

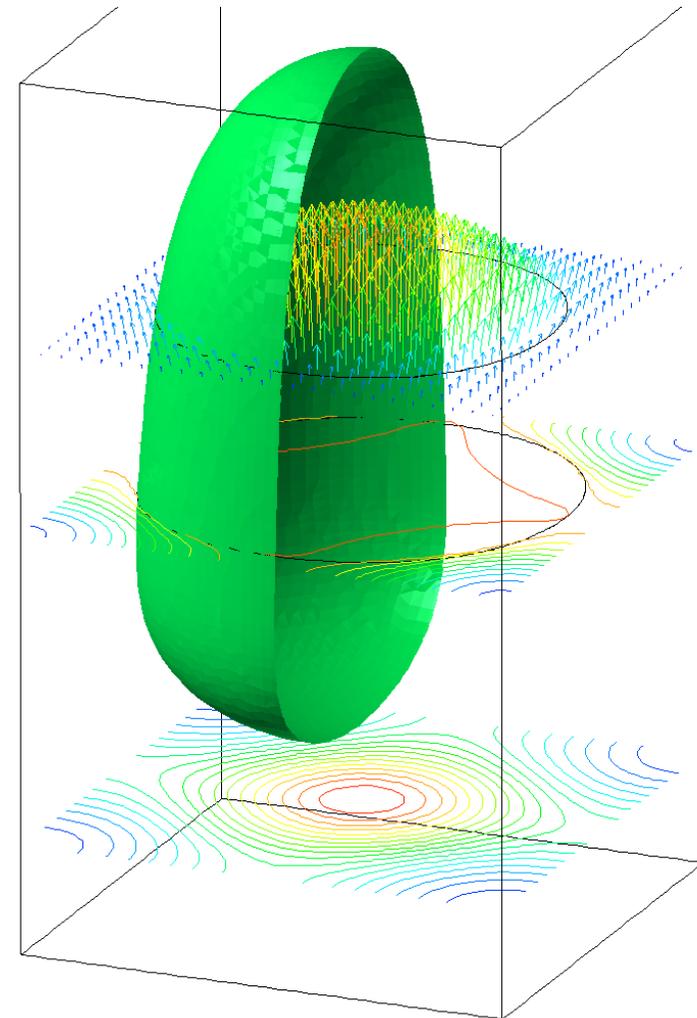
# Numerical investigations of gas-liquid flows in mini-channels for applications in chemical process engineering

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Workshop SimLab@KIT

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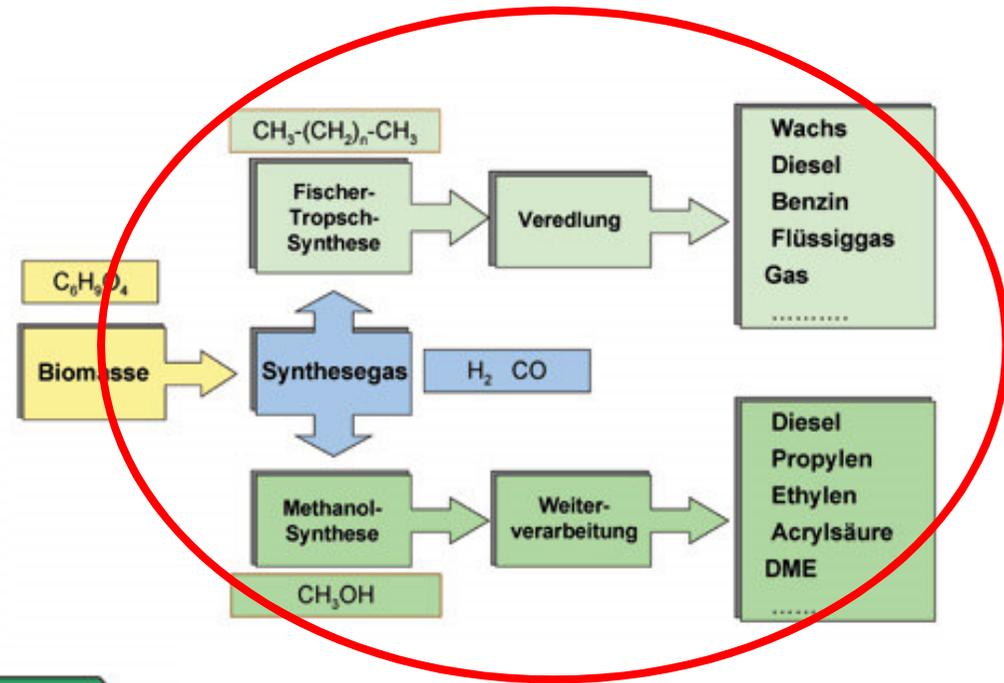
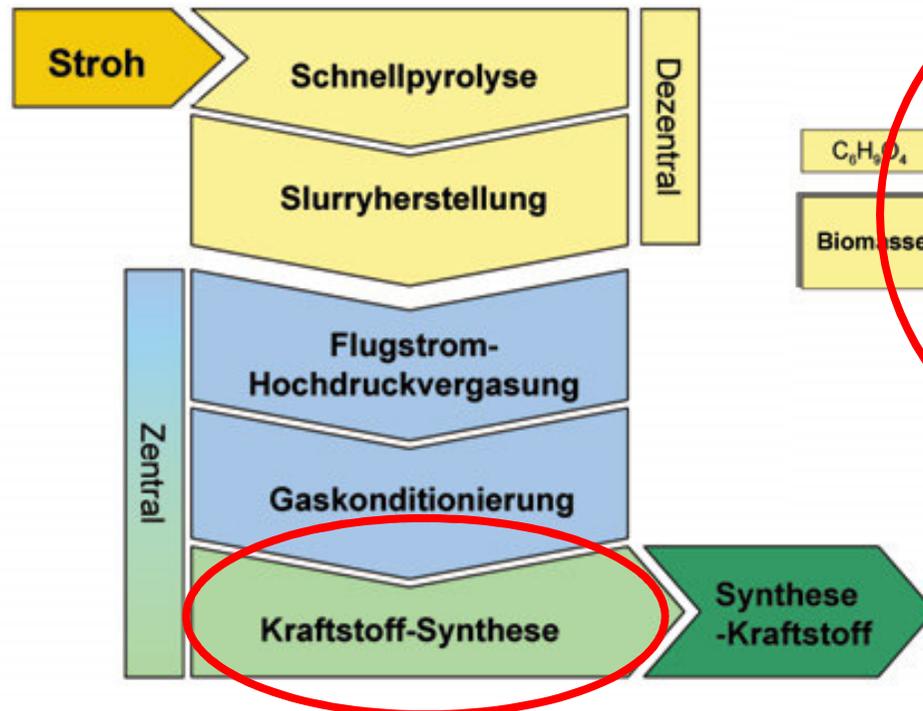
# Outline

