Institut für Angewandte Reaktorphysik

Reactor Temperature Transients with Spatial Variables
First Part: Radial Analysis

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**REACTOR TEMPERATURE TRANSIENTS WITH SPATIAL VARIABLES***)

**FIRST PART: RADIAL ANALYSIS**

von

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1. Introduction

In nuclear reactors the temperature transients are normally treated, by using the well known "lumped model". This model does not take into account any effect due to the heat propagation inside the fuel element and the heat transport along the channel.

Purpose of this paper is therefore a critical analysis of the solutions of the heat balance equations with spatial variables.

The work has been divided in two parts:

(a) **Radial Analysis** in which the heat propagation inside the fuel element is studied

(b) **Axial Analysis**: the results coming from the first part are incorporated in the heat balance equation of the coolant. Then the complete solution, including the heat transport along the channel, is analysed.

In this first part the radial analysis is developed. Two different approximate solutions have been found one expressed in sums of exponentials and the other with the error function.

Numerical examples are included with reference to Sefor reactor (Bibl.7.) and to power reactors.

For simplicity in this mathematical treatment the fuel element has been supposed to be cooled directly without any cladding. Nevertheless the method is still general if, instead of the coolant temperature, we consider the temperature of the internal surface of the cladding.
2. **Mathematical Fundamentals**

Fig.1 shows the section of a cylindrical fuel element in which heat is produced uniformly and which is cooled on the external surface. The following symbols have been used:

- \( T \) = temperature at any point of the cylinder
- \( T_s \) = surface temperature of the cylinder
- \( T_c \) = central temperature of the cylinder
- \( T_{av} \) = average temperature of the cylinder
- \( \Theta \) = coolant temperature (or temperature of the internal surface of the cladding)
- \( q \) = power density
- \( r \) = radius
- \( R \) = external radius
- \( t \) = time
- \( \lambda \) = thermal conductivity (supposed to be constant)
- \( \rho_f \) = mass density (supposed to be constant)
- \( c_f \) = specific heat capacity (supposed to be constant)
- \( h \) = heat transfer coefficient between cylinder surface and coolant (supposed to be constant)

The equation which describes the heat balance in a cylinder is the following:

\[
\frac{\partial T}{\partial t} = \frac{\lambda}{\rho_f c_f} \left( \frac{\partial^2 T}{\partial r^2} + \frac{1}{r} \frac{\partial T}{\partial r} \right) + \frac{q}{\rho_f c_f} \tag{1}
\]

In equation (1) the term related to the heat propagation in the fuel element along the axial direction has been neglected.

The boundary conditions for the full cylinder are:

\[
\int \frac{\partial T}{\partial r} \, dr \bigg|_{r=0} = 0 \tag{2}
\]

\[
\int \frac{\partial T}{\partial r} \, dr \bigg|_{r=R} = -\frac{h}{k} (T_s - \Theta) \tag{3}
\]
Equation (1) can be written as follows:

\[ \frac{\partial^2 T}{\partial y^2} + \frac{1}{y} \frac{\partial T}{\partial y} - \frac{\partial T}{\partial T} = -\frac{R}{2 h y} \quad q \]  

(4)

where:

\[ y = \text{normalized radius} = \frac{r}{R} \]  

(5)

\[ \mathcal{T} = \text{normalized time} = \frac{t}{t_r} \]  

(6)

\[ t_r = \frac{g \rho_f}{\lambda} R^2 = \text{radial time scale} \]  

(7)

\[ \gamma = \frac{\lambda}{2 h R} \]  

(8)

Considering the variation of the system from the stationary conditions, we can introduce the following symbols:

\[ \Delta T = T - T_o \]  

(9)

\[ \Delta \Theta = \Theta - \Theta_o \]  

(10)

\[ \Delta q = q - q_o \]  

(11)

where the subscript "o" indicates initial steady state conditions and "\( \Delta \)" variation from steady state conditions.

Equation (4) becomes:

\[ \frac{\partial^2 \Delta T}{\partial y^2} + \frac{1}{y} \frac{\partial \Delta T}{\partial y} - \frac{\partial \Delta T}{\partial \mathcal{T}} = -\frac{R}{2 h \mathcal{Y}} \Delta q \]  

(12)

The Laplace transform of equation (12) is:

\[ \frac{d^2 \Delta T^*}{d y^2} + \frac{1}{y} \frac{d \Delta T^*}{d y} - \sigma \Delta T^* = -\frac{R}{2 h \gamma} \Delta q^* \]  

(13)

where

"*" indicates Laplace transform

\( \sigma \) = complex variable of the Laplace transformation
The boundary conditions (2) and (3) become respectively:

\[ \int -\frac{d\Delta T^*}{dy} \bigg|_{y=0} = 0 \quad (14) \]

\[ \int \frac{d\Delta T^*}{dy} \bigg|_{y=1} = -\frac{1}{2} \gamma (\Delta T^*_s - \Delta \Theta^*) \quad (15) \]

The solution of equation (13) with the associated boundary conditions (14) and (15) is the following (see Appendix 1):

\[ \Delta T^* = G(\sigma; y) \Delta \Theta^* + \frac{R}{2 h} \int 1 + \frac{1-\gamma^2}{4\gamma} \int F(\sigma; y) \Delta q^* \quad (16) \]

where:

\[ G(\sigma; y) = \frac{1}{1 + \frac{\gamma}{Z(\sigma)}} \frac{J_0(\sqrt{\sigma})}{J_0(\sqrt{-\sigma})} \quad (17) \]

\[ Z(\sigma) = -\frac{J_0(\sqrt{-\sigma})}{2\sqrt{-\sigma} J_1(\sqrt{-\sigma})} \quad (18) \]

\[ F(\sigma; y) = \frac{1}{1 + \frac{1-\gamma^2}{4\gamma}} \frac{1}{\gamma Z(\sigma)} \int 1 - G(\sigma; y) \int \quad (19) \]

\[ J_0(\sqrt{-\sigma}) \text{ and } J_1(\sqrt{-\sigma}) \text{ being Bessel functions of the first kind. For practical purposes it is useful to calculate the variation of the surface temperature, } \Delta T^*_s(y=1), \text{ central temperature, } \Delta T^*_c(y=0), \text{ and average temperature, } \Delta T^*_\text{av} \text{ (see Appendix 2):} \]

\[ \Delta T^*_s = G_s(\sigma) \Delta \Theta^* + \frac{R}{2 h} F_s(\sigma) \Delta q^* \quad (20) \]

\[ \Delta T^*_c = G_c(\sigma) \Delta \Theta^* + \frac{R}{2 h} \int 1 + \frac{1}{4\gamma} \int F_c(\sigma) \Delta q^* \quad (21) \]

\[ \Delta T^*_\text{av} = \frac{1}{\pi} \int_0^\delta 2\pi y \Delta T^* dy = G_{av}(\sigma) \Delta \Theta^* + \frac{R}{2 h} \int 1 + \frac{1}{4\gamma} \int F_{av}(\sigma) \Delta q^* \quad (22) \]

in which:

\[ G_s(\sigma) = \frac{1}{1 + \frac{\gamma}{Z(\sigma)}} \quad (23) \]
It is very important to notice that the functions (23); (24); (27) and (28) depend only on $\gamma$ and $Z(\sigma)$.

