

**KfK 4630**  
**Oktober 1989**

# **A Formal Net Specification of the Communication in a Distributed Computer System**

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A FORMAL NET SPECIFICATION OF THE COMMUNICATION IN A  
DISTRIBUTED COMPUTER SYSTEM

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Postfach 3640, 7500 Karlsruhe 1

ISSN 0303-4003

## Abstract

The *Petri Net Theory* provides a method for the *formal specification of* concurrent systems (e.g. distributed computer systems for diagnostic- and shutdown functions in Fast Reactors).

This method includes the *verification/validation* of the net specification about the causal behavior of the modeled concurrent system.

Especially the *Predicate/Transition Nets* (most important class of *high level nets*) provide very compact net specifications. Additionally, a Predicate/Transition Net can be described by different levels of a system abstraction (for example in form of a *net morphism*).

So it is possible to describe a concurrent system in a formal manner and to validate its causal behavior already during the design phase in the software live cycle. For example it can be shown, that all global states of an application protocol do not include *deadlocks* and *livelocks*.

Formal net specifications and the results of their analysis raise the *reliability* of software systems themselves and also the quality of the software documentation.

For the verification and documentation of net specifications *computer tools* are an absolute necessity.

In our case the operating system UNIX\* is available with a special *Petri Net Tool PROVER* (**P**redicate/**T**ransition Net **O**riented **V**ERification System).

In this environment a net specification was developed which provides a formal description of an *application protocol* for a communication system. This communication system is the central part of our distributed *Fast Reactor Diagnostic System DESYRE* (**D**iagnostic **E**xpert **S**ystem for **R**eactor Surveillance).

## Zusammenfassung

### Eine formale Netz Spezifikation zur Beschreibung der Kommunikation in einem verteilten Rechnersystem

Die Petri Netz Theorie beschreibt eine Methode zur formalen Spezifikation nebenläufiger Systeme (z.B. verteilte Rechnersysteme zur Diagnose und zur Abschaltung in Schnellen Brutreaktoren).

Diese Methode enthält Möglichkeiten zur Verifikation/Validation der Netzspezifikation in bezug auf das kausale Verhalten des modellierten nebenläufigen Systems. Insbesondere die Prädikat/Transitions Netze (eine sehr wichtige Klasse der höheren Netze) unterstützen eine sehr kompakte Netzspezifikation. Zusätzlich können Prädikat/Transitions Netze verschiedene Ebenen einer Systemabstraktion beschreiben (z.B. in Form eines Netz Morphismus).

Auf diese Weise ist es möglich, ein nebenläufiges System in einer formalen Art zu beschreiben und die Validierung bereits während der Entwurfsphase im Rahmen des Software Lebens Zyklus vorzunehmen. Man kann z.B. zeigen, daß alle globalen Zustände des Applikations Protokolls keine Verklemmungen (deadlocks, livelocks) enthalten.

Formale Netzspezifikationen sowie die Ergebnisse ihrer Analyse erhöhen die Zuverlässigkeit von Software Systemen und ebenfalls die Qualität der Softwaredokumentation. Für die Verifikation und Dokumentation von Netzspezifikationen sind rechnergestützte Werkzeuge unbedingt notwendig.

In unserem Fall ist das Petri Netz Werkzeug PROVER (**P**redicate/**T**ransition Net **O**riented **V**ERification System) unter dem Betriebssystem UNIX verfügbar.

In dieser Umgebung wurde eine Netzspezifikation erstellt, welche ein Applikationsprotokoll für ein Kommunikationssystem beschreibt. Dieses Kommunikationssystem ist ein zentraler Teil des verteilten Diagnosesystems am Schnellen Brüter DESYRE (**D**iagnostic **E**xpert **S**ystem for **R**eactor Surveillance).

\* UNIX is a trademark of AT&T

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## 1. Introduction

The *Fast Reactor Diagnostic System DESYRE* (Diagnostic Expert SYstem for REactor Surveillance) [1], [2], [3], [4] is realized as a distributed on-line computer system.

The system includes a set of special *detection computers* (e.g. for the detection of acoustic noise and temperature noise.)

These different detection systems use intelligent signal processing techniques to find out special faults and anomalies and to make partial diagnoses in an early state.

The system also includes a *process computer* for immediate processing of raw data and an on-line simulator for the simulation of faults.

Furthermore, the system contains a special *LISP computer* with an *expert system* for the inference of the correlated predications of the detection computers and the process computer.

A test system [5] allows for the description and the generation of test data in the computer network. Therefore, the inference of rules in the expert system can be easily tested with regards to their logical consistency by application of such a test system.

Figure 1 illustrates the computer network in form of an informal Petri Net (channel/instance net).

The communication between the different computers [6] within the seven levels of the *ISO/OSI communication model* [7] is realized with a *local area network (IEEE 802.3/Ethernet)* [8] and the *TCP/IP Protocol (Transmission Control Protocol/Internet Protocol)* [9].

Figure 2 illustrates the ISO/OSI - seven layer reference model in form of a channel instance net.

The level seven (*application protocol*) of the ISO/OSI communication model is realized in the following way:

- All above mentioned computers are used as *clients* in the computer network,
- an additional computer, the *data manager*, is used as a *server* in the computer network.