- Background and motivation
  - Technological: synthesis of biofuels
  - Scientific: Interaction between flow, transport and reaction
- Numerical simulation method
  - Governing equations and numerical method
  - Typical results for fluid flow and mass transfer
- Performance analysis of the code
  - NEC SX-8 and SX-9
  - hc3
- Conclusions

# Technological background

## ■ Karlsruhe BTL (biomass-to-liquid) process

### Process steps



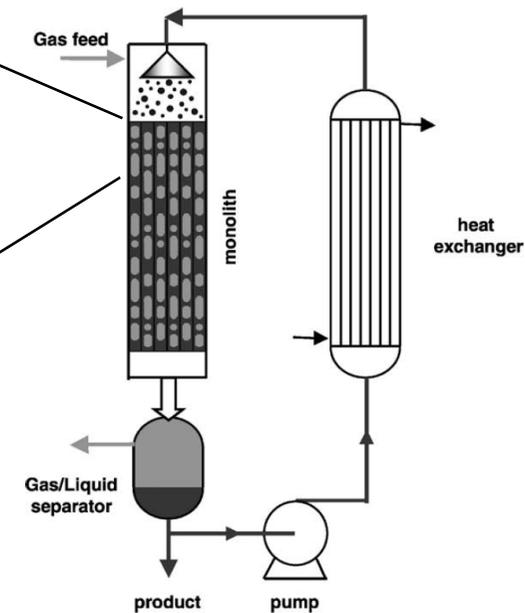
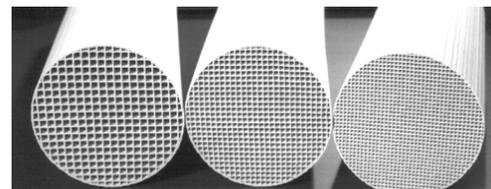
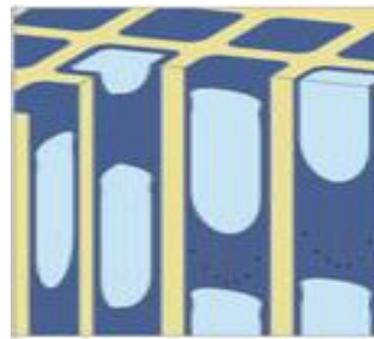
**Fuel synthesis:**  
*a heterogeneously catalyzed gas-liquid process*

<http://iwrwww1.fzk.de/bioliq/index.html>

# Technological background

## ■ Fischer-Tropsch-Synthesis (conversion of CO & H<sub>2</sub> into liquid fuels)

- Sasol Inc: 6 Mio. t fuel per year by bubble column reactors (diam. 12 m)
- Monolith reactors with Taylor flow offer higher yield by similar selectivity  
Güttel et al. Ind. Eng. Chem. Res. 47 (2008) 6589



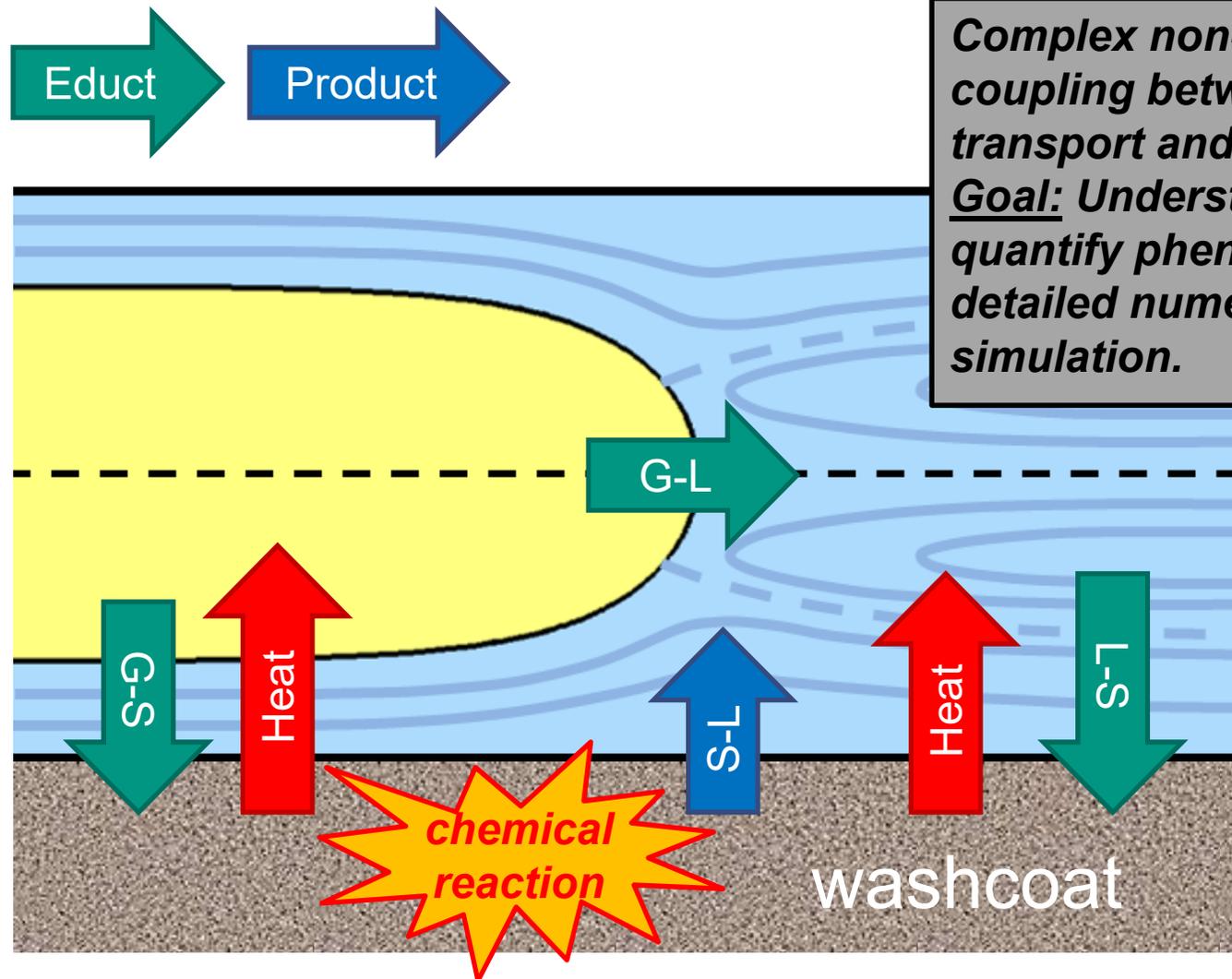
### Monolith-Loop-Reaktor

de Deugd et al. Cat. Today 79 (2003) 495

## ■ Here:

- Investigate hydrodynamics of Taylor flow in a single square mini-channel by detailed numerical simulations