3. Expansion in sums of terms of the type \( \frac{d_n}{l + \sigma_{nn}} \)

The expressions (17); (19) and (23) to (28) can be expanded in a sum of terms of the type \( \frac{d_n}{l + \sigma_{nn}} \) which in the time domain corresponds to a sum of exponential functions.

\[
\begin{align*}
G_s(\sigma) &= \sum_{n=1}^{\infty} \frac{\delta_{sn}}{1 + \sigma_{nn}} \\
F_s(\sigma) &= \sum_{n=1}^{\infty} \frac{\epsilon_{sn}}{1 + \sigma_{nn}} \\
G_c(\sigma) &= \sum_{n=1}^{\infty} \frac{\delta_{cn}}{1 + \sigma_{nn}} \\
F_c(\sigma) &= \sum_{n=1}^{\infty} \frac{\epsilon_{cn}}{1 + \sigma_{nn}}
\end{align*}
\]
All the \( -\sigma_n \), satisfy the characteristic equation:

\[ 1 + \frac{\gamma}{2(\sigma)} = 0 \]  

(37)

The roots of equation (37) are all real and negative (see Appendix 3). A graphical solution of equation (37) is shown also in Appendix 3. The equation has been solved also numerically using a digital computer IBM 7070 and values of \( \sigma_n \) up to \( n=20 \) have been calculated for values of \( \gamma \) between \( 10^{-4} \) and 10.

Fig. 2 shows the normalized "\( \sigma_n \)" as function of \( \gamma \). The relationship between \( \sigma_n \) and \( \sigma_n \) is the following:

\[ \sigma_n = b_n + (a_n - b_n) \sigma_n \]  

(Appendix 3)

(38)

where the meaning and the values of the coefficients \( a_n \) and \( b_n \) are given in Table 1.

The coefficients of the equations (29) to (36) are given by the following expressions (see Appendix 4):

\[ \delta_{sn} = \frac{\gamma}{0.25 + \gamma^2 \sigma_n} \]  

(39)

\[ \xi_{sn} = \frac{1}{\sigma_n(0.25 + \gamma^2 \sigma_n)} \]  

(40)

\[ \delta_{cn} = \frac{\gamma}{0.25 + \gamma^2 \sigma_n} \frac{1}{J_0(\sqrt{\sigma_n})} \]  

(41)
The expressions (39) to (45) satisfy the following relationships:

\[
\begin{align*}
\xi_n &= \frac{4\gamma}{1+4\gamma} \frac{1}{\sigma_n(0.25+\gamma^2\sigma_n^2)} - \frac{1}{J_o(\sqrt{\sigma_n})} \\
\delta_n &= \frac{\gamma}{0.25+\gamma^2\sigma_n^2} \frac{J_o(y\sqrt{\sigma_n})}{J_o(\sqrt{\sigma_n})} \\
\xi_n &= \frac{4\gamma}{4\gamma+1-\gamma^2} \frac{1}{\sigma_n(0.25+\gamma^2\sigma_n^2)} - \frac{J_o(y\sqrt{\sigma_n})}{J_o(\sqrt{\sigma_n})} \\
\mu_n &= \frac{8}{1+8\gamma} \frac{1}{\sigma_n^2(0.25+\gamma^2\sigma_n^2)}
\end{align*}
\]  

(42)  
(43)  
(44)  
(45)

The expressions (39) to (45) satisfy the following relationships:

\[
\begin{align*}
\sum_{n=1}^{\infty} \delta_n &= \Sigma \xi_n = \Sigma \xi_n = \Sigma \xi_n = \Sigma \xi_n = \Sigma \xi_n = \Sigma \xi_n = \Sigma \xi_n = \Sigma \mu_n = 1
\end{align*}
\]  

(46)

Figs. 3; 4; 5; 6; 7 show the various coefficients as function of \( \gamma \). Fig. 8 shows the function \( J_0(y\sqrt{\sigma_n}) \).

4. Comparison with the lumped model and physical meaning of \( \gamma \)

The lumped model is that obtained by considering the fuel element as a simple thermal capacitance and therefore neglecting any heat propagation effect. In this case the heat balance equation is the following:

\[
2\pi R \left( \Delta T - \Delta \Theta \right) + \pi R^2 \rho_f c_f \frac{dT}{dt} = \pi R^2 \Delta q
\]  

(47)

Introducing the notations (6); (7) and (8) and making the Laplace transformation, equation (47) becomes:

\[
\Delta T^* = \frac{1}{1+\gamma \sigma} \Delta \Theta^* + \frac{R}{2h} \frac{1}{1+\gamma \sigma} \Delta q^*
\]  

(48)

Comparing (48) with (20), it appears that they are equal if:

\[
Z(\sigma) = \frac{1}{\sigma}
\]  

(49)
The lumped model gives a good description of the transient when $\gamma \to \infty$. In fact from fig.2:

$$\lim_{\gamma \to \infty} \sigma_1 = \frac{1}{a_1 \gamma}$$

and therefore:

$$\lim_{\gamma \to \infty} \sigma_1 = \frac{1}{\gamma} \quad \text{(51)}$$

and in all the expressions (29) to (36) it is:

$$\lim_{\gamma \to \infty} \delta_1 = \lim_{\gamma \to \infty} \xi_1 = \lim_{\gamma \to \infty} \delta_1 = \lim_{\gamma \to \infty} \xi_1 = \lim_{\gamma \to \infty} \mu_1 = 1 \quad \text{(52)}$$

and for $n \neq 1$

$$\lim_{\gamma \to \infty} \delta_n = \lim_{\gamma \to \infty} \xi_n = \lim_{\gamma \to \infty} \delta_n = \lim_{\gamma \to \infty} \xi_n = \lim_{\gamma \to \infty} \mu_n = 0 \quad \text{(53)}$$

as also it appears from figs.3 to 7.

From (20) and (21), it is possible to obtain (for $\sigma \to 0$):

$$\gamma = \frac{1}{\frac{c}{T_c - T_s}} \quad \text{with reactor in stationary conditions} \quad \text{(54)}$$

Metallic fuel elements (fig.1) are characterized by a flat temperature distribution inside the fuel element in comparison to the temperature drop between surface and coolant, that is $T_c - T_s \ll T_s - \Theta$ ($\gamma$ big). Their temperature transients are therefore well described by the lumped model.