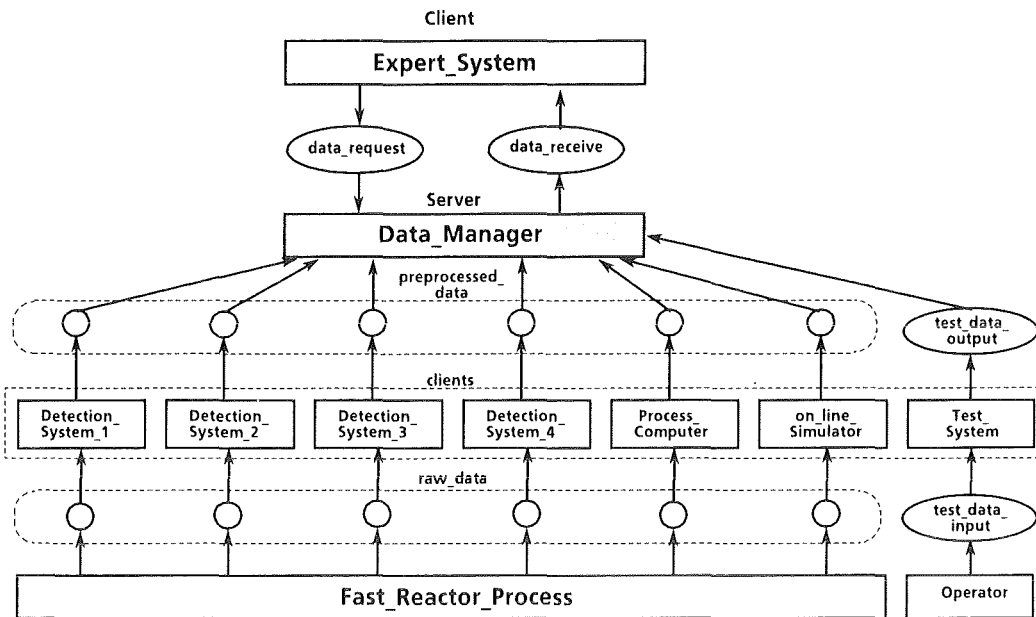


Figure 1: DESYRE: Distributed Expert System for Reactor Surveillance

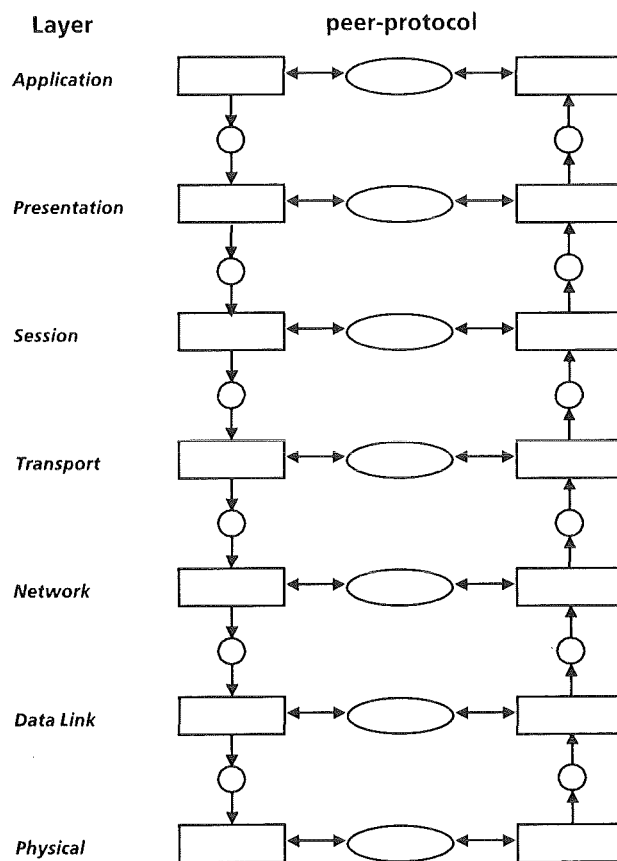


Figure 2: ISO/OSI - seven layer reference model and peer protocol

The data manager (server) *receives* preprocessed data from the detection computers and the process computer (clients) and *sends* these data to the expert system (client) (see also figure 1).

Therefore the data manager provides the following *abstract datatypes*:

- *FIFO* (First In, First Out)
- *RA* (Random Access) for history data.



The description of this application protocol is already made before an implementation. It is realized in form of a *formal net specification* with *Predicate/Transition Nets*.

Before presenting the method of Predicate/Transition Nets and the formal specification of the application protocol a general idea about the structure of the communication between clients and server shall be given.

Figure 3 represents this idea by an example of a File Transfer Protocol in form of a channel/instance net.

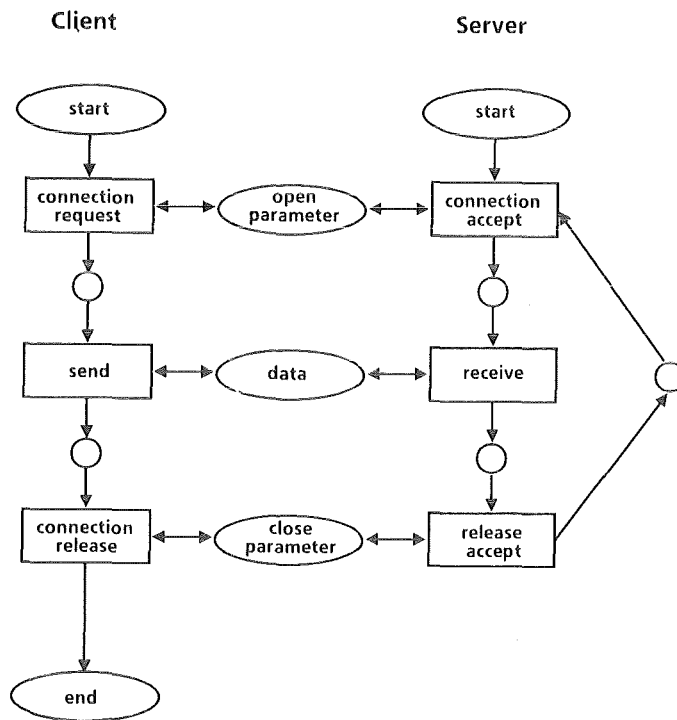


Figure 3: Application Layer: a short form of a File Transfer Protocol

Clients can send open parameters to the server trying in this way to get connections inside the local area network.

If a client gets an available connection, it sends or receives data to/from the server via this allocated connection. After this procedure, the active client gives back the connection to the server and the server can allocate this connection for other clients.

## 2. Formal specifications with Petri Nets

### 2.1 Preliminary remarks

The functionality of concurrent systems (e.g. application protocols inside a distributed computer system) may not completely be verified by tests as the number of dynamic states in the system is too large.

Therefore it is not possible to validate concurrent systems by only using test procedures.

Particularly in case of the integration of computer applications in technical environments with features of high safety (e.g. Fast Reactors) it is necessary to validate these computer applications with regard to the requirements of their reliability.

Verification of the most critical part of systems - *the concurrency* - is possible before realizing the implementation in form of a formal net specification.