# Scientific background



*Complex non-linear coupling between flow, transport and reaction. Goal: Understand and quantify phenomena by detailed numerical simulation.*

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# Governing equations

- Navier-Stokes equation in single field formulation with surface tension term for two incompressible immiscible Newtonian fluids with constant physical properties
- $f$  = liquid volumetric fraction within a mesh cell ( $0 \leq f \leq 1$ )

$$\frac{\partial f}{\partial t} + \nabla \cdot f \mathbf{v}_m = 0$$

$$\nabla \cdot \mathbf{v}_m = 0$$

$$\rho_m \equiv \frac{f \rho_1^* + (1-f) \rho_2^*}{\rho_1^*}$$

$$\mu_m \equiv \frac{f \mu_1^* + (1-f) \mu_2^*}{\mu_1^*}$$

$$\frac{\partial \rho_m \mathbf{v}_m}{\partial t} + \nabla \cdot (\rho_m \mathbf{v}_m \mathbf{v}_m) = -\nabla P + \frac{\nabla \cdot \left[ \mu_m \left( \nabla \mathbf{v}_m + (\nabla \mathbf{v}_m)^T \right) \right]}{Re_{ref}} + \rho_m Fr_{ref} \hat{\mathbf{e}}_g + \frac{Eu_{ref}}{L_{axial}} \hat{\mathbf{e}}_{axial} + \frac{a_i \kappa \hat{\mathbf{n}}_i}{We_{ref}}$$

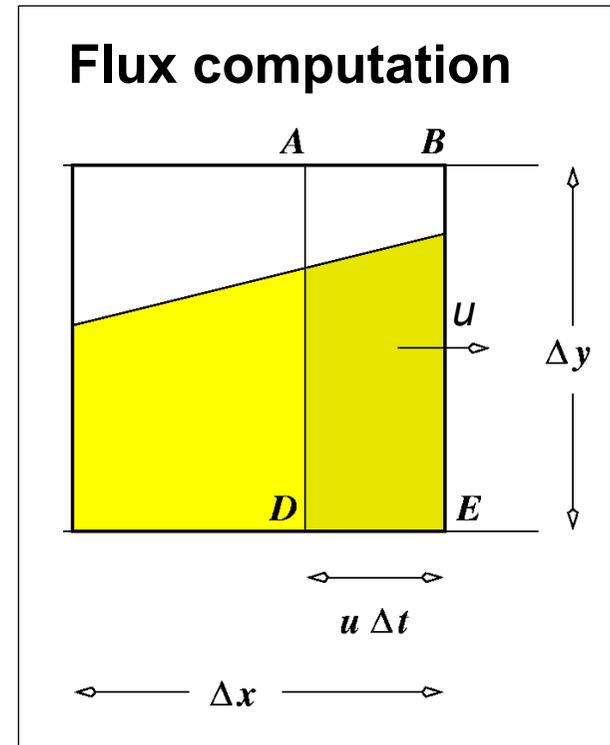
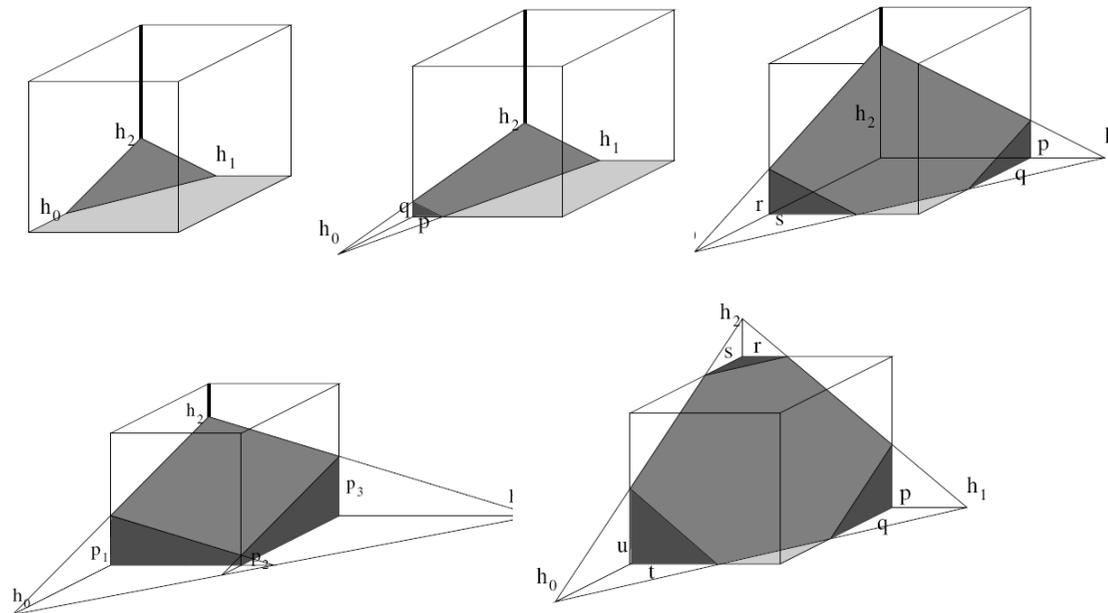
# Numerical method\*

- Finite volume discretization
- Structured 3D Cartesian grid (staggered)
  - equidistant in two directions, optionally non-equid. in third direction
- Approximation of spatial derivatives by central differences
- Explicit 3<sup>rd</sup> order Runge-Kutta time integration scheme
- Projection method for pressure-velocity coupling
  - Resulting pressure Poisson equation is solved by LINSOL package developed at University Karlsruhe
- Volume-of-fluid method with interface reconstruction
- In-house computer code TURBIT-VOF
  - Fortran 77 and Fortran 90
  - The code is not parallelized yet