In the case of ceramic fuel elements (as in Sefor) the temperature distribution inside the fuel element is very shaped ($T_c - T_s \gg T_s - \Theta$; $\gamma$ small) and therefore the more refined model is needed to describe the temperature transients.

$\gamma$ has also other two physical meanings:

$$\gamma = \frac{\lambda}{2hr} = \frac{1}{4} \frac{1/2\pi R h}{\lambda} = \frac{1}{4} \quad \text{thermal resistance between fuel and coolant}$$

$$\text{equivalent thermal resistance of the fuel} \quad \text{(54')}$$. 
with heat production supposed to be concentrated in the center of the fuel element, and
\[
\gamma = \frac{\phi \cdot R/2h}{\phi \cdot R^2/\lambda} = \frac{t}{t_r} = \text{time constant of the lumped model} / \text{radial time scale}
\]  
(54')

5. Antitransformation in sums of exponentials

All the transfer functions calculated in paragraph 3 are of the type:
\[
M(\sigma) = \sum_{n=1}^{\infty} \frac{d_n}{1 + \sigma / \sigma_n}
\]
(55)

with:
\[
\sigma_{n+1} > \sigma_n
\]
(56)
\[
|d_{n+1}| < |d_n|
\]
(57)
\[
\sum_{n=1}^{\infty} d_n = 1
\]
(58)

Let us consider the case in which the power (or the coolant temperature) is a step function. In this case an expression of the type
\[
X^*(\sigma) = \frac{1}{\sigma} \sum_{n=1}^{\infty} \frac{d_n}{1 + \sigma / \sigma_n}
\]
(59)

must be antitransformed. The solution in the time domain is:
\[
X(\tau) = 1 - \sum_{n=1}^{\infty} d_n e^{-\sigma_n \tau}
\]
(60)

For practical purposes the series of exponentials must be arrested to a value \(n=m\). We shall consider the two approximate solutions:
\[
X_{m+}(\tau) = 1 - \sum_{n=1}^{m} d_n e^{-\sigma_n \tau} \quad \text{(upper approximation)}
\]
(61)
\[
X_{m-}(\tau) = 1 - \sum_{n=1}^{m} d_n e^{-\sigma_n \tau} \quad \text{(lower approximation)}
\]
(62)
where:
\[
\frac{1}{D_m} = \sum_{n=1}^{n=m} d_n < 1
\]  (63)

At any value of \( \gamma \) it is:
\[
X_m^- (\gamma) < X (\gamma) < X_m^+ (\gamma)
\]  (64)

The transfer functions corresponding to equations (61) and (62) are respectively:
\[
M'_+ (\sigma) = \sigma X^*_m (\sigma) = (1 - \frac{1}{D_m} + \sum_{n=1}^{n=m} \frac{d_n}{1 + \frac{\sigma}{\sigma_n}})
\]  (65)
\[
M'_- (\sigma) = \sigma X^*_m (\sigma) = D_m \sum_{n=1}^{n=m} \frac{d_n}{1 + \frac{\sigma}{\sigma_n}}
\]  (66)

6. Antitransformation by using for \( Z(\sigma) \) the approximate expression \( R(\sigma) \)

The mathematical treatment already described gives rapidly convergent approximated expressions for the functions \( F_s (\sigma) \), \( F_c (\sigma) \) and \( F_{av} (\sigma) \).

In the case of \( G_s (\sigma) \) the approximated expressions are not rapidly convergent for small values of \( \gamma \).

A complete different approach to the problem is to make the antitransformation by direct integration along the imaginary axis of the complex plane.

Let us examin the frequency response of the function \( Z(\sigma) \), that is when \( \sigma = i \nu \)
\[
Z(\nu) = e^{-\frac{\pi}{4} i} \frac{J_0 (e^{\frac{3\pi}{4} i} \sqrt{\nu})}{2\sqrt{\nu} J_1 (e^{\frac{3\pi}{4} i} \sqrt{\nu})}
\]  (67)

Fig.9 shows the polar diagram of \( Z(\nu) \) and figs.10 and 11 amplitude and phase of \( Z(\nu) \) as function of \( \nu \).
From the asymptotic expressions of the Bessel functions, it is possible to calculate:

\[
\lim_{\nu \to 0} Z(\nu) = \frac{1}{8} + \frac{1}{4\nu} \tag{68}
\]

\[
\lim_{\nu \to \infty} Z(\nu) = \frac{1}{2\sqrt{i\nu} - 1} \tag{69}
\]

Let us consider the function:

\[
R(\nu) = \frac{\sqrt{1+0.25i\nu}}{i\nu} \quad \text{(Bibl.3)} \tag{70}
\]

which has the asymptotes:

\[
\lim_{\nu \to 0} R(\nu) = \frac{1}{8} + \frac{1}{4\nu} \tag{71}
\]

\[
\lim_{\nu \to \infty} R(\nu) = \frac{1}{2\sqrt{i\nu}} \tag{72}
\]

Fig.12 shows the errors in amplitude and phase made by substituting \(Z(\nu)\) with \(R(\nu)\).

Putting \(R(\nu)\) in the expressions \(G_s(\sigma)\), \(F_s(\sigma)\) and \(F_{av}(\sigma)\), we obtain:

\[
G_s(\sigma) = \frac{\sqrt{1+0.25\sigma}}{\sqrt{1+0.25\sigma} + \gamma\sigma} \quad \text{when} \quad \sigma = i\nu \tag{73}
\]

\[
F_s(\sigma) = \frac{1}{\gamma\sigma + \sqrt{1+0.25\sigma}} \quad \text{when} \quad \sigma = i\nu \tag{74}
\]

\[
F_{av}(\sigma) = \frac{1}{1 + \frac{1}{8\gamma}} \frac{1}{\gamma\sigma + \sqrt{1+0.25\sigma}} \quad \text{when} \quad \sigma = i\nu \tag{75}
\]

Let us consider now the case in which the power (or the coolant temperature) is a step function. Then the antitransformed are:
\[
L^{-1} \left[ \frac{1}{\sigma} G_{\sigma}(\sigma) \right] \approx 1(T) - \frac{\beta - \alpha}{2\beta} e^{-\frac{(\beta-\alpha)\gamma}{\gamma}} \left[ 1 + E \left[ 2(\beta-\alpha)\sqrt{T} \right] \right] - \\
- \frac{\beta + \alpha}{2\beta} e^{-\frac{\alpha+\beta\gamma}{\gamma}} \left[ 1 - E \left[ 2(\beta+\alpha)\sqrt{T} \right] \right]
\]

(76)

\[
L^{-1} \left[ \frac{1}{\sigma} F_{\sigma}(\sigma) \right] \approx E(2\sqrt{T}) - \frac{1}{2 \beta} e^{-\frac{\beta - \alpha}{\gamma}} \left[ 1 + E \left[ 2(\beta-\alpha)\sqrt{T} \right] \right] + \\
+ \frac{1}{2 \beta} e^{-\frac{\alpha+\beta\gamma}{\gamma}} \left[ 1 - E \left[ 2(\beta+\alpha)\sqrt{T} \right] \right] 
\]