Compilation of the net specification and simulation of the dynamic behavior of the net (all global states of the net) can be performed by application of a computer tool.

After the simulation all global states of the net are described in the *reachability graph*.

Another part of the computer tool allows for the interpretation of the reachability graph concerning deadlocks, livelocks and other failures of the design (for more information see chapter 3.2).

After validation of the formal net specification has been made the computerized automatic generation of the real runtime system is desirable. This however will not be discussed in this paper.

## 2.2 Place/Transition Nets

The Net Theory [10], [11] provides a method for the description of processes (the dynamic behavior of systems).

Here an axiomatic approach to the description of the information flow is made, assuming that the description of real processes is causal and does not include the arrangement into a time scheme.

Without any theory the figure 4 mediates an idea about *place/transition nets*.

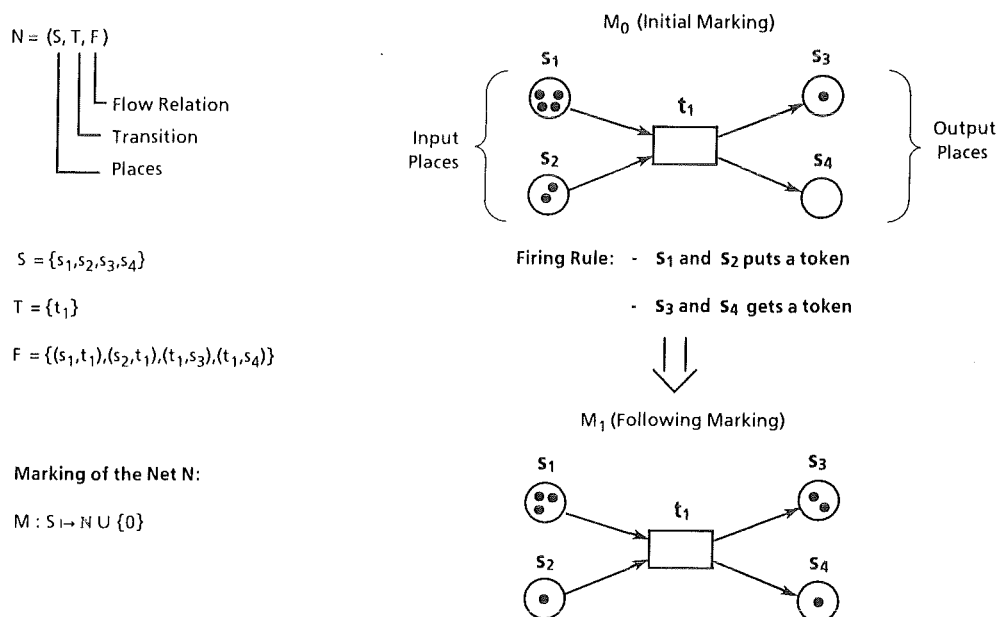


Figure 4: A Place/Transition Net

The static part of a net  $N$  includes *sets of places* (described as cycles in figure 4), *sets of transitions* (described as rectangles in figure 4) and a *flow relation* (described as arcs in figure 4).

We distinguish between input places and output places of a transition.

The dynamic part of a net  $N$  is described as *tokens* which means that the sets of places are mapped into the natural numbers.

The *firing rule* of place/transition nets implies that input places put a token and output places get a token. The first dynamic state in a net  $N$  is named *initial marking*.

A generalization of the firing rule is possible with the multiplicity of arcs and the capacity of places.

The multiplicity of arcs is defined as the "number" of tokens leaving the input places and arriving at the output places of a firing transition.

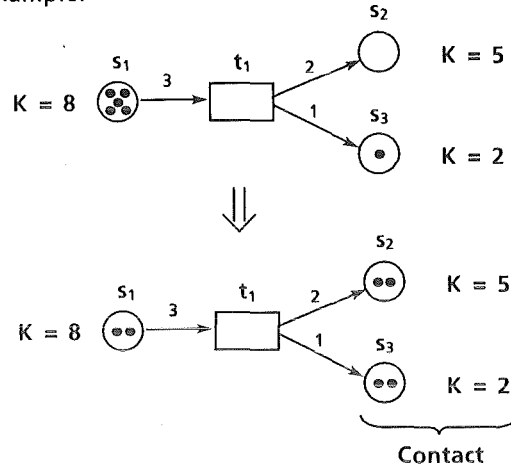
For the safety of nets the *capacity* of a place is necessary.

An example is given in figure 5.

### Generalization of the Firing Rule

- Multiplicity of Arcs
- Capacity of Places (K)

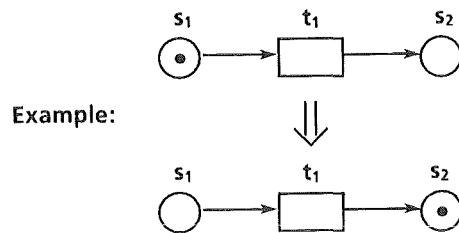
Example:



An Upperbound of the Capacity of a Place is necessary for the Safety of Nets

Figure 5: Generalization of the Firing Rule

### Deadlock



### Livelock

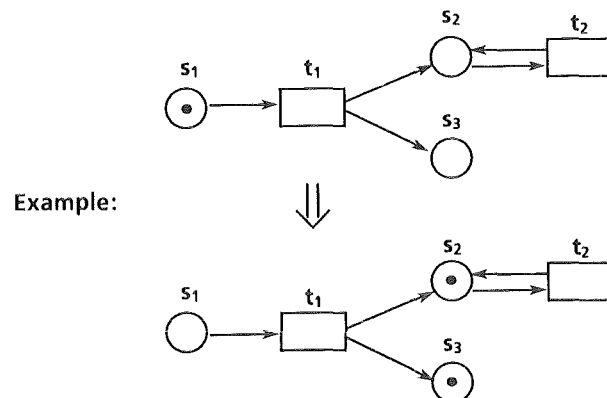


Figure 6: Deadlock and Livelock

Finally, a simple example of failures of the system design (see also chapter 2.1) will be shown.

Figure 6 illustrates a simple *deadlock* and a simple *livelock*.

Every real system working failure-free produces cyclical processes and not only one process step. This example describes the simplest form of a deadlock.