\*see Öztasquin et al. Phys. Fluids **21** (2009) 042108

# Interface reconstruction

- In each mesh with both phases (i.e. where  $0 < f < 1$ ) the interface is locally approximated by a plane
- The location and orientation of this plane is reconstructed from the distribution of  $f$  in neighboring mesh cells



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## ■ Numerical simulation method

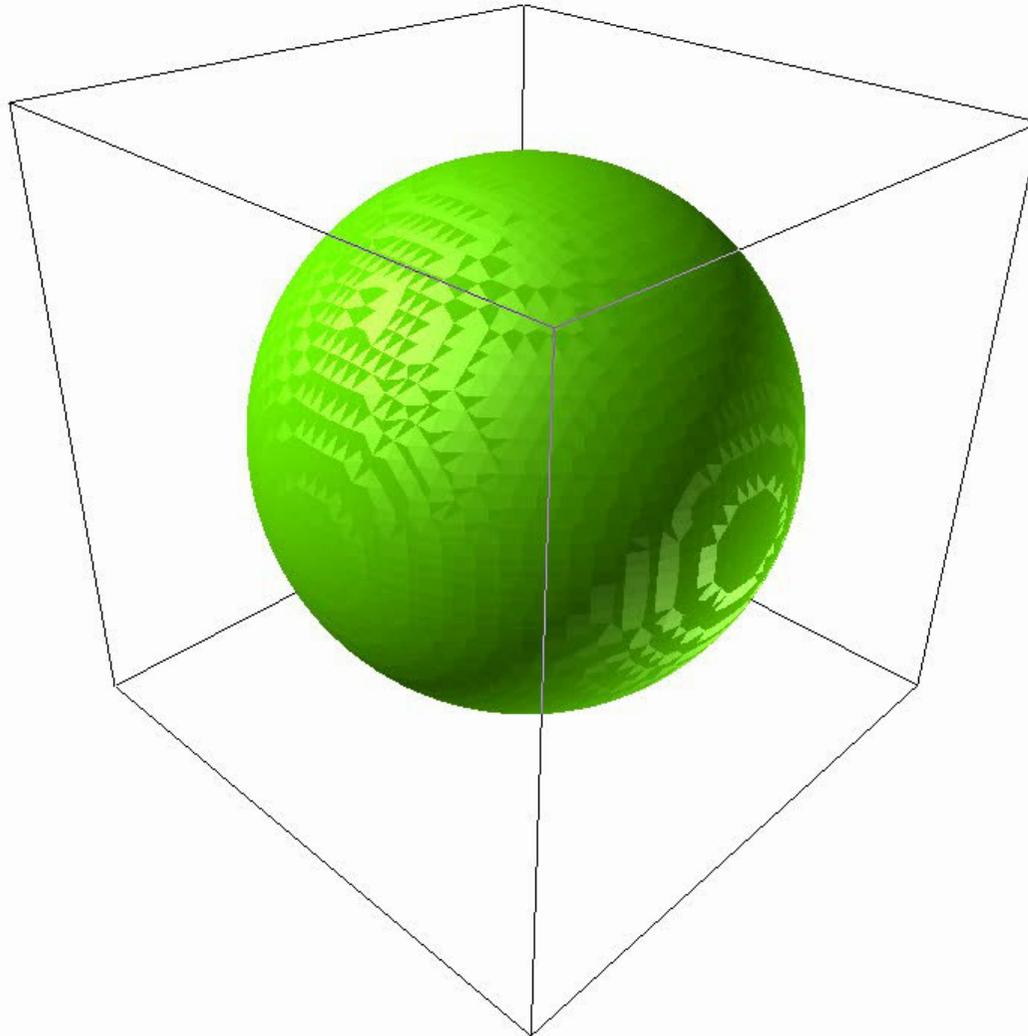
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## ■ Conclusions