(77)

\[
L^{-1} \left[ \frac{1}{\sigma} F_{av}(\sigma) \right] \approx \frac{8\gamma}{1+8\gamma} \left\{ 1(T) + \frac{E(2\sqrt{T})}{8\gamma} - \frac{\sqrt{T} e^{-4\gamma}}{\gamma \cdot 2 \sqrt{\pi}} \right\} \\
+ \frac{T}{\gamma} \left[ 1 - E(2\sqrt{T}) \right] - \frac{\beta + \alpha}{2\beta} e^{-\frac{\beta - \alpha}{\gamma}} \left[ 1 + E \left[ 2(\beta-\alpha)\sqrt{T} \right] \right] - \\
- \frac{\beta - \alpha}{2\beta} e^{-\frac{\alpha+\beta\gamma}{\gamma}} \left[ 1 - E \left[ 2(\beta+\alpha)\sqrt{T} \right] \right]
\]

(78)

where:

\[
L^{-1} = \text{antitransformation} \\
E = \text{error function} \\
\alpha = \frac{0.125}{\gamma} \\
\beta = \sqrt{1+\alpha^2}
\]

(79) (80)

(77) and (78) can be obtained directly by (74) and (75) or by (76), taking into account (24) and (28).

Using (24) and (28), it is also possible to evaluate the case in which the power is a pulse function.
In fact:

\[ L^{-1}\left[ F_S(\sigma) \right] = L^{-1}\left[ \frac{1}{\gamma \sigma} - \frac{1}{\gamma \sigma} G_S(\sigma) \right] = \frac{1}{\gamma} \left[ 1(\tau) - L^{-1}\left[ \frac{1}{\sigma} G_S(\sigma) \right] \right] \]  

(81)

and

\[ L^{-1}\left[ F_{av}(\sigma) \right] = \frac{1}{1+\frac{1}{\delta \gamma}} L^{-1}\left[ \frac{1}{\gamma \sigma} - \frac{1}{\gamma \sigma} \frac{F_S(\sigma)}{\delta \gamma} \right] = \frac{8}{1+3\gamma} \left[ 1(\tau) - L^{-1}\left[ \frac{1}{\sigma} F_S(\sigma) \right] \right] \]  

(82)

where \( L^{-1}\left[ \frac{1}{\sigma} G_S(\sigma) \right] \) and \( L^{-1}\left[ \frac{1}{\sigma} F_S(\sigma) \right] \) are already given respectively by (77) and (78).

It is possible to demonstrate that for \( \gamma \to \infty \) the expressions (76); (77) and (78) all tend to:

\[ 1 - e^{-\frac{\tau}{\gamma}} \]  

(83)

which is the solution given by the lumped model.

It is very interesting to examin the behaviour of the expression (76) for \( \gamma \to 0 \). It is:

\[ \lim_{\gamma \to 0} L^{-1}\left[ \frac{1}{\delta} G_S(\sigma) \right] = 1(\tau) - 16\gamma^2 e^{-4\gamma} \left[ 1 + E(8\gamma\sqrt{\gamma}) \right] e^{-\gamma/\gamma^2} \left[ 1 - E(\sqrt{\gamma}) \right] \to 1(\tau) \]  

(84)

which is difficult to approximate with expressions like (59). Instead from (77) and (78):

\[ \lim_{\gamma \to 0} L^{-1}\left[ \frac{1}{\delta} F_S(\sigma) \right] = E(2\sqrt{\gamma}) \]  

(85)

\[ \lim_{\gamma \to 0} L^{-1}\left[ \frac{1}{\delta} F_{av}(\sigma) \right] = E(2\sqrt{\gamma}) + 8\gamma \left[ 1 - E(2\sqrt{\gamma}) \right] + \frac{4}{\gamma \sqrt{\gamma}} \sqrt{\gamma} e^{-4\gamma} \]  

(86)

which can be easier approximated by expressions like (59). This explains why the series of \( \delta_{sn} \) (fig.3) is poorly convergent for small values of \( \gamma \), while the series of \( E_{sn} \) and \( \eta_n \) (figs.5 and 7) are rapidly convergent.

(76); (77) and (78) can be developed in expressions of the type:

\[ \sum_{n=1}^{\infty} d_n (\sqrt{\gamma})^n \]  

(87)

where the "d_n" are functions of \( \gamma \).
For $\tau \to 0$, we have:

$$\lim_{\tau \to 0} L^{-1}\left[\frac{1}{\sigma} G_S(\sigma)\right] = \frac{\sqrt{\tau}}{\gamma \sqrt{\pi}} - \frac{\tau}{4\gamma^2} \ldots \ldots \tag{88}$$

$$\lim_{\tau \to 0} L^{-1}\left[\frac{1}{\sigma} F_S(\sigma)\right] = \frac{\tau}{\gamma} - \frac{2(\sqrt{\tau})^3}{3\gamma^2 \sqrt{\pi}} + \frac{\tau^2}{8\gamma^3} \ldots \ldots \tag{89}$$

$$\lim_{\tau \to 0} L^{-1}\left[\frac{1}{\sigma} F_{av}(\sigma)\right] = \frac{8}{1+8\gamma} \left[ \tau - \frac{\tau^2}{2 \gamma} + \frac{4(\sqrt{\tau})^5}{15\gamma^2 \sqrt{\pi}} - \frac{\tau^3}{24\gamma^3} \ldots \ldots \right] \tag{90}$$

Let us consider the case in which the coolant temperature remain constant and the power changes as a pulse function $H \cdot \xi(\tau)$, $H$ being the energy of the pulse. From (22) and (82), we have:

$$\frac{2h}{R} \frac{8\gamma}{1+8\gamma} \frac{\Delta T_{av}(\tau)}{H/V_f} = L^{-1}\left[ F_{av}(\sigma) \right] = \frac{8}{1+8\gamma} \left[ L(\tau) - L^{-1}\left[ \frac{1}{\sigma} F_S(\sigma) \right] \right] \tag{91}$$

$V_f$ being the volume of fuel in reactor.

For $\tau \to 0$, (91) becomes:

$$\frac{2h}{R} \frac{8\gamma}{1-8\gamma} \frac{\Delta T_{av}(\tau)}{H/V_f} \to \frac{8}{1+8\gamma} \left[ L(\tau) - \frac{\tau}{\gamma} + \frac{2(\sqrt{\tau})^3}{3\gamma^2 \sqrt{\pi}} \ldots \ldots \right] \tag{92}$$

In the region $0 < \gamma \ll \gamma$ the temperature change is a step function which is the integral of the pulse. In this interval the temperature change can be considered proportional to the time integral of the power change, which means that all the heat produced remains inside the fuel rod.