Considering the example of a livelock the transition  $t_1$  can make exactly one firing step and as a result the transition  $t_2$  can make infinite firing steps. This demonstrates the simplest form of a livelock.

### 2.3 Predicate/Transition Nets

For the description of extensive systems the place/transition nets discussed above are not sufficiently powerful because of the simple mapping of places into natural numbers and the simple firing rule in particular.

Much more powerful are the *predicate/transition* nets (high level petri nets) [12]. In the following these nets will be discussed without making any further remarks on the theory.

A partial formal overview is illustrated in figure 7.

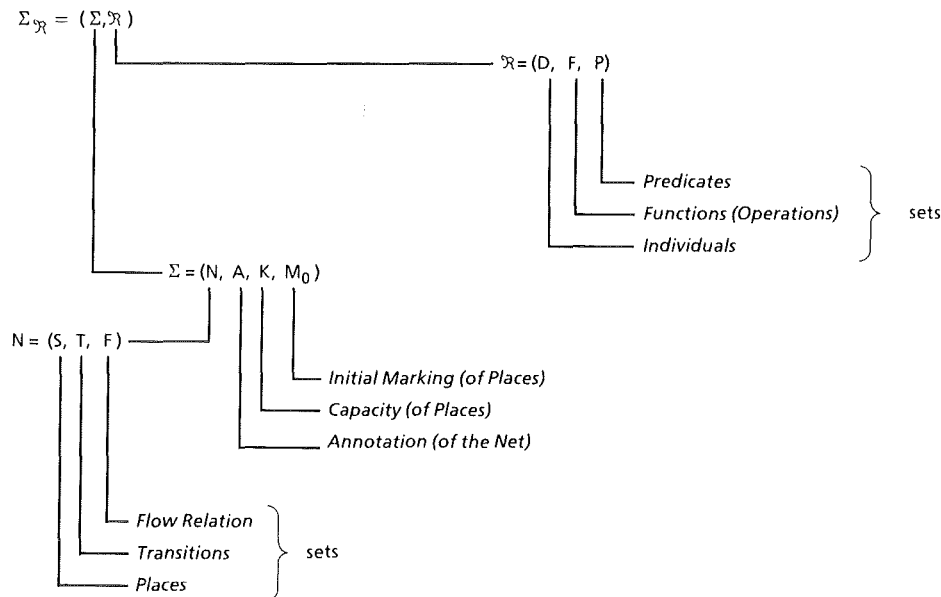


Figure 7: A partial Definition of Predicate / Transition Nets

Predicate/Transition nets consist of syntactical and semantical extensions of place/transition nets. The syntactical extension means the *annotation* of the net. The initial marking and the capacity has been already discussed in chapter 2.2.

The semantical extension implies the possibility to define *individual tokens* and their handling in the net. These individual tokens can be built from *sets of individuals*.

Furthermore, places can be mapped into predicates so that a semantical relationship exists between individual tokens, predicates and functions.

An example for the illustration of this abstraction is shown in figure 8 depicting the relationship between the formalism of predicate/transition nets which we already have discussed before and a simple application with only one place, one transition and the flow relation with two elements (two arcs).

This application describes the communication protocol on the highest possible level of the clients and the server inside the system DESYRE (see chapter 1).

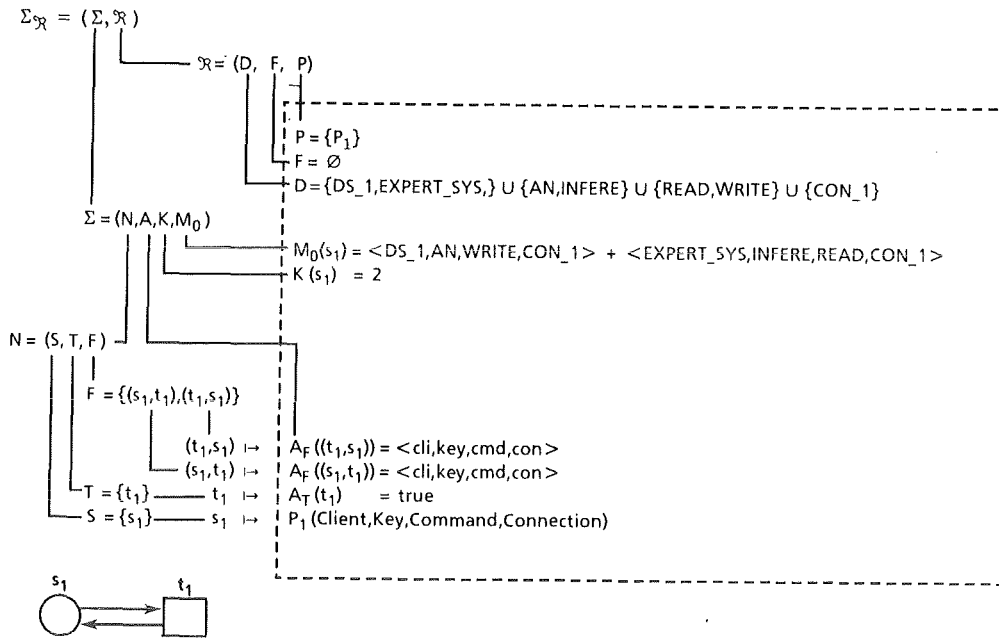


Figure 8: A Predicate / Transition Net in a Formal Form

The individuals in the union set  $D$  were defined as follows:

First subset of  $D$ :

- DS\_1 (detection System 1)
- EXPERT\_SYS (Expert System)

Second subset of  $D$ :

- AN (Acoustic Noise)
- INFERE (Inference)

Third subset of  $D$ :

- READ (receive)
- WRITE (transmit)

Fourth subset of  $D$ :

- CON\_1 (Connection 1)

Based on these individuals we have built the two individual tokens  $\langle DS\_1, AN, WRITE, CON\_1 \rangle$  and  $\langle EXPERT\_SYS, INFERE, READ, CON\_1 \rangle$  which are used for the initial marking of the net in form of a formal sum.

Furthermore, the predicate  $P_1$  of the place  $S_1$  is defined.

$P_1$  has the following meaning:

Some *clients* (e.g. Detection System 1, Expert System) using *keys* (e.g. Acoustic Noise, Inference) and the *command* (READ or WRITE) receive or transmit from/to the server via the symbolic connection CON\_1 inside the local area network.