# Simulation results



# Computed bubble shapes

1 mm × 1 mm

$L_{uc} = 6 \text{ mm}$

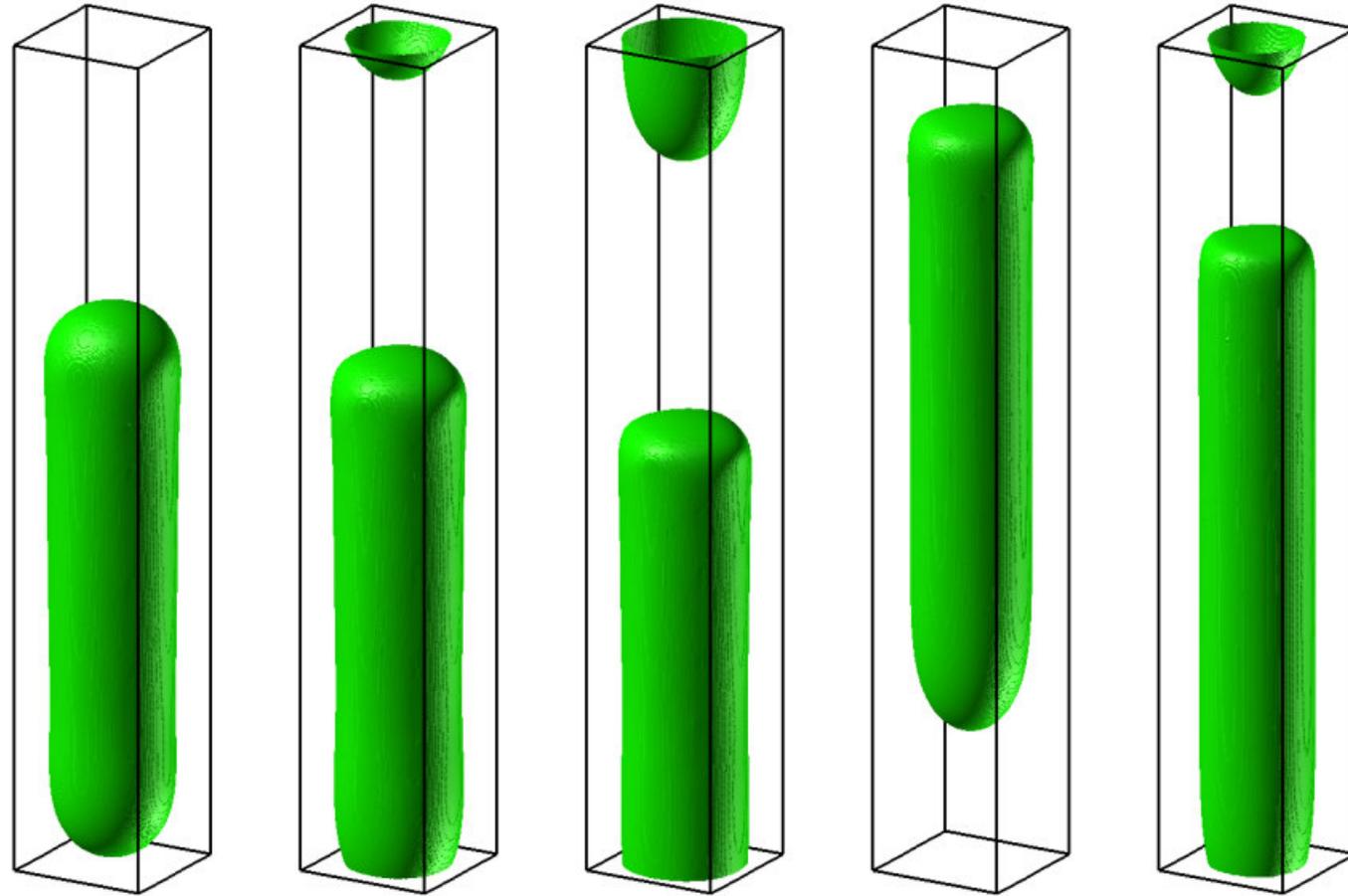
$\varepsilon_G = 0.4$

$$\frac{Re}{Ca} = \frac{\sigma \rho_L D_h}{\mu_L^2}$$

$$\equiv La = 27.27$$

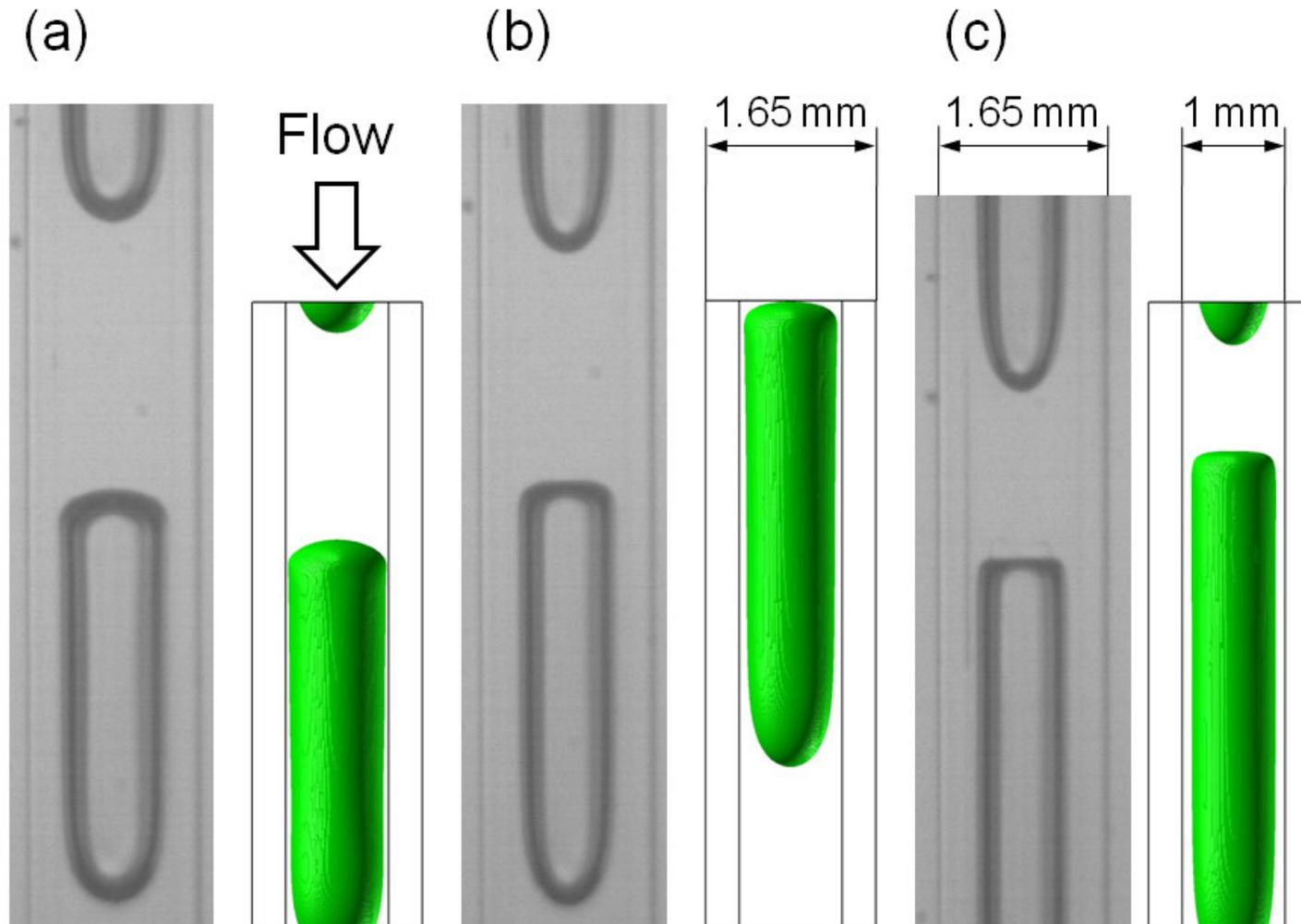
$$Ca \equiv \frac{\mu_L U_B}{\sigma}$$

$$Re \equiv \frac{\rho_L D_h U_B}{\mu_L}$$



$Ca =$	0.045	0.12	0.17	0.26	0.49
$Re =$	1.22	3.19	4.64	7.16	13.4

# Experimental validation\*

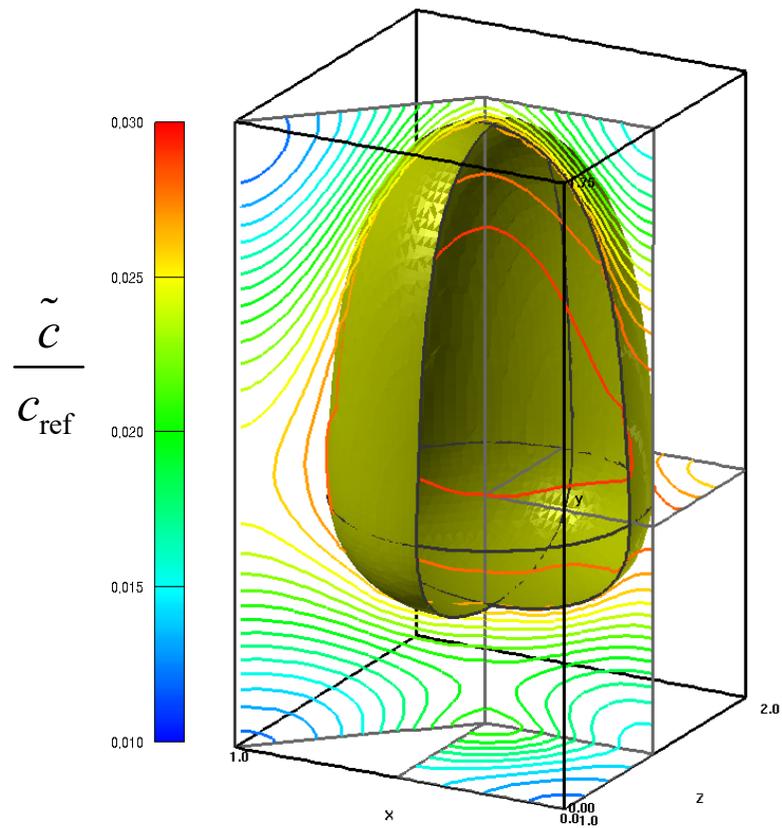


\* Experiments  
by T. Bauer  
and R. Lange

Keskin et al. AIChE J. **56** (2010) 1693–1702