In a super-prompt critical reactivity ramp test (Bibl.6) the power changes in a way very similar to a pulse function, so that we can suppose that all the heat produced remains inside the fuel rods as long as:

$$\tau_{\text{max}} \ll \gamma$$

In the real time domain, taking into account (54'), condition (93) becomes:

$$t_{\text{max}} \ll \gamma t_r = \frac{\rho c_i R}{2h} = t' = \text{time constant of the lumped model} \tag{94}$$
In order to increase the useful experiment time, $t_{\text{max}}$, reactors like Sefor, designed specifically for this type of experiment, must have fuel rods with big radius.

In the Sefor case, it is:

\begin{align*}
\gamma &= 0.07 \\
t_r &= 160 \text{ secs.} \\
t_g &= 11.2 \text{ secs.}
\end{align*}

7. Electrical Analogy and physical meaning of $Z(\xi)$

Fig.13 A shows the cylindrical electrical line equivalent to eq.(1): temperatures are represented by voltages, heat flows by currents, heat sources by current sources, heat resistances by electrical resistances and heat capacitances by electrical capacitances.

Fig.13 B shows the same cylindrical electrical line having introduced the normalized time, $\tau$, the normalized radius, $\alpha$, and $\gamma$. This line is equivalent to eq.(13). The functions $G_s(\xi); F_s(\xi); G_c(\xi); F_c(\xi); G_{av}(\xi)$ and $F_{av}(\xi)$ can therefore be calculated by solving the electrical network of fig.13 B. If in fig.13 B we put $\Delta q = 0$, we can calculate $G_s(\xi)$.

Applying the usual network theorems, we can get the simple circuit of fig.14 A in which $Z(\xi)$ is the output impedance of the cylindrical electrical line.

An empirical approach to calculate temperature transients in a cylindrical fuel element is usually the following: to divide the fuel element in "n" concentric cylinders having the same thickness and to write for each cylinder the equation of the lumped model. This leads to solve the electrical network of fig.14 B. From this network we can calculate approximate expressions for $G_s(\xi); F_s(\xi); G_c(\xi); F_c(\xi); G_{av}(\xi)$ and $F_{av}(\xi)$ and by comparison with the exact functions (23); (24); (25); (26); (27) and (28), it is possible to establish for any function how many concentric cylinders are needed in order to get the wanted degree of accuracy. In the case of $G_s(\xi); F_s(\xi); G_{av}(\xi)$ and $F_{av}(\xi)$, since they depend only on $\gamma$ and on $Z(\xi)$, the problem is reduced to calculate the
output impedance $Z(\sigma)$ of the electrical network of fig.14 B:

$$Z(\sigma) = \frac{1}{\sigma^{2n-1} + \frac{1}{\sigma^{2n-3}} + \frac{1}{\sigma^{2n-5}} + \cdots}$$

(98)

8. Numerical Examples

Fig.15 shows the polar diagram of the functions $G_s(i\nu)$; $G_c(i\nu)$ and $G_{av}(i\nu)$ in the Sefor case ($\gamma=0.07$). Fig.16 shows the polar diagram of the functions $F_s(i\nu)$; $F_c(i\nu)$ and $F_{av}(i\nu)$ always in the Sefor case. In both the figures the dotted line represents the lumped model. The value $\gamma=0.07$ has been calculated including in "h" the heat transfer coefficients fuel to cladding, internal to external surface of the cladding and cladding to coolant. Let us consider the average temperature transients in the two simple cases in which the power, $P$, changes as a step $[\Delta P_0 \cdot \delta(\tau)]$ and as a pulse function $[H \cdot \delta(T)]$, $H$ being the energy of the pulse. During the transients under consideration, it has been supposed that the coolant temperature, $Q$, is constant.

We have from (22) in the case of the step function:

$$\Delta T_{av}(\tau) = \frac{R \cdot \Delta Q}{2h} \left[1 + \frac{1}{8Y}\right] L^{-1} \left[\frac{1}{\sigma} F_{av}(\sigma)\right] = \frac{R}{2h} \frac{\Delta P_0}{V_f} \frac{8\gamma}{1+8\gamma} \left[\frac{1}{\sigma} F_{av}(\sigma)\right]$$

(99)

$V_f$ being the volume of fuel in reactor.

From (22) and (28) in the case of the pulse function we have:

$$\Delta T_{av}(\gamma) = \frac{R H}{2h V_f} \left[1 + \frac{1}{8Y}\right] L^{-1} \left[F_{av}(\sigma)\right] = \frac{R H}{2h V_f} \frac{1}{Y} L^{-1} \left[\frac{1}{\sigma} \delta F_{av}(\sigma)\right]$$

(100)

Fig.17 shows the function $\frac{2h V_f}{R \Delta P_0} \frac{1}{1+\frac{1}{8Y}} \Delta T_{av}(\gamma) = L^{-1} \left[\frac{1}{\sigma} F_{av}(\sigma)\right]$.

Fig.18 shows the function $\frac{2h V_f}{R H} \frac{1}{1+\frac{1}{8Y}} \Delta T_{av}(\gamma) = L^{-1} \left[F_{av}(\sigma)\right]$.
Both the figures are referred to the Sefor case ($\gamma=0.07$). Both the figures have on the horizontal axis the normalized time scale and the real time scale. The vertical axis of fig.17 has the scale relative to $L^{-1}\left[\frac{1}{6}F_{av}(\delta)\right]$ and that relative to $\Delta T_{av}/\Delta P$ in $^\circ$C/MW. The vertical axis of fig.18 has the scale relative to $L^{-1}\left[F_{av}(\delta)\right]$ and that relative to $\Delta T_{av}/H$ in $^\circ$C/MW sec.

Fig.21 and 22 show respectively amplitude and phase of the frequency response of the function $\frac{1}{6}F_{s}(\delta)$ and its approximations which enter in (100).

The upper and lower approximations with exponentials have been calculated, according to (65) and (66). The frequency response is better approximated by increasing the number "n" of exponentials (fig.21 and 22).

Fig.23 and 24 show the case $\gamma=0.35$ and figs.25 and 26 the case $\gamma=0.01$. These two values of $\gamma$ have been chosen as limiting values of the range in which $\gamma$ can vary depending on the uncertainty of the heat transfer characteristics of a power reactor. Particularly the heat transfer constant "n" can have very different values depending mainly on the model used to calculate the heat transfer coefficient fuel to cladding (gap conduction or contact conductance model).

