 0.20 $\mu\text{g}/(\text{m}^2 \text{ s})$

among this from agriculture: 0.13 $\mu\text{g}/(\text{m}^2 \text{ s})$

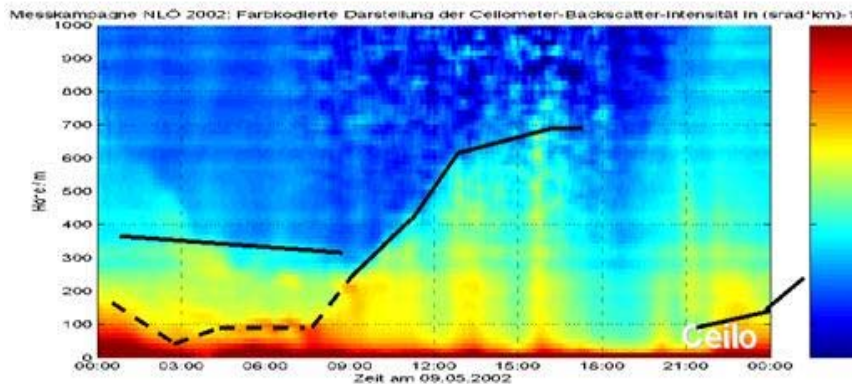
Summary

Comparison of MLH retrievals with three different remote sensing techniques

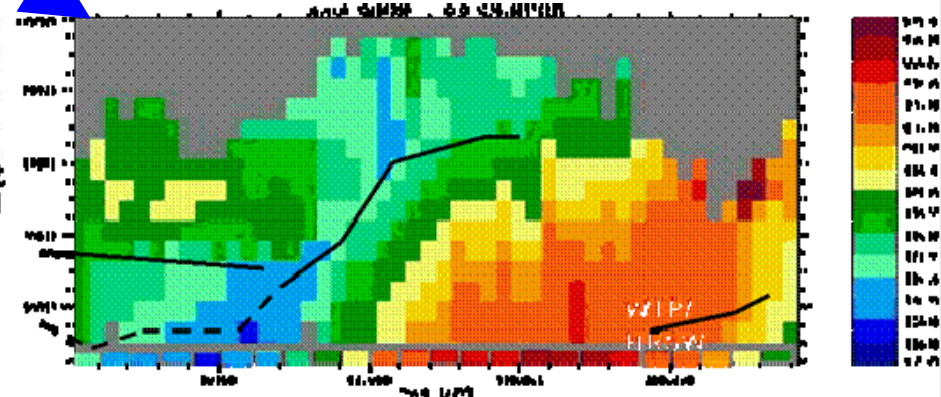
SODAR
acoustic backscatter



ceilometer
optical backscatter



RASS
temperature



Emeis, S., Chr. Münkel, S. Vogt, W.J. Müller, K. Schäfer, 2004: Atmospheric boundary-layer structure from simultaneous SODAR, RASS, and ceilometer measurements. Atmos. Environ., 38, 273-286.

Overview on methods using ground-based remote sensing for the derivation of the mixing-layer height

method	short description
acoustic ARE method	analysis of acoustic received echo intensity profiles
“ HWS method	analysis of horizontal wind speed profiles
“ VWV method	analysis of vertical wind variance profiles
“ EARE method	analysis of acoustic backscatter intensity and vertical wind variance profiles (enhanced acoustic received echo method)
optical threshold method	detection of a given backscatter intensity threshold
“ gradient method	analysis of optical backscatter intensity profiles
“ idealised backscatter method	analysis of optical backscatter intensity profiles
“ wavelet method	analysis of optical backscatter intensity profiles
“ variance method	analysis of optical backscatter intensity profiles
acoustic / electro-magnetic	ARE method applied to sodar and wind profiler data
acoustic / optical	EARE method plus gradient method
electro-magnetic / electro-magnetic	combination of a sodar-RASS and a wind profiler RASS: analysis of the vertical temperature profile plus analysis of the electro-magnetic backscatter intensity profile
acoustic / in situ	ARE method plus in-situ surface flux measurement
RASS	analysis of the temperature profile from the measured speed of sound

Conclusions:

RASS directly delivers temperature profiles, MLH, inversions, and stable layers can easily be detected, wind profiles are additionally available.

Does not work properly with high wind speeds.

SODAR detects temperature fluctuations and gradients, but no absolute temperature. Inversions and stable layers can indirectly be inferred with a MLH algorithm.

Does not work properly with perfectly neutral stratification, with very high wind speeds, and during stronger precipitation events.

Ceilometer detects aerosol distribution and water droplets. It has to be assumed that the aerosol follows the thermal structure of the atmosphere. Inversions and MLH can indirectly be inferred with a MLH algorithm.

Does not work properly in extreme clear (aerosol-free) air and during precipitation events and fog.

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**Thank you very
much for your
attention**