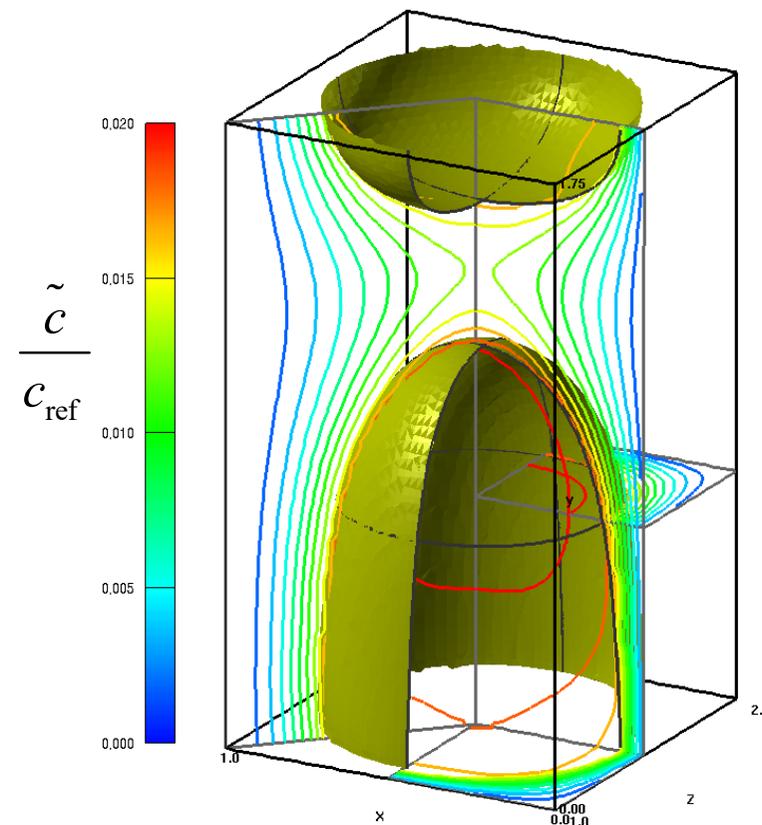
# Mass transfer and chemical reaction

■ Without chemical reaction



*short bubbles are more efficient*

■ Fast heterog. reaction (1<sup>st</sup> o.)



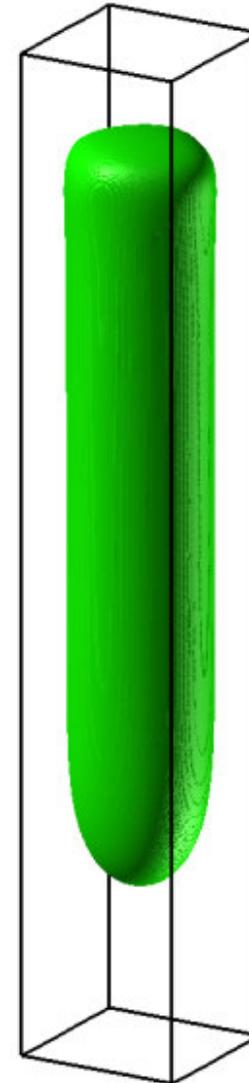
*long bubbles are more efficient*

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# Test case for benchmarking

- Grid  $80 \times 480 \times 80$  mesh cells (about 3 million in total)
- Computation of 10 time steps
- Hardware
  - NEC SX-8 (sxf90 compiler)
  - NEC SX-9
  - hc3 (Intel compiler)
  - All runs on a single processor
  - Memory requirement 4GB