9. Acknowledgements

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Appendix 1 - Solution of the heat balance equation

The Laplace transform of the heat balance equation is (eq.13 of par.2):

\[
\frac{d^2 \Delta T^*}{dy^2} + \frac{1}{y} \frac{d \Delta T^*}{dy} - \sigma \Delta T^* = - \frac{R}{2h\gamma} \Delta q^*
\]  

(1)

and the boundary conditions are (eqs.14 and 15 of par.2):

\[
\left[ \frac{d \Delta T^*}{dy} \right]_{y=0} = 0
\]  

(2)

\[
\left[ \frac{d \Delta T^*}{dy} \right]_{y=1} = - \frac{1}{2\gamma} (\Delta T^*_S - \Delta \Phi^*)
\]  

(3)

with \( \gamma = \frac{\lambda}{2hR} \)  

(4)

The solution of equation (1) is:

\[
\Delta T^* = \frac{R}{2h\gamma \sigma} \Delta q^* + A J_0 (y \sqrt{-\sigma}) + B K_0 (y \sqrt{-\sigma})
\]  

(5)

where the symbols \( J \) and \( K \) indicate Bessel functions respectively of first and second kind.

Boundary condition (2) gives:

\[
B = 0
\]  

(6)

and therefore (5) becomes

\[
\Delta T^* = \frac{R}{2h\gamma \sigma} \Delta q^* + A J_0 (y \sqrt{-\sigma})
\]  

(7)

Differentiating equation (7), we obtain:

\[
\frac{d(\Delta T^* - \frac{R}{2h\gamma \sigma} \Delta q^*)}{dy} = - A \sqrt{-\sigma} J_1 (y \sqrt{-\sigma})
\]  

(8)

The ratio between (7) and (8) gives:

\[
\frac{\Delta T^* - \frac{R}{2h\gamma \sigma} \Delta q^*}{d(\Delta T^* - \frac{R}{2h\gamma \sigma} \Delta q^*)} = 2y Z(y^2 \sigma)
\]  

(9)
where:
\[ Z(y^2; \sigma) = - \frac{J_0(y \sqrt{-\sigma})}{2y \sqrt{-\sigma} J_1(y \sqrt{-\sigma})} \]  
(10)

Taking into account (9), (3) becomes:
\[ \frac{1}{2Z(\sigma)} \left[ \Delta T_s^* - \frac{R}{2hY \sigma} \Delta q^* \right] = - \frac{1}{2Y} (\Delta T_s^* - \Delta q^*) \]  
(11)

and therefore:
\[ \Delta T_s^* = G_s(\sigma) \Delta q^* + \frac{R}{2h} F_s(\sigma) \Delta q^* \]  
(12)

where:
\[ G_s(\sigma) = \frac{1}{1 + \frac{\sigma}{Z(\sigma)}} \]  
(13)

and
\[ F_s(\sigma) = \frac{1}{Z(\sigma)} = \frac{1}{Y \sigma} \left[ 1 - G_s(\sigma) \right] \]  
(14)

From (7) and (12), we obtain (putting \( y = 1 \)):
\[ A = \frac{G_s(\sigma)}{J_0(\sqrt{-\sigma})} \Delta q^* - \frac{R}{2h} \frac{1}{Y \sigma} \frac{G_s(\sigma)}{J_0(\sqrt{-\sigma})} \Delta q^* \]  
(15)

Introducing (15) in (7), we have:
\[ \Delta T^* = G(y; \sigma) \Delta q^* + \frac{R}{2h} \left[ 1 + \frac{1 - \frac{Y^2}{4Y}}{4} \right] F(y; \sigma') \Delta q^* \]  
(16)

where:
\[ G(y; \sigma) = G_s(\sigma) \frac{J_0(y \sqrt{-\sigma})}{J_0(\sqrt{-\sigma})} = \frac{1}{1 + \frac{\sigma}{Z(\sigma)}} \frac{J_0(y \sqrt{-\sigma})}{J_0(\sqrt{-\sigma})} \]  
(17)

and
\[ F(y; \sigma) = \frac{1}{1 + \frac{1 - \frac{Y^2}{4Y}}{4Y}} \frac{1}{Y \sigma} \left[ 1 - G(y; \sigma') \right] \]  
(18)
Appendix 2 - Calculation of the average temperature variation

The average temperature is given by the following formula:

$$\Delta T_{av} = \frac{1}{n} \int_{0}^{1} 2\pi y \Delta T^* dy$$

(1)

Taking into account equations (17) and (18) of Appendix 1, we can write:

$$\Delta T_{av} = G_{av}(\sigma) \Delta q^* + \frac{R}{2h} (1 + \frac{1}{\delta_{Y}}) F_{av}(\sigma) \Delta q^*$$

(2)

where:

$$G_{av}(\sigma) = \frac{2G_{s}(\sigma)}{J_{o}(\sqrt{-\delta})} \int_{0}^{1} y J_{o}(y\sqrt{-\delta}) dy = \frac{2G_{s}(\sigma)}{J_{o}(\sqrt{-\delta})} \frac{J_{1}(\sqrt{-\delta})}{\sqrt{-\delta}} = \frac{G_{s}(\sigma)}{\delta Z(\sigma)} = F_{s}(\sigma)$$

(3)

$$F_{av}(\sigma) = \frac{1}{1 + \frac{1}{\delta_{Y}}} \frac{1}{\sqrt{\delta}} \left[ 1 - G_{av}(\sigma) \right]$$

(4)

Appendix 3 - Solution of the characteristic equation

The characteristic equation is the following:

$$1 + \frac{\gamma}{Z(\sigma)} = 0$$

(1)

with:

$$Z(\sigma) = -\frac{J_{o}(\sqrt{-\sigma})}{2\sqrt{-\sigma} J_{1}(\sqrt{-\sigma})} = \frac{d}{d\sigma} \log \left[ \sqrt{-\sigma} J_{1}(\sqrt{-\sigma}) \right]$$

(2)

Equation (1) can be written as follows:

$$\frac{d}{d\sigma} \log \left[ \sqrt{-\sigma} J_{1}(\sqrt{-\sigma}) \right] = -\gamma$$

(3)
It is:

\[ J_1(\sqrt{-\sigma}) = \frac{\sqrt{-\sigma}}{2} \sum_{n=2}^{\infty} \frac{1}{b_n} (1 + \frac{\sigma}{b_n}) \]  \hspace{3cm} (4)

where \( b_n \) are the real zeros of the Bessel function \( J_1 \).

Equation (3) can be written:

\[ \frac{1}{\sigma} + \sum_{n=2}^{\infty} \frac{1}{b_n} \frac{1}{1 + \frac{\sigma}{b_n}} = -\gamma \]  \hspace{3cm} (5)

with all the \( b_n \) real and positive.

If \( \sigma = x + iy \) is a root of equation (5), then, putting it in (5), the imaginary part must be equal to zero, that is:

\[ y \left[ \frac{1}{x^2 + y^2} + \sum_{n=2}^{\infty} \frac{1/b_n^2}{(1+x/b_n)^2 + y^2/b_n^2} \right] = 0 \]  \hspace{3cm} (6)

Equation (6) is satisfied only if:

\[ y = 0 \]  \hspace{3cm} (7)

From (7) we can conclude that all the roots of the characteristic equation (1) are real. Since the coefficients of equation (1) are all positive, the roots will also be all negative.