In this example the set of functions is empty and the capacity of  $s_1$  is 2.

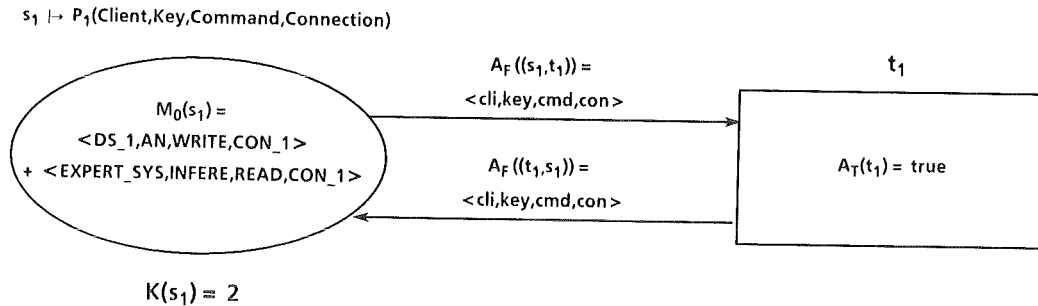
The remaining will be easy to understand.

The flow relation (from the place to the transition and reverse) is described by the variables  $\langle cli, key, cmd, con \rangle$ .

There is a direct association between the variables, the predicate  $P_1$  and the individual tokens.

The annotation of the transition is true (logical formula) and does not include any further conditions in this case.

Figure 9 shows the same net representing the graphical elements of place/transition nets in a more visual form.



**Figure 9: A Predicate / Transition Net in a Visual Form**

The dynamic behavior of this net may as well be easily understood.

The reachability graph of the net which represents the dynamic behavior of the net includes only one node because all the following markings are exactly the same as the initial marking.

It is trivial that the node of the graph builds only one strongly connected component (SCC). That means that there is a mutual reachability of all markings in the net.

"Only one SCC" permits the interpretation that no deadlocks and no livelocks occurred and that a correction of the system design is not necessary.

On such a very high level of a model abstraction a view of single steps of the communication protocol of DESYRE is not possible and it should suffice here to understand the principles of predicate/transition nets.

In the next chapter we will try to give a more detailed view of the stepwise development of the communication protocol with predicate/transition nets.

### 3. A part of a formally specified communication protocol

#### 3.1 Modeling by stepwise refinement

Designing a system in only one step is not possible. This would not be a good style of engineering and lead to unconditionally bad system designs which as a result produce unreliable systems.

The methods of structured programming [13] and stepwise refinement [14] teach us a good style of programming design and can be easily transferred into the context of the system design with nets.

The net specification of the application protocol consists two principles of *software engineering*:

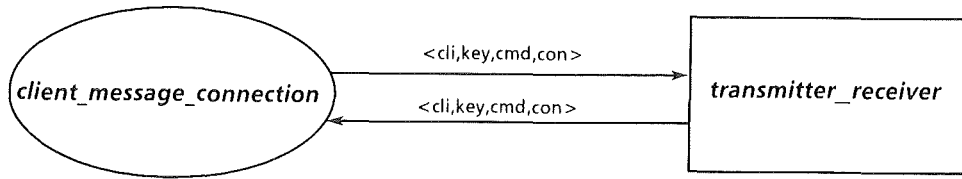
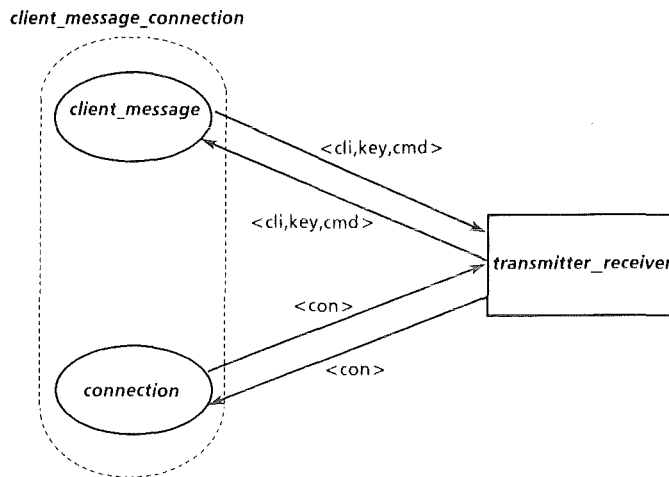
- *stepwise refinement* of nets (net morphism),
- *embedding* of nets in other nets (net morphism).

Based on these principles a large net specification can be subdivided into a set of several consistent net parts.

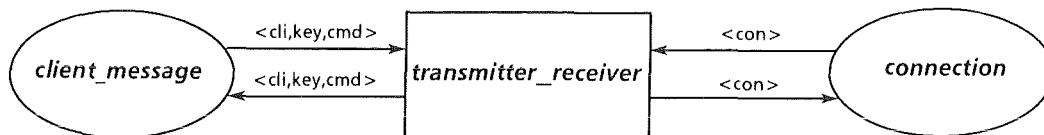
The description of the net parts by different steps is more comfortable than the description of the whole net in only one step because the number of nodes and arcs in a single net part can be handled much easier.

Accordingly, the verification of the net parts in small steps is much easier than the verification of the whole net in only one step because the number of all dynamical states (*reachability graph*) in a single part is not so large.



Figure 11: The net  $\Sigma_0$ Figure 12: The net  $\Sigma_1$ 

We split the place `client_message_connection` into the two places `client_message` and `connection`. The flow relation is split as well, depending on the protocol semantic and the topology of the net. Another representation of the net  $\Sigma_1$  is shown in figure 13.

Figure 13: The net  $\Sigma_1$ 

Here exactly the same net is discussed but the overall idea of the client/server system gets more clear. The transition `transmitter_receiver` includes the activities of the server and on this level of model abstraction we can see that the server provides connections for the clients.

Now let us consider the next step of refinement which is presented in figure 14.

In the net  $\Sigma_2$  the place `client_message` is split into the two places `client` and `message` and the flow relation as well. This net provides more information about the clients showing the client as object and its message.