# NEC SX-8: F\_PROGINF=DETAIL



\*\*\*\*\* Program Information \*\*\*\*\*

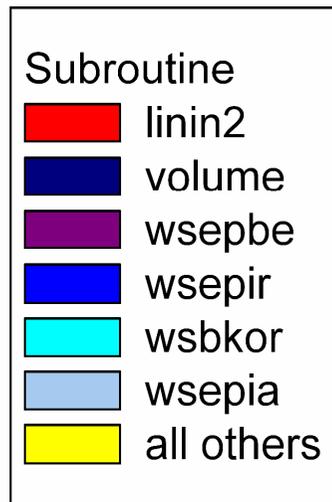
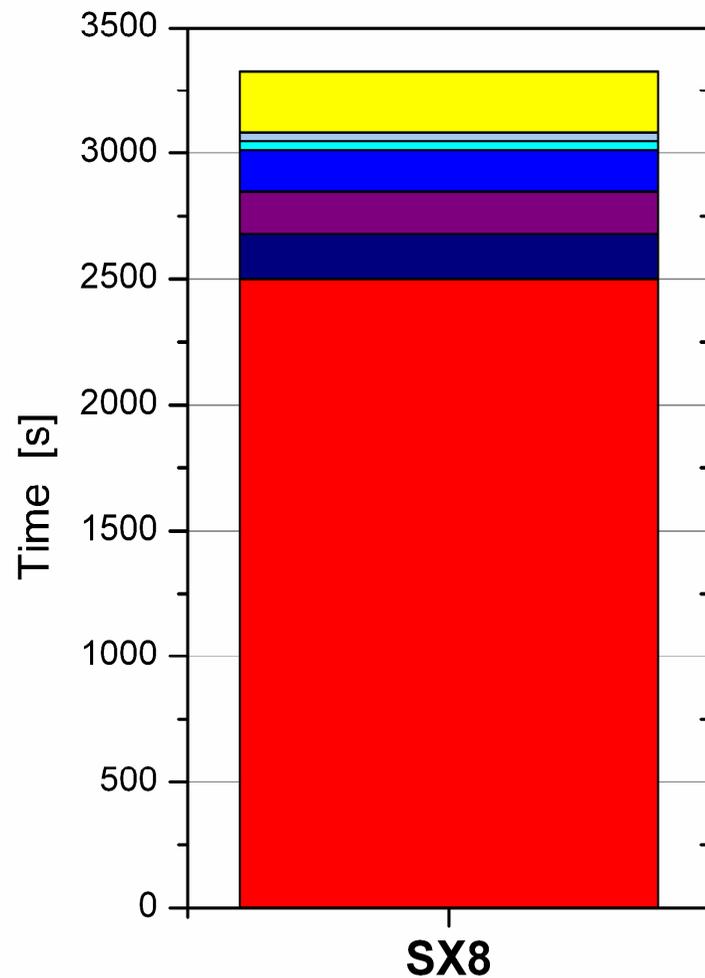
Real Time (sec)	:	35032.602790
User Time (sec)	:	33705.743498
Sys Time (sec)	:	143.167463
Vector Time (sec)	:	29690.202492
Inst. Count	:	5976477160968.
V. Inst. Count	:	1471193564599.
V. Element Count	:	370048534017314.
FLOP Count	:	134402975301641.
MOPS	:	11112.462706
MFLOPS	:	3987.539255
VLEN	:	251.529468
V. Op. Ratio (%)	:	98.797160
Memory Size (MB)	:	4032.031250
MIPS	:	177.313316
I-Cache (sec)	:	94.098275
O-Cache (sec)	:	731.221560
Bank (sec)	:	2824.320016

(100 time steps)

# Flow trace analysis for SX-8

PROG.UNIT	FREQUENCY	EXCLUSIVE TIME[sec]( % )	AVER.TIME [msec]	MOPS	MFLOPS	V.OP RATIO	AVER. V.LEN	VECTOR TIME
linin2	10	2499.715 ( 75.1)	249971.500	13672.0	4921.2	99.37	256.0	2499.365
volume	13165932	181.144 ( 5.4)	0.014	647.0	111.1	47.16	24.2	49.248
wsepbe	103814562	168.516 ( 5.1)	0.002	282.9	8.0	0.00	0.0	0.000
wsepir	415258248	160.700 ( 4.8)	0.000	308.5	158.4	0.00	0.0	0.000
wsbkor	10802207	39.003 ( 1.2)	0.004	275.4	42.2	0.00	0.0	0.000
wsepia	1590	34.446 ( 1.0)	21.664	280.4	25.3	0.00	0.0	0.000
putfb3	1	30.856 ( 0.9)	30856.229	439.9	18.7	2.81	256.0	0.056
getfb3	1	28.885 ( 0.9)	28885.197	488.7	6.9	0.00	28.1	0.000
fvn	2229034	17.924 ( 0.5)	0.008	209.7	15.2	0.00	0.0	0.000
wsepic	31136532	14.283 ( 0.4)	0.000	397.0	154.0	0.00	0.0	0.000
wsepbc	7784133	13.074 ( 0.4)	0.002	241.7	6.0	0.00	0.0	0.000
wsstal	880	12.569 ( 0.4)	14.282	563.6	76.9	0.00	0.0	0.000
bterm	1010916	9.707 ( 0.3)	0.010	243.4	23.1	0.68	8.0	0.165
ofsber	2043501	9.618 ( 0.3)	0.005	232.1	23.2	0.00	21.2	0.000
nvtouv	24522012	9.206 ( 0.3)	0.000	149.8	49.3	0.00	0.0	0.000
wslins	10	9.031 ( 0.3)	903.084	923.3	186.2	9.55	152.5	0.087
wsreko	880	8.714 ( 0.3)	9.902	527.8	24.4	0.00	0.0	0.000
envber	1112019	7.473 ( 0.2)	0.007	322.1	20.4	0.05	34.5	0.002
area	3032748	7.295 ( 0.2)	0.002	581.8	116.2	57.95	23.9	2.350
wsebl	7784133	6.681 ( 0.2)	0.001	203.2	29.1	0.00	0.0	0.000
gbpgc	10	6.488 ( 0.2)	648.821	373.3	24.7	19.73	48.5	0.640
wsfvkx	2400	6.420 ( 0.2)	2.675	382.0	20.0	0.03	36.2	0.001