Fig.27 shows the function \( Z(\sigma) \) plotted against negative values of \( \sigma \) on logarithmic scales. The roots are given by the intersection of the curve \( Z(\sigma) \) with the horizontal lines \( \gamma = \text{constant} \).

Eq.(1) has been programmed on a digital computer IBM 7070 and its roots, \(-\sigma_n\), have been calculated up to the value \( n=20 \) for values of \( \gamma \) between \( 10^{-4} \) and 10.

Fig.2 shows the normalized values, \( \bar{\sigma}_n \), as function of \( \gamma \). The relationship between \( \sigma_n \) and \( \bar{\sigma}_n \) is the following:

\[ \sigma_n = b_n + (a_n - b_n) \bar{\sigma}_n \]  \hspace{3cm} (8)
where $\sqrt{a_n}$ and $\sqrt{b_n}$ are respectively the n-th zeros of the Bessel functions $J_0$ and $J_1$. The values of the coefficients $a_n$ and $b_n$ are given in table 1.

It is interesting to know that

$$\lim_{\gamma \to \infty} \sigma_1 = \frac{1}{\gamma}$$

and therefore

$$\lim_{\gamma \to \infty} \sigma_1 = \frac{1}{a_1 \gamma}$$

being $b_1 = 0$ (table 1)

Appendix 4 - Evaluation of the coefficients associated to the series of exponentials

We shall start with the coefficients $\delta_{sn}$ from eq.(29) par.3. $\delta_{sn}$ is calculated in the following way:

$$\delta_{sn} = \lim_{\sigma \to -\sigma_n} G_n(\sigma) (1 + \frac{\sigma}{\sigma_n}) = \lim_{\sigma \to -\sigma_n} \frac{1 + \frac{\sigma}{\sigma_n}}{1 + \frac{\gamma}{2(\sigma)}}$$

$$= \lim_{\sigma \to -\sigma_n} \frac{(1 + \frac{\sigma}{\sigma_n}) J_0(\sqrt{-\sigma})}{J_0(\sqrt{-\sigma}) - 2\gamma \sqrt{-\sigma} J_1(\sqrt{-\sigma})} = \frac{J_0(\sqrt{\sigma_n})}{\sqrt{\sigma_n}} - \frac{\gamma J_0(\sqrt{\sigma_n})}{2 \sqrt{\sigma_n}} + \gamma J_0(\sqrt{\sigma_n})$$

$$= \frac{1}{\sigma_n} \frac{1}{\gamma - \frac{1}{\sigma_n}}$$

(1)
With reference to eq.(1) in Appendix 3

\[ Z(\sqrt{-\sigma_n}) = -\gamma \]  

(2)

the final expression is:

\[ \delta_{sn} = \frac{\gamma}{0.25 + \gamma^2 \sigma_n} \]  

(3)

We obtain:

a) from eqs.(24) and (39)

\[ \mathcal{E}_{sn} = \frac{\delta_{sn}}{\gamma \sigma_n} = \frac{1}{\sigma_n(0.25+\gamma^2 \sigma_n)} \]  

(4)

b) from eqs.(25) and (31)

\[ \delta_{cn} = \frac{\delta_{sn}}{J_o(\sqrt{\sigma_n})} = \frac{\gamma}{0.25 + \gamma^2 \sigma_n} \]  

(5)

c) from eqs.(26) and (32)

\[ \mathcal{E}_{cn} = \frac{1}{1 + \frac{1}{\delta \gamma}} \cdot \frac{\delta_{cn}}{\gamma \sigma_n} = \frac{4 \gamma}{1+4 \gamma} \cdot \frac{1}{\sigma_n(0.25+\gamma^2 \sigma_n)} \]  

(6)

d) from eqs.(28) and (36)

\[ \mu_n = \frac{1}{1 + \frac{1}{\delta \gamma}} \cdot \frac{\mathcal{E}_{sn}}{\gamma \sigma_n} = \frac{8}{1+8 \gamma} \cdot \frac{1}{\sigma_n(0.25+\gamma^2 \sigma_n)} \]  

(7)

e) from eqs.(17), (25) and (33)

\[ \delta_n = \delta_{cn} \cdot J_o(\gamma \sqrt{\sigma_n}) = \frac{\gamma}{0.25+\gamma^2 \sigma_n} \cdot \frac{J_o(\gamma \sqrt{\sigma_n})}{J_o(\sqrt{\sigma_n})} \]  

(8)

f) from eqs.(19), (33) and (34)

\[ \mathcal{E}_n = \frac{1+ \frac{\delta_n}{\gamma \sigma_n}}{1+ \frac{1-\gamma^2}{4 \gamma}} \cdot \mathcal{E}_{cn} \cdot J_o(\gamma \sqrt{\sigma_n}) = \frac{4 \gamma}{1-\gamma^2+4 \gamma} \cdot \frac{1}{\sigma_n(0.25+\gamma^2 \sigma_n)} \cdot \frac{J_o(\gamma \sqrt{\sigma_n})}{J_o(\sqrt{\sigma_n})} \]  

(9)
Appendix 5 - Antitransformation by using for $Z(\sigma)$ the approximate expression $R(\sigma)$

From (73) of par. 6, it is:

$$\frac{1}{6} G_2(\sigma) \approx \frac{1}{6} \frac{\sqrt{1+0.25\sigma^2}}{\sqrt{1+0.25\sigma^2} + \gamma \sigma}$$  \hspace{1cm} (1)

(1) can be written as follows:

$$\frac{1}{6} G_2(\sigma) = \frac{1}{6} - \frac{c_1}{c_1 - c_2} \frac{1}{\sigma + c_1} - \frac{1}{2\gamma(c_1 - c_2)} \frac{\sqrt{\sigma + 4}}{\sigma + c_1} - \frac{c_2}{c_2 - c_1} \frac{1}{\sigma + c_2} - \frac{1}{2\gamma(c_2 - c_1)} \frac{\sqrt{\sigma + 4}}{\sigma + c_2}$$  \hspace{1cm} (2)

where:

$$c_1 = \frac{1}{\gamma} (\beta - \alpha)$$  \hspace{1cm} (3)

$$c_2 = -\frac{1}{\gamma} (\beta + \alpha)$$  \hspace{1cm} (4)

$$\alpha = \frac{0.125}{\gamma}$$  \hspace{1cm} (5)

$$\beta = \sqrt{1 + \alpha^2}$$  \hspace{1cm} (6)