The next step of refinement is presented in figure 15.

The net  $\Sigma_3$  provides more detailed information about the transition `transmitter_receiver` because of its splitting into the two transitions `open_accept` and `send_receive_close`.

Clients get connections and leave connections. In which way the clients send and receive messages will not be discussed more concretely in this paper.

Let us consider the next step of refinement giving more information about the connection handling in the communication protocol.



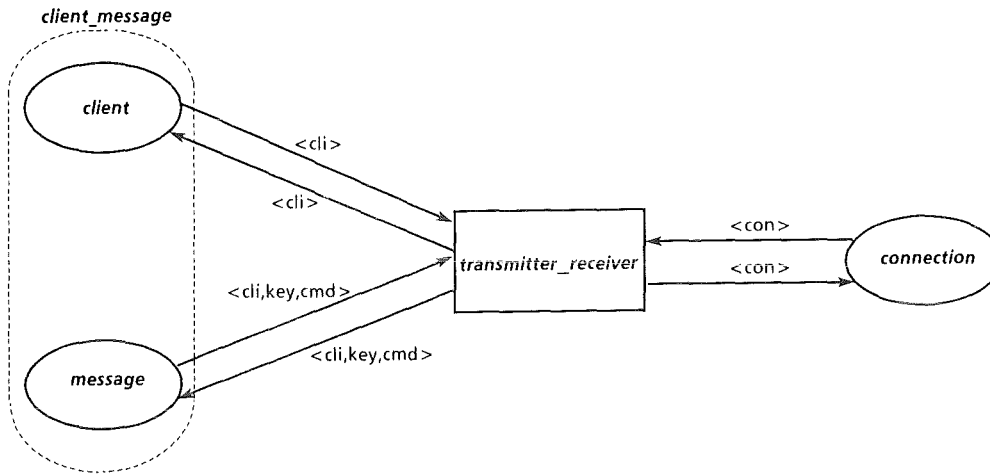


Figure 14: The net  $\Sigma_2$

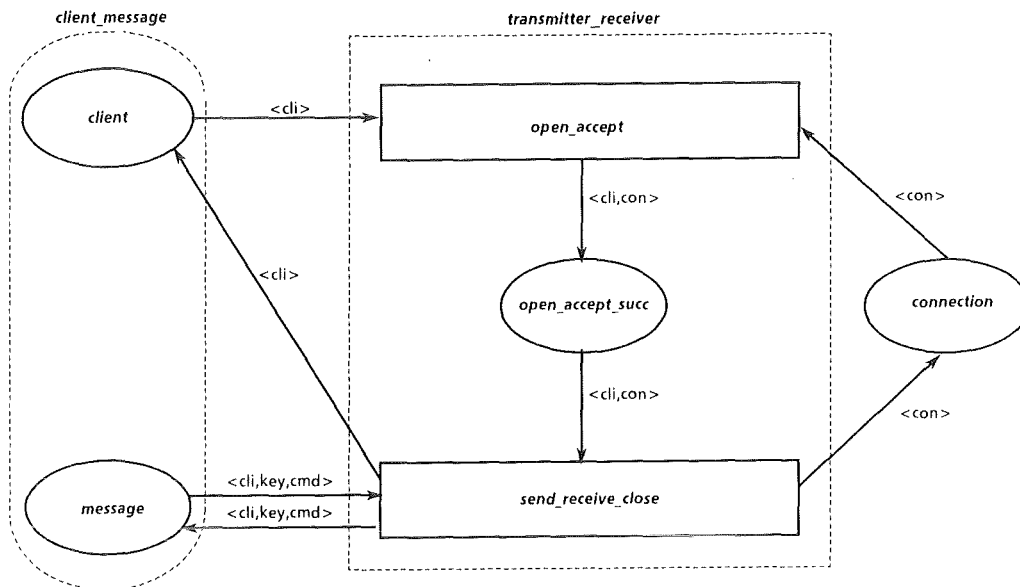


Figure 15: The net  $\Sigma_3$

Figure 16 presents additional information about the open of the client and the accept of the server.

The refinement step of the net  $\Sigma_4$  includes the refinement of the transition open\_accept and the refinement of the place open\_accept\_succ in parallel.

This net clearly represents the separation of clients and server.

Figure 17 shows the next step of refinement by splitting the place accept\_succ in the net  $\Sigma_4$  into the two places state\_con and con\_succ.

The refinement step in the net  $\Sigma_5$  is a suitable step for error handling if there is no connection available in the system.

If a client does not get a connection it cannot send or receive a message so that closing of this client would be of no purpose.

For a systematic interruption of the protocol procedure we define an additional transition error\_empty\_con with the condition if con=EMPTY\_CON and, subsequently an embedding (a special step of refinement) of this transition in the net  $\Sigma_5$  will be designed.

The embedded net has the symbolic name  $\Sigma_a$  (see also figure 10) presented in Figure 18.