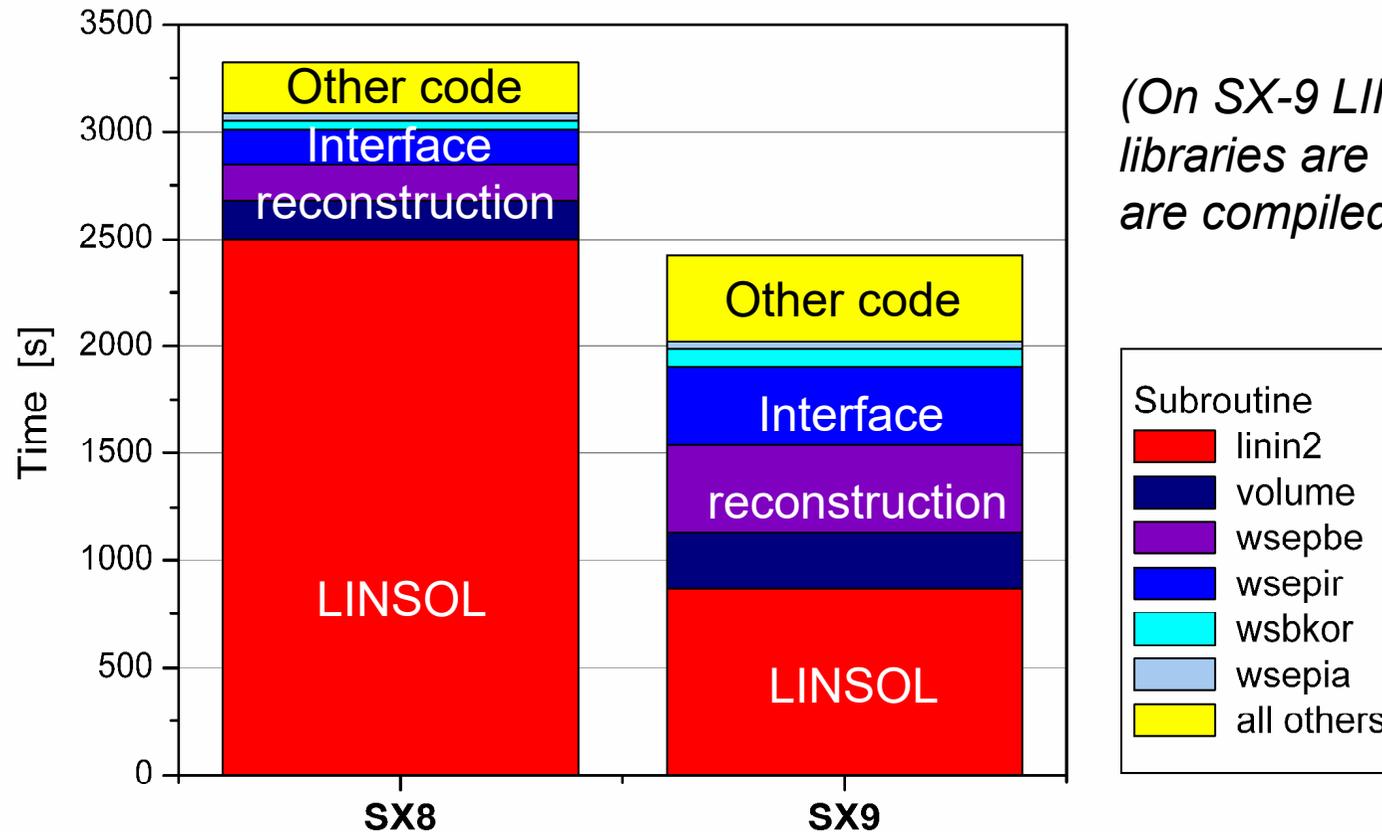
# Flow trace analysis for SX-8



V.OP  
RATIO

99.37	<b>Poisson solver</b>
47.16	
0.00	<b>Interface</b>
0.00	<b>reconstruction</b>
0.00	
0.00	

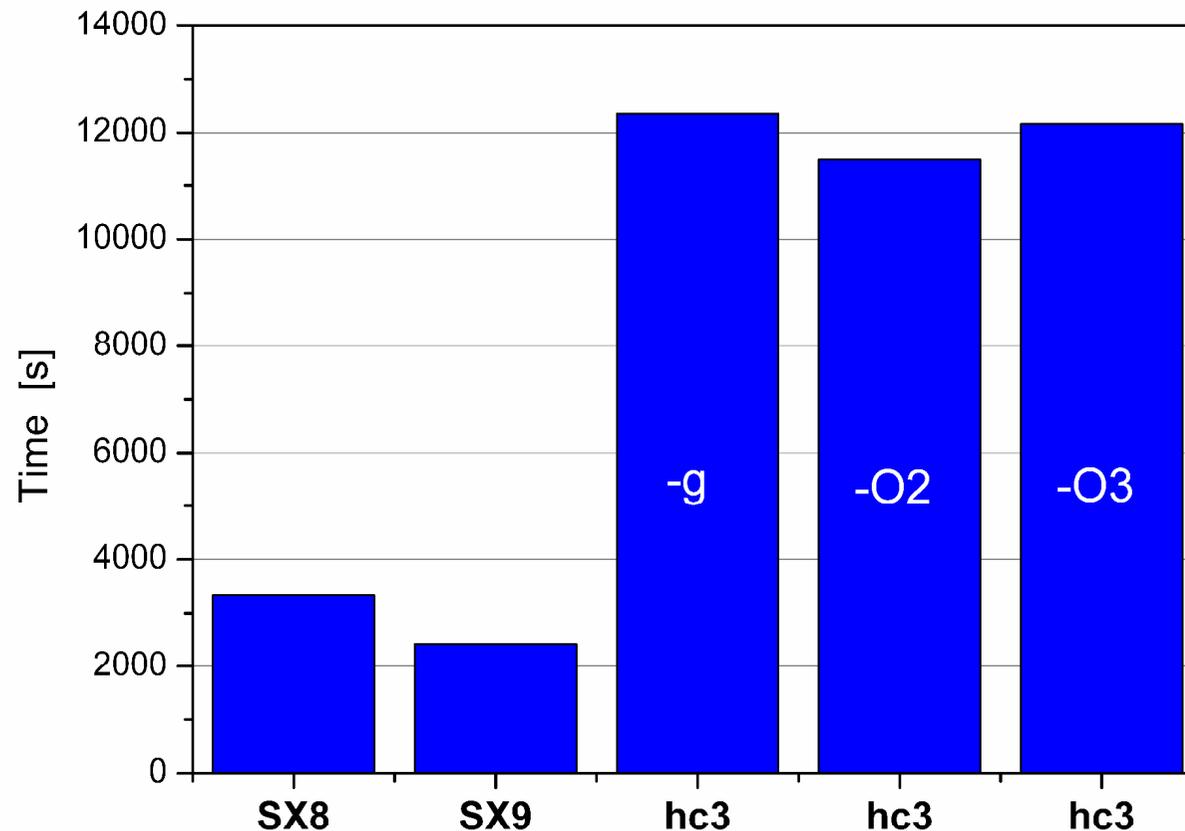
# Comparison NEC SX-8 and SX-9



*(On SX-9 LINSOL libraries are used which are compiled on SX-8)*

- CPU time on SX-9 is about 27% lower than on SX-8
- Vector code (LINSOL) is on SX-9 about 65% faster than on SX-8
- Scalar code (IR) is on SX-9 more than 100% slower than on SX-8

# Comparison SX-8/SX-9 and hc3



- CPU time on hc3 is more than three times larger than on SX-8
- On hc3 optimization options have a minor effect because about 97% of the total CPU time is used by LINSOL library which is already optimized

# Conclusions

- Strategies for optimization of TURBIT-VOF code
  - Usage of LINSOL (suggestions by H. Häfner)
    - Test performance of different CG solvers available within the LINSOL package
    - Test weaker residuum criterion (currently  $10^{-8}$ )
  - NEC SX-8 and SX-9
    - Try to vectorize critical interface reconstruction subroutines
  - hc3
    - Run unparallelized TURBIT-VOF code on a single processor but branch to multiple processors when LINSOL is called (parallelized version of LINSOL is available)

# Acknowledgement

- Many thanks to SimLab Energy especially to Daniela Piccioni-Koch and Hartmut Häfner