Taking into account that:

$$L^{-1}\left(\frac{1}{6}\right) = 1(\tau)$$  \hspace{1cm} (7)

$$L^{-1}\left(\frac{c_1}{c_1 - c_2} \frac{1}{\sigma + c_1}\right) \approx \frac{c_1}{c_1 - c_2} e^{-c_1\tau} = \frac{\beta - \alpha}{2\beta} e^{-\frac{\beta - \alpha}{\gamma} \tau}$$  \hspace{1cm} (8)
We obtain:

\begin{align*}
L^{-1} \left[ \frac{1}{2\gamma(c_1-c_2)} \sqrt{\sigma+c_1} \right] & = \frac{1}{2\gamma(c_1-c_2)} \left[ \sqrt{\pi} e^{-4\tau} + \sqrt{4-c_1} e^{-c_1\tau} E(\sqrt{4-c_1}\tau) \right] \\
& = \frac{1}{4\beta} e^{-4\tau} + \frac{\beta-\alpha}{2\beta} e^{-\frac{\beta-\alpha}{\gamma} \sqrt{2(\beta-\alpha)\tau}} \\
(9)
\end{align*}

\begin{align*}
L^{-1} \left[ \frac{c_2}{c_2-c_1} \right] & = \frac{c_2}{c_2-c_1} e^{-c_2\tau} = \frac{\beta+\alpha}{\gamma} \\
(10)
\end{align*}

\begin{align*}
L^{-1} \left[ \frac{1}{2\gamma(c_2-c_1)} \sqrt{\sigma+c_2} \right] & = \frac{1}{2\gamma(c_2-c_1)} \left[ \sqrt{\pi} e^{-4\tau} + \sqrt{4-c_2} e^{-c_2\tau} E(\sqrt{4-c_2}\tau) \right] \\
& = -\frac{1}{4\beta} e^{-4\tau} - \frac{\beta+\alpha}{2\beta} e^{-\frac{\beta+\alpha}{\gamma} \sqrt{2(\beta+\alpha)\tau}} \\
(11)
\end{align*}

We obtain:

\begin{align*}
L^{-1} \left[ \frac{1}{\sigma} G_s(\sigma) \right] &= 1(\tau) - \frac{\beta-\alpha}{2\beta} e^{-\frac{\beta-\alpha}{\gamma} \sqrt{2(\beta-\alpha)\sqrt{\tau}}} \\
& \quad - \frac{\beta+\alpha}{2\beta} e^{-\frac{\beta+\alpha}{\gamma} \sqrt{2(\beta+\alpha)\sqrt{\tau}}} \\
(12)
\end{align*}

(9) and (10) have been calculated according to Bibl.5, vol.1,p.235, Nr.22.

The antitransformed of \( \frac{1}{\sigma} F_s(\sigma) \) and \( \frac{1}{\sigma} F_{av}(\sigma) \) can be calculated in the same way or by integration of \( L^{-1} \left( \frac{1}{\sigma} G_s(\sigma) \right) \) in the time domain using respectively eqs.(24) and (28) of par.2.
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System Geometry

Fig. 1
Coefficients $\delta_{sn}$ associated to the poles of $G_s(\sigma)$ as function of $\gamma$.
Coefficients $\varepsilon_{sn}$ associated to the poles of $F_\alpha(\delta) = G_{\alpha\nu}(\delta)$ as function of $\gamma$.
Coefficient $E_n$ associated to the poles of $F(0)$ as function of $y$.
Coefficient $\mu_n$ associated to the poles of $F_\nu(\theta)$ as function of $\gamma$.

\[
\sum_{n=1}^{\infty} \mu_n = \mu_0 + \mu_1 \mu_2 + \cdots
\]
Polar diagram of the function

$$Z(z) = \frac{1}{2} \left( 1 + e^{\frac{z^2}{2}} \right)$$

with $z = iy$

Fig. 9
Phase diagram of the function

\[ Z = \frac{e^{\frac{s}{1000}} (e^{\frac{100}{1000}} - 1)}{2 \cdot \frac{\sigma}{1000} (e^{\frac{100}{1000}} - 1)} \]

Phase diagram of the function \( Z(\sigma) \) with \( \sigma = i \nu 

Fig. 11

Eine Achse logar. geteilt von 1 bis 10000, Einheit 62,5 mm, die andere in mm mit Prozentmaßstab
Fig. 13 A

Fig. 13 B

Fig. 13

Electrical Analogy
Fig. 14

Electrical Analogy
Approximated curves of the antitransformed of the function \( \frac{1}{0} F_{av}(\alpha) \) in the case \( \gamma = 0.07 \)

Response of the average fuel temperature, \( T_{av} \), to a power step. Initial power = 20 MW
FIG. 18

To a power pulse steady state power = 20 MW

Response of the average fuel temperature, Tavg

Of the function Favg(6) in the case y = 0.07

Approximeted curves of the untransformed

fitted model

7 approximation with the erroj function

4 lower approximations with two ex-

Upper approximations with four ex-

Lower approximations with one ex-

2 upper approximations with one ex-

1
Amplitude diagram of the frequency response of $F_0(x)$ and its approximations ($y=0.07$)

1. $F_0(x)$
2. Lumped model
3. Upper approximation with 1 exponential
4. Lower approximation with 1 exponential

Fig. 19

Beide Achsen logar. geteilt von 1 bis 10000 und 1 bis 300 Einheit 62,5 mm
Amplitude diagram of the frequency response of \( f_0(x) \) and its approximations (\( y = 0.07 \)).

Fig. 21

- \( f_0(x) \)
- lumped model
- upper approximation with 1 exponential
- lower approximation with 1 exponential
- upper approximation with 4 exponentials
- lower approximation with 4 exponentials

Beide Achsen logar. geteilt von 1 bis 10000 und 1 bis 300 Einheit 62,5 mm
Approximated curves of the antitransformed of the function $I^{\frac{1}{3}} \frac{1}{a} F_\alpha(a)$ in the case $\gamma = 0.25$

1. lower approximation
   approximation with one exponential
2. upper approximation
   approximation with the error function
   lumped model
Approximated curves of the antitransformed of the function $L^*\left[F_x(\theta)\right]$ in the case $\gamma = 0.25$.

1. lower approximation
2. upper approximation
   approximation with one exponential
   approximation with the error function
   lumped model

Fig 24
Approximated curves of the antitransformed
of the function \( \frac{1}{\sigma} \text{F}_{\alpha}(\sigma) \) in the case \( \gamma = 0.01 \).

Fig. 25

1. Upper approximation with one exponential
2. Lower approximation with one exponential
3. Approximation with the error function
4. Lumped model
Graphical solution of the characteristic equation

$z(0) = 1$
Table 1

Relationship between the zeros $\sigma_n$ and the normalized zeros $\hat{\sigma}_n$ of
the characteristic equation

$$\sigma_n = b_n + (a_n - b_n) \hat{\sigma}_n$$

$\sqrt{a_n} = n$-th zero of the Bessel function $J_0$

$\sqrt{b_n} = n$-th zero of the Bessel function $J_1$

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