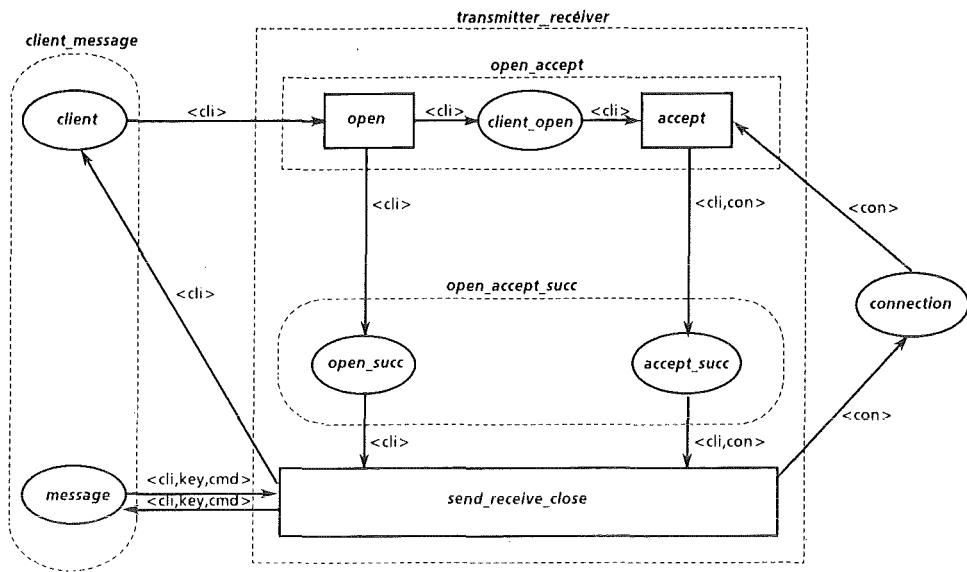


Figure 16: The net  $\Sigma_4$

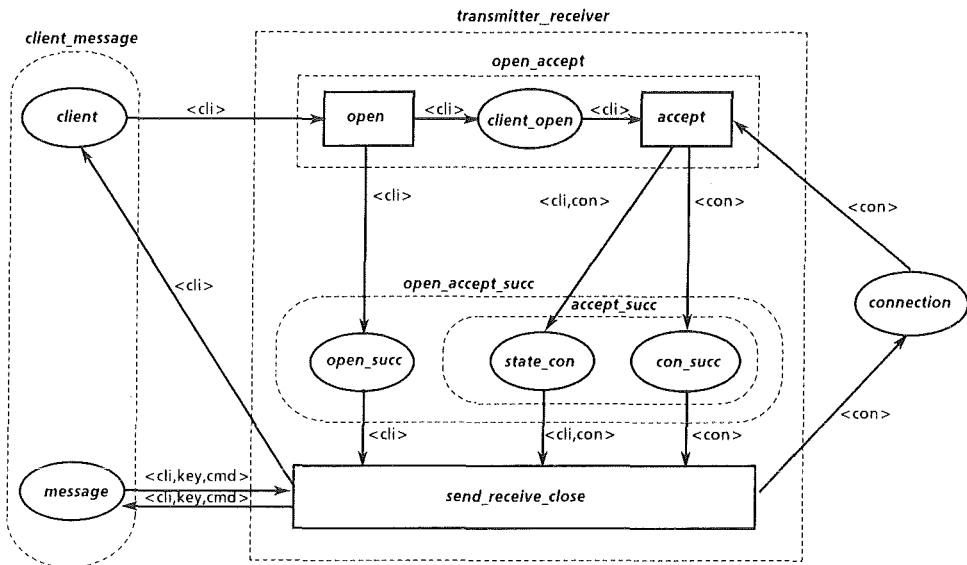


Figure 17: The net  $\Sigma_5$

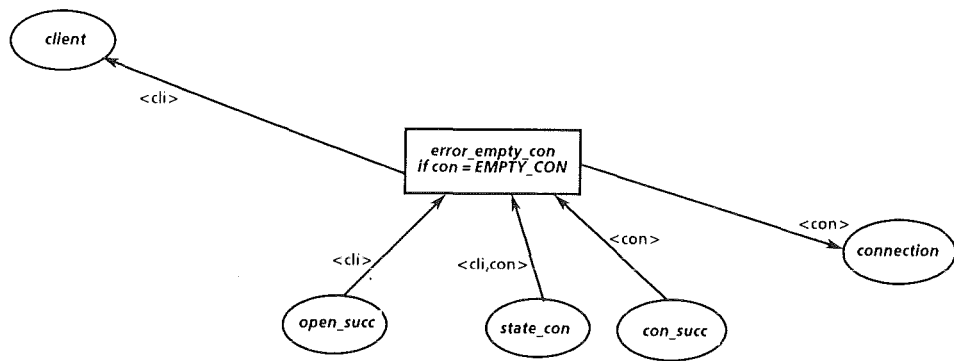


Figure 18: The net  $\Sigma_a$

Figure 19 shows the net  $\Sigma_6$ . This net includes error handling of unavailable connections in the communication system.



- (1) The Petri Net Compiler (PDLC) translates a net model which is described in the PDL (predicate/transition net description language). Syntactical errors and an internal net description will be generated.
- (2) Based on the internal net description and the initial marking the Reachability Graph Generator (RGG) generates the complete reachability graph.
- (3) The Reachability Graph Interpreter (RGS) applies a number of different methods for the reachability analysis. The most important method is the analysis of deadlocks and livelocks.

For more information see [16].

### 3.2.2 The partial verification of the net model with PROVER

First of all the net model in the PDL has to be described. The PDL representation of the net model  $\Sigma_6$  (see figure 19) is demonstrated in the following.

```

petrinet      sigma_6;

const  max_cli      = 8;
       max_con      = 8;

var     cli:        (DS_1, DS_2, DS_3, DS_4, PROCESS_COMP, TEST_SYS, ON_LINE_SIM,
                    EXPERT_SYS);
       key:         (AN, DN, FT, CM, TN, TMFI, PRIM_PUMP, INFERE, EMPTY_KEY);
       cmd:         (READ, WRITE);
       con:         (CON_1, CON_2, CON_3, CON_4, CON_5, CON_6, CON_7, CON_8,
                    EMPTY_CON);

place  client (max_cli)           'clients enters the system';
       message (max_cli)         'messages of the clients';
       client_open (max_cli)     'client send open';
       open_succ (max_cli)       'open is successful';
       state_con (max_cli)       'state of connections';
       con_succ (max_con)        'connection successful';
       connection (max_con)      'connections of the system';

trans  open                    'open of the system';
       accept                 'accept of the system';
       error_empty_con      if con = EMPTY_CON 'error no connection available';
       send_receive_close   'send_receive_close of the system';

flow   open                    < client (<cli>)
                               > client_open (<cli>), open_succ (<cli>);

       accept                 < client_open (<cli>), connection (<con>)
                               > state_con (<cli, con>), con_succ (<con>);

       error_empty_con       < open_succ (<cli>), state_con (<cli, con>),
                               con_succ (<con>)
                               > client (<cli>), connection (<con>);

       send_receive_close    < open_succ (<cli>), state_con (<cli, con>),
                               con_succ (<con>), message (<cli, key, cmd>)
                               > message (<cli, key, cmd>), client (<cli>),
                               connection (<con>);

mark   client:                <DS_1>+<EXPERT_SYS>;
       message:               <DS_1, AN, WRITE>+<EXPERT_SYS, INFERE, READ>;
       connection:           <CON_1>+<EMPTY_CON>;

endnet

```

Any further remarks on this PDL will not be interesting as the syntactical structure of this code is very simple (for more information see [16]) and the semantical structure of the net has already been discussed in chapter 3.1.

Just a remark on the initial marking of the net will be necessary.

The last part of the PDL representation of the net  $\Sigma_6$  is mark (that means the initial marking of the net  $\Sigma_6$ ).

In the place client there are two individual tokens in form of a formal sum,  
 $\langle DS\_1 \rangle + \langle EXPERT\_SYS \rangle$ .

The place message also includes two individual tokens in form of a formal sum,  
 $\langle DS\_1, AN, WRITE \rangle + \langle EXPERT\_SYS, INFERE, READ \rangle$ .

The place connection includes two individual tokens in form of a formal sum,  
 $\langle CON\_1 \rangle + \langle EMPTY\_CON \rangle$ .

That means that the detection system 1 tries to write (transmit) the results of its detection method "acoustic noise" to the server via the symbolic connection CON\_1.

And that means also that the expert system tries to read (receive) the results from the server via the symbolic connection CON\_1, too.

These processes are concurrent on the shared resource CON\_1.

The symbolic connection EMPTY\_CON simulates the error handling (see chapter 3.1). In fact, much more concurrency and shared resources exist in the net model but we will not consider these features on this level of model abstraction.

Now let us call the net compiler PDLC with the following input:

**pdlc sigma\_6**

The net compiler provides the following output:

```
PDL compilation summary : No errors reported
  Number of objects found, assorted by type:
    4 variables
   28 values
    0 functions
    7 places
    4 transitions
    0 facts

in predicate/transition net SIGMA_6
```

After the compilation of the net  $\Sigma_6$  has been done we call the reachability graph generator RGG with the following input:

```
rgg -m sigma_6
```

The reachability graph generator provides the following output:

```
Reading PRT net model      ...done.
Building reachability graph. One dot = 12 markings.
. done.
Writing reachability graph  ...done.

Reachability graph has  14 nodes in  1 strongly connected components
```

By making the following input our dialog is transferred into the rgi subsystem:

```
rgi sigma_6
```

The rgi subsystem provides the following output and stops with the prompt rgi>.

```
Reading      reachability graph ... done
Building strong component graph ... done
Calculating transition dynamics ... done
Calculating graph statistics    ... done

rgi>
```

Now we are in the rgi subsystem and we select a subset of questions about the reachability graph of the net  $\Sigma_6$  with its initial marking which we discussed before.

```
rgi> show statistics

      Number of variables :    4
      of values           :   28

      of places           :    7
      --"-- dead         :    0
      of transitions      :    4
      --"-- dead         :    0
      of overflows       :    0

      of facts            :    0
      of false facts     :    0

      of graph nodes     :   14
      of graph arcs      :   38
      of SCCs            :    1

Mean rel. place density  %(places / marking) : 74.5
Mean token density      (tokens / place)    :  1.4
Mean attribute density  (attributes / token) :  1.6
```

As all the questions are answered positively by the reachability graph interpreter RGI it has been proved that the net  $\Sigma_6$  is free of any design failures. For more information about design failures see [16].

rgi> show places

Places :

1. place : CLIENT  
 semantics : clients enters the system  
 arity : 1  
 capacity : 8  
 max. tokens: 2
2. place : MESSAGE  
 semantics : messages of the clients  
 arity : 3  
 capacity : 8  
 max. tokens: 2
3. place : CLIENT\_OPEN  
 semantics : client send open  
 arity : 1  
 capacity : 8  
 max. tokens: 2
4. place : OPEN\_SUCC  
 semantics : open is successful  
 arity : 1  
 max. tokens: 2
5. place : STATE\_CON  
 semantics : state of connections  
 arity : 2  
 capacity : 8  
 max. tokens: 2
6. place : CON\_SUCC  
 semantics : connection successful  
 arity : 1  
 capacity : 8  
 max. tokens: 2
7. place : CONNECTION  
 semantics : connections of the system  
 arity : 1  
 capacity : 8  
 max. tokens: 2

rgi> show variables

Variables :

1. variable : CLI  
 range : DS\_1, DS\_2, DS\_3, DS\_4, PROCESS\_COMP, TEST\_SYS,  
 ON\_LINE\_SIM, EXPERT\_SYS
2. variable : KEY  
 range : AN, DN, FT, CM, TN, TMFI, PRIM\_PUMP, INFERE, EMPTY\_KEY
3. variable : CMD  
 range : READ, WRITE
4. variable : CON  
 range : CON\_1, CON\_2, CON\_3, CON\_4, CON\_5, CON\_6, CON\_7, CON\_8,  
 EMPTY\_CON

```
rgi> show transitions
```

```
Transitions :
```

1. transition : OPEN (infinitely-firable, strongly-live & fair)  
semantics : open of the system
2. transition : ACCEPT (infinitely-firable, strongly-live & fair)  
semantics : accept of the system
3. transition : ERROR\_EMPTY\_CON (infinitely-firable, strongly-live & fair)  
semantics : error no connection available
4. transition : SEND\_RECEIVE\_CLOSE (infinitely-firable, strongly-live & fair)  
semantics : send\_receive\_close of the system

```
rgi> show deads
```

```
The dead places : none.
```

```
The dead transitions : none.
```

```
rgi> find livelocks
```

```
The livelocks : none.
```

We leave the Reachability Graph Interpreter with the command quit.

```
rgi> quit
```

#### 4. Conclusion

Formal net specifications and the results of their analysis raise the *reliability* of software systems themselves and also the *quality* of the *software documentation*.

In the future it may be necessary in West Germany to use formal net specifications and their verification/validation for *licence procedures* of the TÜV (Technischer Überwachungs Verein) in case of the integration of computer applications in the Fast Reactor and other technical environments with features of *high safety*.

Concerning the further development of the Petri Net tool PROVER we are currently working on the following components:

- graphical net editor with a better PDL representation and semantical features on homomorphism
- implementation of further possibilities of interpretation of the reachability graph.

We hope that for the future it will be possible to connect the Petri Net method with methods of algebraic specifications for algorithms.



This will be the basic assumption for the generation of real computer systems by formal system specifications.

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